# Trace, Metric, and Reality: Notes on Abstract Linear Algebra 

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Abstract. Elementary properties of the trace operator, and of some natural vector valued generalizations, are given basis-free statements and proofs, using canonical maps from abstract linear algebra. Properties of tensor contraction with respect to a non-degenerate (but possibly indefinite) metric are similarly analyzed.

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## Preface

These notes are a mostly self-contained collection of some theorems of linear algebra that arise in geometry, particularly results about the trace and bilinear forms. Many results are stated with complete proofs, the main method of proof being the use of canonical maps from abstract linear algebra.

So, the content of these notes is highly dependent on the notation for these maps developed in Chapter 1. This notation will be used in all the subsequent Chapters, which appear in a logical order, but for $1<m<n$, it is possible to follow Chapter 1 immediately by Chapter $n$, with only a few citations of Chapter $m$. To review the elementary prerequisites, some foundational material appears in Chapter 0 and the Appendices.

In such a collection of results, there will be several statements which will not be needed in later Lemmas, Theorems, or Examples, and can be skipped without losing any logical steps. Such statements will be labeled "Proposition" or "Exercise," with a short proof following from a "Hint" or left to the reader entirely. There are a few statements which are needed in later steps but whose proofs do not fit the basis-free theme; they are labeled "Claim," with proofs left to the references.

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## Overview

The goal of these notes is to present the subject of linear algebra in a way that is both natural as its own area of mathematics, and applicable, particularly to geometry. The unifying theme is the trace operator on spaces of linear maps, and generalizations of the trace, including vector valued traces, and traces with respect to non-degenerate inner products. The emphasis is on the canonical nature of the objects and maps, and on the basis-free methods of proof. The first definition of the trace (Definition 2.3) is essentially the "conceptual" approach of Mac Lane-Birkhoff ([MB] §IX.10) and Bourbaki ([B]). This approach also is taken in disciplines using linear algebra as a tool, for example, representation theory and mathematical physics $([\mathbf{F H}] \S 13.1$, $[\mathbf{G e r o c h}]$ Chapter $14,[\mathbf{K}])$. Some of the subsequent formulas for the trace (Theorem 2.10, and in Section 2.4) could be used as alternate but equivalent definitions. In most cases, it is not difficult to translate the results into the usual statements about matrices and tensors, and in some cases, the proofs are more economical than choosing a basis and using matrices. In particular, no unexpected deviations from matrix theory arise.

Part of the motivation for this approach is a study of vector valued Hermitian forms, with respect to abstractly defined complex and real structures. The conjugate linear nature of these objects necessitates careful treatment of scalar multiplication, duality of vector spaces and maps, and tensor products of vector spaces and maps ([GM], $[\mathbf{P}])$. The study of Hermitian forms seems to require a preliminary investigation into the fundamentals of the theory of bilinear forms, which now forms the first half of these notes. The payoff from the detailed treatment of bilinear forms will be the natural way in which the Hermitian case follows, in the second half.

Chapter 0 gives a brief review of elementary facts about vector spaces, as in a first college course; this should be prerequisite knowledge for most readers. Chapter 1 then sketches a review of notions of spaces of maps $\operatorname{Hom}(U, V)$, tensor products $U \otimes V$, and direct sums $U \oplus V$, and introduces some canonical linear maps, with the notation and basic concepts which will be used in all the subsequent Chapters. Chapter 2 starts with a definition of the usual trace of a map $V \rightarrow V$, and then states definitions for the generalized trace of maps $V \otimes U \rightarrow V \otimes W$, or $V \rightarrow V \otimes W$, whose output is an element of $\operatorname{Hom}(U, W)$, or $W$, respectively. Many of the theorems can be viewed as linear algebra versions of more general statements in category theory, as considered by [JSV], [Maltsiniotis], $[\mathbf{K}],[\mathbf{P S}]$, [Stolz-Teichner], [S].

Chapter 3 offers a similar basis-free approach to definitions, properties, and examples of a metric on a vector space, and the trace, or contraction, with respect to a metric. The metrics are assumed to be non-degenerate, and finite-dimensionality is a consequence. The main construction is a generalization of the well-known
inner product $\operatorname{Tr}\left(A^{T} \cdot B\right)$ on the space of matrices; the construction of Theorem 3.41 shows how a metric on $\operatorname{Hom}(U, V)$ is induced by arbitrary metrics on $U$ and $V$, so that $\operatorname{Hom}(U, V)$ is isometric to $U^{*} \otimes V$ with the induced tensor product metric. Chapter 4 develops the $W$-valued case of the trace with respect to a metric.

The basis-free approach is motivated in part by its usefulness in the geometry of vector bundles and structures on them, including bilinear and Hermitian forms, and almost complex structures. Important geometric applications include real vector bundles with Riemannian metrics, pseudo-Riemannian metrics (since definiteness is not assumed), or symplectic forms. The linear algebra results can be restated geometrically, with linear maps directly replaced by bundle morphisms, "distinguished non-zero element" by "nonvanishing section," and in some cases, " $\mathbb{K}$ " by "trivial line bundle."

The plan is to proceed at an elementary pace, so that if the first few Lemmas in Chapter 1 make sense to the reader, then nothing more advanced will be encountered after that. In particular, the relationships with differential geometry and category theory can be ignored entirely by the uninterested reader and are mentioned here only in optional "Remarks." It will be pointed out when the finite-dimensionality is used- for example, in the Theorems in Chapter 2 about the vector valued trace $\operatorname{Tr}_{V ; U, W}, V$ must be finite-dimensional, but $U$ and $W$ need not be.

## CHAPTER 0

## Review of Elementary Linear Algebra

### 0.1. Vector spaces

Definition 0.1. Given a set $V$, a field $\mathbb{K}$, a binary operation $+: V \times V \rightarrow V$ (addition), and a function $\cdot: \mathbb{K} \times V \rightarrow V$ (scalar multiplication), $V$ is a vector space means that the operations have all of the following properties:
(1) Associative Law for Addition: For any $u \in V$ and $v \in V$ and $w \in V$, $(u+v)+w=u+(v+w)$.
(2) Existence of a Zero Element: There exists an element $0_{V} \in V$ such that for any $v \in V, v+0_{V}=v$.
(3) Existence of an Opposite: For each $v \in V$, there exists an element of $V$, called $-v \in V$, such that $v+(-v)=0_{V}$.
(4) Associative Law for Scalar Multiplication: For any $\rho, \sigma \in \mathbb{K}$ and $v \in V$, $(\rho \sigma) \cdot v=\rho \cdot(\sigma \cdot v)$.
(5) Scalar Multiplication Identity: For any $v \in V, 1 \cdot v=v$.
(6) Distributive Law: For all $\rho, \sigma \in \mathbb{K}$ and $v \in V,(\rho+\sigma) \cdot v=(\rho \cdot v)+(\sigma \cdot v)$.
(7) Distributive Law: For all $\rho \in \mathbb{K}$ and $u, v \in V, \rho \cdot(u+v)=(\rho \cdot u)+(\rho \cdot v)$.

The following Exercises refer to a vector space $V$.
Exercise 0.2 (Right Cancellation). Given $u, v, w \in V$, if $u+w=v+w$, then $u=v$.

Hint. These first several Exercises, 0.2 through 0.11 , can be proved using only the first three axioms about addition.

Exercise 0.3. Given $u, w \in V$, if $u+w=w$, then $u=0_{V}$.
Exercise 0.4. For any $v \in V,(-v)+v=0_{V}$.
Exercise 0.5 . For any $v \in V, 0_{V}+v=v$.
Exercise 0.6 (Left Cancellation). Given $u, v, w \in V$, if $w+u=w+v$, then $u=v$.

Exercise 0.7 (Uniqueness of Zero Element). Given $u, w \in V$, if $w+u=w$, then $u=0_{V}$.

ExErcise 0.8 (Uniqueness of Additive Inverse). Given $v, w \in V$, if $v+w=0_{V}$ then $v=-w$ and $w=-v$.

EXERCISE 0.9. $-0_{V}=0_{V}$.
Exercise 0.10 . For any $v \in V,-(-v)=v$.
Exercise 0.11. Given $u, x \in V,-(u+x)=(-x)+(-u)$.

The previous results only used the properties of "+," but the next result, even though its statement refers only to + , uses a scalar multiplication trick, together with the distributive axioms, which relate scalar multiplication to addition.

Theorem 0.12 (Commutative Property of Addition). For any $v, w \in V$,

$$
v+w=w+v
$$

Proof. We start with this element of $V,(1+1) \cdot(v+w)$, and then set LHS $=$ RHS, and use both distributive laws:

$$
\begin{aligned}
(1+1) \cdot(v+w) & =(1+1) \cdot(v+w) \\
((1+1) \cdot v)+((1+1) \cdot w) & =(1 \cdot(v+w))+(1 \cdot(v+w)) \\
((1 \cdot v)+(1 \cdot v))+((1 \cdot w)+(1 \cdot w)) & =(v+w)+(v+w) \\
(v+v)+(w+w) & =(v+w)+(v+w) .
\end{aligned}
$$

Then, the associative law gives $v+(v+(w+w))=v+(w+(v+w))$, and Left Cancellation leaves $v+(w+w)=w+(v+w)$. Using the associative law again, $(v+w)+w=(w+v)+w$, and Right Cancellation gives the result $v+w=w+v$.

Exercise 0.13. For any $v \in V, 0 \cdot v=0_{V}$.
Exercise 0.14 . For any $v \in V,(-1) \cdot v=-v$.
ExErcise 0.15 . For any $\rho \in \mathbb{K}, \rho \cdot 0_{V}=0_{V}$.
Exercise 0.16 . For any $\rho \in \mathbb{K}$ and $u \in V,(-\rho) \cdot u=-(\rho \cdot u)$.
ExErcise 0.17. Given $\rho \in \mathbb{K}$ and $u \in V$, if $\rho \cdot u=0_{V}$, then $\rho=0$ or $u=0_{V}$.
EXERCISE 0.18. If $\frac{1}{2} \in \mathbb{K}$, then for any $v \in V$, the following are equivalent. (1) $v+v=0_{V}$, (2) $v=-v$, (3) $v=0_{V}$.

Hint. Only the implication $(1) \Longrightarrow$ (3) requires $\frac{1}{2} \in \mathbb{K}$; the others can be proved using only properties of + .

DEFINITION 0.19. It is convenient to abbreviate the sum $v+(-w)$ as $v-w$. This defines vector subtraction, so that $v$ minus $w$ is defined to be the sum of $v$ and the opposite (or "additive inverse") of $w$.

Notation 0.20 . Considering the associative law for addition, it is convenient to write the sum of more than two terms without all the parentheses: $u+v+w$ can mean either $(u+v)+w$, or $u+(v+w)$, since we get the same result either way. In light of Exercise 0.16, we can write $-\rho \cdot v$ to mean either $(-\rho) \cdot v$ or $-(\rho \cdot v)$, since these are the same. The multiplication "dot" can be used, or omitted, for both scalar times scalar and scalar times vector, when it is clear which symbols are scalars and which are vectors: instead of $3 \cdot u$, just write $3 u$. It is also convenient to establish an "order of operations," so that scalar multiplication is done before addition or subtraction. So, $4 v+u-3 w$ is a short way to write $(4 \cdot v)+(u+(-(3 \cdot w)))$.

### 0.2. Subspaces

The general idea of the statement " $W$ is a subspace of $V$ " is that $W$ is a vector space contained in a bigger vector space $V$ with the same field $\mathbb{K}$, and the + and . operations are the same in $W$ as they are in $V$.

Definition 0.21 . Let $\left(V,+_{V}, \cdot V\right)$ be a vector space with field of scalars $\mathbb{K}$. A set $W$ is a subspace of $V$ means:

- $W \subseteq V$, and
- There are operations $+_{W}: W \times W \rightarrow W$ and $\cdot W: \mathbb{K} \times W \rightarrow W$ such that $\left(W,+{ }_{W},{ }^{W}\right)$ is a vector space, and
- For all $x, y \in W, x+_{V} y=x+{ }_{W} y$, and
- For all $x \in W, \rho \in \mathbb{K}, \rho \cdot{ }_{V} x=\rho \cdot W x$.

THEOREM 0.22. If $W$ is a subspace of $V$, where $V$ has zero element $0_{V}$, then $0_{V}$ is an element of $W$, and is equal to the zero element of $W$.

Proof. By the second part of Definition $0.21, W$ is a vector space, so by Definition 0.1 applied to $W, W$ contains a zero element $0_{W} \in W$. By the first part of Definition $0.21, W \subseteq V$, which implies $0_{W} \in V$. By Definition 0.1 applied to $W$, $0_{W}+{ }_{W} 0_{W}=0_{W}$, and by Definition $0.21,0_{W}+{ }_{V} 0_{W}=0_{W}+{ }_{W} 0_{W}$. It follows that $0_{W}+V 0_{W}=0_{W} \in V$, and then Exercise 0.3 implies $0_{W}=0_{V}$.

Theorem 0.22 can be used in this way: if $W$ is a set that does not contain $0_{V}$ as one of its elements, then $W$ is not a subspace of $V$.

Theorem 0.23. If $W$ is a subspace of $V$, then for every $w \in W$, the opposite of $w$ in $W$ is the same as the opposite of $w$ in $V$.

Proof. Let $w$ be an element of $W$; then $w \in V$ because $W \subseteq V$.
First, we show that an additive inverse of $w$ in $W$ is also an additive inverse of $w$ in $V$. Let $y$ be any additive inverse of $w$ in $W$, meaning $y \in W$ and $w+{ }_{W} y=0_{W}$. (There exists at least one such $y$, by Definition 0.1 applied to $W$.) $W \subseteq V$ implies $y \in V$. From Theorem $0.22,0_{W}=0_{V}$, and $w+_{W} y=w+_{V} y$ by Definition 0.21, so $w+_{V} y=0_{V}$, which means $y$ is an additive inverse of $w$ in $V$.

Second, we show that an additive inverse of $w$ in $V$ is also an additive inverse of $w$ in $W$. Let $z$ be any additive inverse of $w$ in $V$, meaning $z \in V$ and $w+_{V} z=0_{V}$. (There exists at least one such $z$, by Definition 0.1 applied to $V$.) Then $w{ }_{V} z=$ $0_{V}=w+_{V} y$, so by Left Cancellation in $V, z=y$ and $y \in W$, which imply $z \in W$ and $w+{ }_{W} z=w+{ }_{W} y=0_{W}$, meaning $z$ is an additive inverse of $w$ in $W$.

By uniqueness of opposites (Exercise 0.8 applied to either $V$ or $W$ ), we can refer to $y=z$ as "the" opposite of $w$, and denote it $y=-w$.

Theorem 0.23 also implies that subtraction in $W$ is the same as subtraction in $V$ : by Definition 0.19, for $v, w \in W, v-_{W} w=v+_{W} y=v+_{V} y=v{ }_{V} w$.

Theorem 0.23 can be used in this way: if $W$ is a subset of a vector space $V$ and there is an element $w \in W$, where the opposite of $w$ in $V$ is not an element of $W$, then $W$ is not a subspace of $V$.

Theorem 0.24. Let $\left(V,+_{V},{ }^{\prime}\right)$ be a vector space, and let $W$ be a subset of $V$. Then $W$, with the same addition and scalar multiplication operations, is a subspace of $V$ if and only if:
(1) $x \in W, y \in W$ imply $x+_{V} y \in W$ (closure under $+_{V}$ addition), and
(2) $\rho \in \mathbb{K}, x \in W$ imply $\rho \cdot V x \in W$ (closure under $\cdot V$ scalar multiplication), and
(3) $W \neq \varnothing$.

Proof. Let $V$ have zero element $0_{V}$.
First suppose $W$ is a subspace, so that as in the Proof of Theorem $0.22, W$ contains a zero element $0_{W}$, which shows $W \neq \emptyset$, and (3) is true. From Property 1. of Definition $0.1, x \in W, y \in W$ imply $x+W y \in W$, and from the definition of subspace, $x+_{W} y=x+_{V} y$, so $x+_{V} y \in W$, establishing (1). Similarly, from Property 5. of Definition 0.1, $\rho \in \mathbb{K}$ implies $\rho \cdot W x \in W$, and from the definition of subspace, $\rho \cdot{ }_{W} x=\rho \cdot{ }_{V} x$, so $\rho \cdot{ }_{V} x \in W$, establishing (2).

Conversely, it follows from (1), (2), and (3) that $W$ is a subspace of $V$, as follows: $W$ is a subset of $V$ by hypothesis. Define $+_{W}$ and ${ }^{W} W$ by $x+{ }_{W} y=x+{ }_{V} y$, and $\rho \cdot{ }_{W} x=\rho \cdot{ }_{V} x$ - these define operations on $W$ by (1) and (2) (the closure Properties 1. and 5. from Definition 0.1, and also parts of Definition 0.21), but it remains to check the other properties to show that $\left(W,+_{W}, \cdot{ }_{W}\right)$ is a vector space. Since $W \neq \emptyset$ by (3), there is some $x \in W$, and by (2), $0 \cdot{ }_{V} x \in W$. By Exercise 0.13 , $0 \cdot{ }_{V} x=0_{V}$, so $0_{V} \in W$, and it satisfies $x+{ }_{W} 0_{V}=x+{ }_{V} 0_{V}=x$ for all $x \in W$, so $0_{V}$ is a zero element for $W$. The scalar multiple identity also works: $1 \cdot{ }_{W} x=1 \cdot{ }_{V} x=x$. Also by (2), for any $x \in W,(-1) \cdot V x \in W$, and it is easy to check $(-1) \cdot V x$ is an additive inverse of $x$ in $W: x+{ }_{W}\left((-1) \cdot{ }_{V} x\right)=\left(1 \cdot{ }_{V} x\right)+{ }_{V}\left((-1) \cdot{ }_{V} x\right)=$ $(1+(-1)) \cdot V x=0 \cdot V x=0_{V}$. The other vector space properties, $(2,6,8,9)$ from Definition 0.1 , follow immediately from the facts that these properties hold in $V$ and the operations in $W$ give the same sums and scalar multiples.

Definition 0.25 . Given a vector space $V$ and any subset $S \subseteq V$, the span of $S$ is the subset of $V$ defined as the set of all (finite) sums of elements of $\bar{S}$ with coefficients in $\mathbb{K}$ :

$$
\left\{\alpha_{1} s_{1}+\alpha_{2} s_{2}+\ldots+\alpha_{\nu} s_{\nu}: \alpha_{1}, \ldots, \alpha_{\nu} \in \mathbb{K}, s_{1}, \ldots, s_{\nu} \in S\right\}
$$

This is always a subspace of $V$. (We define the span of $\varnothing$ to be $\left\{0_{V}\right\}$.)
Definition 0.26 . A vector space $V$ is finite-dimensional means that there exists a finite subset $S \subseteq V$ such that the span of $S$ is equal to $V$.

Definition 0.27. Given an ordered list (possibly with repeats) of elements of a vector space $V,\left(u_{1}, u_{2}, \ldots, u_{\nu}\right)$, the list is linearly independent means that the following implication holds for scalars $\alpha_{1}, \ldots, \overline{\alpha_{\nu} \in \mathbb{K} \text { : }}$

$$
\alpha_{1} u_{1}+\alpha_{2} u_{2}+\ldots+\alpha_{\nu} u_{\nu}=0_{V} \Longrightarrow \alpha_{1}=\alpha_{2}=\ldots=\alpha_{\nu}=0
$$

The empty list is linearly independent. We will not have occasion to consider infinite lists.

Claim 0.28. If $V$ is a vector space equal to the span of a finite set $S$ with $\nu$ elements, then there is no linearly independent list of elements of $V$ of length $>\nu$.

Definition 0.29. Given an ordered list of elements of a vector space $V$, $\left(u_{1}, u_{2}, \ldots, u_{\nu}\right)$, the list is an ordered basis of $V$ means that the list is linearly independent and the span of the set $\left\{u_{1}, u_{2}, \ldots, u_{\nu}\right\}$ is equal to $V$.

### 0.3. Additive functions and linear functions

Let $U, V$, and $W$ be vector spaces with the same field of scalars $\mathbb{K}$.
Definition 0.30. A function $F: U \rightarrow V$ is additive means: $F$ has the property that $F(u+w)=F(u)+F(w)$ for all $u, w \in U$.

Definition 0.31. A function $F: U \rightarrow V$ is linear means: $F$ is additive and also has the scaling property: $F(\rho \cdot u)=\rho \cdot F(u)$ for all $\rho \in \mathbb{K}$ and all $u \in U$.

ExErcise 0.32. If $F: U \rightarrow V$ is additive, then: $F\left(0_{U}\right)=0_{V}$, and for all $u \in U$, $F(-u)=-F(u)$.

ExERCISE 0.33 . If $\mathbb{K}$ contains the rational numbers $\mathbb{Q}$ as a subrng, and $F$ : $U \rightarrow V$ is additive, then for every rational number $\rho \in \mathbb{Q}, F(\rho \cdot u)=\rho \cdot F(u)$.

Hint. Start by showing that for integers $\nu \in \mathbb{Z}, F(\nu \cdot u)=\nu \cdot F(u)$.
Exercise 0.34. Give an example of a field, vector spaces $V$ and $W$, and a function $F: V \rightarrow W$, such that $F$ has the scaling property, but which is not linear because it is not additive.

Exercise 0.35. Give an example of a field, vector spaces $V$ and $W$, and a function $F: V \rightarrow W$ such that $F$ has the additive property, but which is not linear because it does not have the scaling property.

Hint. Try this for $\mathbb{K}=\mathbb{C}$ and then for $\mathbb{K}=\mathbb{R}$ (harder).
Notation 0.36 . At this point, the arrow notation $F: V \rightarrow W$ will only be used for functions that are linear from a vector space $V$ (the domain) to another vector space $W$ (the target). A linear function will also be called a map, linear map, or arrow, or when it is convenient to emphasize the scalar field, a $\mathbb{K}$-linear map. A function which is not necessarily linear will be denoted with a variant $\rightsquigarrow$ arrow symbol.

Example 0.37. Given a vector space $V$ and a subspace $W$, the canonical subspace inclusion function $Q: W \rightarrow V$ defined by $Q(w)=w$ is linear.

Notation 0.38 . As a special case of the above inclusion map (and as in Example 6.15), the identity map $I d_{V}: V \rightarrow V$, defined by the formula $I d_{V}(v)=v$, is linear.

Exercise 0.39. Given vector spaces $U, V, W$, and functions $F: W \rightarrow V$, $G: V \rightarrow U$, if $F$ and $G$ are linear, then the composite $G \circ F: W \rightarrow U$ is linear.

The $\circ$ notation for composites is as in Notation 6.16.
Example 0.40. For a linear function $F: W \rightarrow V$, the image of $F$ is the set $F(W)=\{F(w) \in V: w \in W\}$. The image is always a subspace of the target $V$.

Example 0.41. For a linear function $F: W \rightarrow V$, the kernel of $F$ is the set $\operatorname{ker}(F)=\left\{w \in W: F(w)=0_{V}\right\}$. The kernel is always a subspace of the domain $W$.

Definition 0.42 . A linear map $C: X \rightarrow Y$ is a linear monomorphism means: $C$ has the following cancellation property for any compositions with linear maps $A$ and $B$ (which are well-defined in the sense that $X$ is the target space of both $A$ and $B$ ),

$$
C \circ A=C \circ B \Longrightarrow A=B .
$$

Exercise 0.43. Given a linear map $F: U \rightarrow V$, the following are equivalent.
(1) $F$ is one-to-one.
(2) $F$ is left cancellable.
(3) $F$ has a left inverse: there exists a function $H: V \rightsquigarrow U$ such that $H \circ F=$ $I d_{U}$.
(4) $F$ is a linear monomorphism.
(5) $\operatorname{ker}(F)=\left\{0_{U}\right\}$.

Hint. The first three properties are considered in Exercise 6.17, and their equivalence is a matter of set theory only, without using the linearity of $F$. In particular, the function $H$ is not necessarily linear. The implication $(2) \Longrightarrow(4)$ is trivial, and $(1) \Longrightarrow(5)$ uses only $F\left(0_{U}\right)=0_{V}$ from Exercise 0.32 . The implications $(5) \Longrightarrow(1)$ and $(4) \Longrightarrow(5)$ follow from the linearity of $F$.

ExERCISE 0.44. If $V$ is finite-dimensional and $F: U \rightarrow V$ is linear and one-toone, then $U$ is finite-dimensional.

Hint. This follows from Claim 0.28 and the fact that an independent list in $U$ is transformed to an independent list in $V$ by a one-to-one map.

ExErcise 0.45. Given linear maps $A: W \rightarrow V$ and $F: U \rightarrow V$, if $A(W) \subseteq$ $F(U)$ and $H: V \rightsquigarrow U$ is any left inverse of $F$, then $H \circ A: W \rightarrow U$ is linear.

Hint. For any two elements $v_{1}, v_{2} \in F(U), v_{1}=F\left(u_{1}\right)$ for some unique $u_{1}$ as in Exercise 0.43 , and similarly $v_{2}=F\left(u_{2}\right)$. Using the linearity of $F$ and any scalar $\lambda$,

$$
\begin{align*}
H\left(v_{1}+v_{2}\right) & =H\left(F\left(u_{1}\right)+F\left(u_{2}\right)\right)=H\left(F\left(u_{1}+u_{2}\right)\right) \\
& =u_{1}+u_{2}=H\left(F\left(u_{1}\right)\right)+H\left(F\left(u_{2}\right)\right)=H\left(v_{1}\right)+H\left(v_{2}\right),  \tag{0.1}\\
H\left(\lambda \cdot v_{1}\right) & =H\left(\lambda \cdot F\left(u_{1}\right)\right)=H\left(F\left(\lambda \cdot u_{1}\right)\right) \\
& =\lambda \cdot u_{1}=\lambda \cdot H\left(F\left(u_{1}\right)\right)=\lambda \cdot H\left(v_{1}\right) .
\end{align*}
$$

In particular, for $w_{1}, w_{2} \in W$, let $A\left(w_{1}\right)=F\left(u_{1}\right)$ and $A\left(w_{2}\right)=F\left(u_{2}\right)$. Then, using the additivity of $A$ and (0.1),

$$
(H \circ A)\left(w_{1}+w_{2}\right)=H\left(A\left(w_{1}\right)+A\left(w_{2}\right)\right)=(H \circ A)\left(w_{1}\right)+(H \circ A)\left(w_{2}\right) .
$$

The scaling property for $H \circ A$ follows similarly.
Definition 0.46. A map $C: X \rightarrow Y$ is a linear epimorphism means: $C$ has the following cancellation property for any compositions with linear maps $A$ and $B$,

$$
A \circ C=B \circ C \Longrightarrow A=B
$$

EXERCISE 0.47. If the linear map $F: U \rightarrow V$ has a right inverse, meaning that there exists $H: V \rightsquigarrow U$ so that $F \circ H=I d_{V}$, then $F$ is onto and right cancellable as in Exercise 6.18, and the right cancellable property implies that $F$ is a linear epimorphism.

Exercise 0.48 . Given vector spaces $V, W$, and a linear function $F: W \rightarrow V$, the following are equivalent.
(1) $F$ is both one-to-one and onto.
(2) $F$ has a right inverse $H_{1}: V \rightsquigarrow W$ and a left inverse $H_{2}: V \rightsquigarrow W$.
(3) There exists a linear map $G: V \rightarrow W$ such that $G$ is a left inverse of $F$ and $G$ is a right inverse of $F$.

Hint. The $(3) \Longrightarrow(2)$ direction is trivial. The equivalence $(1) \Longleftrightarrow(2)$ does not use the linearity of $F$ - see Exercise 6.20, which also shows that (2) implies $H_{1}=H_{2}$, so $G: V \rightsquigarrow W$ in (3) can be chosen to equal $H_{1}=H_{2}$. The linearity of $F$ then implies the linearity of $G$ by Exercise 0.45.

Notation 0.49. Given vector spaces $V, W$, and a linear function $F: W \rightarrow V$, $F$ is invertible means that $F$ satisfies any of the three equivalent properties (1), (2), or (3) from Exercise 0.48 , as in Definition 6.21 . However, we usually use property (3), so that as in Notation $6.22, G$ is the unique inverse of $F$, denoted $G=F^{-1}$. It follows that $F^{-1}$ is also invertible, with inverse $F$.

Claim 0.50. If $V$ is finite-dimensional and $F: V \rightarrow V$ is linear and $F$ is either a linear monomorphism or a linear epimorphism, then $F$ is invertible.

Claim 0.51. Given a finite-dimensional vector space $V$ and a linear map $F$ : $V \rightarrow V$, the following are equivalent.
(1) For all linear maps $A: V \rightarrow V, A \circ F=F \circ A: V \rightarrow V$.
(2) There exists a scalar $\lambda \in \mathbb{K}$ so that for all $v \in V, F(v)=\lambda \cdot v$.

Proof. The second property can be denoted $F=\lambda \cdot I d_{V}$. See [B] Exercise II.1.26 or [J] §3.11.

## CHAPTER 1

## Abstract Linear Algebra

### 1.1. Spaces of linear maps

For this Chapter, we fix an arbitrary field $(\mathbb{K},+, \cdot, 0,1)$. All vector spaces use the same scalar field $\mathbb{K}$, and + and $\cdot$ also refer to the vector space addition and scalar multiplication. A $\mathbb{K}$-linear map $A$ with domain $U$ and target $V$, such that $A(u)=v$, will be written as $A: U \rightarrow V: u \mapsto v$, or the $A$ may appear near the arrow when several maps are combined in a diagram.

Notation 1.1. The set of all $\mathbb{K}$-linear maps from $U$ to $V$ is denoted $\operatorname{Hom}(U, V)$.
Claim 1.2. $\operatorname{Hom}(U, V)$ is itself a vector space over $\mathbb{K}$. If $U$ and $V$ are finitedimensional, then $\operatorname{Hom}(U, V)$ is finite-dimensional.

Notation 1.3. $\operatorname{Hom}(V, V)$ is abbreviated $\operatorname{End}(V)$, the space of endomorphisms of $V$. The space $\operatorname{End}(V)$ has a distinguished element, the identity map denoted $I d_{V}: v \mapsto v$ from Notation 0.38.

Notation 1.4. $\operatorname{Hom}(V, \mathbb{K})$ is abbreviated $V^{*}$, the dual space of $V$.
Definition 1.5. For maps $A: U^{\prime} \rightarrow U$ and $B: V \rightarrow V^{\prime}$, define

$$
\operatorname{Hom}(A, B): \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}\left(U^{\prime}, V^{\prime}\right)
$$

so that for $F: U \rightarrow V$,

$$
\operatorname{Hom}(A, B)(F)=B \circ F \circ A: U^{\prime} \rightarrow V^{\prime}
$$

Lemma 1.6. ([B] §II.1.2) If $A: U \rightarrow V, B: V \rightarrow W, C: X \rightarrow Y, D: Y \rightarrow Z$, then
$\operatorname{Hom}(A, D) \circ \operatorname{Hom}(B, C)=\operatorname{Hom}(B \circ A, D \circ C): \operatorname{Hom}(W, X) \rightarrow \operatorname{Hom}(U, Z)$.

Definition 1.7. For any vector spaces $U, V, W$, define a generalized transpose map,

$$
t_{U V}^{W}: \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}(\operatorname{Hom}(V, W), \operatorname{Hom}(U, W))
$$

so that for $A: U \rightarrow V, B: V \rightarrow W$,

$$
t_{U V}^{W}(A)=\operatorname{Hom}\left(A, I d_{W}\right): B \mapsto B \circ A
$$

Lemma 1.8. For any vector spaces $U, V, W, U^{\prime}, V^{\prime}, W^{\prime}$, and any maps $E: U^{\prime} \rightarrow U, F: V \rightarrow V^{\prime}, G: W \rightarrow W^{\prime}$, the following diagram is commutative.


Proof. For any $A: U \rightarrow V$,

$$
\begin{aligned}
& \operatorname{Hom}\left(\operatorname{Hom}\left(I d_{V^{\prime}}, G\right), \operatorname{Hom}\left(I d_{U^{\prime}}, I d_{W^{\prime}}\right)\right) \circ t_{U^{\prime} V^{\prime}}^{W^{\prime}} \circ \operatorname{Hom}(E, F): \\
A \mapsto & \left.\mapsto t_{U^{\prime} V^{\prime}}^{W^{\prime}}(F \circ A \circ E)\right) \circ \operatorname{Hom}\left(I d_{V^{\prime}}, G\right) \\
= & \operatorname{Hom}\left(F \circ A \circ E, I d_{W^{\prime}}\right) \circ \operatorname{Hom}\left(I d_{V^{\prime}}, G\right) \\
& \operatorname{Hom}\left(\operatorname{Hom}\left(F, I d_{W}\right), \operatorname{Hom}(E, G)\right) \circ t_{U V}^{W}: \\
A \mapsto & \operatorname{Hom}(E, G) \circ \operatorname{Hom}\left(A, I d_{W}\right) \circ \operatorname{Hom}\left(F, I d_{W}\right) .
\end{aligned}
$$

The claimed equality follows from Lemma 1.6.
Notation 1.9. In the special case $W=\mathbb{K}, t_{U V}^{\mathbb{K}}$ is a canonical transpose map from $\operatorname{Hom}(U, V)$ to $\operatorname{Hom}\left(V^{*}, U^{*}\right)$, and it is abbreviated $t_{U V}^{\mathbb{K}}=t_{U V}$.

Notation 1.10. $t_{U V}(A)=\operatorname{Hom}\left(A, I d_{\mathbb{K}}\right)$ is abbreviated by $A^{*}: V^{*} \rightarrow U^{*}$, so that for $\phi \in V^{*}, A^{*}(\phi)$ is the $\operatorname{map} \phi \circ A: U \rightarrow \mathbb{K}$, i.e., $\left(A^{*}(\phi)\right)(u)=\phi(A(u))$.

Lemma 1.11. For $A: U \rightarrow V$ and $F: V \rightarrow V^{\prime},(F \circ A)^{*}=A^{*} \circ F^{*}$, and if $A$ is invertible, then so is $A^{*}$, with $\left(A^{-1}\right)^{*}=\left(A^{*}\right)^{-1}$. Also, $I d_{V^{*}}=I d_{V}^{*}$.

Proof. The claim about $F \circ A$ follows from Lemma 1.8 (with $E=I d_{U}, G=$ $I d_{\mathbb{K}}$, or by applying Lemma 1.6 directly. Note that $t_{V V}: \operatorname{End}(V) \rightarrow \operatorname{End}\left(V^{*}\right)$ takes the distinguished element $I d_{V} \in \operatorname{End}(V)$ to the distinguished element $t_{V V}\left(I d_{V}\right)=$ $I d_{V}^{*}=I d_{V^{*}} \in \operatorname{End}\left(V^{*}\right)$.

Definition 1.12. For any vector spaces $V, W$, define

$$
d_{V W}: V \rightarrow \operatorname{Hom}(\operatorname{Hom}(V, W), W)
$$

so that for $v \in V, H \in \operatorname{Hom}(V, W)$,

$$
\left(d_{V W}(v)\right): H \mapsto H(v)
$$

Lemma 1.13. For any vector spaces $U, V, W, X$ and any maps $H: U \rightarrow V$, $G: W \rightarrow X$, the following diagram is commutative.


Proof. For $u \in U, A: V \rightarrow W$,
$\operatorname{Hom}\left(\operatorname{Hom}\left(I d_{V}, G\right), I d_{X}\right) \circ d_{V X} \circ H: u \quad \mapsto \quad\left(d_{V X}(H(u))\right) \circ \operatorname{Hom}\left(I d_{V}, G\right):$

$$
A \mapsto(G \circ A)(H(u))
$$

$$
\operatorname{Hom}\left(\operatorname{Hom}\left(H, I d_{W}\right), G\right) \circ d_{U W}: u \quad \mapsto \quad G \circ\left(d_{U W}(u)\right) \circ \operatorname{Hom}\left(H, I d_{W}\right):
$$

$$
A \mapsto G\left(\left(d_{U W}(u)\right)(A \circ H)\right)
$$

$$
=G((A \circ H)(u))
$$

As a special case of Lemma 1.13 with $W=X, G=I d_{W}$, for any $H: U \rightarrow V$,

$$
\begin{equation*}
\left(t_{\operatorname{Hom}(V, W), \operatorname{Hom}(U, W)}^{W}\left(t_{U V}^{W}(H)\right)\right) \circ d_{U W}=d_{V W} \circ H \tag{1.1}
\end{equation*}
$$

where $t_{\operatorname{Hom}(V, W), \operatorname{Hom}(U, W)}^{W}\left(t_{U V}^{W}(H)\right)=\operatorname{Hom}\left(\operatorname{Hom}\left(H, I d_{W}\right), I d_{W}\right)$ by Definition 1.7 of the $t$ maps.

Notation 1.14. In the special case $W=\mathbb{K}, d_{V \mathbb{K}}$ is abbreviated $d_{V}$. It is the canonical double duality map $d_{V}: V \rightarrow V^{* *}$, defined by $\left(d_{V}(v)\right)(\phi)=\phi(v)$.

The case (1.1) of Lemma 1.13 then gives the equation ([B] §II.2.7, $[\mathbf{A F}] \S 20$ )

$$
\begin{equation*}
d_{V} \circ A=A^{* *} \circ d_{U} \tag{1.2}
\end{equation*}
$$

where for $A: U \rightarrow V, A^{* *}$ abbreviates $t_{V^{*} U^{*}}\left(t_{U V}(A)\right)$.
Claim 1.15. The canonical map $d_{V}$ is one-to-one. $d_{V}$ is invertible if and only if $V$ is finite-dimensional.

Proof. The one-to-one property is easily checked. See [B] §II.7.5.
LEMmA 1.16. $\operatorname{Hom}\left(d_{V W}, I d_{W}\right) \circ d_{\operatorname{Hom}(V, W), W}=I d_{\operatorname{Hom}(V, W)}$.
Proof. For $v \in V, K: V \rightarrow W$,

$$
\begin{aligned}
\left(\left(\operatorname{Hom}\left(d_{V W}, I d_{W}\right) \circ d_{\operatorname{Hom}(V, W), W}\right)(K)\right)(v) & =\left(d_{\operatorname{Hom}(V, W), W}(K)\right)\left(d_{V W}(v)\right) \\
& =\left(d_{V W}(v)\right)(K)=K(v)
\end{aligned}
$$

In the $W=\mathbb{K}$ case, this one-sided inverse relation gives $([\mathbf{A F}] \S 20)$

$$
d_{V}^{*} \circ d_{V^{*}}=I d_{V^{*}}
$$

Remark 1.17. In some applications, the vector space $V$ is often identified with a subspace of $V^{* *}$, or the map $d_{V}$ is ignored, but it is less trouble than might be expected to keep $V$ and $V^{* *}$ distinct, and always accounting for $d_{V}$ turns out to be convenient bookkeeping.

Lemma 1.18. Suppose $U$ is finite-dimensional. For $A: U \rightarrow V$, if $A^{*}$ has a linear right inverse $F: U^{*} \rightarrow V^{*}$, so that $A^{*} \circ F=I d_{U^{*}}$, then $A$ has a linear left inverse. If $A^{*}$ has a linear left inverse $E: U^{*} \rightarrow V^{*}$, so that $E \circ A^{*}=I d_{V^{*}}$, then A has a linear right inverse.

Proof. Using Lemma 1.11, case (1.2) of Lemma 1.13, and Claim 1.15,

$$
d_{U}^{-1} \circ F^{*} \circ d_{V} \circ A=d_{U}^{-1} \circ F^{*} \circ A^{* *} \circ d_{U}=d_{U}^{-1} \circ\left(A^{*} \circ F\right)^{*} \circ d_{U}=I d_{U}
$$

Using the one-to-one property of $d_{V}$,

$$
\begin{aligned}
d_{V} \circ A \circ d_{U}^{-1} \circ E^{*} \circ d_{V} & =A^{* *} \circ E^{*} \circ d_{V}=\left(E \circ A^{*}\right)^{*} \circ d_{V}=d_{V} \\
\Longrightarrow A \circ d_{U}^{-1} \circ E^{*} \circ d_{V} & =I d_{V} .
\end{aligned}
$$

Definition 1.19. For any vector space $W$, define $m: W \rightarrow \operatorname{Hom}(\mathbb{K}, W)$ so that for $w \in W$,

$$
m(w): \lambda \mapsto \lambda \cdot w
$$

Lemma 1.20. For any vector spaces $W, W^{\prime}$, with two maps $m, m^{\prime}$ as indicated, and any maps $\phi \in \mathbb{K}^{*}, G: W \rightarrow W^{\prime}$, the following diagram is commutative.


Proof. For $\lambda \in \mathbb{K}, w \in W$,

$$
\begin{array}{rll}
\operatorname{Hom}(\phi, G) \circ m: w & \mapsto & G \circ(m(w)) \circ \phi: \lambda \mapsto G(\phi(\lambda) \cdot w), \\
m^{\prime} \circ(\phi(1) \cdot G): w & \mapsto & m^{\prime}(\phi(1) \cdot G(w)): \lambda \mapsto \lambda \cdot \phi(1) \cdot G(w) .
\end{array}
$$

Lemma 1.21. For any vector space $W, m: W \rightarrow \operatorname{Hom}(\mathbb{K}, W)$ is invertible.
Proof. An inverse is

$$
m^{-1}=d_{\mathbb{K} W}(1): \operatorname{Hom}(\mathbb{K}, W) \rightarrow W: A \mapsto A(1)
$$

Checking both composites, $\left(\left(m \circ m^{-1}\right)(A)\right)(\lambda)=\lambda \cdot A(1)=A(\lambda)$, and $\left(m^{-1} \circ\right.$ $m)(w)=(m(w))(1)=1 \cdot w=w$.

### 1.2. Tensor products

Definition 1.22. For vector spaces $U, V, W$, a function $A: U \times V \rightsquigarrow W$ is a bilinear function means: for any $\lambda \in \mathbb{K}, u_{1}, u_{2} \in U, v_{1}, v_{2} \in V$,

$$
\begin{aligned}
A\left(u_{1}+u_{2}, v_{1}\right) & =A\left(u_{1}, v_{1}\right)+A\left(u_{2}, v_{1}\right) \\
A\left(u_{1}, v_{1}+v_{2}\right) & =A\left(u_{1}, v_{1}\right)+A\left(u_{1}, v_{2}\right), \text { and } \\
A\left(\lambda \cdot u_{1}, v_{1}\right) & =A\left(u_{1}, \lambda \cdot v_{1}\right)=\lambda \cdot A\left(u_{1}, v_{1}\right) .
\end{aligned}
$$

Remark 1.23. We remark that the above Definition is different from the notion of bilinear form, from Definition 3.1 in Chapter 3. The way in which these types of functions are related is described in Example 1.50.

For any vector spaces $U$ and $V$, there exists a tensor product vector space $U \otimes V$, which we informally define as the set of formal finite sums

$$
\begin{equation*}
\rho_{1} \cdot u_{1} \otimes v_{1}+\rho_{2} \cdot u_{2} \otimes v_{2}+\cdots+\rho_{\nu} \cdot u_{\nu} \otimes v_{\nu} \tag{1.3}
\end{equation*}
$$

for scalars $\rho_{1}, \ldots, \rho_{\nu} \in \mathbb{K}$, elements $u_{1}, \ldots, u_{\nu} \in U$, and elements $v_{1}, \ldots, v_{\nu} \in V$, with addition and scalar multiplication carried out in the usual way, subject to the relations:

$$
\begin{aligned}
\left(u_{1}+u_{2}\right) \otimes v & =u_{1} \otimes v+u_{2} \otimes v \\
u \otimes\left(v_{1}+v_{2}\right) & =u \otimes v_{1}+u \otimes v_{2} \\
(\rho \cdot u) \otimes v & =u \otimes(\rho \cdot v)=\rho \cdot(u \otimes v)
\end{aligned}
$$

A term $u \otimes v$ is also called a tensor product of the vectors $u$ and $v$. The operation taking a pair of vectors to their tensor product is a bilinear function, denoted

$$
\boldsymbol{\tau}: U \times V \rightsquigarrow U \otimes V:(u, v) \mapsto u \otimes v .
$$

$U \otimes V$ and $\boldsymbol{\tau}$ have the property that for any bilinear function $A: U \times V \rightsquigarrow W$ as in Definition 1.22, there is a unique linear map $a: U \otimes V \rightarrow W$ such that $A=a \circ \boldsymbol{\tau}$, that is, for any $u \in U$ and $v \in V$,

$$
\begin{equation*}
A(u, v)=a(u \otimes v) \tag{1.4}
\end{equation*}
$$

So bilinear functions can be converted to linear maps, by replacing the domain $U \times V$ with the tensor product $U \otimes V$.

A more formal proof of the existence of $U \otimes V$ and $\boldsymbol{\tau}$ as above uses methods different from the main stream of this Chapter, so we refer to Appendix 6.3, where (1.4) is stated as Theorem 6.35. The following re-statement of the description (1.3) also follows from the construction of Appendix 6.3:

Lemma 1.24. For any $U, V$, there exists a space $U \otimes V$ and a bilinear function $\boldsymbol{\tau}: U \times V \rightsquigarrow U \otimes V$ such that $U \otimes V$ is equal to the span of elements of the form $\boldsymbol{\tau}(u, v)=u \otimes v$. Any linear map $B: U \otimes V \rightarrow W$ is uniquely determined by its values on the set of elements $u \otimes v$.

REMARK 1.25. In general, although the set of tensor products of vectors, $\{u \otimes v$ : $u \in U, v \in V\}$ spans the space $U \otimes V$, not every element of $U \otimes V$ is of the form $u \otimes v$ - generally elements are finite sums as in (1.3).

Lemma 1.26. If $U$ and $V$ are finite-dimensional, then so is $U \otimes V$.
Example 1.27. The scalar multiplication operation $\cdot U: \mathbb{K} \times U \rightsquigarrow U$ is a bilinear function, and induces a map

$$
l_{U}: \mathbb{K} \otimes U \rightarrow U: \lambda \otimes u \mapsto \lambda \cdot u .
$$

The map $l_{U}$ is invertible, with inverse $l_{U}^{-1}(u)=1 \otimes u$, and sometimes $l_{U}$ is abbreviated $l$, with the same $l$ notation used for maps $U \otimes \mathbb{K} \rightarrow U: u \otimes \lambda \mapsto \lambda \cdot u$.

Example 1.28. The switching function

$$
\mathbf{S}: U \times V \rightsquigarrow V \times U:(u, v) \mapsto(v, u)
$$

composes with $\boldsymbol{\tau}: V \times U \rightsquigarrow V \otimes U$ :

$$
\boldsymbol{\tau} \circ \mathbf{S}: U \times V \rightsquigarrow V \otimes U:(u, v) \mapsto v \otimes u .
$$

This composite is a bilinear function and induces an invertible, $\mathbb{K}$-linear switching map

$$
s: U \otimes V \rightarrow V \otimes U: u \otimes v \mapsto v \otimes u
$$

Claim 1.29. The spaces $(U \otimes V) \otimes W$ and $U \otimes(V \otimes W)$ are related by a canonical, invertible, $\mathbb{K}$-linear map.

Remark 1.30. In addition to the discussion in Appendix 6.3, the above statements about tensor products follow standard constructions as in references [MB] $\S$ IX. $8,[\mathbf{A F}] \S 19,[\mathbf{K}] \S$ II.1. From this point, product sets $U \times V$ and the function $\boldsymbol{\tau}$ will not appear often, but could be used by the reader to verify certain maps are well-defined. Lemma 1.24 will be used frequently and without comment when defining maps (as already done in Examples 1.27 and 1.28) or proving equality of two maps (as in Lemma 1.35, below).

Remark 1.31. The notion of a multilinear map is also standard, and the spaces from Claim 1.29 can be identified with each other and yet another space, a triple tensor product $U \otimes V \otimes W$. This is spanned by elements of the form $u \otimes v \otimes w$, and it is a convenient abbreviation for our purposes to also identify elements $(u \otimes v) \otimes w=$ $u \otimes(v \otimes w)=u \otimes v \otimes w$. We leave the justification for this to the references; some applications or generalizations of linear algebra keep track of this associativity and do not use such abbrevations, but we will make these identifications without comment. Similarly, notions of associativity for tensor products of more than three spaces or vectors will be implicitly assumed as needed.

A tensor product of $\mathbb{K}$-linear maps canonically induces a $\mathbb{K}$-linear map between tensor product spaces, as follows.

Definition 1.32. For any vector spaces $U_{1}, U_{2}, V_{1}, V_{2}$, define

$$
j: \operatorname{Hom}\left(U_{1}, V_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, V_{2}\right) \rightarrow \operatorname{Hom}\left(U_{1} \otimes U_{2}, V_{1} \otimes V_{2}\right)
$$

so that for $A: U_{1} \rightarrow V_{1}, B: U_{2} \rightarrow V_{2}, u \in U_{1}$, and $v \in U_{2}$, the map $j(A \otimes B)$ acts as:

$$
(j(A \otimes B)): u \otimes v \mapsto(A(u)) \otimes(B(v))
$$

Claim 1.33. The canonical map $j$ is one-to-one. If one of the ordered pairs $\left(U_{1}, U_{2}\right),\left(U_{1}, V_{1}\right)$, or $\left(U_{2}, V_{2}\right)$ consists of finite-dimensional spaces, then $j$ is invertible.

Proof. See [B] §II.7.7 or [K] §II.2.
Although it frequently occurs in the literature that $j(A \otimes B)$ and $A \otimes B$ are identified, we will maintain the distinction. In this Section and later (many times in Section 2.2), the canonical map $j$ will appear in diagrams as a function in its own right, and it is useful to keep track of it everywhere, instead of only ignoring it sometimes. However, the notation $j(A \otimes B)$ is not always as convenient as the following abbreviation.

Notation 1.34. Let $[A \otimes B]$ denote $j(A \otimes B)$, so that, for example, the equation

$$
(j(A \otimes B))(u \otimes v)=(A(u)) \otimes(B(v))
$$

appears as

$$
[A \otimes B](u \otimes v)=(A(u)) \otimes(B(v))
$$

Lemma 1.35. ([B] §II.3.2, [K] §II.6)

$$
[A \otimes B] \circ[E \otimes F]=[(A \circ E) \otimes(B \circ F)]
$$

Note that the brackets conveniently establish an order of operations, and appear three times in the Lemma, but may stand for three distinct canonical $j$ maps, depending on the domains of $A, B, E$, and $F$. When it is necessary or convenient to keep track of different maps, the $j$ symbols are used instead of the brackets, and are sometimes labeled with subscripts, primes, etc., as in the following Lemma.

Lemma 1.36. For any vector spaces $U_{1}, U_{2}, U_{3}, U_{4}, V_{1}, V_{2}, V_{3}, V_{4}$, with maps $j^{\prime}, j^{\prime \prime}$ as indicated, and any maps $A_{1}: U_{3} \rightarrow U_{1}, A_{2}: U_{4} \rightarrow U_{2}, B_{1}: V_{1} \rightarrow V_{3}$, $B_{2}: V_{2} \rightarrow V_{4}$, the following diagram is commutative.


Proof. For $E: U_{1} \rightarrow V_{1}$ and $F: U_{2} \rightarrow V_{2}$,

$$
\begin{aligned}
E \otimes F & \mapsto\left(j^{\prime \prime} \circ\left[\operatorname{Hom}\left(A_{1}, B_{1}\right) \otimes \operatorname{Hom}\left(A_{2}, B_{2}\right)\right]\right)(E \otimes F) \\
& =j^{\prime \prime}\left(\left(\operatorname{Hom}\left(A_{1}, B_{1}\right)(E)\right) \otimes\left(\operatorname{Hom}\left(A_{2}, B_{2}\right)(F)\right)\right) \\
& =j^{\prime \prime}\left(\left(B_{1} \circ E \circ A_{1}\right) \otimes\left(B_{2} \circ F \circ A_{2}\right)\right), \\
E \otimes F & \mapsto\left(\operatorname{Hom}\left(\left[A_{1} \otimes A_{2}\right],\left[B_{1} \otimes B_{2}\right]\right) \circ j^{\prime}\right)(E \otimes F) \\
& =\left[B_{1} \otimes B_{2}\right] \circ\left(j^{\prime}(E \otimes F)\right) \circ\left[A_{1} \otimes A_{2}\right] \\
& =j^{\prime \prime}\left(\left(B_{1} \circ E \circ A_{1}\right) \otimes\left(B_{2} \circ F \circ A_{2}\right)\right) .
\end{aligned}
$$

The last step uses Lemma 1.35.

Lemma 1.37. For any vector spaces $U, W$, and any maps $\phi \in \mathbb{K}^{*}, F \in$ $\operatorname{Hom}(U, W)$, the following diagram is commutative.


Proof. For $\lambda \in \mathbb{K}, u \in U$,

$$
\begin{aligned}
& l_{W} \circ[\phi \otimes F]: \lambda \otimes u \mapsto \\
& l_{W}((\phi(\lambda)) \otimes(F(u)))=\phi(\lambda) \cdot F(u), \\
&(\phi(1) \cdot F) \circ l_{U}: \lambda \otimes u \mapsto
\end{aligned} \phi(1) \cdot F(\lambda \cdot u) .
$$

Definition 1.38. For arbitrary vector spaces $U, V, W$, define

$$
n: \operatorname{Hom}(U, V) \otimes W \rightarrow \operatorname{Hom}(U, V \otimes W)
$$

so that for $A: U \rightarrow V, w \in W, u \in U$,

$$
n(A \otimes w): u \mapsto(A(u)) \otimes w
$$

Notation 1.39. The ordering of the spaces from Definition 1.38 is not canonical; the " $n$ " label (with various subscripts) is used for analogously defined maps:

$$
\begin{aligned}
& n_{0}: \operatorname{Hom}(U, V) \otimes W \quad \rightarrow \quad \operatorname{Hom}(U, V \otimes W): A \otimes w:(u \mapsto(A(u)) \otimes w) \\
& n_{1}: \operatorname{Hom}(U, V) \otimes W \quad \rightarrow \quad \operatorname{Hom}(U, W \otimes V): A \otimes w:(u \mapsto w \otimes(A(u))) \\
& n_{2}: W \otimes \operatorname{Hom}(U, V) \quad \rightarrow \quad \operatorname{Hom}(U, V \otimes W): w \otimes A:(u \mapsto(A(u)) \otimes w) \\
& n_{3}: W \otimes \operatorname{Hom}(U, V) \quad \rightarrow \quad \operatorname{Hom}(U, W \otimes V): w \otimes A:(u \mapsto w \otimes(A(u))) .
\end{aligned}
$$

For map with an $n$ label appearing in a diagram or equation, its type from the above list of four formulas can usually be determined by context.

Lemma 1.40. For any vector spaces $U, U^{\prime}, V, V^{\prime}, W, W^{\prime}$, with maps $n, n^{\prime}$ as indicated, and any maps $F: U^{\prime} \rightarrow U, B: V \rightarrow V^{\prime}, C: W \rightarrow W^{\prime}$, the following diagram is commutative.


Proof. For $A: U \rightarrow V, w \in W, u^{\prime} \in U^{\prime}$,

$$
\begin{aligned}
A \otimes w & \mapsto(\operatorname{Hom}(F,[B \otimes C]) \circ n)(A \otimes w)=[B \otimes C] \circ(n(A \otimes w)) \circ F: \\
u^{\prime} & \mapsto[B \otimes C]\left(\left(A\left(F\left(u^{\prime}\right)\right)\right) \otimes w\right)=\left((B \circ A \circ F)\left(u^{\prime}\right)\right) \otimes(C(w)), \\
A \otimes w & \mapsto\left(n^{\prime} \circ[\operatorname{Hom}(F, B) \otimes C]\right)(A \otimes w)=n^{\prime}((B \circ A \circ F) \otimes(C(w))): \\
u^{\prime} & \mapsto\left((B \circ A \circ F)\left(u^{\prime}\right)\right) \otimes(C(w)) .
\end{aligned}
$$

The $n$ map is related to a canonical $j$ map.
LEMMA 1.41. The following diagram is commutative.


Proof. Starting with $A \otimes w \in \operatorname{Hom}(U, V) \otimes W$,

$$
\begin{aligned}
A \otimes w & \mapsto\left(j \circ\left[I d_{\operatorname{Hom}(U, V)} \otimes m\right]\right)(A \otimes w)=j(A \otimes(m(w))): \\
u \otimes \lambda & \mapsto(A(u)) \otimes(\lambda \cdot w)=\lambda \cdot(A(u)) \otimes w \\
A \otimes w & \mapsto\left(\operatorname{Hom}\left(l_{U}, I d_{V \otimes W}\right) \circ n\right)(A \otimes w)=(n(A \otimes w)) \circ l_{U}: \\
u \otimes \lambda & \mapsto(A(\lambda \cdot u)) \otimes w=\lambda \cdot(A(u)) \otimes w
\end{aligned}
$$

Lemma 1.42. The canonical map $n$ is one-to-one, and if $U$ or $W$ is finitedimensional, then $n$ is invertible.

Proof. This follows from Lemma 1.21, Claim 1.33, Lemma 1.41, and the invertibility of the $l_{U}$ map as in Example 1.27. See also [B] §II.7.7 or [AF] §20.

Lemma 1.40, Lemma 1.41, and Lemma 1.42 all generalize in a straightforward way to the variant $n$ maps as in Notation 1.39.

Definition 1.43. For arbitrary vector spaces $U, V, W$ define

$$
q: \operatorname{Hom}(V, \operatorname{Hom}(U, W)) \rightarrow \operatorname{Hom}(V \otimes U, W)
$$

so that for $K: V \rightarrow \operatorname{Hom}(U, W), v \in V, u \in U$,

$$
(q(K))(v \otimes u)=(K(v))(u)
$$

Lemma 1.44. For any vector spaces $U, V, W, q$ is invertible.
Proof. For $D \in \operatorname{Hom}(V \otimes U, W)$, check that

$$
q^{-1}(D): v \mapsto(u \mapsto D(v \otimes u))
$$

defines an inverse. See also $[\mathbf{A F}] \S 19,[\mathbf{B}] \S$ II.4.1, $[\mathbf{M B}] \S I X .11$, or $[\mathbf{K}] \S$ II.1.
REMARK 1.45. In some applications, the map $q^{-1}$ is called a "currying" transformation, and so $q$ is an "uncurrying" map.

Lemma 1.46. ([AF] §20) For any vector spaces $U_{1}, V_{1}, W_{1}, U_{2}, V_{2}, W_{2}$, with maps $q_{1}, q_{2}$ as indicated, and any maps $D: V_{2} \rightarrow V_{1}, E: U_{2} \rightarrow U_{1}, F: W_{1} \rightarrow W_{2}$, the following diagram is commutative.


Proof. Starting with any $G: V_{1} \rightarrow \operatorname{Hom}\left(U_{1}, W_{1}\right)$,

$$
\begin{aligned}
\left(\operatorname{Hom}([E \otimes D], F) \circ q_{1}\right)(G): u \otimes v & \mapsto\left(F \circ\left(q_{1}(G)\right) \circ[E \otimes D]\right)(u \otimes v) \\
& =F((G(D(v)))(E(u))), \\
\left(q_{2} \circ \operatorname{Hom}(D, \operatorname{Hom}(E, F))\right)(G): u \otimes v & \mapsto\left(q_{2}(\operatorname{Hom}(E, F) \circ G \circ D)\right)(u \otimes v) \\
& =((\operatorname{Hom}(E, F) \circ G \circ D)(v))(u) \\
& =(F \circ(G(D(v))) \circ E)(u) \\
& =F((G(D(v)))(E(u))) .
\end{aligned}
$$

Lemma 1.47. The following diagram is commutative.


Proof. For $G \in \operatorname{Hom}(X, \operatorname{Hom}(Y, \operatorname{Hom}(Z, U))), x \in X, y \in Y, z \in Z$,

$$
\left(q_{2} \circ q_{1}\right)(G): x \otimes y \otimes z \quad \mapsto \quad\left(q_{2}\left(q_{1}(G)\right)\right)(x \otimes y \otimes z)
$$

$$
=\quad\left(\left(q_{1}(G)\right)(x \otimes y)\right)(z)
$$

$$
=((G(x))(y))(z)
$$

$$
\left(q_{4} \circ \operatorname{Hom}\left(I d_{X}, q_{3}\right)\right)(G): x \otimes y \otimes z \quad \mapsto \quad\left(q_{4}\left(q_{3} \circ G\right)\right)(x \otimes y \otimes z)
$$

$$
=\left(\left(q_{3} \circ G\right)(x)\right)(y \otimes z)=\left(q_{3}(G(x))\right)(y \otimes z)
$$

$$
=((G(x))(y))(z)
$$

Example 1.48. The generalized transpose map from Definition 1.7 is a distinguished element in the following vector space:

$$
t_{U V}^{W} \in \operatorname{Hom}(\operatorname{Hom}(U, V), \operatorname{Hom}(\operatorname{Hom}(V, W), \operatorname{Hom}(U, W)))
$$

and its image under this $q$ map,

$$
\begin{aligned}
q & : \quad \operatorname{Hom}(\operatorname{Hom}(U, V), \operatorname{Hom}(\operatorname{Hom}(V, W), \operatorname{Hom}(U, W))) \\
& \rightarrow \quad \operatorname{Hom}(\operatorname{Hom}(U, V) \otimes \operatorname{Hom}(V, W), \operatorname{Hom}(U, W))
\end{aligned}
$$

is the following map:

$$
\begin{align*}
q\left(t_{U V}^{W}\right): \operatorname{Hom}(U, V) \otimes \operatorname{Hom}(V, W) & \rightarrow \operatorname{Hom}(U, W) \\
A \otimes B & \mapsto\left(q\left(t_{U V}^{W}\right)\right)(A \otimes B)=\left(t_{U V}^{W}(A)\right)(B) \\
& =\operatorname{Hom}\left(A, I d_{W}\right)(B)=B \circ A \tag{1.5}
\end{align*}
$$

The operation of composition of linear maps is a bilinear function, as in Definition 1.22:

$$
\begin{align*}
\circ: \operatorname{Hom}(U, V) \times \operatorname{Hom}(V, W) & \rightsquigarrow \operatorname{Hom}(U, W) \\
(A, B) & \mapsto B \circ A . \tag{1.6}
\end{align*}
$$

The agreement of (1.5) and (1.6) shows that $q\left(t_{U V}^{W}\right)$ is the unique linear map corresponding to composition as a bilinear function as in (1.4) and Theorem 6.35:

$$
\circ=q\left(t_{U V}^{W}\right) \circ \boldsymbol{\tau}
$$

Remark 1.49. The conclusion of Example 1.48 is that the generalized transpose map is a linear, curried version of composition. Considering

$$
q\left(t_{U V}^{W}\right) \in \operatorname{Hom}(\operatorname{Hom}(U, V) \otimes \operatorname{Hom}(V, W), \operatorname{Hom}(U, W))
$$

as a distinguished element in a vector space has an analogue in matrix algebra (see, for example, $[\mathbf{C H L}]$ ), where matrix multiplication can be viewed as an element of a space of tensors.

Example 1.50. Let $\mathbf{B}: V \times V \rightsquigarrow \mathbb{K}$ be a bilinear function as in Definition 1.22 , so that there exists a unique linear map $B: V \otimes V \rightarrow \mathbb{K}$ satisfying $B \circ \boldsymbol{\tau}=$ $\mathbf{B}$ as in (1.4). The invertible map $q^{-1}: \operatorname{Hom}(V \otimes V, \mathbb{K}) \rightarrow \operatorname{Hom}(V, \operatorname{Hom}(V, \mathbb{K}))$ transforms $B \in(V \otimes V)^{*}$ to $q^{-1}(B) \in \operatorname{Hom}\left(V, V^{*}\right)$. So, every bilinear function $\mathbf{B}: V \times V \rightsquigarrow \mathbb{K}$ has a linearized, curried form which is an element of $\operatorname{Hom}\left(V, V^{*}\right)$, called a bilinear form - such maps are the main topic of Chapter 3.

Definition 1.51 . For any vector spaces $U, V, W$ define

$$
e_{U V}^{W}: \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}(\operatorname{Hom}(V, W) \otimes U, W)
$$

so that for $A: U \rightarrow V, B: V \rightarrow W$, and $u \in U$,

$$
e_{U V}^{W}(A): B \otimes u \mapsto B(A(u)) \in W
$$

Lemma 1.52. For any vector spaces $U, V, W, U^{\prime}, V^{\prime}, W^{\prime}$, and any maps $E: U^{\prime} \rightarrow U, F: V \rightarrow V^{\prime}, G: W \rightarrow W^{\prime}$, the following diagram is commutative.


Proof. For any $A: U \rightarrow V, C: V^{\prime} \rightarrow W, u \in U^{\prime}$,

$$
\begin{aligned}
& \operatorname{Hom}\left(\left[\operatorname{Hom}\left(I d_{V^{\prime}}, G\right) \otimes I d_{U^{\prime}}\right], I d_{W^{\prime}}\right) \circ e_{U^{\prime} V^{\prime}}^{W^{\prime}} \circ \operatorname{Hom}(E, F): \\
A \mapsto & \left(e_{U^{\prime} V^{\prime}}^{W^{\prime}}(F \circ A \circ E)\right) \circ\left[\operatorname{Hom}\left(I d_{V^{\prime}}, G\right) \otimes I d_{U^{\prime}}\right]: \\
C \otimes u \mapsto & \left(e_{U^{\prime} V^{\prime}}^{W^{\prime}}(F \circ A \circ E)\right)((G \circ C) \otimes u) \\
= & (G \circ C)((F \circ A \circ E)(u)), \\
& \operatorname{Hom}\left(\left[\operatorname{Hom}\left(F, I d_{W}\right) \otimes E\right], G\right) \circ e_{U V}^{W}: \\
A \rightarrow & G \circ\left(e_{U V}^{W}(A)\right) \circ\left[\operatorname{Hom}\left(F, I d_{W}\right) \otimes E\right]: \\
C \otimes u \mapsto & G\left(\left(e_{U V}^{W}(A)\right)((C \circ F) \otimes(E(u)))\right) \\
= & G((C \circ F)(A(E(u)))) .
\end{aligned}
$$

Lemma 1.53. The following diagram is commutative.


$$
\operatorname{Hom}(\operatorname{Hom}(V, W), \operatorname{Hom}(U, W))
$$

Proof.

$$
q \circ t_{U V}^{W}: A \mapsto q\left(\operatorname{Hom}\left(A, I d_{W}\right)\right): B \otimes u \mapsto(B \circ A)(u)=\left(e_{U V}^{W}(A)\right)(B \otimes u)
$$

Notation 1.54. For the special case $W=\mathbb{K}$, abbreviate $e_{U V}^{\mathbb{K}}=e_{U V}$ (or sometimes just $e$ ):

$$
e_{U V}: \operatorname{Hom}(U, V) \rightarrow\left(V^{*} \otimes U\right)^{*}
$$

so that for $A: U \rightarrow V, \phi \in V^{*}$, and $u \in U$,

$$
e_{U V}(A): \phi \otimes u \mapsto \phi(A(u)) \in \mathbb{K}
$$

Claim 1.55. If $U$ and $V$ are finite-dimensional, then $e_{U V}$ is invertible.
Definition 1.56. For any vector spaces $U, V$, define

$$
k_{U V}: U^{*} \otimes V \rightarrow \operatorname{Hom}(U, V)
$$

so that for $\xi \in U^{*}, v \in V$, and $u \in U$,

$$
\left(k_{U V}(\xi \otimes v)\right): u \mapsto \xi(u) \cdot v \in V
$$

Lemma 1.57. For maps $A: U^{\prime} \rightarrow U, B: V \rightarrow V^{\prime}$, the following diagram is commutative.


Proof. For $\phi \otimes v \in U^{*} \otimes V, u \in U^{\prime}$,

$$
\begin{aligned}
\left(\operatorname{Hom}(A, B) \circ k_{U V}\right)(\phi \otimes v) & =B \circ\left(k_{U V}(\phi \otimes v)\right) \circ A: \\
u & \mapsto B(\phi(A(u)) \cdot v)=\phi(A(u)) \cdot B(v), \\
\left(k_{U^{\prime} V^{\prime}} \circ\left[A^{*} \otimes B\right]\right)(\phi \otimes v) & =k_{U^{\prime} V^{\prime}}\left(\left(A^{*}(\phi)\right) \otimes(B(v))\right): \\
u & \mapsto\left(A^{*}(\phi)\right)(u) \cdot B(v)=\phi(A(u)) \cdot B(v) .
\end{aligned}
$$

Lemma 1.58. For any vector space $V, k_{V \mathbb{K}}=l_{V^{*}}: V^{*} \otimes \mathbb{K} \rightarrow V^{*}$.
Proof. For $v \in V, \varphi \in V^{*}, \lambda \in \mathbb{K}$,

$$
\begin{aligned}
k_{V \mathbb{K}}: \varphi \otimes \lambda & \mapsto \quad k_{V \mathbb{K}}(\varphi \otimes \lambda): v \mapsto \varphi(v) \cdot \lambda, \\
l_{V^{*}}: \varphi \otimes \lambda & \mapsto \\
& \lambda \cdot \varphi: v \mapsto(\lambda \cdot \varphi)(v) .
\end{aligned}
$$

Lemma 1.59. The canonical map $k_{U V}$ is one-to-one, and if $U$ or $V$ is finitedimensional then $k_{U V}$ is invertible.

Proof. The $k_{U V}$ map (sometimes abbreviated $k$ ) is related to a canonical $n$ map. The following diagram is commutative.


The $n$ map is one-to-one, and, if $U$ or $V$ is finite-dimensional, then $n$ is invertible by Lemma 1.42, which used Claim 1.33. The $l_{V}$ map is invertible as in Example 1.27. See also [B] §II.7.7 or [K] §II.2.

REMARK 1.60. Unlike the canonical maps $t_{U V}^{W}, d_{V W}, s, j, n, q$, and $e_{U V}^{W}$, the $k$ maps explicitly refer to the set of scalars $\mathbb{K}$, in both the dual space $U^{*}$ and the scalar multiplication - in $V$. The maps $l$ and $m$ also refer to scalar multiplication.

Remark 1.61. The canonical maps appearing in this Chapter are well-known in abstract linear algebra. Lemma 1.8, Lemma 1.13, Lemma 1.20, Lemma 1.36, Lemma 1.37, Lemma 1.40, Lemma 1.46, Lemma 1.52, and Lemma 1.57 can be interpreted as statements about the naturality of the $t, d, m, j, l, n, q, e$, and $k$ maps, in a technical sense of category theory. In geometry, these same lemmas also are enough to show that these maps transform in the right way under (pointwise linear, invertible) changes from one local trivialization to another in a vector bundle,
so that these basis-free constructions on vector spaces extend to well-defined maps of vector bundles.

REmARK 1.62. These canonical maps also appear in concrete matrix algebra and applications: see [Magnus], [G् $\mathbf{2}_{2}$ (particularly §I. 8 and §VI.3), [Graham], and [HJ] (Chapter 4), which also has historical references. For example, the map $k_{U V}^{-1}: \operatorname{Hom}(U, V) \rightarrow U^{*} \otimes V$ is a "vectorization," or "vec" operator. The $t_{U V}$ map, of course, is analogous to the transpose operation $\left(A \mapsto A^{\prime}\right.$, in the notation of [Magnus]) and the identity $\operatorname{vec}(A B C)=\left(C^{\prime} \otimes A\right) \operatorname{vec} B$ ([Nissen], [HJ], [Magnus] $\S 1.10)$ is the analogue of Lemma 1.57.

Notation 1.63. The composite of the $e$ and $k$ maps is denoted

$$
f_{U V}=e_{U V} \circ k_{U V}: U^{*} \otimes V \rightarrow\left(V^{*} \otimes U\right)^{*}
$$

Sometimes $f_{U V}$ is abbreviated $f$.
The output $f_{U V}(\phi \otimes v)$ acts on $\xi \otimes u$ to give $\phi(u) \cdot \xi(v) \in \mathbb{K}$ :
$\left(e_{U V}\left(k_{U V}(\phi \otimes v)\right)\right)(\xi \otimes u)=\xi\left(\left(k_{U V}(\phi \otimes v)\right)(u)\right)=\xi(\phi(u) \cdot v)=\phi(u) \cdot \xi(v)$.
EXERCISE 1.64. For maps $A: U^{\prime} \rightarrow U, B: V \rightarrow V^{\prime}$, the following diagram is commutative.


Hint. This can be checked directly as in the Proof of Lemma 1.57; it also follows as a corollary of Lemma 1.52 and Lemma 1.57.

LEmma 1.65. $f_{U V}^{*} \circ d_{V^{*} \otimes U}=f_{V U}: V^{*} \otimes U \rightarrow\left(U^{*} \otimes V\right)^{*}$.
Proof. For $\xi \otimes u \in V^{*} \otimes U$, and $\phi \otimes v \in U^{*} \otimes V$,

$$
\begin{aligned}
\left(f_{U V}^{*}\left(d_{V^{*} \otimes U}(\xi \otimes u)\right)\right)(\phi \otimes v) & =\left(d_{V^{*} \otimes U}(\xi \otimes u)\right)\left(f_{U V}(\phi \otimes v)\right) \\
& =\left(f_{U V}(\phi \otimes v)\right)(\xi \otimes u) \\
& =\phi(u) \cdot \xi(v) \\
& =\left(f_{V U}(\xi \otimes u)\right)(\phi \otimes v)
\end{aligned}
$$

Notation 1.66. For any vector spaces $U, V$, the following composite is denoted:

$$
p_{U V}=\left[d_{V} \otimes I d_{U^{*}}\right] \circ s: U^{*} \otimes V \rightarrow V^{* *} \otimes U^{*}
$$

So, for $\phi \in U^{*}, v \in V, p_{U V}(\phi \otimes v)=\left(d_{V}(v)\right) \otimes \phi$. Sometimes $p_{U V}$ is abbreviated $p$.
Exercise 1.67. For maps $B: V \rightarrow V^{\prime}, C: U^{*} \rightarrow U^{*}$, the following diagram is commutative.


Hint. This can be checked using case (1.2) of Lemma 1.13.

Lemma 1.68. The following diagram is commutative.


Proof.

$$
\begin{aligned}
\phi \otimes v & \mapsto\left(\operatorname{Hom}\left(I d_{V^{*} \otimes U}, l\right) \circ j \circ p_{U V}\right)(\phi \otimes v)=l \circ\left[\left(d_{V}(v)\right) \otimes \phi\right]: \\
\xi \otimes u & \mapsto \xi(v) \cdot \phi(u) \\
& =(f(\phi \otimes v))(\xi \otimes u)
\end{aligned}
$$

Lemma 1.69. The following diagram is commutative.


Proof.

$$
\begin{aligned}
\phi \otimes v & \mapsto\left(k_{V^{*} U^{*}} \circ p_{U V}\right)(\phi \otimes v)=k_{V^{*} U^{*}}\left(\left(d_{V}(v)\right) \otimes \phi\right): \\
\xi & \mapsto\left(k_{V^{*} U^{*}}\left(\left(d_{V}(v)\right) \otimes \phi\right)\right)(\xi)=\left(d_{V}(v)\right)(\xi) \cdot \phi=\xi(v) \cdot \phi: \\
u & \mapsto \xi(v) \cdot \phi(u) \\
\phi \otimes v & \mapsto\left(t_{U V} \circ k_{U V}\right)(\phi \otimes v): \\
\xi & \mapsto\left(t_{U V}\left(k_{U V}(\phi \otimes v)\right)\right)(\xi)=\xi \circ\left(k_{U V}(\phi \otimes v)\right): \\
u & \mapsto \xi\left(\left(k_{U V}(\phi \otimes v)\right)(u)\right)=\xi(\phi(u) \cdot v)=\phi(u) \cdot \xi(v) .
\end{aligned}
$$

REMARK 1.70. The map $p$ also corresponds to a well-known object in matrix algebra, the "commutation matrix" $K$ in [Magnus] §3.1. The identity $K v e c A=$ $\operatorname{vec}\left(A^{\prime}\right)$ corresponds to the identity $k \circ p=t \circ k$. It has also been called the "shuffle matrix" ([L], [HJ]).

### 1.3. Direct sums

The following definition applies to any integer $\nu \geq 2$ (see also [AF] §6).
Definition 1.71. Given vector spaces $V, V_{1}, V_{2}, \ldots, V_{\nu}$ and ordered $\nu$-tuples of maps $\left(P_{1}, P_{2}, \ldots, P_{\nu}\right)$ and $\left(Q_{1}, Q_{2}, \ldots, Q_{\nu}\right)$, where $P_{i}: V \rightarrow V_{i}, Q_{i}: V_{i} \rightarrow V$ for $i=1,2, \ldots, \nu, V$ is a direct sum of $V_{1}, V_{2}, \ldots, V_{\nu}$ means:

$$
Q_{1} \circ P_{1}+Q_{2} \circ P_{2}+\cdots+Q_{\nu} \circ P_{\nu}=I d_{V}
$$

and

$$
P_{i} \circ Q_{I}=\left\{\begin{array}{ll}
I d_{V_{i}} & \text { if } i=I \\
0_{\operatorname{Hom}\left(V_{I}, V_{i}\right)} & \text { if } i \neq I
\end{array} .\right.
$$

This data is sometimes abbreviated $V=V_{1} \oplus V_{2} \oplus \cdots \oplus V_{\nu}$, when the maps $P_{i}$ (called projections or projection operators) and $Q_{i}$ (inclusions or inclusion operators) are understood. Note that each map $Q_{i}$ is one-to-one (having a left inverse as in Exercise 0.43 ) and that if $V$ is finite-dimensional then each $V_{i}$ is also finite-dimensional (by Exercise 0.44 - this fact may not be mentioned at every subsequent occurence).

We will most frequently consider direct sums of two spaces; in this $\nu=2$ case, the above Definition requires that five equations are satisfied by $\left(P_{1}, P_{2}\right),\left(Q_{1}, Q_{2}\right)$, but it is enough to check only three of these equations.

Lemma 1.72. Given vector spaces $V, V_{1}, V_{2}$, if there exist $P_{1}: V \rightarrow V_{1}$, $P_{2}: V \rightarrow V_{2}, Q_{1}: V_{1} \rightarrow V, Q_{2}: V_{2} \rightarrow V$ such that:

$$
\begin{aligned}
Q_{1} \circ P_{1}+Q_{2} \circ P_{2} & =I d_{V} \\
P_{1} \circ Q_{1} & =I d_{V_{1}} \\
P_{2} \circ Q_{2} & =I d_{V_{2}}
\end{aligned}
$$

then $V=V_{1} \oplus V_{2}$.
Proof. The conclusion is that the pairs $\left(P_{1}, P_{2}\right)$ and $\left(Q_{1}, Q_{2}\right)$ satisfy Definition 1.71, and the only two equations remaining to be checked are $P_{2} \circ Q_{1}=$ $0_{\mathrm{Hom}\left(V_{1}, V_{2}\right)}$ and $P_{1} \circ Q_{2}=0_{\mathrm{Hom}\left(V_{2}, V_{1}\right)}$.

$$
\begin{aligned}
P_{2} \circ Q_{1} & =P_{2} \circ I d_{V} \circ Q_{1}=P_{2} \circ\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right) \circ Q_{1} \\
& =P_{2} \circ Q_{1} \circ P_{1} \circ Q_{1}+P_{2} \circ Q_{2} \circ P_{2} \circ Q_{1} \\
& =P_{2} \circ Q_{1} \circ I d_{V_{1}}+I d_{V_{2}} \circ P_{2} \circ Q_{1} \\
& =P_{2} \circ Q_{1}+P_{2} \circ Q_{1} \\
& =0_{H \circ m\left(V_{1}, V_{2}\right)},
\end{aligned}
$$

the last step using Theorem 0.3. The other equation is similarly checked.
Theorem 1.73. Given vector spaces $V, V_{1}, V_{2}, V_{3}, V_{4}$, if $V=V_{1} \oplus V_{2}$ and $V_{2}=V_{3} \oplus V_{4}$, then $V=V_{1} \oplus V_{3} \oplus V_{4}$.

Proof. Let $\left(P_{1}, P_{2}\right),\left(Q_{1}, Q_{2}\right)$ be the operators for $V=V_{1} \oplus V_{2}$, and let $\left(P_{3}, P_{4}\right),\left(Q_{3}, Q_{4}\right)$ be the operators for $V_{2}=V_{3} \oplus V_{4}$. The projection operators $\left(P_{1}, P_{3} \circ P_{2}, P_{4} \circ P_{2}\right)$ and inclusions $\left(Q_{1}, Q_{2} \circ Q_{3}, Q_{2} \circ Q_{4}\right)$ give a canonical construction for the claimed direct sum. The first equation from Definition 1.71 is:

$$
\begin{aligned}
& Q_{1} \circ P_{1}+\left(Q_{2} \circ Q_{3}\right) \circ\left(P_{3} \circ P_{2}\right)+\left(Q_{2} \circ Q_{4}\right) \circ\left(P_{4} \circ P_{2}\right) \\
= & Q_{1} \circ P_{1}+Q_{2} \circ\left(Q_{3} \circ P_{3}+Q_{4} \circ P_{4}\right) \circ P_{2} \\
= & Q_{1} \circ P_{1}+Q_{2} \circ I d_{V_{2}} \circ P_{2} \\
= & I d_{V} .
\end{aligned}
$$

The remaining nine equations are also easily checked.
Example 1.74. If $H: U \rightarrow V$ is an invertible map between arbitrary vector spaces, and $V=V_{1} \oplus V_{2}$, then $U$ is a direct sum of $V_{1}$ and $V_{2}$, with projections $P_{i} \circ H: U \rightarrow V_{i}$ for $i=1,2$, and inclusions $H^{-1} \circ Q_{i}: V_{i} \rightarrow U$.

Example 1.75. If $V=V_{1} \oplus V_{2}$, and $U$ is any vector space, then $V \otimes U$ is a direct sum of $V_{1} \otimes U$ and $V_{2} \otimes U$. The projection and inclusion operators are $\left[P_{i} \otimes I d_{U}\right]: V \otimes U \rightarrow V_{i} \otimes U$, and $\left[Q_{i} \otimes I d_{U}\right]: V_{i} \otimes U \rightarrow V \otimes U$. There is an analogous direct sum $U \otimes V=U \otimes V_{1} \oplus U \otimes V_{2}$.

Example 1.76. If $V=V_{1} \oplus V_{2}$, and $U$ is any vector space, then $\operatorname{Hom}(U, V)$ is a direct sum of $\operatorname{Hom}\left(U, V_{1}\right)$ and $\operatorname{Hom}\left(U, V_{2}\right)$. The projection and inclusion operators are $\operatorname{Hom}\left(I d_{U}, P_{i}\right): \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}\left(U, V_{i}\right)$, and $\operatorname{Hom}\left(I d_{U}, Q_{i}\right): \operatorname{Hom}\left(U, V_{i}\right) \rightarrow$ $\operatorname{Hom}(U, V)$.

Example 1.77. If $V=V_{1} \oplus V_{2}$, and $U$ is any vector space, then $\operatorname{Hom}(V, U)$ is a direct sum of $\operatorname{Hom}\left(V_{1}, U\right)$ and $\operatorname{Hom}\left(V_{2}, U\right)$. The projection operators are $\operatorname{Hom}\left(Q_{i}, I d_{U}\right): \operatorname{Hom}(V, U) \rightarrow \operatorname{Hom}\left(V_{i}, U\right)$, and the inclusion operators are

$$
\operatorname{Hom}\left(P_{i}, I d_{U}\right): \operatorname{Hom}\left(V_{i}, U\right) \rightarrow \operatorname{Hom}(V, U)
$$

Example 1.78. As the $U=\mathbb{K}$ special case of the previous Example, if $V=$ $V_{1} \oplus V_{2}$, then $V^{*}=V_{1}^{*} \oplus V_{2}^{*}$, with projections $Q_{i}^{*}$ and inclusions $P_{i}^{*}$.

Lemma 1.79. Given $V=V_{1} \oplus V_{2}$, the image of $Q_{2}$, i.e., the subspace $Q_{2}\left(V_{2}\right)$ of $V$, is equal to the subspace $\operatorname{ker}\left(P_{1}\right)$, the kernel of $P_{1}$, which is also equal to $\operatorname{ker}\left(Q_{1} \circ P_{1}\right)$.

Proof. The second equality follows from $\operatorname{ker}\left(P_{1}\right) \subseteq \operatorname{ker}\left(Q_{1} \circ P_{1}\right) \subseteq \operatorname{ker}\left(P_{1} \circ Q_{1} \circ\right.$ $\left.P_{1}\right)=\operatorname{ker}\left(P_{1}\right)$. It follows from $P_{1} \circ Q_{2}=0_{\mathrm{Hom}\left(V_{2}, V_{1}\right)}$ that $Q_{2}\left(V_{2}\right) \subseteq \operatorname{ker}\left(P_{1}\right)$, and if $P_{1}(v)=0_{V_{1}}$, then $v=\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right)(v)=Q_{2}\left(P_{2}(v)\right)$, so $\operatorname{ker}\left(P_{1}\right) \subseteq Q_{2}\left(V_{2}\right)$.

Lemma 1.80. Given $U=U_{1} \oplus U_{2}$ and $V=V_{1} \oplus V_{2}$, with projections and inclusions $P_{i}^{\prime}, Q_{i}^{\prime}, P_{i}, Q_{i}$, respectively, if the maps $A_{1}: U_{1} \rightarrow V_{1}$ and $A_{2}: U_{2} \rightarrow V_{2}$ are both invertible, then the map $Q_{1} \circ A_{1} \circ P_{1}^{\prime}+Q_{2} \circ A_{2} \circ P_{2}^{\prime}: U \rightarrow V$ is invertible.

Proof. The inverse is $Q_{1}^{\prime} \circ A_{1}^{-1} \circ P_{1}+Q_{2}^{\prime} \circ A_{2}^{-1} \circ P_{2}$.
Lemma 1.81. Given a direct sum $V=V_{1} \oplus V_{2}$ as in Definition 1.71, another direct sum $U=U_{1} \oplus U_{2}$, with operators $P_{i}^{\prime}$ and $Q_{i}^{\prime}$, and $H: U \rightarrow V$, the following are equivalent.
(1) $Q_{1} \circ P_{1} \circ H=H \circ Q_{1}^{\prime} \circ P_{1}^{\prime}$.
(2) $Q_{2} \circ P_{2} \circ H=H \circ Q_{2}^{\prime} \circ P_{2}^{\prime}$.
(3) $P_{1} \circ H \circ Q_{2}^{\prime}=0_{\mathrm{Hom}\left(U_{2}, V_{1}\right)}$ and $P_{2} \circ H \circ Q_{1}^{\prime}=0_{\operatorname{Hom}\left(U_{1}, V_{2}\right)}$.
(4) There exist maps $H_{1}: U_{1} \rightarrow V_{1}$ and $H_{2}: U_{2} \rightarrow V_{2}$ such that $H=$ $Q_{1} \circ H_{1} \circ P_{1}^{\prime}+Q_{2} \circ H_{2} \circ P_{2}^{\prime}$.

Proof. First, for $(1) \Longleftrightarrow(2)$,

$$
\begin{aligned}
& H=\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right) \circ H=H \circ\left(Q_{1}^{\prime} \circ P_{1}^{\prime}+Q_{2}^{\prime} \circ P_{2}^{\prime}\right) \\
& =Q_{1} \circ P_{1} \circ H+Q_{2} \circ P_{2} \circ H=H \circ Q_{1}^{\prime} \circ P_{1}^{\prime}+H \circ Q_{2}^{\prime} \circ P_{2}^{\prime} .
\end{aligned}
$$

Applying either equality (1) or (2), then subtracting, gives the other equality. For $(1) \Longrightarrow$ (3),

$$
\begin{aligned}
P_{1} \circ H \circ Q_{2}^{\prime} & =P_{1} \circ\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right) \circ H \circ Q_{2}^{\prime} \\
& =P_{1} \circ H \circ Q_{1}^{\prime} \circ P_{1}^{\prime} \circ Q_{2}^{\prime}=0_{\mathrm{Hom}\left(U_{2}, V_{1}\right)}, \\
P_{2} \circ H \circ Q_{1}^{\prime} & =P_{2} \circ H \circ\left(Q_{1}^{\prime} \circ P_{1}^{\prime}+Q_{2}^{\prime} \circ P_{2}^{\prime}\right) \circ Q_{1}^{\prime} \\
& =P_{2} \circ Q_{1} \circ P_{1} \circ H \circ Q_{1}^{\prime}=0_{\mathrm{Hom}\left(U_{1}, V_{2}\right)} .
\end{aligned}
$$

Next, to show that (3) implies (1) or (2), let $i=1$ or 2 :

$$
\begin{aligned}
Q_{i} \circ P_{i} \circ H & =Q_{i} \circ P_{i} \circ H \circ\left(Q_{1}^{\prime} \circ P_{1}^{\prime}+Q_{2}^{\prime} \circ P_{2}^{\prime}\right) \\
& =Q_{i} \circ P_{i} \circ H \circ Q_{i}^{\prime} \circ P_{i}^{\prime} \\
& =\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right) \circ H \circ Q_{i}^{\prime} \circ P_{i}^{\prime}=H \circ Q_{i}^{\prime} \circ P_{i}^{\prime} .
\end{aligned}
$$

The construction in (4) is the same as in Lemma 1.80 (without requiring invertibility). The implication $(4) \Longrightarrow(1)$ is straightforward. To show that (1) and (2) imply (4), let $H_{1}=P_{1} \circ H \circ Q_{1}^{\prime}$ and $H_{2}=P_{2} \circ H \circ Q_{2}^{\prime}$. Then,

$$
\begin{aligned}
Q_{1} \circ H_{1} \circ P_{1}^{\prime}+Q_{2} \circ H_{2} \circ P_{2}^{\prime} & =Q_{1} \circ P_{1} \circ H \circ Q_{1}^{\prime} \circ P_{1}^{\prime}+Q_{2} \circ P_{2} \circ H \circ Q_{2}^{\prime} \circ P_{2}^{\prime} \\
& =Q_{1} \circ P_{1} \circ Q_{1} \circ P_{1} \circ H+Q_{2} \circ P_{2} \circ Q_{2} \circ P_{2} \circ H \\
& =\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right) \circ H=H .
\end{aligned}
$$

Definition 1.82. For $V=V_{1} \oplus V_{2}, U=U_{1} \oplus U_{2}$, and $H: U \rightarrow V, H$ respects the direct sums means: $H$ satisfies any of the equivalent conditions from Lemma 1.81. For such a map and $i=1,2$, the composites $P_{i} \circ H \circ Q_{i}^{\prime}: U_{i} \rightarrow V_{i}$ are said to be induced by $H$.

Lemma 1.83. If $H: U \rightarrow V$ is an invertible map which respects the direct sums as in Definition 1.82, then $H^{-1}$ also respects the direct sums, and for each $i=1,2$, the induced map $P_{i} \circ H \circ Q_{i}^{\prime}: U_{i} \rightarrow V_{i}$ is invertible, with inverse $P_{i}^{\prime} \circ H^{-1} \circ Q_{i}$.

Proof.

$$
\begin{aligned}
\left(P_{i} \circ H \circ Q_{i}^{\prime}\right) \circ\left(P_{i}^{\prime} \circ H^{-1} \circ Q_{i}\right) & =P_{i} \circ Q_{i} \circ P_{i} \circ H \circ H^{-1} \circ Q_{i} \\
& =P_{i} \circ Q_{i}=I d_{V_{i}} \\
\left(P_{I}^{\prime} \circ H^{-1} \circ Q_{i}\right) \circ\left(P_{i} \circ H \circ Q_{i}^{\prime}\right) & =P_{I}^{\prime} \circ H^{-1} \circ H \circ Q_{i}^{\prime} \circ P_{i}^{\prime} \circ Q_{i}^{\prime} \\
& =P_{I}^{\prime} \circ Q_{i}^{\prime}
\end{aligned}
$$

If $i=I$, this shows $P_{i} \circ H \circ Q_{i}^{\prime}$ is invertible. If $i \neq I$, then $P_{I}^{\prime} \circ H^{-1} \circ Q_{i}=0_{\operatorname{Hom}\left(V_{i}, U_{I}\right)}$, so $H^{-1}$ respects the direct sums.

Lemma 1.84. Given $U=U_{1} \oplus U_{2}, V=V_{1} \oplus V_{2}$, $W=W_{1} \oplus W_{2}$, if $H: U \rightarrow V$ respects the direct sums and $H^{\prime}: V \rightarrow W$ respects the direct sums, then $H^{\prime} \circ H$ : $U \rightarrow W$ respects the direct sums. A map induced by the composite is equal to the composite of the corresponding induced maps.

Lemma 1.85. Suppose $V=V_{1} \oplus V_{2}, U=U_{1} \oplus U_{2}$, and $H: U \rightarrow V$ respects the direct sums, inducing maps $P_{i} \circ H \circ Q_{i}^{\prime}$. Then, for any $A: W \rightarrow X$, the map $[H \otimes A]: U \otimes W \rightarrow V \otimes X$ respects the direct sums

$$
U_{1} \otimes W \oplus U_{2} \otimes W \rightarrow V_{1} \otimes X \oplus V_{2} \otimes X
$$

from Example 1.75. The induced map $\left[P_{i} \otimes I d_{X}\right] \circ[H \otimes A] \circ\left[Q_{i}^{\prime} \otimes I d_{W}\right]$ is equal to $\left[\left(P_{i} \circ H \circ Q_{i}^{\prime}\right) \otimes A\right]$.

Proof. All the claims follow immediately from Lemma 1.35.
Lemma 1.86. Suppose $V=V_{1} \oplus V_{2}, U=U_{1} \oplus U_{2}$, and $H: U \rightarrow V$ respects the direct sums, inducing maps $P_{i} \circ H \circ Q_{i}^{\prime}$. Then, for any $A: W \rightarrow X$, the map $\operatorname{Hom}(A, H): \operatorname{Hom}(X, U) \rightarrow \operatorname{Hom}(W, V)$ respects the direct sums

$$
\operatorname{Hom}\left(X, U_{1}\right) \oplus \operatorname{Hom}\left(X, U_{2}\right) \rightarrow \operatorname{Hom}\left(W, V_{1}\right) \oplus \operatorname{Hom}\left(W, V_{2}\right)
$$

from Example 1.76. The induced map $\operatorname{Hom}\left(I d_{W}, P_{i}\right) \circ \operatorname{Hom}(A, H) \circ \operatorname{Hom}\left(I d_{X}, Q_{i}^{\prime}\right)$ is equal to $\operatorname{Hom}\left(A, P_{i} \circ H \circ Q_{i}^{\prime}\right)$. Analogously, the map $\operatorname{Hom}(H, A): \operatorname{Hom}(V, W) \rightarrow$ $\operatorname{Hom}(U, X)$ respects the direct sums

$$
\operatorname{Hom}\left(V_{1}, W\right) \oplus \operatorname{Hom}\left(V_{2}, W\right) \rightarrow \operatorname{Hom}\left(U_{1}, X\right) \oplus \operatorname{Hom}\left(U_{2}, X\right)
$$

from Example 1.77, and the induced map $\operatorname{Hom}\left(Q_{i}^{\prime}, I d_{W}\right) \circ \operatorname{Hom}(H, A) \circ \operatorname{Hom}\left(P_{i}, I d_{X}\right)$ is equal to $\operatorname{Hom}\left(P_{i} \circ H \circ Q_{i}^{\prime}, A\right)$.

Proof. All the claims follow immediately from Lemma 1.6.
Notation 1.87. Given a direct sum $V=V_{1} \oplus V_{2}$ with operator pairs $\left(P_{1}, P_{2}\right)$, $\left(Q_{1}, Q_{2}\right)$, the pairs in the other order, $\left(P_{2}, P_{1}\right),\left(Q_{2}, Q_{1}\right)$, also satisfy the definition of direct sum. The notation $V=V_{2} \oplus V_{1}$ refers to these re-ordered pairs.

Example 1.88. A map $H \in \operatorname{End}(V)$ which satisfies $Q_{2} \circ P_{2} \circ H=H \circ Q_{1} \circ P_{1}$ respects the direct sums $H: V_{1} \oplus V_{2} \rightarrow V_{2} \oplus V_{1}$ (and so $H$ also satisfies the other identities from Lemma 1.81).

Lemma 1.89. Given a vector space $V$ that admits two direct sums, $V=V_{1} \oplus V_{2}$, $V=V_{1}^{\prime \prime} \oplus V_{2}^{\prime \prime}$ with projections and inclusions $P_{i}, Q_{i}, P_{i}^{\prime \prime}, Q_{i}^{\prime \prime}$, respectively, the following are equivalent.
(1) The identity map $I d_{V}: V_{1} \oplus V_{2} \rightarrow V_{1}^{\prime \prime} \oplus V_{2}^{\prime \prime}$ respects the direct sums.
(2) $Q_{1} \circ P_{1}=Q_{1}^{\prime \prime} \circ P_{1}^{\prime \prime}$.
(3) $Q_{2} \circ P_{2}=Q_{2}^{\prime \prime} \circ P_{2}^{\prime \prime}$.
(4) $P_{I}^{\prime \prime} \circ Q_{i}=0_{\operatorname{Hom}\left(V_{i}, V_{I}^{\prime \prime}\right)}$ for $i \neq I$.
(5) $P_{I} \circ Q_{i}^{\prime \prime}=0_{\mathrm{Hom}\left(V_{i}^{\prime \prime}, V_{I}\right)}$ for $i \neq I$.

Proof. The first statement is, by Definition 1.82 and Lemma 1.81, equivalent to any of the next three statements. The equivalence with the last statement follows from Lemma 1.83.

Definition 1.90. Given $V$, two direct sums $V=V_{1} \oplus V_{2}$ and $V=V_{1}^{\prime \prime} \oplus V_{2}^{\prime \prime}$ are equivalent direct sums means: they satisfy any of the properties from Lemma 1.89 .

For a fixed $V$, this notion is clearly an equivalence relation on direct sum decompositions of $V$.

Example 1.91. If $V=V_{1} \oplus V_{2}$ and $H_{1}: U_{1} \rightarrow V_{1}$ and $H_{2}: U_{2} \rightarrow V_{2}$ are invertible, then $V$ is a direct sum $U_{1} \oplus U_{2}$, with projections $H_{i}^{-1} \circ P_{i}$ and inclusions $Q_{i} \circ H_{i}$. The direct sums $V=V_{1} \oplus V_{2}$ and $V=U_{1} \oplus U_{2}$ are equivalent.

Lemma 1.92. Given $U$ and $V$, a direct sum $U=U_{1} \oplus U_{2}$, and a map $H: U \rightarrow$ $V$, suppose $V=V_{1} \oplus V_{2}$ and $V=V_{1}^{\prime \prime} \oplus V_{2}^{\prime \prime}$ are equivalent direct sums. Then $H$ respects the direct sums $U_{1} \oplus U_{2} \rightarrow V_{1} \oplus V_{2}$ if and only if $H$ respects the direct sums $U_{1} \oplus U_{2} \rightarrow V_{1}^{\prime \prime} \oplus V_{2}^{\prime \prime}$. Similarly, a map $A: V \rightarrow U$ respects the direct sums $V_{1} \oplus V_{2} \rightarrow U_{1} \oplus U_{2}$ if and only if $A$ respects the direct sums $V_{1}^{\prime \prime} \oplus V_{2}^{\prime \prime} \rightarrow U_{1} \oplus U_{2}$.

Lemma 1.93. Given $V=V_{1} \oplus V_{2}$ and $V=V_{1}^{\prime \prime} \oplus V_{2}^{\prime \prime}$ with operators $P_{i}, Q_{i}, P_{i}^{\prime \prime}$, $Q_{i}^{\prime \prime}$, if $P_{1} \circ Q_{2}^{\prime \prime}=0_{\mathrm{Hom}\left(V_{2}^{\prime \prime}, V_{1}\right)}$, and $P_{1}^{\prime \prime} \circ Q_{2}=0_{\mathrm{Hom}\left(V_{2}, V_{1}^{\prime \prime}\right)}$, then $P_{1}^{\prime \prime} \circ Q_{1}: V_{1} \rightarrow V_{1}^{\prime \prime}$ and $P_{2}^{\prime \prime} \circ Q_{2}: V_{2} \rightarrow V_{2}^{\prime \prime}$ are both invertible.

Proof. The inverse of $P_{i}^{\prime \prime} \circ Q_{i}$ is $P_{i} \circ Q_{i}^{\prime \prime}: V_{i}^{\prime \prime} \rightarrow V_{i}$.
As a special case of both Lemma 1.93 and Lemma 1.83, if $V=V_{1} \oplus V_{2}$ and $V=$ $V_{1}^{\prime \prime} \oplus V_{2}^{\prime \prime}$ are equivalent direct sums, then there are canonically induced invertible maps $P_{i}^{\prime \prime} \circ Q_{i}: V_{i} \rightarrow V_{i}^{\prime \prime}, i=1,2$.

Lemma 1.94. Suppose $\phi \in V^{*}$. If $\phi \neq 0_{V^{*}}$ then there exists a direct sum $V=\mathbb{K} \oplus \operatorname{ker}(\phi)$.

Proof. Let $Q_{2}$ be the inclusion of the kernel subspace $\operatorname{ker}(\phi)=\{w \in V$ : $\phi(w)=0\}$ in $V$. Since $\phi \neq 0_{V^{*}}$, there exists some $v \in V$ so that $\phi(v) \neq 0$. Let $\alpha$, $\beta \in \mathbb{K}$ be any constants so that $\alpha \cdot \beta \cdot \phi(v)=1$. Define $Q_{1}^{\beta}: \mathbb{K} \rightarrow V$ so that for $\gamma \in \mathbb{K}, Q_{1}^{\beta}(\gamma)=\beta \cdot \gamma \cdot v$. Define $P_{1}^{\alpha}=\alpha \cdot \phi: V \rightarrow \mathbb{K}$. Then,

$$
P_{1}^{\alpha} \circ Q_{1}^{\beta}: \gamma \mapsto \alpha \cdot \phi(\beta \cdot \gamma \cdot v)=\alpha \cdot \beta \cdot \phi(v) \cdot \gamma=\gamma
$$

For any $w \in \operatorname{ker}(\phi),\left(P_{1}^{\alpha} \circ Q_{2}\right)(w)=\alpha \cdot \phi(w)=0$. Define $P_{2}=I d_{V}-Q_{1}^{\beta} \circ P_{1}^{\alpha}$, which is a map from $V$ to $\operatorname{ker}(\phi)$ : if $u \in V$, then

$$
\begin{aligned}
\left(\phi \circ P_{2}\right)(u) & =\left(\phi \circ I d_{V}-\phi \circ Q_{1}^{\beta} \circ P_{1}^{\alpha}\right)(u) \\
& =\phi(u)-\phi\left(Q_{1}^{\beta}(\alpha \cdot \phi(u))\right) \\
& =\phi(u)-\phi(\beta \cdot \alpha \cdot \phi(u) \cdot v) \\
& =\phi(u)-\alpha \cdot \beta \cdot \phi(v) \cdot \phi(u)=0 .
\end{aligned}
$$

Also, for $w \in \operatorname{ker}(\phi)$,

$$
\left(P_{2} \circ Q_{2}\right)(w)=\left(\left(I d_{V}-Q_{1}^{\beta} \circ P_{1}^{\alpha}\right) \circ Q_{2}\right)(w)=\left(Q_{2}-Q_{1}^{\beta} \circ 0_{(\operatorname{ker}(\phi))^{*}}\right)(w)=w
$$

so $P_{2} \circ Q_{2}=I d_{\operatorname{ker}(\phi)}$, and the claim follows from Lemma 1.72.
Given $V$ and $\phi$, the direct sum from the previous Lemma is generally not unique, nor are two such direct sums, depending on $v, \alpha, \beta$, even equivalent in general. However, in some later examples, there will be a canonical element $v \notin \operatorname{ker}(\phi)$, and in such a case, different choices of $\alpha, \beta$ give equivalent direct sums.

Lemma 1.95. Given $V, \phi \in V^{*}$, and $v \in V$ so that $\phi(v) \neq 0$, let $\alpha, \beta, \alpha^{\prime}$, $\beta^{\prime} \in \mathbb{K}$ be any constants so that $\alpha \cdot \beta \cdot \phi(v)=\alpha^{\prime} \cdot \beta^{\prime} \cdot \phi(v)=1$. Then the direct sum $V=\mathbb{K} \oplus \operatorname{ker}(\phi)$ constructed in the Proof of Lemma 1.94 is equivalent to the analogous direct sum with operators $Q_{1}^{\beta^{\prime}}: \gamma \mapsto \beta^{\prime} \cdot \gamma \cdot v, P_{1}^{\alpha^{\prime}}=\alpha^{\prime} \cdot \phi, Q_{2}$, and $P_{2}^{\prime}=I d_{V}-Q_{1}^{\beta^{\prime}} \circ P_{1}^{\alpha^{\prime}}$.

The following result will be used as a step in Theorem 4.40.
Theorem 1.96. Suppose $U=U_{1} \oplus U_{2}$ is a direct sum with projection and inclusion operators $P_{i}, Q_{i}$, and that there are vector spaces $V, V_{1}, V_{2}$, and maps $P_{1}^{\prime}: V \rightarrow V_{1}, Q_{2}^{\prime}: V_{2} \rightarrow V, H: U \rightarrow V, H_{1}: U_{1} \rightarrow V_{1}, H_{2}: U_{2} \rightarrow V_{2}$, such that $P_{1}^{\prime} \circ H=H_{1} \circ P_{1}, Q_{2}^{\prime} \circ H_{2}=H \circ Q_{2}$, and $P_{1}^{\prime} \circ Q_{2}^{\prime}=0_{\mathrm{Hom}\left(V_{2}, V_{1}\right)}$. Suppose further that $H$ and $H_{1}$ are invertible, and that $Q_{2}^{\prime}$ is a linear monomorphism. Then, there exist maps $Q_{1}^{\prime}: V_{1} \rightarrow V$ and $P_{2}^{\prime}: V \rightarrow V_{2}$ such that $V=V_{1} \oplus V_{2}$. Also, $H$ respects the direct sums, and $H_{2}$ is invertible.

Proof. Let $Q_{1}^{\prime}=H \circ Q_{1} \circ H_{1}^{-1}$. Then

$$
P_{1}^{\prime} \circ Q_{1}^{\prime}=P_{1}^{\prime} \circ H \circ Q_{1} \circ H_{1}^{-1}=H_{1} \circ P_{1} \circ Q_{1} \circ H_{1}^{-1}=I d_{V_{1}} .
$$

Let $P_{2}^{\prime}=H_{2} \circ P_{2} \circ H^{-1}$. Then

$$
\begin{aligned}
Q_{1}^{\prime} \circ P_{1}^{\prime}+Q_{2}^{\prime} \circ P_{2}^{\prime} & =H \circ Q_{1} \circ H_{1}^{-1} \circ P_{1}^{\prime}+Q_{2}^{\prime} \circ H_{2} \circ P_{2} \circ H^{-1} \\
& =H \circ Q_{1} \circ P_{1} \circ H^{-1}+H \circ Q_{2} \circ P_{2} \circ H^{-1} \\
& =I d_{V} \\
Q_{2}^{\prime} \circ P_{2}^{\prime} \circ Q_{2}^{\prime} & =\left(I d_{V}-Q_{1}^{\prime} \circ P_{1}^{\prime}\right) \circ Q_{2}^{\prime}=Q_{2}^{\prime},
\end{aligned}
$$

so $P_{2}^{\prime} \circ Q_{2}^{\prime}=I d_{V_{2}}$, by the monomorphism property (Definition 0.42 ), and this shows $V=V_{1} \oplus V_{2}$ by Lemma 1.72. $H$ respects the direct sums:

$$
\begin{aligned}
& P_{1}^{\prime} \circ H \circ Q_{2}=H_{1} \circ P_{1} \circ Q_{2}=0_{\operatorname{Hom}\left(U_{2}, V_{1}\right)} \\
& P_{2}^{\prime} \circ H \circ Q_{1}=H_{2} \circ P_{2} \circ H^{-1} \circ H \circ Q_{1}=0_{\operatorname{Hom}\left(U_{1}, V_{2}\right)}
\end{aligned}
$$

By Lemma 1.83, $P_{2}^{\prime} \circ H \circ Q_{2}=H_{2} \circ P_{2} \circ H^{-1} \circ H \circ Q_{2}=H_{2}$ has inverse $P_{2} \circ H^{-1} \circ$ $Q_{2}^{\prime}$.

ExErcise 1.97. Let $V=V_{1} \oplus V_{2} \oplus \cdots \oplus V_{\nu}$ be a direct sum, as in Definition 1.71, with projections $\left(P_{1}, P_{2}, \ldots, P_{\nu}\right)$ and inclusions $\left(Q_{1}, Q_{2}, \ldots, Q_{\nu}\right)$. For another vector space $W$ and additive functions $A: V \rightsquigarrow W, B: V \rightsquigarrow W$, the following are equivalent.
(1) For all $i=1, \ldots, \nu, A \circ Q_{i}=B \circ Q_{i}: V_{i} \rightarrow W$.
(2) $A=B$.

Hint. The additive property is used in steps (1.7), (1.8).

$$
\begin{align*}
A & =A \circ\left(Q_{1} \circ P_{1}+\cdots+Q_{\nu} \circ P_{\nu}\right) \\
& =\left(A \circ Q_{1}\right) \circ P_{1}+\cdots+\left(A \circ Q_{\nu}\right) \circ P_{\nu}  \tag{1.7}\\
& =\left(B \circ Q_{1}\right) \circ P_{1}+\cdots+\left(B \circ Q_{\nu}\right) \circ P_{\nu} \\
& =B \circ\left(Q_{1} \circ P_{1}+\cdots+Q_{\nu} \circ P_{\nu}\right)  \tag{1.8}\\
& =B .
\end{align*}
$$

EXERCISE 1.98. Let $V=V_{1} \oplus V_{2} \oplus \cdots \oplus V_{\nu}$ be a direct sum. Suppose there is some $i$ and some additive function $P^{\prime}: V \rightsquigarrow V_{i}$ so that $P^{\prime} \circ Q_{i}=I d_{V_{i}}$, and $P^{\prime} \circ Q_{I}=0_{\operatorname{Hom}\left(V_{I}, V_{i}\right)}$ for $I \neq i$. Then, $P^{\prime}=P_{i}$.

Hint. This is a special case of Exercise 1.97. $P^{\prime}$ is not assumed to be linear, but the above calculation uses the additive property to conclude that $P^{\prime}$ is linear because it equals a given linear map.

In the above sense, given all the operators $P_{1}, \ldots, Q_{\nu}$ in a direct sum, each individual map $P_{i}$ is unique. Exercise 1.100 states an analogous uniqueness result for $Q_{i}$.

ExERCISE 1.99. Let $V=V_{1} \oplus V_{2} \oplus \cdots \oplus V_{\nu}$ be a direct sum. For any set $W$ and any functions $A: W \rightsquigarrow V, B: W \rightsquigarrow V$, the following are equivalent.
(1) For all $i=1, \ldots, \nu, P_{i} \circ A=P_{i} \circ B: W \rightarrow V_{i}$.
(2) $A=B$.

Hint. The calculation is similar to that in Exercise 1.97, but does not assume any additive property.

EXERCISE 1.100. For $V=V_{1} \oplus V_{2} \oplus \cdots \oplus V_{\nu}$, suppose there is some $i$ and some function $Q^{\prime}: V_{i} \rightsquigarrow V$ so that $P_{i} \circ Q^{\prime}=I d_{V_{i}}$, and $P_{I} \circ Q^{\prime}=0_{\operatorname{Hom}\left(V_{i}, V_{I}\right)}$ for $I \neq i$. Then, $Q^{\prime}=Q_{i}$.

Hint. This is a special case of Exercise 1.99.

Exercise 1.101. Let $V=V_{1} \oplus V_{2}$ be a direct sum with projections $\left(P_{1}, P_{2}\right)$ and inclusions $\left(Q_{1}, Q_{2}\right)$, and let $A: V_{1} \rightarrow V_{2}$. Then the following operators $\left(P_{1}^{\prime}, P_{2}^{\prime}\right)$, $\left(Q_{1}^{\prime}, Q_{2}^{\prime}\right)$ also define a direct sum.

$$
\begin{aligned}
Q_{1}^{\prime} & =Q_{1}+Q_{2} \circ A: V_{1} \rightarrow V \\
Q_{2}^{\prime} & =Q_{2}: V_{2} \rightarrow V \\
P_{1}^{\prime} & =P_{1}: V \rightarrow V_{1} \\
P_{2}^{\prime} & =P_{2}-A \circ P_{1}: V \rightarrow V_{2} .
\end{aligned}
$$

This is equivalent to the original direct sum if and only if $A=0_{\mathrm{Hom}\left(V_{1}, V_{2}\right)}$.
Hint. The first equation from Definition 1.71 is:

$$
\begin{aligned}
Q_{1}^{\prime} \circ P_{1}^{\prime}+Q_{2}^{\prime} \circ P_{2}^{\prime} & =\left(Q_{1}+Q_{2} \circ A\right) \circ P_{1}+Q_{2} \circ\left(P_{2}-A \circ P_{1}\right) \\
& =Q_{1} \circ P_{1}+Q_{2} \circ A \circ P_{1}+Q_{2} \circ P_{2}-Q_{2} \circ A \circ P_{1} \\
& =I d_{V} .
\end{aligned}
$$

The remaining equations from Definition 1.71 (or Lemma 1.72) are also easy to check. If the direct sums are equivalent, then $0_{\operatorname{Hom}\left(V_{1}, V_{2}\right)}=P_{2} \circ Q_{1}^{\prime}=P_{2} \circ\left(Q_{1}+\right.$ $\left.Q_{2} \circ A\right)=A$, and conversely.

The direct sum $P_{i}^{\prime}, Q_{i}^{\prime}$ is the graph of $A$. In a certain sense, Exercise 1.101 has a converse: if a space $V$ decomposes in two ways as a direct sum, with the same inclusion $Q_{2}$, then the two direct sums are related using the graph construction, up to equivalence.

ExERCISE 1.102. Given $V, V_{1}, V_{2}$, suppose the pairs $\left(P_{1}, P_{2}\right)$ and $\left(Q_{1}, Q_{2}\right)$ define a direct sum $V=V_{1} \oplus V_{2}$, and the pairs $\left(P_{1}^{\prime}, P_{2}^{\prime}\right)$, $\left(Q_{1}^{\prime}, Q_{2}^{\prime}\right)$ also satisfy Definition 1.71. If $Q_{2}=Q_{2}^{\prime}$, then there exists a map $A: V_{1} \rightarrow V_{2}$, and there exist $\left(P_{1}^{\prime \prime}, P_{2}^{\prime \prime}\right),\left(Q_{1}^{\prime \prime}, Q_{2}^{\prime \prime}\right)$ which define a third direct sum, and which satisfy:

$$
\begin{aligned}
Q_{1}^{\prime \prime} & =Q_{1}+Q_{2} \circ A: V_{1} \rightarrow V \\
Q_{2}^{\prime \prime} & =Q_{2}: V_{2} \rightarrow V \\
P_{1}^{\prime \prime} & =P_{1}: V \rightarrow V_{1} \\
P_{2}^{\prime \prime} & =P_{2}-A \circ P_{1}: V \rightarrow V_{2} .
\end{aligned}
$$

This $\left(P_{1}^{\prime \prime}, P_{2}^{\prime \prime}\right),\left(Q_{1}^{\prime \prime}, Q_{2}^{\prime \prime}\right)$ direct sum is equivalent to the $\left(P_{1}^{\prime}, P_{2}^{\prime}\right),\left(Q_{1}^{\prime}, Q_{2}^{\prime}\right)$ direct sum.

Hint. Note that by Exercise 1.100, the hypothesis $Q_{2}=Q_{2}^{\prime}$ is equivalent to assuming that $Q_{2}^{\prime}$ satisfies $P_{2} \circ Q_{2}^{\prime}=I d_{V_{2}}$ and $P_{1} \circ Q_{2}^{\prime}=0_{\mathrm{Hom}\left(V_{2}, V_{1}\right)}$. Choosing $Q_{2}^{\prime \prime}=Q_{2}$ gives the identity $P_{1}^{\prime} \circ Q_{2}^{\prime \prime}=0_{\mathrm{Hom}\left(V_{2}, V_{1}\right)}$.

The above four equations are the properties defining a graph. The claimed existence follows from checking that the following choices have the claimed properties.

$$
\begin{aligned}
A & =-P_{2}^{\prime} \circ Q_{1}: V_{1} \rightarrow V_{2} \\
Q_{1}^{\prime \prime} & =Q_{1}^{\prime} \circ P_{1}^{\prime} \circ Q_{1}: V_{1} \rightarrow V \\
P_{2}^{\prime \prime} & =P_{2}^{\prime}: V \rightarrow V_{2}
\end{aligned}
$$

The equivalence of direct sums as in Definition 1.90 is verified by checking $P_{2}^{\prime} \circ Q_{1}^{\prime \prime}=$ $0_{\mathrm{Hom}\left(V_{1}, V_{2}\right)}$.

### 1.4. Idempotents and involutions

Definition 1.103. An element $P \in \operatorname{End}(V)$ is an idempotent means: $P \circ P=$ $P$.

Lemma 1.104. Given $V$ and $P_{1}, P_{2} \in \operatorname{End}(V)$, any three out of the following four properties $(1)-(4)$ imply the remaining fourth.
(1) $P_{1}$ is an idempotent.
(2) $P_{2}$ is an idempotent.
(3) $P_{1} \circ P_{2}+P_{2} \circ P_{1}=0_{\operatorname{End}(V)}$.
(4) $P_{1}+P_{2}$ is an idempotent.

Property (4) is equivalent to:
(5) There exists $P_{3} \in \operatorname{End}(V)$ such that $P_{3}$ is an idempotent and $P_{1}+P_{2}+P_{3}=$ $I d_{V}$.
If, further, either $\frac{1}{2} \in \mathbb{K}$ or $P_{1}+P_{2}=I d_{V}$, then $P_{1}, P_{2}, P_{3}$ satisfying properties (1) - (5) also satisfy:
(6) For distinct $i_{1}, i_{2} \in\{1,2,3\}, P_{i_{1}} \circ P_{i_{2}}=0_{\operatorname{End}(V)}$.

Conversely, if $P_{1}, P_{2}, P_{3} \in \operatorname{End}(V)$ satisfy (6) and $P_{1}+P_{2}+P_{3}=I d_{V}$, then $P_{1}, P_{2}, P_{3}$ are idempotents satisfying (1) - (5).

ExErcise 1.105. For $P \in \operatorname{End}(V)$, the following are equivalent.
(1) $P$ is an idempotent.
(2) For any $A \in \operatorname{End}(V), P+P \circ A-P \circ A \circ P$ is an idempotent.
(3) For any $A \in \operatorname{End}(V), P+A \circ P-P \circ A \circ P$ is an idempotent.

Exercise 1.106. If $P \in \operatorname{End}(V)$ is an idempotent, then the following are equivalent.
(1) $P^{\prime} \circ P=P \circ P^{\prime}$ for all idempotents $P^{\prime} \in \operatorname{End}(V)$.
(2) $P=0_{\operatorname{End}(V)}$ or $P=I d_{V}$.

Hint. This follows from Exercise 1.105 and Claim 0.51.
Example 1.107. An idempotent $P$ defines a direct sum structure as follows. Let $V_{1}=P(V)$, the subspace of $V$ which is the image of $P$. Define $Q_{1}: V_{1} \rightarrow V$ to be the subspace inclusion map, and define $P_{1}: V \rightarrow V_{1}$ by restricting the target of $P: V \rightarrow V$ to get $P_{1}: V \rightarrow V_{1}$ with $P_{1}(v)=P(v)$ for all $v \in V$. Then $P=Q_{1} \circ P_{1}: V \rightarrow V$ by construction. The map $I d_{V}-P$ is also an idempotent (this is a special case of Lemma 1.104), so proceeding analogously, define $V_{2}=\left(I d_{V}-P\right)(V)$, the image of the linear map $I d_{V}-P: V \rightarrow V$. Again, let $Q_{2}: V_{2} \rightarrow V$ be the subspace inclusion, and define $P_{2}=I d_{V}-P$, with its target space restricted to $V_{2}$, so that $Q_{2} \circ P_{2}=I d_{V}-P$ by construction, and $Q_{1} \circ P_{1}+Q_{2} \circ P_{2}=P+\left(I d_{V}-P\right)=I d_{V}$. To show $V=V_{1} \oplus V_{2}$, it remains only to check that these maps satisfy the two remaining equations from Lemma 1.72. For $v_{1} \in V_{1}, Q_{1}\left(v_{1}\right)=v_{1}=P\left(w_{1}\right)$ for some $w_{1} \in V$, so $\left(P_{1} \circ Q_{1}\right)\left(v_{1}\right)=$ $P_{1}\left(P\left(w_{1}\right)\right)=P\left(P\left(w_{1}\right)\right)=P\left(w_{1}\right)=v_{1}$. Similarly, for $Q_{2}\left(v_{2}\right)=v_{2}=\left(I d_{V}-P\right)\left(w_{2}\right)$, $\left(P_{2} \circ Q_{2}\right)\left(v_{2}\right)=\left(I d_{V}-P\right)\left(\left(I d_{V}-P\right)\left(w_{2}\right)\right)=\left(I d_{V}-P\right)\left(w_{2}\right)=v_{2}$. This construction of the direct sum $V=V_{1} \oplus V_{2}$ is canonical up to re-ordering.

The statement of Lemma 1.79 in the special case of Example 1.107 is that the image of $I d_{V}-P$ is the kernel of $P$, and the image of $P$ is the kernel of $I d_{V}-P$.

Example 1.108. Given any direct sum $V=U_{1} \oplus U_{2}$ as in Definition 1.71 with projections $\left(P_{1}, P_{2}\right)$ and inclusions $\left(Q_{1}, Q_{2}\right)$, the composite $Q_{1} \circ P_{1}: V \rightarrow V$ is an idempotent, and so is $I d_{V}-Q_{1} \circ P_{1}=Q_{2} \circ P_{2}$. This is a converse to the construction of Example 1.107; any direct sum canonically defines an unordered pair of two idempotents. For $P=Q_{1} \circ P_{1}$, the direct sum $V=V_{1} \oplus V_{2}$ constructed in Example 1.107 is equivalent, as in Definition 1.90, to the original direct sum.

Lemma 1.109. Given idempotents $P: V \rightarrow V, P^{\prime}: U \rightarrow U$ defining direct sums $V_{1} \oplus V_{2}$ and $U_{1} \oplus U_{2}$ as in Example 1.107, and a map $H: U \rightarrow V$, the following are equivalent.
(1) $H$ respects the direct sums (as in Definition 1.82).
(2) $H \circ P^{\prime}=P \circ H$.

Definition 1.110. An element $K \in \operatorname{End}(V)$ is an involution means: $K \circ K=$ $I d_{V}$.

Lemma 1.111. If $\frac{1}{2} \in \mathbb{K}$ and $K \in \operatorname{End}(V)$, then the following are equivalent.
(1) $K \in \operatorname{End}(V)$ is an involution.
(2) $P=\frac{1}{2} \cdot\left(I d_{V}+K\right)$ is an idempotent.
(3) $I d_{V}-P=\frac{1}{2} \cdot\left(I d_{V}-K\right)$ is an idempotent.

Lemma 1.112. For an involution $K \in \operatorname{End}(V)$, let $V_{1}=\{v \in V: K(v)=v\}$, and $V_{2}=\{v \in V: K(v)=-v\}$. If $\frac{1}{2} \in \mathbb{K}$, then $V=V_{1} \oplus V_{2}$, with $Q_{i}$ the subspace inclusion maps, and projections:

$$
\begin{align*}
P_{1} & =\frac{1}{2} \cdot\left(I d_{V}+K\right)  \tag{1.9}\\
P_{2} & =\frac{1}{2} \cdot\left(I d_{V}-K\right) \tag{1.10}
\end{align*}
$$

Proof. This can be proved directly, but also follows from the construction of Example 1.107. It is easy to check that $V_{1}$ is a subspace of $V$, equal to the image of the idempotent $P$ from Lemma 1.111 and that $V_{2}$ is equal to the image of $I d_{V}-P$. The composites $Q_{1} \circ P_{1}, Q_{2} \circ P_{2} \in \operatorname{End}(V)$ are also given by the formulas $\frac{1}{2} \cdot\left(I d_{V} \pm K\right)$.

Notation 1.113. We refer to the construction of $V=V_{1} \oplus V_{2}$ as in Lemma 1.112 as the direct sum produced by the involution $K$. The subspaces $V_{1}, V_{2}$ and maps $P_{1}, P_{2}$ in (1.9), (1.10) are canonical, but Lemma 1.112 made a choice of order in the direct sum $V=V_{1} \oplus V_{2}$. With this ordering convention, the involution $-K$ produces the direct sum $V=V_{2} \oplus V_{1}$ as in Notation 1.87. For the projection maps defined by formulas (1.9), (1.10), the double arrow will appear in diagrams, $P_{1}: V \rightarrow V_{1}, P_{2}: V \rightarrow V_{2}$, and the same arrow for composites of such projections. For the subspace inclusion maps as in Lemma 1.112, the hook arrow will appear: $Q_{1}: V_{1} \hookrightarrow V$ for the fixed point subspace of $K$, and $Q_{2}: V_{2} \hookrightarrow V$ for the fixed point subspace of $-K$, and similarly for composites of such inclusions.

Example 1.114. Given any direct sum $V=U_{1} \oplus U_{2}$ as in Definition 1.71 with projections $\left(P_{1}, P_{2}\right)$ and inclusions $\left(Q_{1}, Q_{2}\right)$, the map

$$
Q_{1} \circ P_{1}-Q_{2} \circ P_{2}=I d_{V}-2 \cdot Q_{2} \circ P_{2}: V \rightarrow V
$$

is an involution, and it respects the direct sums $U_{1} \oplus U_{2} \rightarrow U_{1} \oplus U_{2}$. If $\frac{1}{2} \in \mathbb{K}$, then the direct sum produced by this involution, $V=V_{1} \oplus V_{2}$ as in Lemma 1.112, is
equivalent, as in Definition 1.90, to the original direct sum. As in Lemma 1.83 and Lemma 1.93, there are invertible maps $U_{i} \rightarrow V_{i}$. If the direct sum operators $Q_{i}, P_{i}$ were defined by some involution $K$ as in Lemma 1.112, then $Q_{1} \circ P_{1}-Q_{2} \circ P_{2}=K$.

Lemma 1.115. For an idempotent $P: V \rightarrow V$, let $V=V_{1} \oplus V_{2}$ be the direct sum from Example 1.107. The maps $K=2 \cdot P-I d_{V}: V \rightarrow V$ and $I d_{V}-2 \cdot P=-K$ are involutions, and both $K$ and $-K$ respect the direct sums $V_{1} \oplus V_{2} \rightarrow V_{1} \oplus V_{2}$. If $\frac{1}{2} \in \mathbb{K}$, then the direct sum from Lemma 1.112 produced by $K$ is the same as $V=V_{1} \oplus V_{2}$.

Proof. The claim that $K$ and $-K$ respect the direct sums is a special case of Lemma 1.109.

Example 1.116. For any space $V$, the switching map $s: V \otimes V \rightarrow V \otimes V$ from Example 1.28 is an involution. For $\frac{1}{2} \in \mathbb{K}, s$ produces a direct sum on $V \otimes V$, denoted:

$$
V \otimes V=S^{2} V \oplus \Lambda^{2} V
$$

with projections $P_{1}=\frac{1}{2} \cdot\left(I d_{V \otimes V}+s\right): V \otimes V \rightarrow S^{2} V$ and $P_{2}=\frac{1}{2} \cdot\left(I d_{V \otimes V}-s\right)$ : $V \otimes V \rightarrow \Lambda^{2} V$ and corresponding subspace inclusions $Q_{1}, Q_{2}$.

Theorem 1.117. Given $\frac{1}{2} \in \mathbb{K}$, an involution $K \in \operatorname{End}(V)$, let $V=V_{1} \oplus V_{2}$ be the direct sum produced by $K$. For any $\phi \in V^{*}$, if $\phi \neq 0_{V^{*}}$ and $\phi \circ K=\phi$, then there is a direct sum $V=\mathbb{K} \oplus \operatorname{ker}\left(\phi \circ Q_{1}\right) \oplus V_{2}$.

Proof. Let $\left(P_{1}, P_{2}\right)$ and $\left(Q_{1}, Q_{2}\right)$ be the operators as in Lemma 1.112; the inclusion $Q_{1}$ appears in the claim. From $\phi \neq 0_{V^{*}}$, there is some $w \in V$ so that $\phi(w) \neq 0$. Let $v=\frac{1}{2} \cdot(w+K(w)) \in V_{1}$. Then

$$
\left(\phi \circ Q_{1}\right)(v)=\phi(v)=\phi\left(\frac{1}{2} \cdot(w+K(w))\right)=\frac{1}{2} \cdot \phi(w)+\frac{1}{2} \cdot \phi(K(w))=\phi(w) \neq 0
$$

So $\phi \circ Q_{1} \neq 0_{V_{1}^{*}}$ and Lemma 1.94 applies to get a direct sum $V_{1}=\mathbb{K} \oplus \operatorname{ker}\left(\phi \circ Q_{1}\right)$, depending on parameters $\alpha, \beta \in \mathbb{K}$ such that $\alpha \cdot \beta \cdot \phi(w)=1$. The inclusions are $Q_{3}^{\beta}: \mathbb{K} \rightarrow V_{1}: \gamma \mapsto \beta \cdot \gamma \cdot v$, and the subspace inclusion $Q_{4}: \operatorname{ker}\left(\phi \circ Q_{1}\right) \rightarrow V_{1}$. The projections are $P_{3}^{\alpha}=\alpha \cdot \phi \circ Q_{1}: V_{1} \rightarrow \mathbb{K}, P_{4}=I d_{V_{1}}-Q_{3}^{\beta} \circ P_{3}^{\alpha}: V_{1} \rightarrow \operatorname{ker}\left(\phi \circ Q_{1}\right)$. Theorem 1.73 applies to get the claimed direct sum. In particular, the first inclusion is $Q_{1} \circ Q_{3}^{\beta}: \mathbb{K} \rightarrow V$, the second is a subspace inclusion $Q_{1} \circ Q_{4}: \operatorname{ker}\left(\phi \circ Q_{1}\right) \rightarrow V$, and the third is the subspace inclusion not depending on $\phi, Q_{2}: V_{2} \hookrightarrow V$. The three projections are $\alpha \cdot \phi \circ Q_{1} \circ P_{1}: V \rightarrow \mathbb{K},\left(I d_{V_{1}}-Q_{3}^{\beta} \circ\left(\alpha \cdot \phi \circ Q_{1}\right)\right) \circ P_{1}: V \rightarrow \operatorname{ker}\left(\phi \circ Q_{1}\right)$, and $P_{2}: V \rightarrow V_{2}$.

For $K$ and $\phi$ as in Theorem 1.117, any element $u \in V$ can be written in the following way as a sum of terms that do not depend on $\alpha$ or $\beta$ :
(1.11) $u=I d_{V}(u)$

$$
\begin{aligned}
= & \left(Q_{1} \circ Q_{3}^{\beta} \circ\left(\alpha \cdot \phi \circ Q_{1} \circ P_{1}\right)\right. \\
& \left.\quad+Q_{1} \circ Q_{4} \circ\left(I d_{V_{1}}-Q_{3}^{\beta} \circ\left(\alpha \cdot \phi \circ Q_{1}\right)\right) \circ P_{1}+Q_{2} \circ P_{2}\right)(u) \\
= & \frac{\phi(u)}{2 \phi(w)}(w+K(w))+\left(\frac{1}{2}(u+K(u))-\frac{\phi(u)}{2 \phi(w)}(w+K(w))\right)+\frac{1}{2}(u-K(u))
\end{aligned}
$$

The second and third terms are in the kernel of $\phi$; the third term is the projection of $u$ onto the -1 eigenspace of $K$, not depending on $\phi$ or $w$. The first two terms
are both in the +1 eigenspace of $K$, and they both depend on $\phi$ and on $v=$ $\frac{1}{2} \cdot(w+K(w))$.

Lemma 1.118. Given $\frac{1}{2} \in \mathbb{K}$ and two involutions $K: V \rightarrow V$ and $K^{\prime}: U \rightarrow U$, which produce direct sums $V_{1} \oplus V_{2}, U_{1} \oplus U_{2}$ as in Lemma 1.112, a map $H: U \rightarrow V$ respects the direct sums $U_{1} \oplus U_{2} \rightarrow V_{1} \oplus V_{2}$ if and only if $K \circ H=H \circ K^{\prime}$.

Lemma 1.119. Given $\frac{1}{2} \in \mathbb{K}$ and two involutions $K: V \rightarrow V$ and $K^{\prime}: U \rightarrow U$, which produce direct sums $V_{1} \oplus V_{2}, U_{1} \oplus U_{2}$ as in Lemma 1.112, a map $H: U \rightarrow V$ respects the direct sums $U_{1} \oplus U_{2} \rightarrow V_{2} \oplus V_{1}$ if and only if $K \circ H=-H \circ K^{\prime}$.

Proof. Note the order of the spaces $V_{2} \oplus V_{1}$ is different from that appearing in Lemma 1.118, so the notation refers to the identities $Q_{1} \circ P_{1} \circ H=H \circ Q_{2}^{\prime} \circ P_{2}^{\prime}$ and $Q_{2} \circ P_{2} \circ H=H \circ Q_{1}^{\prime} \circ P_{1}^{\prime}$. The claims can be checked directly, but also follow from applying Lemma 1.118 to the involutions $K$ and $-K^{\prime}$.

Lemma 1.120. Given $V$ and a pair of involutions on $V, K_{1}$ and $K_{2}$, if $\frac{1}{2} \in \mathbb{K}$, then the following are equivalent.
(1) The involutions commute, i.e., $K_{1} \circ K_{2}=K_{2} \circ K_{1}$.
(2) The composite $K_{1} \circ K_{2}$ is an involution.
(3) $K_{2}$ respects the direct sum $V=V_{1} \oplus V_{2}$ produced by $K_{1}$.
(4) $K_{1}$ respects the direct sum $V=V_{3} \oplus V_{4}$ produced by $K_{2}$.

Proof. The equivalence (1) $\Longleftrightarrow(2)$ is elementary and does not require $\frac{1}{2} \in \mathbb{K}$. The direct sums in (3), (4) are as in Lemma 1.112. The equivalences $(1) \Longleftrightarrow(3)$ and $(1) \Longleftrightarrow(4)$ are special cases of Lemma 1.118.

In statement (3) of Lemma $1.120, K_{2}$ induces an involution on both $V_{1}$ and $V_{2}$ as in Definition 1.82 and Lemma 1.83, and similarly for $K_{1}$ in statement (4).

Given $\frac{1}{2} \in \mathbb{K}$, and $V$ with commuting involutions $K_{1}, K_{2}$ as in Lemma 1.120 and Lemma 1.121, and corresponding direct sums $V=V_{1} \oplus V_{2}, V=V_{3} \oplus V_{4}$, respectively, as in Lemma 1.120, let $V=V_{5} \oplus V_{6}$ be the direct sum produced by the involution $K_{1} \circ K_{2}$.

Lemma 1.121. Given $V$, subspaces $V_{1}, \ldots, V_{5}$ as above, and commuting involutions $K_{1}, K_{2} \in \operatorname{End}(V)$, for $v \in V$, any pair of two of the following three statements implies the remaining one:
(1) $v=K_{1}(v) \in V_{1}$.
(2) $v=K_{2}(v) \in V_{3}$.
(3) $v=\left(K_{1} \circ K_{2}\right)(v) \in V_{5}$.

It follows from Lemma 1.121 that these subspaces of $V$ are equal:

$$
\begin{equation*}
V_{1} \cap V_{3}=V_{1} \cap V_{5}=V_{3} \cap V_{5}=V_{1} \cap V_{3} \cap V_{5} . \tag{1.12}
\end{equation*}
$$

Let $\left(P_{5}, P_{6}\right),\left(Q_{5}, Q_{6}\right)$ denote the projections and inclusions for the above direct sum $V=V_{5} \oplus V_{6}$ produced by $K_{1} \circ K_{2}$. Since $K_{1} \circ Q_{5}=K_{2} \circ Q_{5}$, the maps induced by $K_{1}$ and $K_{2}$ are equal:

$$
\begin{equation*}
P_{5} \circ K_{1} \circ Q_{5}=P_{5} \circ K_{2} \circ Q_{5}: V_{5} \rightarrow V_{5} \tag{1.13}
\end{equation*}
$$

this map is a canonical involution on $V_{5}$, producing a direct sum $V_{5}=V_{5}^{\prime} \oplus V_{5}^{\prime \prime}$ with projection $P_{5}^{\prime}: V_{5} \rightarrow V_{5}^{\prime}$ from (1.9). Similarly, there is an involution induced by $K_{1}$ or $K_{1} \circ K_{2}$ on $V_{3}$, producing $V_{3}=V_{3}^{\prime} \oplus V_{3}^{\prime \prime}$, and there is another involution
induced by $K_{2}$ or $K_{1} \circ K_{2}$ on $V_{1}$, producing $V_{1}=V_{1}^{\prime} \oplus V_{1}^{\prime \prime}$. On the set $V_{6}$, the induced involutions are opposite:

$$
\begin{equation*}
P_{6} \circ K_{1} \circ Q_{6}=-P_{6} \circ K_{2} \circ Q_{6}: V_{6} \rightarrow V_{6} \tag{1.14}
\end{equation*}
$$

if one produces a direct sum $V_{6}=V_{6}^{\prime} \oplus V_{6}^{\prime \prime}$, the other produces $V_{6}=V_{6}^{\prime \prime} \oplus V_{6}^{\prime}$. Similarly, there are opposite induced involutions on $V_{2}$ and $V_{4}$.

Theorem 1.122. Given $\frac{1}{2} \in \mathbb{K}$, and commuting involutions on $V$ with the above notation,

$$
V_{5}^{\prime}=V_{3}^{\prime}=V_{1}^{\prime}=V_{1} \cap V_{3} \cap V_{5}
$$

The composite projections are all equal:

$$
P_{5}^{\prime} \circ P_{5}=P_{3}^{\prime} \circ P_{3}=P_{1}^{\prime} \circ P_{1}: V \rightarrow V_{1} \cap V_{3} \cap V_{5}
$$

Also, $V_{5}^{\prime \prime}=V_{2} \cap V_{4}, V_{3}^{\prime \prime}=V_{2} \cap V_{6}$, and $V_{1}^{\prime \prime}=V_{4} \cap V_{6}$.
Proof. $V_{5}^{\prime}$ is the set of fixed points $v \in V_{5}$ of the involution $P_{5} \circ K_{1} \circ Q_{5}$. Denote the operators from Lemma $1.112 P_{5}^{\prime}, Q_{5}^{\prime}$, so

$$
Q_{5}^{\prime} \circ P_{5}^{\prime}=\frac{1}{2} \cdot\left(I d_{V_{5}}+P_{5} \circ K_{1} \circ Q_{5}\right)
$$

To establish the first claim, it is enough to show $V_{5}^{\prime}=V_{1} \cap V_{3}$; the claims $V_{3}^{\prime}=V_{1} \cap V_{5}$ and $V_{1}^{\prime}=V_{3} \cap V_{5}$ are similar, and then (1.12) applies. To show $V_{5}^{\prime} \subseteq V_{1}$, use the fact that $K_{1}$ commutes with $Q_{5} \circ P_{5}=\frac{1}{2} \cdot\left(I d_{V}+K_{1} \circ K_{2}\right)$; if $v \in V_{5}^{\prime} \subseteq V_{5}$, then

$$
v=Q_{5}(v)=\left(P_{5} \circ K_{1} \circ Q_{5}\right)(v)=Q_{5}\left(\left(P_{5} \circ K_{1} \circ Q_{5}\right)(v)\right)=K_{1}\left(Q_{5}(v)\right),
$$

so $v \in V_{1}$. Showing $V_{5}^{\prime} \subseteq V_{3}$ is similar, so $V_{5}^{\prime} \subseteq V_{1} \cap V_{3}$.
Another argument would be to consider the subspace $V_{5}^{\prime}$ as the image of $Q_{5} \circ$ $Q_{5}^{\prime} \circ P_{5}^{\prime} \circ P_{5}$ in $V$. Then

$$
\begin{align*}
Q_{5} \circ Q_{5}^{\prime} \circ P_{5}^{\prime} \circ P_{5} & =Q_{5} \circ \frac{1}{2} \cdot\left(I d_{V_{5}}+P_{5} \circ K_{1} \circ Q_{5}\right) \circ P_{5} \\
& =\frac{1}{2} \cdot Q_{5} \circ P_{5}+\frac{1}{2} \cdot K_{1} \circ Q_{5} \circ P_{5} \\
& =Q_{1} \circ P_{1} \circ Q_{5} \circ P_{5}, \tag{1.15}
\end{align*}
$$

which shows $V_{5}^{\prime}$ is contained in $V_{1}$, the image of $Q_{1}$ in $V$.
Conversely, if $v \in V_{1} \cap V_{3}$, then $v=K_{1}(v)=Q_{5}(v) \in V_{5}$ (Lemma 1.121) and $\left(P_{5} \circ K_{1} \circ Q_{5}\right)(v)=\left(P_{5} \circ Q_{5}\right)(v)=v \in V_{5}^{\prime}$.

The equality of the composites of projections follows from using the commutativity of the involutions to get $Q_{1} \circ P_{1} \circ Q_{5} \circ P_{5}=Q_{5} \circ P_{5} \circ Q_{1} \circ P_{1}$, and then (1.15) implies $Q_{5} \circ Q_{5}^{\prime} \circ P_{5}^{\prime} \circ P_{5}=Q_{1} \circ Q_{1}^{\prime} \circ P_{1}^{\prime} \circ P_{1}$.

The last claim of the Theorem follows from similar calculations. However, the three subspaces are in general not equal to each other.

The projection $P_{5}: V \rightarrow V_{5}$ satisfies $P_{5} \circ K_{1}=\left(P_{5} \circ K_{1} \circ Q_{5}\right) \circ P_{5}$, so Lemma 1.118 applies: $P_{5}$ respects the direct sums $V_{1} \oplus V_{2} \rightarrow V_{5}^{\prime} \oplus V_{5}^{\prime \prime}$ and the map $V_{1} \rightarrow V_{5}^{\prime}$ induced by $P_{5}$ is $P_{5}^{\prime} \circ P_{5} \circ Q_{1}$. By Theorem 1.122,

$$
\begin{equation*}
P_{5}^{\prime} \circ P_{5} \circ Q_{1}=P_{1}^{\prime} \circ P_{1} \circ Q_{1}=P_{1}^{\prime}: V_{1} \rightarrow V_{1}^{\prime}=V_{5}^{\prime} \tag{1.16}
\end{equation*}
$$

This gives an alternate construction of $P_{1}^{\prime}$ as a map induced by $P_{5}$, or similarly, any $P_{i}^{\prime}$ is equal to a map induced by $P_{I}$ for any distinct $i=1,3,5, I=1,3,5$.

THEOREM 1.123. Given $\frac{1}{2} \in \mathbb{K}$, suppose $K_{V}^{1}, K_{V}^{2}$ are commuting involutions on $V$ as in Theorem 1.122. Similarly, let $K_{U}^{1}, K_{U}^{2}$ be commuting involutions on $U$, with corresponding notation for the direct sums: $U=U_{1} \oplus U_{2}, U=U_{3} \oplus U_{4}$, etc. If a map $H: U \rightarrow V$ satisfies $H \circ K_{U}^{1}=K_{V}^{1} \circ H$ and $H \circ K_{U}^{2}=K_{V}^{2} \circ H$, then $H$ respects the corresponding direct sums $U_{1} \oplus U_{2} \rightarrow V_{1} \oplus V_{2}$ and $U_{3} \oplus U_{4} \rightarrow V_{3} \oplus V_{4}$. Further, the induced map $P_{V}^{1} \circ H \circ Q_{U}^{1}: U_{1} \rightarrow V_{1}$ respects the direct sums $U_{1}^{\prime} \oplus U_{1}^{\prime \prime} \rightarrow V_{1}^{\prime} \oplus V_{1}^{\prime \prime}$ and similarly for the maps $U_{3} \rightarrow V_{3}, U_{5} \rightarrow V_{5}$ induced by $H$. The induced map $U_{1}^{\prime} \rightarrow V_{1}^{\prime}$ is equal to the map $U_{3}^{\prime} \rightarrow V_{3}^{\prime}$ induced by $P_{V}^{3} \circ H \circ Q_{U}^{3}: U_{3} \rightarrow V_{3}$.

Proof. The fact that $H$ respects each pair of direct sums is Lemma 1.118. The subspace $U_{1}$ has a canonical involution $P_{U}^{1} \circ K_{U}^{2} \circ Q_{U}^{1}$, and since $K_{U}^{1}, K_{U}^{2}$ commute, $K_{U}^{2}$ also commutes with $Q_{U}^{1} \circ P_{U}^{1}=\frac{1}{2} \cdot\left(I d_{U}+K_{U}^{1}\right)$. The map induced by $H, P_{V}^{1} \circ H \circ Q_{U}^{1}: U_{1} \rightarrow V_{1}$, satisfies:

$$
\begin{aligned}
\left(P_{V}^{1} \circ H \circ Q_{U}^{1}\right) \circ\left(P_{U}^{1} \circ K_{U}^{2} \circ Q_{U}^{1}\right) & =P_{V}^{1} \circ H \circ K_{U}^{2} \circ Q_{U}^{1} \circ P_{U}^{1} \circ Q_{U}^{1} \\
& =P_{V}^{1} \circ K_{V}^{2} \circ H \circ Q_{U}^{1} \\
& =\left(P_{V}^{1} \circ K_{V}^{2} \circ Q_{V}^{1}\right) \circ\left(P_{V}^{1} \circ H \circ Q_{U}^{1}\right) .
\end{aligned}
$$

It follows from Lemma 1.118 again that $P_{V}^{1} \circ H \circ Q_{U}^{1}$ respects the direct sums as claimed. The induced map is $P_{V}^{1 /} \circ\left(P_{V}^{1} \circ H \circ Q_{U}^{1}\right) \circ Q_{U}^{1 \prime}: U_{1}^{\prime} \rightarrow V_{1}^{\prime}$.

The last claim of the Theorem is that this induced map is equal to the map $P_{V}^{3 \prime} \circ\left(P_{V}^{3} \circ H \circ Q_{U}^{3}\right) \circ Q_{U}^{3 \prime}: U_{3}^{\prime} \rightarrow V_{3}^{\prime}$. The claim follows from the idea that the induced maps are restrictions of $H$ to the same subspace $U_{1}^{\prime}=U_{3}^{\prime}=U_{1} \cap U_{3}$, by Theorem 1.122. More specifically, the subspace inclusions are equal: $Q_{U}^{3} \circ Q_{U}^{3 \prime}=Q_{U}^{1} \circ Q_{U}^{1 \prime}$ : $U_{1} \cap U_{3} \hookrightarrow U$, and the composites of projections are equal: $P_{V}^{1 \prime} \circ P_{V}^{1}=P_{V}^{3 /} \circ P_{V}^{3}$.

Example 1.124. Given $\frac{1}{2} \in \mathbb{K}$, suppose $K_{1}$ and $K_{2}$ are commuting involutions on $V$ as in Theorem 1.122, and suppose $H$ is another involution on $V$ so that $K_{1} \circ H=H \circ K_{2}$. The three involutions $K_{1}, K_{2}, K_{1} \circ K_{2}$ produce direct sums $V=V_{1} \oplus V_{2}, V_{3} \oplus V_{4}$, and $V_{5} \oplus V_{6}$. Similarly, because $K_{1} \circ K_{2}$ commutes with $H$, the three involutions $K_{1} \circ K_{2}, H$, and $K_{1} \circ K_{2} \circ H$ produce corresponding direct sums $V=V_{5} \oplus V_{6}, V_{7} \oplus V_{8}$, and $V_{9} \oplus V_{10}$. As in (1.13), there are induced involutions on $V_{5}, P_{5} \circ K_{1} \circ Q_{5}=P_{5} \circ K_{2} \circ Q_{5}$ and $P_{5} \circ H \circ Q_{5}=P_{5} \circ K_{1} \circ K_{2} \circ H \circ Q_{5}$. These two involutions commute: for $v=Q_{5}(v)=\left(K_{1} \circ K_{2}\right)(v) \in V_{5}, v$ satisfies $K_{1}(v)=K_{2}(v)$ and

$$
\begin{aligned}
& \left(P_{5} \circ K_{1} \circ Q_{5} \circ P_{5} \circ H \circ Q_{5}\right)(v)=\left(P_{5} \circ K_{1} \circ H\right)(v)=\left(P_{5} \circ H \circ K_{2}\right)(v), \\
& \left(P_{5} \circ H \circ Q_{5} \circ P_{5} \circ K_{1} \circ Q_{5}\right)(v)=\left(P_{5} \circ H \circ K_{1}\right)(v) .
\end{aligned}
$$

By Lemma 1.120, their product

$$
\left(P_{5} \circ K_{1} \circ Q_{5}\right) \circ\left(P_{5} \circ H \circ Q_{5}\right)=P_{5} \circ K_{1} \circ H \circ Q_{5}=P_{5} \circ K_{2} \circ H \circ Q_{5}
$$

is also an involution on $V_{5}$ (although in general, $K_{1} \circ H$ and $K_{2} \circ H$ need not be involutions). So, Theorem 1.122 applies to these three commuting involutions on $V_{5}$, with $P_{5} \circ K_{1} \circ Q_{5}$ producing a direct sum $V_{5}=V_{5}^{\prime} \oplus V_{5}^{\prime \prime}$, where $V_{5}^{\prime}=V_{1} \cap V_{3} \cap V_{5}$ is the fixed point subspace of $P_{5} \circ K_{1} \circ Q_{5}$. Similarly, $V_{5} \cap V_{7} \cap V_{9}$ is the fixed point subspace of $P_{5} \circ H \circ Q_{5}$, and denoting by $V_{11}$ the fixed point subspace of $P_{5} \circ K_{1} \circ H \circ Q_{5}$, the three fixed point subspaces have the following intersection:

$$
\begin{aligned}
\left(V_{1} \cap V_{3} \cap V_{5}\right) \cap\left(V_{5} \cap V_{7} \cap V_{9}\right) \cap V_{11} & =\left(V_{1} \cap V_{3}\right) \cap\left(V_{5} \cap V_{7}\right) \\
& =\left(V_{1} \cap V_{3} \cap V_{5}\right) \cap V_{7}=V_{1} \cap V_{3} \cap V_{7} \\
& =\left\{v \in V: v=K_{1}(v)=K_{2}(v)=H(v)\right\} .
\end{aligned}
$$

The projections from Theorem 1.122 appear in the following commutative diagram.


Example 1.125. The construction in Example 1.124 also works under the hypothesis that $H$ commutes with both $K_{1}$ and $K_{2}\left(\right.$ instead of $\left.K_{1} \circ H=H \circ K_{2}\right)$.

ExERCISE 1.126. For involutions on $V$ as in Example 1.124 satisfying $K_{1} \circ K_{2}=$ $K_{2} \circ K_{1}$ and $K_{1} \circ H=H \circ K_{2}$, the set

$$
\left\{I d_{V}, K_{1}, K_{2}, K_{1} \circ K_{2}, H, K_{1} \circ H, K_{2} \circ H, K_{1} \circ K_{2} \circ H\right\}
$$

is the image of a representation $D_{4} \rightsquigarrow \operatorname{End}(V)$, where $D_{4}$ is the eight-element dihedral group.

REmARK 1.127. An example of a vector space over $\mathbb{K}=\mathbb{Q}$ admitting three involutions satisfying the relations of Example 1.124 is $\mathbb{Q}(\sqrt{-1}, \sqrt[4]{2})$, as considered by [Cox] (Example 7.3.4), along with diagrams analogous to the above diagram.

THEOREM 1.128. Given $V$, the following statements (1) to (7) are equivalent, and any implies (8). Further, if $\frac{1}{2} \in \mathbb{K}$, then all eight statements are equivalent.
(1) $V$ admits a direct sum of the form $V=U \oplus U$.
(2) $V=U_{1} \oplus U_{2}$ and there exist invertible maps $A_{1}: U_{3} \rightarrow U_{1}$ and $A_{2}: U_{3} \rightarrow$ $U_{2}$.
(3) $V=U^{\prime} \oplus U^{\prime \prime}$ and there exists an invertible map $A: U^{\prime \prime} \rightarrow U^{\prime}$.
(4) $V=U^{\prime} \oplus U^{\prime \prime}$ and there exists an involution $K \in \operatorname{End}(V)$ that respects the direct sums $U^{\prime} \oplus U^{\prime \prime} \rightarrow U^{\prime \prime} \oplus U^{\prime}$.
(5) $V$ admits an idempotent $P \in \operatorname{End}(V)$ and an involution $K \in \operatorname{End}(V)$ such that $P \circ K=K \circ\left(I d_{V}-P\right)$.
(6) $V=U^{\prime} \oplus U^{\prime \prime}$ and there exists an invertible $H \in \operatorname{End}(V)$ that respects the direct sums $U^{\prime} \oplus U^{\prime \prime} \rightarrow U^{\prime \prime} \oplus U^{\prime}$.
(7) $V$ admits an idempotent $P \in \operatorname{End}(V)$ and an invertible map $H \in \operatorname{End}(V)$ such that $P \circ H=H \circ\left(I d_{V}-P\right)$.
(8) $V$ admits anticommuting involutions $K_{1}, K_{2}$ (i.e., $K_{1} \circ K_{2}=-K_{2} \circ K_{1}$ ).

Proof. The implication (1) $\Longrightarrow(2)$ is canonical: let $U_{1}=U_{2}=U_{3}=U$, and $A_{1}=A_{2}=I d_{U}$.

The implication (2) $\Longrightarrow(1)$ is canonical. Given $V=U_{1} \oplus U_{2}$ with projections $\left(P_{1}, P_{2}\right)$ and inclusions $\left(Q_{1}, Q_{2}\right)$, Example 1.91 applies. Let $U=U_{3}$, to get $V=$ $U \oplus U$ with projections $\left(A_{1}^{-1} \circ P_{1}, A_{2}^{-1} \circ P_{2}\right)$ and inclusions $\left(Q_{1} \circ A_{1}, Q_{2} \circ A_{2}\right)$. The direct sums are equivalent.

The implication $(1) \Longrightarrow(3)$ is canonical: let $U^{\prime}=U^{\prime \prime}=U$ and $A=I d_{U}$.

The implication $(2) \Longrightarrow(3)$ is canonical: let $U^{\prime}=U_{1}, U^{\prime \prime}=U_{2}$ and $A=$ $A_{1} \circ A_{2}^{-1}$.

For $(3) \Longrightarrow(1)$, there are two choices. Given $V=U^{\prime} \oplus U^{\prime \prime}$ with projections $\left(P^{\prime}, P^{\prime \prime}\right)$ and inclusions $\left(Q^{\prime}, Q^{\prime \prime}\right)$, one choice is to let $U=U^{\prime}$. Then $V=U \oplus U$ with projections $\left(P_{1}, A \circ P_{2}\right)$ and inclusions $\left(Q_{1}, Q_{2} \circ A^{-1}\right)$. The other choice is to let $U=U^{\prime \prime}$, with projections $\left(A^{-1} \circ P_{1}, P_{2}\right)$ and inclusions $\left(Q_{1} \circ A, Q_{2}\right)$. As in Example 1.91, either of the two constructions gives a direct sum equivalent to $V=U^{\prime} \oplus U^{\prime \prime}$, so they are equivalent to each other.

For $(3) \Longrightarrow(2)$, there are two choices. One choice is to let $U_{3}=U^{\prime}, A_{1}=I d_{U^{\prime}}$, $A_{2}=A^{-1}$. Applying the canonical $(2) \Longrightarrow(1)$ construction then gives projections $\left(P_{1}, A \circ P_{2}\right)$ as in the first choice of the previous implication. The second choice is to let $U_{3}=U^{\prime \prime}, A_{1}=A, A_{2}=I d_{U^{\prime \prime}}$, which similarly corresponds to the second choice in the previous implication.

The implication $(3) \Longrightarrow(4)$ is canonical. Given $A: U^{\prime \prime} \rightarrow U^{\prime}$, let

$$
\begin{equation*}
K=Q^{\prime \prime} \circ A^{-1} \circ P^{\prime}+Q^{\prime} \circ A \circ P^{\prime \prime} \tag{1.17}
\end{equation*}
$$

It is straightforward to check that $K$ is an involution, and $Q^{\prime} \circ P^{\prime} \circ K=K \circ Q^{\prime \prime} \circ P^{\prime \prime}$, so $K$ respects the direct sums as in Example 1.88.

The implication (4) $\Longrightarrow(3)$ is canonical. Given $K$, let $A=P^{\prime} \circ K \circ Q^{\prime \prime}$ : $U^{\prime \prime} \rightarrow U^{\prime}$, which by Lemma 1.83 has inverse $A^{-1}=P^{\prime \prime} \circ K \circ Q^{\prime}$.

The implication $(4) \Longrightarrow(6)$ is canonical: let $H=K$.
For $(6) \Longrightarrow(3)$, there are two choices. One choice is to let $A=P^{\prime} \circ H \circ Q^{\prime \prime}$ : $U^{\prime \prime} \rightarrow U^{\prime}$, so $A^{-1}=P^{\prime \prime} \circ H^{-1} \circ Q^{\prime}$. The canonical involution (1.17) from the implication $(3) \Longrightarrow(4)$ is then $K=Q^{\prime \prime} \circ P^{\prime \prime} \circ H^{-1} \circ Q^{\prime} \circ P^{\prime}+Q^{\prime} \circ P^{\prime} \circ H \circ Q^{\prime \prime} \circ P^{\prime \prime}$. The second choice is to let $A=P^{\prime} \circ H^{-1} \circ Q^{\prime \prime}$. This similarly leads to an involution $Q^{\prime \prime} \circ P^{\prime \prime} \circ H \circ Q^{\prime} \circ P^{\prime}+Q^{\prime} \circ P^{\prime} \circ H^{-1} \circ Q^{\prime \prime} \circ P^{\prime \prime}$, which, unless $H$ is an involution, may be different from the involution from the first choice.

For $(4) \Longrightarrow(5)$, and for $(6) \Longrightarrow(7)$, there are two choices: $P=Q^{\prime} \circ P^{\prime}$, or $P=Q^{\prime \prime} \circ P^{\prime \prime}$. This choice between two idempotents was already mentioned in Example 1.108.

Conversely, for $(5) \Longrightarrow(4)$ (and similarly for $(7) \Longrightarrow(6)$ ), there are two choices. For $U^{\prime}=\operatorname{ker}(P)$ and $U^{\prime \prime}=P(V)$, as in Example 1.107, there are two ways to form a direct sum: $V=U^{\prime} \oplus U^{\prime \prime}$ or $V=U^{\prime \prime} \oplus U^{\prime}$. The map $K($ similarly $H)$ respects the direct sums as in Lemma 1.109.

For $(4) \Longrightarrow(8)$, which does not require $\frac{1}{2} \in \mathbb{K}$, there are two choices (assuming the ordering of the pair $K_{1}, K_{2}$ does not matter). Given $K$, let $K_{1}=K$. One choice is to let $K_{2}=Q^{\prime} \circ P^{\prime}-Q^{\prime \prime} \circ P^{\prime \prime}$, as in Example 1.114. It follows from $K \circ Q^{\prime} \circ P^{\prime}=Q^{\prime \prime} \circ P^{\prime \prime} \circ K$ that $K_{1} \circ K_{2}=-K_{2} \circ K_{1}$. The second choice is to let $K_{2}=-Q^{\prime} \circ P^{\prime}+Q^{\prime \prime} \circ P^{\prime \prime}$.

Similarly for $(5) \Longrightarrow(8)$, there are two choices. Given $K$, let $K_{1}=K$. One choice is to let $K_{2}=2 \cdot P-I d_{V}$, as in Lemma 1.115. The second choice is to let $K_{2}=I d_{V}-2 \cdot P$.

For $(8) \Longrightarrow(4)$ using $\frac{1}{2} \in \mathbb{K}$, the involution $K_{1}$ produces a direct sum $V=$ $V_{1} \oplus V_{2}$ as in Lemma 1.112, with projections $P_{1}=\frac{1}{2}\left(I d_{V}+K_{1}\right), P_{2}=\frac{1}{2}\left(I d_{V}-K_{1}\right)$ (the order of the direct sum could be chosen the other way, $V_{2} \oplus V_{1}$ ). By Lemma $1.119, K=K_{2}$ satisfies (4). In this case, the invertible map from (3) is, by Lemma 1.83 , the composite

$$
\begin{equation*}
A=P_{1} \circ K_{2} \circ Q_{2}: V_{2} \rightarrow V_{1} \tag{1.18}
\end{equation*}
$$

with inverse $P_{2} \circ K_{2} \circ Q_{1}: V_{1} \rightarrow V_{2}$. Another choice for (8) $\Longrightarrow(4)$ is to use $K_{2}$ to produce a different direct sum, and then let $K=K_{1}$.

Theorem 1.129. Given $\frac{1}{2} \in \mathbb{K}$ and two involutions $K, K^{\prime} \in \operatorname{End}(V)$, which produce direct sums $V=V_{1} \oplus V_{2}, V=V_{1}^{\prime} \oplus V_{2}^{\prime}$ as in Lemma 1.112, if $K$ and $K^{\prime}$ anticommute, then for $i=1,2, I=1,2$, and $\beta \in \mathbb{K}, \beta \neq 0$, the map

$$
\beta \cdot P_{I}^{\prime} \circ Q_{i}: V_{i} \rightarrow V_{I}^{\prime}
$$

is invertible.
Proof. Consider $P_{I}^{\prime} \circ Q_{i}: V_{i} \rightarrow V_{I}^{\prime}$ and $P_{i} \circ Q_{I}^{\prime}: V_{I}^{\prime} \rightarrow V_{i}$. Then

$$
P_{I}^{\prime} \circ Q_{i} \circ P_{i} \circ Q_{I}^{\prime}=P_{I}^{\prime} \circ \frac{1}{2} \cdot\left(I d_{V} \pm K\right) \circ Q_{I}^{\prime}
$$

Since $K$ respects the direct sums $V_{1}^{\prime} \oplus V_{2}^{\prime} \rightarrow V_{2}^{\prime} \oplus V_{1}^{\prime}$ by Lemma 1.119, $P_{I}^{\prime} \circ K \circ Q_{I}^{\prime}=$ $0_{\operatorname{End}\left(V_{I}^{\prime}\right)}$ by Lemma 1.81. In the other order,

$$
P_{i} \circ Q_{I}^{\prime} \circ P_{I}^{\prime} \circ Q_{i}=P_{i} \circ \frac{1}{2} \cdot\left(I d_{V} \pm K^{\prime}\right) \circ Q_{i}
$$

and similarly, $P_{i} \circ K^{\prime} \circ Q_{i}=0_{\operatorname{End}\left(V_{i}\right)}$.
Since $P_{I}^{\prime} \circ Q_{I}^{\prime}=I d_{V_{I}^{\prime}}$ and $P_{i} \circ Q_{i}=I d_{V_{i}}$, the conclusion is that for any scalar $\beta \in \mathbb{K}, \beta \neq 0$, the map $\beta \cdot P_{I}^{\prime} \circ Q_{i}$ has inverse $\frac{2}{\beta} \cdot P_{i} \circ Q_{I}^{\prime}$.

Lemma 1.130. Given involutions $K_{1}, K_{2}, K_{3} \in \operatorname{End}(V)$, any pair of two of the following three statements implies the remaining one.
(1) $K_{3}$ commutes with $K_{1} \circ K_{2}$.
(2) $K_{3}$ anticommutes with $K_{1}$.
(3) $K_{3}$ anticommutes with $K_{2}$.

Exercise 1.131. If $K_{1}, K_{2}, K_{3}$ are involutions such that $K_{1}$ and $K_{2}$ commute and $K_{3}$ satisfies the three conditions from Lemma 1.130, then the set

$$
\left\{ \pm I d_{V}, \pm K_{1}, \pm K_{2}, \pm K_{3}, \pm K_{2} \circ K_{3}, \pm K_{1} \circ K_{3}, \pm K_{1} \circ K_{2}, \pm K_{1} \circ K_{2} \circ K_{3}\right\}
$$

is the image of a representation $D_{4} \times \mathbb{Z}_{2} \rightsquigarrow \operatorname{End}(V)$, where $D_{4}$ is the eight-element dihedral group and $\mathbb{Z}_{2}$ is the two-element group.

For $\frac{1}{2} \in \mathbb{K}$ and commuting involutions $K_{1}, K_{2}$, recall the direct sums $V=$ $V_{1} \oplus V_{2}, V=V_{3} \oplus V_{4}, V=V_{5} \oplus V_{6}$ from Lemma 1.121 produced by $K_{1}, K_{2}$, $K_{1} \circ K_{2}$. Further, suppose $K_{3}$ is another involution satisfying the three conditions from Lemma 1.130, and let $V=V_{7} \oplus V_{8}$ and $V=V_{9} \oplus V_{10}$ be the direct sums produced by the involutions $K_{3}$ and $K_{1} \circ K_{2} \circ K_{3}$. Theorem 1.122 applies to $V_{5}$ twice: first, to the pair $K_{1}, K_{2}$ to get the canonical involution $P_{5} \circ K_{1} \circ Q_{5}$ from (1.13) producing $V_{5}=V_{5}^{\prime} \oplus V_{5}^{\prime \prime}$ with $V_{5}^{\prime}=V_{1} \cap V_{3} \cap V_{5}$, and second, to the other pair $K_{1} \circ K_{2}, K_{3}$ to get another involution $P_{5} \circ K_{3} \circ Q_{5}=P_{5} \circ K_{1} \circ K_{2} \circ K_{3} \circ Q_{5}$ as in (1.13), producing another direct sum $V_{5}=V_{5}^{\prime \prime \prime} \oplus V_{5}^{\prime \prime \prime \prime}$, with $V_{5}^{\prime \prime \prime}=V_{5} \cap V_{7} \cap V_{9}$.

Corollary 1.132. Given $\frac{1}{2} \in \mathbb{K}, 0 \neq \beta \in \mathbb{K}$, commuting involutions $K_{1}, K_{2}$, and an involution $K_{3}$ as in Lemma 1.130, the map

$$
\beta \cdot P_{5}^{\prime \prime \prime} \circ Q_{5}^{\prime}: V_{5}^{\prime} \rightarrow V_{5}^{\prime \prime \prime}
$$

is invertible.

Proof. $Q_{5}^{\prime}$ is as in the Proof of Theorem 1.122. The projection $P_{5}^{\prime \prime \prime}: V_{5} \rightarrow V_{5}^{\prime \prime \prime}$ is from the direct sum $V_{5}=V_{5}^{\prime \prime \prime} \oplus V_{5}^{\prime \prime \prime \prime}$ produced by $P_{5} \circ K_{3} \circ Q_{5}$. The involutions $P_{5} \circ K_{1} \circ Q_{5}, P_{5} \circ K_{3} \circ Q_{5} \in \operatorname{End}\left(V_{5}\right)$ anticommute, and Theorem 1.129 applies.

Using a step analogous to (1.15), the output of the above invertible map, for input $v \in V_{5}^{\prime}$, can be written as:

$$
\begin{align*}
\beta \cdot P_{5}^{\prime \prime \prime} \circ Q_{5}^{\prime}: v & \mapsto \beta \cdot\left(P_{5}^{\prime \prime \prime} \circ Q_{5}^{\prime}\right)(v) \\
& =Q_{5}\left(Q_{5}^{\prime \prime \prime}\left(\beta \cdot\left(P_{5}^{\prime \prime \prime} \circ\left(P_{5} \circ Q_{5}\right) \circ Q_{5}^{\prime}\right)(v)\right)\right)  \tag{1.19}\\
& =\beta \cdot\left(\left(Q_{5} \circ Q_{5}^{\prime \prime \prime} \circ P_{5}^{\prime \prime \prime} \circ P_{5}\right) \circ Q_{5} \circ Q_{5}^{\prime}\right)(v) \\
& =\beta \cdot\left(\left(Q_{7} \circ P_{7} \circ Q_{5} \circ P_{5}\right) \circ Q_{5} \circ Q_{5}^{\prime}\right)(v) \\
& =\beta \cdot\left(Q_{7} \circ P_{7} \circ Q_{5} \circ Q_{5}^{\prime}\right)(v) \\
& =\frac{\beta}{2} \cdot\left(v+K_{3}(v)\right) .
\end{align*}
$$

Corollary 1.132 could be re-stated as constructing an invertible map between these subspaces of $V_{5}=\left\{v \in V: v=\left(K_{1} \circ K_{2}\right)(v)\right\}$ :

$$
\left\{v=K_{1}(v)=K_{2}(v)\right\} \rightarrow\left\{v=K_{3}(v)=\left(K_{1} \circ K_{2} \circ K_{3}\right)(v)\right\}
$$

Two more subspaces of $V_{5}$, from Theorem 1.122, are:

$$
\begin{aligned}
V_{5}^{\prime \prime} & =\left\{v \in V: v=-K_{1}(v)=-K_{2}(v)\right\}=V_{2} \cap V_{4} \\
V_{5}^{\prime \prime \prime \prime} & =\left\{v \in V: v=-K_{3}(v)=-\left(K_{1} \circ K_{2} \circ K_{3}\right)(v)\right\}=V_{8} \cap V_{10}
\end{aligned}
$$

and Theorem 1.129 also gives a construction of invertible maps: $V_{5}^{\prime} \rightarrow V_{5}^{\prime \prime \prime \prime}, V_{5}^{\prime \prime} \rightarrow$ $V_{5}^{\prime \prime \prime}$, and $V_{5}^{\prime \prime} \rightarrow V_{5}^{\prime \prime \prime \prime}$.

Example 1.133. Given any spaces $V$ and $W$, and an involution $K$ on $V$, the map $\left[I d_{W} \otimes K\right]$ is an involution on $W \otimes V$. If $\frac{1}{2} \in \mathbb{K}$, then the direct sum produced by $\left[I d_{W} \otimes K\right]$ has projections $\frac{1}{2} \cdot\left(I d_{W \otimes V} \pm\left[I d_{W} \otimes K\right]\right)$. For the direct sum $V=V_{1} \oplus V_{2}$ as in Lemma 1.112 with inclusions $Q_{1}, Q_{2}$, there is also a direct sum $W \otimes V=W \otimes V_{1} \oplus W \otimes V_{2}$ as in Example 1.75, with projections [ $I d_{W} \otimes \frac{1}{2} \cdot\left(I d_{V} \pm K\right)$ ] and inclusions $\left[I d_{W} \otimes Q_{i}\right]$. The two constructions lead to the same formula for the projection operators, so the projections are canonical and $K$ produces a direct sum $W \otimes V=W \otimes V_{1} \oplus W \otimes V_{2}$. The space $W \otimes V_{1}$ is a subspace of $W \otimes V$, equal to the fixed point set of $\left[I d_{W} \otimes K\right]$, with inclusion map $\left[I d_{W} \otimes Q_{1}\right]$, and similarly $W \otimes V_{2}$ is the fixed point subspace of $-\left[I d_{W} \otimes K\right]$. The space $V \otimes W$ admits an analogous involution and direct sum.

Example 1.134. Given any spaces $U, W$ with involutions $K_{U}$ on $U$ and $K_{W}$ on $W$, the involutions $\left[I d_{U} \otimes K_{W}\right]$ and $\left[K_{U} \otimes I d_{W}\right]$ on $U \otimes W$ commute, so Lemma 1.121 applies, and if $\frac{1}{2} \in \mathbb{K}$, then Lemma 1.120 and Theorem 1.122 apply. For the direct sums $U=U_{1} \oplus U_{2}$ and $W=W_{1} \oplus W_{2}$ produced as in Lemma 1.112, $\left[K_{U} \otimes I d_{W}\right]$ respects the direct sum $U \otimes W_{1} \oplus U \otimes W_{2}$ from Example 1.133; the induced involution on $U \otimes W_{1}$ is exactly $\left[K_{U} \otimes I d_{W_{1}}\right]$, so $U \otimes W_{1}$ admits a direct sum $U_{1} \otimes W_{1} \oplus U_{2} \otimes W_{1}$. Similarly, $\left[I d_{U} \otimes K_{W}\right]$ induces an involution on $U_{1} \otimes W$ and a direct sum $U_{1} \otimes W_{1} \oplus U_{1} \oplus W_{2}$. The subspace $U_{1} \otimes W_{1}$ appears in two different ways, but there is no conflict in naming it: by Theorem $1.122, U_{1} \otimes W_{1}=$ $\left(U \otimes W_{1}\right) \cap\left(U_{1} \otimes W\right)$.

Example 1.135. Given any spaces $V$ and $W$, and an involution $K$ on $V$, the map $\operatorname{Hom}\left(I d_{W}, K\right)$ is an involution on $\operatorname{Hom}(W, V)$. If $\frac{1}{2} \in \mathbb{K}$, then the direct sum produced by $\operatorname{Hom}\left(I d_{W}, K\right)$ has projections

$$
\frac{1}{2} \cdot\left(I d_{\operatorname{Hom}(W, V)} \pm \operatorname{Hom}\left(I d_{W}, K\right)\right): A \mapsto \frac{1}{2} \cdot(A \pm K \circ A)
$$

For the direct sum $V=V_{1} \oplus V_{2}$ as in Lemma 1.112, there is also a direct sum $\operatorname{Hom}(W, V)=\operatorname{Hom}\left(W, V_{1}\right) \oplus \operatorname{Hom}\left(W, V_{2}\right)$ as in Example 1.76, with projections

$$
\operatorname{Hom}\left(I d_{W}, P_{i}\right): \operatorname{Hom}(W, V) \rightarrow \operatorname{Hom}\left(W, V_{i}\right): A \mapsto P_{i} \circ A=\frac{1}{2} \cdot\left(I d_{V} \pm K\right) \circ A
$$

The two constructions lead to the same formula for the projection operators. The only difference is in the target space: the fixed point set of $\operatorname{Hom}\left(I d_{W}, K\right)$ is the set of maps $A: W \rightarrow V$ such that $A=K \circ A$, while the image of the projection $\operatorname{Hom}\left(I d_{W}, P_{1}\right)$ is a set of maps with domain $W$ and target $V_{1}=\{v \in V: v=K(v)\}$, which is a subspace of $V$. It will not cause any problems to consider $\operatorname{Hom}\left(W, V_{i}\right)$ as a subspace of $\operatorname{Hom}(W, V)$; more precisely, in the case where $V=V_{1} \oplus V_{2}$ is a direct sum produced by an involution, the operator $\operatorname{Hom}\left(I d_{W}, Q_{i}\right)$ from Example 1.76 can be regarded as a subspace inclusion as in Lemma 1.112, so $A$ and $Q_{i} \circ A$ are identified. Then the above two direct sum constructions have the same projection and inclusion operators, so the projections are canonical and $K$ produces a direct $\operatorname{sum} \operatorname{Hom}(W, V)=\operatorname{Hom}\left(W, V_{1}\right) \oplus \operatorname{Hom}\left(W, V_{2}\right)$.

Example 1.136. Given any spaces $V$ and $W$, and an involution $K$ on $V$, the $\operatorname{map} \operatorname{Hom}\left(K, I d_{W}\right)$ is an involution on $\operatorname{Hom}(V, W)$. If $\frac{1}{2} \in \mathbb{K}$, then the direct sum produced by $\operatorname{Hom}\left(K, I d_{W}\right)$ has projections

$$
\begin{equation*}
\frac{1}{2} \cdot\left(I d_{\operatorname{Hom}(V, W)} \pm \operatorname{Hom}\left(K, I d_{W}\right)\right): A \mapsto \frac{1}{2} \cdot(A \pm A \circ K) . \tag{1.20}
\end{equation*}
$$

For the direct sum $V=V_{1} \oplus V_{2}$ as in Lemma 1.112, there is also a direct sum $\operatorname{Hom}(V, W)=\operatorname{Hom}\left(V_{1}, W\right) \oplus \operatorname{Hom}\left(V_{2}, W\right)$ as in Example 1.77, with projections

$$
\operatorname{Hom}\left(Q_{i}, I d_{W}\right): \operatorname{Hom}(V, W) \rightarrow \operatorname{Hom}\left(V_{i}, W\right): A \mapsto A \circ Q_{i}
$$

Unlike Example 1.135, the two constructions lead to different formulas for the projection operators. The fixed point set of $\operatorname{Hom}\left(K, I d_{W}\right)$ is the set of maps $A$ : $V \rightarrow W$ such that $A=A \circ K$, while the image of the projection $\operatorname{Hom}\left(Q_{1}, I d_{W}\right)$ is a set of maps with domain $V_{1}$ and target $W$ - which does not look like a subspace of $\operatorname{Hom}(V, W)$. The conclusion is that the two direct sum constructions are different. However, they are equivalent, as in Definition 1.90. Checking statements (2) and (3) of Lemma 1.89,

$$
\operatorname{Hom}\left(P_{i}, I d_{W}\right) \circ \operatorname{Hom}\left(Q_{i}, I d_{W}\right): A \mapsto A \circ Q_{i} \circ P_{i}=A \circ \frac{1}{2} \cdot\left(I d_{V} \pm K\right)
$$

which is the same as (1.20).
Example 1.137. Given any spaces $U, V, W$, with involutions $K_{U}$ on $U, K_{V}$ on $V$, and $\operatorname{Hom}\left(K_{V}, I d_{W}\right)$ on $\operatorname{Hom}(V, W)$ as in Example 1.136, suppose $\frac{1}{2} \in \mathbb{K}$ and $H: U \rightarrow \operatorname{Hom}(V, W)$ satisfies $\operatorname{Hom}\left(K_{V}, I d_{W}\right) \circ H=H \circ K_{U}$. Let $U=U_{1} \oplus U_{2}$ be the direct sum produced by $K_{U}$, and consider the direct sum on $\operatorname{Hom}(V, W)$ produced by $\operatorname{Hom}\left(K_{V}, I d_{W}\right)$ as in (1.20) from Example 1.136. Then, by Lemma 1.118, $H$ respects the direct sums:

$$
H: U_{1} \oplus U_{2} \rightarrow\left\{A: V \rightarrow W: A \circ K_{V}=A\right\} \oplus\left\{A: V \rightarrow W: A \circ K_{V}=-A\right\}
$$

Let $V=V_{1} \oplus V_{2}$ be the direct sum produced by $K_{V}$; then by Lemma $1.92, H$ also respects the other, equivalent direct sum on $\operatorname{Hom}(V, W)$ from Example 1.136:

$$
H: U_{1} \oplus U_{2} \rightarrow \operatorname{Hom}\left(V_{1}, W\right) \oplus \operatorname{Hom}\left(V_{2}, W\right)
$$

Example 1.138. Given $\frac{1}{2} \in \mathbb{K}$, any spaces $U$ and $W$, and involutions $K_{U} \in$ $\operatorname{End}(U)$ and $K_{W} \in \operatorname{End}(W)$, let $U=U_{1} \oplus U_{2}$ be the direct sum produced by $K_{U}$, with projections $\left(P_{1}, P_{2}\right)$ and inclusions $\left(Q_{1}, Q_{2}\right)$, and let $W=W_{1} \oplus W_{2}$ be the direct sum produced by $K_{W}$, with operators $\left(P_{1}^{\prime}, P_{2}^{\prime}\right),\left(Q_{1}^{\prime}, Q_{2}^{\prime}\right)$. Then there are commuting involutions $\operatorname{Hom}\left(I d_{U}, K_{W}\right), \operatorname{Hom}\left(K_{U}, I d_{W}\right)$, on $\operatorname{Hom}(U, W)$, and their composite $\operatorname{Hom}\left(K_{U}, K_{W}\right)$ is another involution. Theorem 1.122 applies, and we re-use its $V_{1}, \ldots, V_{6}$ notation for the produced direct sums. As in Example 1.135, there is a direct sum

$$
\begin{aligned}
\operatorname{Hom}(U, W) & =\left\{A=K_{W} \circ A\right\} \oplus\left\{A=-K_{W} \circ A\right\} \\
& =\operatorname{Hom}\left(U, W_{1}\right) \oplus \operatorname{Hom}\left(U, W_{2}\right) \\
& =V_{1} \oplus V_{2} .
\end{aligned}
$$

As in Example 1.136, there are two different but equivalent direct sums, the first is

$$
\operatorname{Hom}(U, W)=\left\{A=A \circ K_{U}\right\} \oplus\left\{A=-A \circ K_{U}\right\}=V_{3} \oplus V_{4}
$$

with projections and inclusions denoted $\left(P_{3}, P_{4}\right),\left(Q_{3}, Q_{4}\right)$, and the second is

$$
\operatorname{Hom}(U, W)=\operatorname{Hom}\left(U_{1}, W\right) \oplus \operatorname{Hom}\left(U_{2}, W\right)
$$

with projections and inclusions

$$
\left(\operatorname{Hom}\left(Q_{1}, I d_{W}\right), \operatorname{Hom}\left(Q_{2}, I d_{W}\right)\right),\left(\operatorname{Hom}\left(P_{1}, I d_{W}\right), \operatorname{Hom}\left(P_{2}, I d_{W}\right)\right)
$$

From Lemma 1.93, there are canonical, invertible maps

$$
\begin{array}{rll}
P_{3} \circ \operatorname{Hom}\left(P_{1}, I d_{W}\right) & : \quad \operatorname{Hom}\left(U_{1}, W\right) \rightarrow V_{3}, \\
\operatorname{Hom}\left(Q_{1}, I d_{W}\right) \circ Q_{3} & : \quad V_{3} \rightarrow \operatorname{Hom}\left(U_{1}, W\right) .
\end{array}
$$

There is also the direct sum produced by the composite involution,

$$
\begin{aligned}
\operatorname{Hom}(U, W) & =\left\{A=K_{W} \circ A \circ K_{U}\right\} \oplus\left\{A=-K_{W} \circ A \circ K_{U}\right\} \\
& =V_{5} \oplus V_{6}
\end{aligned}
$$

It follows from Theorem 1.122 that $V_{1}, V_{3}$, and $V_{5}$ admit canonical involutions and direct sums. For example, $P_{3} \circ \operatorname{Hom}\left(I d_{U}, K_{W}\right) \circ Q_{3}$ is the involution on $V_{3}$, and it produces the direct sum $V_{3}=V_{3}^{\prime} \oplus V_{3}^{\prime \prime}$, where $V_{3}^{\prime}=V_{1} \cap V_{3} \cap V_{5}$. The above invertible map $\operatorname{Hom}\left(Q_{1}, I d_{W}\right) \circ Q_{3}: V_{3} \rightarrow \operatorname{Hom}\left(U_{1}, W\right)$ satisfies

$$
\begin{aligned}
& \operatorname{Hom}\left(I d_{U_{1}}, K_{W}\right) \circ\left(\operatorname{Hom}\left(Q_{1}, I d_{W}\right) \circ Q_{3}\right) \\
= & \operatorname{Hom}\left(Q_{1}, K_{W}\right) \circ Q_{3} \\
= & \left(\operatorname{Hom}\left(Q_{1}, I d_{W}\right) \circ Q_{3}\right) \circ\left(P_{3} \circ \operatorname{Hom}\left(I d_{U}, K_{W}\right) \circ Q_{3}\right),
\end{aligned}
$$

so by Lemma 1.118, it respects the direct sums

$$
V_{3}^{\prime} \oplus V_{3}^{\prime \prime} \rightarrow \operatorname{Hom}\left(U_{1}, W_{1}\right) \oplus \operatorname{Hom}\left(U_{1}, W_{2}\right)
$$

By Lemma 1.83, there is a canonical, invertible map from

$$
V_{3}^{\prime}=V_{1} \cap V_{3} \cap V_{5}=\left\{A: U \rightarrow W: A=K_{W} \circ A=A \circ K_{U}=K_{W} \circ A \circ K_{U}\right\}
$$

to $\operatorname{Hom}\left(U_{1}, W_{1}\right)$, specifically, the map

$$
\begin{aligned}
A & \mapsto P_{1}^{\prime} \circ\left(Q_{3}\left(Q_{3}^{\prime}(A)\right)\right) \circ Q_{1} \\
& =P_{1}^{\prime} \circ A \circ Q_{1}=\frac{1}{2} \cdot\left(I d_{W}+K_{W}\right) \circ A \circ Q_{1}=A \circ Q_{1}
\end{aligned}
$$

The inverse is defined for $B \in \operatorname{Hom}\left(U_{1}, W_{1}\right)$ by

$$
B \mapsto P_{3}^{\prime}\left(P_{3}\left(Q_{1}^{\prime} \circ B \circ P_{1}\right)\right)
$$

which, since $Q_{1}^{\prime} \circ B \circ P_{1}$ is an element of the subspace $V_{1} \cap V_{3}$, simplifies to

$$
Q_{1}^{\prime} \circ B \circ P_{1}=B \circ P_{1}=B \circ \frac{1}{2} \cdot\left(I d_{U}+K_{U}\right)
$$

Example 1.139. For $\frac{1}{2} \in \mathbb{K}$, and involutions $K_{U}$ on $U$ and $K_{W}$ on $W$ as in the previous Example, suppose $K_{3}$ is an involution on $\operatorname{Hom}(U, W)$ that commutes with $\operatorname{Hom}\left(K_{U}, K_{W}\right)$ and anticommutes with either $\operatorname{Hom}\left(K_{U}, I d_{W}\right)$ or $\operatorname{Hom}\left(I d_{U}, K_{W}\right)$. Then Lemma 1.130 and Corollary 1.132 apply. Continuing with the $V_{1}, \ldots, V_{6}$ notation from Theorem 1.122 and Example 1.138, and also the $V_{5}=V_{5}^{\prime \prime \prime} \oplus V_{5}^{\prime \prime \prime \prime}$ and $V_{7}, \ldots, V_{10}$ notation from Corollary 1.132, the result of the Corollary is that for $0 \neq \beta \in \mathbb{K}$, there is an invertible map:

$$
\beta \cdot P_{5}^{\prime \prime \prime} \circ Q_{5}^{\prime}: V_{5}^{\prime} \rightarrow V_{5}^{\prime \prime \prime}
$$

which maps

$$
\left\{A \in \operatorname{Hom}(U, W): A=A \circ K_{U}=K_{W} \circ A\right\}
$$

to

$$
\left\{A \in \operatorname{Hom}(U, W): A=K_{W} \circ A \circ K_{U}=K_{3}(A)\right\}
$$

There is also the canonical, invertible map from Example 1.138,

$$
P_{3}^{\prime} \circ\left(P_{3} \circ \operatorname{Hom}\left(P_{1}, I d_{W}\right)\right) \circ \operatorname{Hom}\left(I d_{U_{1}}, Q_{1}^{\prime}\right)
$$

which maps $\operatorname{Hom}\left(U_{1}, W_{1}\right)$ to $V_{3}^{\prime}=V_{5}^{\prime}$. The composite of these maps is an invertible $\operatorname{map} \operatorname{Hom}\left(U_{1}, W_{1}\right) \rightarrow V_{5}^{\prime \prime \prime}:$

$$
\left(\beta \cdot P_{5}^{\prime \prime \prime} \circ Q_{5}^{\prime}\right) \circ\left(P_{3}^{\prime} \circ\left(P_{3} \circ \operatorname{Hom}\left(P_{1}, I d_{W}\right)\right) \circ \operatorname{Hom}\left(I d_{U_{1}}, Q_{1}^{\prime}\right)\right)
$$

For $B \in \operatorname{Hom}\left(U_{1}, W_{1}\right)$, its output in $V_{5}^{\prime \prime \prime} \subseteq \operatorname{Hom}(U, W)$ under the above map simplifies as follows, using the equality of subspace inclusions $Q_{5} \circ Q_{5}^{\prime}=Q_{3} \circ Q_{3}^{\prime}$ and steps similar to (1.19):

$$
\begin{aligned}
B & \mapsto\left(\left(\beta \cdot P_{5}^{\prime \prime \prime} \circ Q_{5}^{\prime}\right) \circ\left(P_{3}^{\prime} \circ P_{3} \circ \operatorname{Hom}\left(P_{1}, Q_{1}^{\prime}\right)\right)\right)(B) \\
& =Q_{5}\left(Q_{5}^{\prime \prime \prime}\left(\beta \cdot\left(P_{5}^{\prime \prime \prime} \circ\left(P_{5} \circ Q_{5}\right) \circ Q_{5}^{\prime} \circ P_{3}^{\prime} \circ P_{3} \circ \operatorname{Hom}\left(P_{1}, Q_{1}^{\prime}\right)\right)(B)\right)\right) \\
& =\beta \cdot\left(\left(Q_{5} \circ Q_{5}^{\prime \prime \prime} \circ P_{5}^{\prime \prime \prime} \circ P_{5}\right) \circ\left(Q_{3} \circ Q_{3}^{\prime} \circ P_{3}^{\prime} \circ P_{3}\right) \circ \operatorname{Hom}\left(P_{1}, Q_{1}^{\prime}\right)\right)(B) \\
& =\beta \cdot\left(\left(Q_{7} \circ P_{7} \circ Q_{5} \circ P_{5}\right) \circ\left(Q_{5} \circ P_{5} \circ Q_{3} \circ P_{3}\right) \circ \operatorname{Hom}\left(P_{1}, Q_{1}^{\prime}\right)\right)(B),
\end{aligned}
$$

which, since $Q_{1}^{\prime} \circ B \circ P_{1}$ is an element of the subspace $V_{3} \cap V_{5}$, simplifies to

$$
\beta \cdot\left(Q_{7} \circ P_{7}\right)\left(Q_{1}^{\prime} \circ B \circ P_{1}\right)=\frac{\beta}{2} \cdot\left(Q_{1}^{\prime} \circ B \circ P_{1}+K_{3}\left(Q_{1}^{\prime} \circ B \circ P_{1}\right)\right) .
$$

The inverse map

$$
\left\{A=K_{W} \circ A \circ K_{U}=K_{3}(A)\right\} \rightarrow \operatorname{Hom}\left(U_{1}, W_{1}\right)
$$

is the composite:

$$
\begin{aligned}
& \left(\operatorname{Hom}\left(I d_{U_{1}}, P_{1}^{\prime}\right) \circ\left(\operatorname{Hom}\left(Q_{1}, I d_{W}\right) \circ Q_{3}\right) \circ Q_{3}^{\prime}\right) \circ\left(\frac{2}{\beta} \cdot P_{5}^{\prime} \circ Q_{5}^{\prime \prime \prime}\right) \\
= & \frac{2}{\beta} \cdot \operatorname{Hom}\left(Q_{1}, P_{1}^{\prime}\right) \circ\left(Q_{5} \circ Q_{5}^{\prime}\right) \circ P_{5}^{\prime} \circ\left(P_{5} \circ Q_{5}\right) \circ Q_{5}^{\prime \prime \prime} \\
= & \frac{2}{\beta} \cdot \operatorname{Hom}\left(Q_{1}, P_{1}^{\prime}\right) \circ\left(Q_{3} \circ P_{3} \circ Q_{5} \circ P_{5}\right) \circ Q_{5} \circ Q_{5}^{\prime \prime \prime} \\
= & \frac{2}{\beta} \cdot \operatorname{Hom}\left(Q_{1}, P_{1}^{\prime}\right) \circ Q_{3} \circ P_{3} \circ Q_{5} \circ Q_{5}^{\prime \prime \prime}
\end{aligned}
$$

which acts as $A \mapsto \frac{2}{\beta} \cdot P_{1}^{\prime} \circ\left(\frac{1}{2} \cdot\left(A+A \circ K_{U}\right)\right) \circ Q_{1}=\frac{2}{\beta} \cdot A \circ Q_{1}$.

## CHAPTER 2

## A Survey of Trace Elements

### 2.1. Endomorphisms: the scalar valued trace

In the following diagram, the canonical maps $k_{V V}, e_{V V}$, and $f_{V V}$ are abbreviated $k, e, f$, and the double duality $d_{V^{*} \otimes V}$ is abbreviated $d$.

Lemma 2.1. For any vector space $V$, the following diagram is commutative.


Proof. The left triangle is commutative by the definition of $f$ from Notation 1.63. The right triangle is commutative by Lemma 1.6 , and the middle by Lemma 1.65.

The spaces $\operatorname{End}(V)$ and $\left(V^{*} \otimes V\right)^{*}$ each have the interesting property of containing a distinguished element, which is nonzero when $V$ has nonzero dimension. The identity $I d_{V}: v \mapsto v$ is the distinguished element of $\operatorname{End}(V)$.

Definition 2.2. The distinguished element of $\left(V^{*} \otimes V\right)^{*}$ is the evaluation operator, $E v_{V}: \phi \otimes v \mapsto \phi(v)$.

The two distinguished elements are related by $e: I d_{V} \mapsto E v_{V}$ :

$$
\begin{equation*}
\left(e\left(I d_{V}\right)\right)(\phi \otimes v)=\phi\left(I d_{V}(v)\right)=E v_{V}(\phi \otimes v) \tag{2.1}
\end{equation*}
$$

Definition 2.3. For finite-dimensional $V$, define the trace operator by

$$
\operatorname{Tr}_{V}=\left(k^{*}\right)^{-1}\left(E v_{V}\right) \in \operatorname{End}(V)^{*}
$$

This distinguished element is the output of either of the two previously mentioned distinguished elements under any path of maps in the above diagram leading to $\operatorname{End}(V)^{*}$, by Lemma 2.1, and the fact that all the arrows are invertible when $V$ is finite-dimensional. At least one arrow in any path taking $I d_{V}$ or $E v_{V}$ to $T r_{V}$ is the inverse of one of the arrows indicated in the diagram.

Remark 2.4. Using Definition 2.3 as the definition of trace, so that $\operatorname{Tr}_{V}(A)=$ $E v_{V}\left(k^{-1}(A)\right)$, is exactly the approach of $[\mathbf{M B}],[\mathbf{B}] \S$ II.4.3, and $[\mathbf{K}] \S$ II.3. In $\left[\mathbf{G}_{2}\right]$ $\S$ I.8, this formula is stated as a consequence of a different definition of trace.

Lemma 2.5. For finite-dimensional $V$, and $H \in \operatorname{End}(V)$,

$$
\operatorname{Tr}_{V^{*}}\left(H^{*}\right)=\operatorname{Tr}_{V}(H)
$$

Proof. In this case, $H^{*}$ is $t_{V V}(H)$. In the following diagram, $t_{V V}, k_{V^{*} V^{*}}$, $e_{V^{*} V^{*}}, f_{V^{*} V^{*}}$, and $d_{V^{* *} \otimes V^{*}}$ are abbreviated $t, k^{\prime}, e^{\prime}, f^{\prime}$, and $d^{\prime}$. There is also a $\operatorname{map} p: V^{*} \otimes V \rightarrow V^{* *} \otimes V^{*}$ from Notation 1.66, and $p^{*}$ maps the distinguished element $E v_{V^{*}} \in\left(V^{* *} \otimes V^{*}\right)^{*}$ to $E v_{V}$ :

$$
\left(p^{*}\left(E v_{V^{*}}\right)\right)(\phi \otimes v)=E v_{V^{*}}\left(\left(d_{V}(v)\right) \otimes \phi\right)=\left(d_{V}(v)\right)(\phi)=\phi(v)=E v_{V}(\phi \otimes v)
$$



Some of the squares in the diagram are commutative, for example, $k^{\prime} \circ p=t \circ k$ from Lemma 1.69, and then $p^{*} \circ\left(k^{* *}\right)=k^{*} \circ t^{*}$ by Lemma 1.6, and this is enough to give the result:

$$
t^{*}\left(\operatorname{Tr}_{V^{*}}\right)=\left(t^{*} \circ\left(k^{\prime *}\right)^{-1}\right)\left(E v_{V^{*}}\right)=\left(\left(k^{*}\right)^{-1} \circ p^{*}\right)\left(E v_{V^{*}}\right)=\left(k^{*}\right)^{-1}\left(E v_{V}\right)=\operatorname{Tr}_{V}
$$

The equality $q \circ t=e$ from Lemma 1.53 , which could fit in the back left square of the above diagram, shows that $q$ maps the distinguished element $I d_{V^{*}}$ to $E v_{V}$. So, there is another formula for the trace,

$$
\begin{equation*}
\operatorname{Tr}_{V}=\left(\left(k^{*}\right)^{-1} \circ q\right)\left(I d_{V^{*}}\right) \tag{2.2}
\end{equation*}
$$

Lemma 2.6. For maps $A: V \rightarrow U$ and $B: U \rightarrow V$ between vector spaces of finite, but possibly different, dimensions, $\operatorname{Tr}_{V}(B \circ A)=\operatorname{Tr}_{U}(A \circ B)$.

Proof. Abbreviated names for maps are used again in the following diagram, with primes in the lower pentagon.


Some of the squares in the diagram are commutative. In the back left square with upward arrows, it follows from Lemma 1.52 (and can also be checked directly) that:

$$
e \circ \operatorname{Hom}(A, B)=\left[B^{*} \otimes A\right]^{*} \circ e^{\prime}
$$

For a front left square, by Lemma 1.57,

$$
\operatorname{Hom}(B, A) \circ k=k^{\prime} \circ\left[B^{*} \otimes A\right],
$$

then by Lemma $1.6, k^{*} \circ \operatorname{Hom}(B, A)^{*}=\left[B^{*} \otimes A\right]^{*} \circ k^{*}$, corresponding to a back right square. The claimed equality follows from the following steps, including Lemma 2.1:

$$
\begin{aligned}
\operatorname{Tr}_{U}(A \circ B) & =\operatorname{Tr}_{U}\left(\operatorname{Hom}(B, A)\left(I d_{V}\right)\right)=\left(\operatorname{Hom}(B, A)^{*}\left(\operatorname{Tr}_{U}\right)\right)\left(I d_{V}\right) \\
& =\left(\left(\operatorname{Hom}(B, A)^{*} \circ\left(k^{\prime *}\right)^{-1} \circ e^{\prime}\right)\left(I d_{U}\right)\right)\left(I d_{V}\right) \\
& \left.=\left(\left(k^{*}\right)^{-1} \circ\left[B^{*} \otimes A\right]^{*} \circ e^{\prime}\right)\left(I d_{U}\right)\right)\left(I d_{V}\right) \\
& \left.=\left(\left(k^{*}\right)^{-1} \circ e \circ \operatorname{Hom}(A, B)\right)\left(I d_{U}\right)\right)\left(I d_{V}\right) \\
& =\left(\left(e^{*} \circ d \circ k^{-1} \circ \operatorname{Hom}(A, B)\right)\left(I d_{U}\right)\right)\left(I d_{V}\right) \\
& =\left(d\left(k^{-1}\left(\operatorname{Hom}(A, B)\left(I d_{U}\right)\right)\right)\left(e\left(I d_{V}\right)\right)\right. \\
& =\left(e\left(I d_{V}\right)\right)\left(k^{-1}\left(\operatorname{Hom}(A, B)\left(I d_{U}\right)\right)\right) \\
& =\left(\left(\left(k^{*}\right)^{-1} \circ e\right)\left(I d_{V}\right)\right)\left(\operatorname{Hom}(A, B)\left(I d_{U}\right)\right)=\operatorname{Tr}_{V}(B \circ A) .
\end{aligned}
$$

Example 2.7. In the case $V=\mathbb{K}, k\left(I d_{\mathbb{K}} \otimes 1\right)=I d_{\mathbb{K}} \in \operatorname{End}(\mathbb{K})=\mathbb{K}^{*}$. The trace is $T r_{\mathbb{K}}=e^{*}\left(d\left(I d_{\mathbb{K}} \otimes 1\right)\right) \in \mathbb{K}^{* *}$, and for $\phi \in \mathbb{K}^{*}, \operatorname{Tr}_{\mathbb{K}}(\phi)=(e(\phi))\left(I d_{\mathbb{K}} \otimes 1\right)=$ $I d_{\mathbb{K}}(\phi(1))=\phi(1)$. So, $T r_{\mathbb{K}}=d_{\mathbb{K}}(1)$, and in particular, $T r_{\mathbb{K}}\left(I d_{\mathbb{K}}\right)=1$.

Example 2.8. If $V$ is finite-dimensional and admits a direct sum of the form $V=\mathbb{K} \oplus U$, with projection $P_{1}: V \rightarrow \mathbb{K}$ and $Q_{1}: \mathbb{K} \rightarrow V$, then by Lemma 2.6 and Example 2.7, $\operatorname{Tr}_{V}\left(Q_{1} \circ P_{1}\right)=T r_{\mathbb{K}}\left(P_{1} \circ Q_{1}\right)=T r_{\mathbb{K}}\left(I d_{\mathbb{K}}\right)=1$. Similarly, if $V$ is a direct sum of finitely many copies of $\mathbb{K}, V=\mathbb{K} \oplus \mathbb{K} \oplus \cdots \oplus \mathbb{K}$, then $\operatorname{Tr}_{V}\left(I d_{V}\right)=\operatorname{Tr}_{V}\left(\Sigma Q_{i} \circ P_{i}\right)=\Sigma \operatorname{Tr}_{\mathbb{K}}\left(P_{i} \circ Q_{i}\right)=\Sigma 1$.

Example 2.9. Assume $\operatorname{Tr}_{V}\left(I d_{V}\right) \neq 0$. Let $\operatorname{End}_{0}(V)$ denote the kernel of $T r_{V}$, i.e., the subspace of trace 0 endomorphisms. Recall from Lemma 1.94 that there exists a direct sum $\operatorname{End}(V)=\mathbb{K} \oplus \operatorname{End}_{0}(V)$, and in particular, there exist constants $\alpha, \beta \in \mathbb{K}$ so that $\alpha \cdot \beta \cdot \operatorname{Tr}_{V}\left(\operatorname{Id}_{V}\right)=1$, and a direct sum is defined by

$$
\begin{align*}
P_{1}^{\alpha} & =\alpha \cdot \operatorname{Tr}_{V} \\
Q_{1}^{\beta}: \mathbb{K} & \rightarrow \operatorname{End}(V): \gamma \mapsto \beta \cdot \gamma \cdot I d_{V}  \tag{2.3}\\
P_{2} & =I d_{\operatorname{End}(V)}-Q_{1}^{\beta} \circ P_{1}^{\alpha}
\end{align*}
$$

and the subspace inclusion map $Q_{2}: \operatorname{End}_{0}(V) \rightarrow \operatorname{End}(V)$. Such a direct sum admits a free parameter and is generally not unique, but since $I d_{V}$ is a canonical element of $\operatorname{End}(V)$ and is not in $\operatorname{ker}\left(T r_{V}\right)$ by assumption, Lemma 1.95 applies, and any choice of constants $\alpha, \beta$ leads to an equivalent direct sum. So, any endomorphism $H$ can be written as a sum of a scalar multiple of $I d_{V}$, and a trace zero endomorphism:

$$
H=\frac{\operatorname{Tr}_{V}(H)}{T r_{V}\left(I d_{V}\right)} \cdot I d_{V}+\left(H-\frac{T r_{V}(H)}{T r_{V}\left(I d_{V}\right)} \cdot I d_{V}\right)
$$

and this decomposition of $H$ is canonical.
Theorem 2.10. For $V$ finite-dimensional, and $A \in \operatorname{End}(V)$,

$$
\operatorname{Tr}_{V}(A)=\left(E v_{V} \circ\left[I d_{V^{*}} \otimes A\right] \circ k^{-1}\right)\left(I d_{V}\right)
$$

Proof. By Lemma 1.57,

$$
\left[I d_{V *} \otimes A\right] \circ k^{-1}=\left[I d_{V}^{*} \otimes A\right] \circ k^{-1}=k^{-1} \circ \operatorname{Hom}\left(I d_{V}, A\right)
$$

so

$$
\left(E v_{V} \circ\left[I d_{V^{*}} \otimes A\right] \circ k^{-1}\right)\left(I d_{V}\right)=E v_{V}\left(k^{-1}(A)\right)=\operatorname{Tr}_{V}(A)
$$

Remark 2.11. The idea of Theorem 2.10 (as in [K] §II.3) is that the trace of $A$ is the output of the distinguished element $k^{-1}\left(I d_{V}\right)$ under the composite of maps in this diagram:

$$
V^{*} \otimes V \xrightarrow{\left[I d_{V^{*}} \otimes A\right]} V^{*} \otimes V \xrightarrow{E v_{V}} \mathbb{K}
$$

The statement of Theorem 2.10 could also be written as

$$
\operatorname{Tr}_{V}(A)=\left(\left(d_{\operatorname{End}(V)}\left(I d_{V}\right)\right) \circ \operatorname{Hom}\left(k^{-1}, E v_{V}\right) \circ j\right)\left(I d_{V^{*}} \otimes A\right)
$$

In terms of the scalar multiplication map $l$ from Example 1.27 and the $\beta=1$ case of (2.3) from Example 2.9,

$$
\begin{equation*}
Q_{1}^{1}: \mathbb{K} \rightarrow \operatorname{End}\left(V^{*}\right): 1 \mapsto I d_{V^{*}} \tag{2.4}
\end{equation*}
$$

the composite $\left[Q_{1}^{1} \otimes I d_{\operatorname{End}(V)}\right] \circ l^{-1}: \operatorname{End}(V) \rightarrow \operatorname{End}\left(V^{*}\right) \otimes \operatorname{End}(V)$ takes $A$ to $I d_{V^{*}} \otimes A$, so

$$
\begin{equation*}
\operatorname{Tr}_{V}=\left(d_{\operatorname{End}(V)}\left(I d_{V}\right)\right) \circ \operatorname{Hom}\left(k^{-1}, E v_{V}\right) \circ j \circ\left[Q_{1}^{1} \otimes I d_{\operatorname{End}(V)}\right] \circ l^{-1} \tag{2.5}
\end{equation*}
$$

The map $Q_{1}^{1}$ from (2.4) is used in (2.5), and again in later Sections, without any assumption on the identity map's trace, so $Q_{1}^{1}$ is not necessarily part of the data for some direct sum as in Example 2.9.

Proposition 2.12. For $V=V_{1} \oplus V_{2}, A \in \operatorname{End}\left(V_{1}\right)$, and $B \in \operatorname{End}\left(V_{2}\right)$, let $A \oplus B$ be the element of $\operatorname{End}(V)$ defined by $A \oplus B=Q_{1} \circ A \circ P_{1}+Q_{2} \circ B \circ P_{2}$. If $V$ is finite-dimensional, then

$$
\operatorname{Tr}_{V}(A \oplus B)=\operatorname{Tr}_{V_{1}}(A)+\operatorname{Tr}_{V_{2}}(B)
$$

Proof. Recall $V_{1}$ and $V_{2}$ are finite-dimensional by Exercise 0.44 . The construction of $A \oplus B$ is as in Lemma 1.80.

$$
\begin{aligned}
\operatorname{Tr}_{V}(A \oplus B) & =\operatorname{Tr}_{V}\left(Q_{1} \circ A \circ P_{1}\right)+\operatorname{Tr}_{V}\left(Q_{2} \circ B \circ P_{2}\right) \\
& =\operatorname{Tr}_{V_{1}}\left(P_{1} \circ Q_{1} \circ A\right)+\operatorname{Tr}_{V_{2}}\left(P_{2} \circ Q_{2} \circ B\right) \\
& =\operatorname{Tr}_{V_{1}}(A)+\operatorname{Tr}_{V_{2}}(B),
\end{aligned}
$$

using Lemma 2.6.
Proposition 2.13. If $V$ is finite-dimensional, $V=V_{1} \oplus V_{2}$, and $K \in \operatorname{End}(V)$, then

$$
\operatorname{Tr}_{V}(K)=\operatorname{Tr}_{V_{1}}\left(P_{1} \circ K \circ Q_{1}\right)+\operatorname{Tr}_{V_{2}}\left(P_{2} \circ K \circ Q_{2}\right)
$$

Proof. Using Lemma 2.6,
$\operatorname{Tr}_{V}(K)=\operatorname{Tr}_{V}\left(\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right) \circ K\right)=\operatorname{Tr}_{V_{1}}\left(P_{1} \circ K \circ Q_{1}\right)+\operatorname{Tr}_{V_{2}}\left(P_{2} \circ K \circ Q_{2}\right)$.

The formula $\operatorname{Tr}_{V}\left(I d_{V}\right)=\operatorname{Tr}_{V_{1}}\left(I d_{V_{1}}\right)+\operatorname{Tr}_{V_{2}}\left(I d_{V_{2}}\right)$ can be considered as a special case of either Proposition 2.12 or Proposition 2.13.

Exercise 2.14. Given $V$ finite-dimensional and $A, P \in \operatorname{End}(V)$, suppose $P$ is an idempotent with image subspace $V_{1}=P(V)$, and let $P_{1}$ and $Q_{1}$ be the projection and inclusion operators from Example 1.107. Then

$$
\operatorname{Tr}_{V}(P \circ A)=\operatorname{Tr}_{V_{1}}\left(P_{1} \circ A \circ Q_{1}\right)
$$

In particular, for $A=I d_{V}, \operatorname{Tr}_{V}(P)=\operatorname{Tr}_{V_{1}}\left(I d_{V_{1}}\right)$.
ExErcise 2.15. ([AFMC] P1993-3) For $V$ finite-dimensional, $\phi \in V^{*}, v \in V$, the following are equivalent.
(1) $\operatorname{Tr}_{V}\left(k_{V V}(\phi \otimes v)\right)=1$.
(2) $k_{V V}(\phi \otimes v) \in \operatorname{End}(V)$ is a non-zero idempotent.

Proposition 2.16. ([ $\left.\left.\mathbf{G}_{1}\right] \S I V .7\right)$ For $V$ finite-dimensional and $A \in \operatorname{End}(V)$, the following are equivalent.
(1) $\operatorname{Tr}_{V}(A \circ B)=0$ for all $B$.
(2) $A=0_{\operatorname{End}(V)}$.

Proof.

$$
\begin{aligned}
\operatorname{Hom}\left(I d_{V}, A\right)^{*}\left(T r_{V}\right) & =\left(\operatorname{Hom}\left(I d_{V}, A\right)^{*} \circ\left(k^{*}\right)^{-1} \circ e\right)\left(I d_{V}\right) \\
& =\left(\left(k^{*}\right)^{-1} \circ e \circ \operatorname{Hom}\left(A, I d_{V}\right)\right)\left(I d_{V}\right) \\
& =\left(\left(k^{*}\right)^{-1} \circ e\right)(A),
\end{aligned}
$$

by the commutativity of the diagram from Lemma 2.6 , with $U=V$. If

$$
\operatorname{Tr}_{V}(A \circ B)=\left(\operatorname{Hom}\left(I d_{V}, A\right)^{*}\left(\operatorname{Tr}_{V}\right)\right)(B)=\left(\left(\left(k^{*}\right)^{-1} \circ e\right)(A)\right)(B)
$$

is always zero, then $\left(\left(k^{*}\right)^{-1} \circ e\right)(A)=0_{\operatorname{End}(V)^{*}}$, and since $\left(k^{*}\right)^{-1} \circ e$ has zero kernel, $A$ must be $0_{\operatorname{End}(V)}$. The converse is trivial.

Proposition 2.17. ([B] §II.10.11) Suppose $V$ is finite-dimensional and $\Phi \in$ $\operatorname{End}(V)^{*}$. Then there exists $F \in \operatorname{End}(V)$ such that $\Phi(A)=\operatorname{Tr}_{V}(F \circ A)$ for all $A \in \operatorname{End}(V)$.

Proof. Let $F=e^{-1}\left(k^{*}(\Phi)\right)$. The result follows from the commutativity of the appropriate paths in the diagram for the Proof of Lemma 2.6 in the case $U=V$.

$$
\begin{aligned}
\Phi(A) & =\left(\operatorname{Hom}\left(I d_{V}, A\right)^{*}(\Phi)\right)\left(I d_{V}\right) \\
& =\left(\left(e^{*} \circ d \circ k^{-1} \circ \operatorname{Hom}\left(A, I d_{V}\right) \circ e^{-1} \circ k^{*}\right)(\Phi)\right)\left(I d_{V}\right) \\
& =\left(\left(k^{-1}\right)^{*}\left(e\left(I d_{V}\right)\right)\right)\left(\operatorname{Hom}\left(A, I d_{V}\right)\left(e^{-1}\left(k^{*}(\Phi)\right)\right)\right) \\
& =\operatorname{Tr}_{V}(F \circ A) .
\end{aligned}
$$

Proposition 2.18. ([B] §II.10.11) For $V$ finite-dimensional and $\Phi \in \operatorname{End}(V)^{*}$, the following are equivalent.
(1) $\Phi$ satisfies $\Phi(A \circ B)=\Phi(B \circ A)$ for all $A, B \in \operatorname{End}(V)$.
(2) There exists $\lambda \in \mathbb{K}$ such that $\Phi=\lambda \cdot T r_{V}$.

Proof. By Proposition 2.17, $\Phi(A \circ B)=\operatorname{Tr}_{V}(F \circ A \circ B)=\Phi(B \circ A)=$ $\operatorname{Tr}_{V}(F \circ B \circ A)$. By Lemma 2.6, $\operatorname{Tr}_{V}(F \circ B \circ A)=\operatorname{Tr}_{V}(A \circ B \circ F)$ for all $B$, so $\operatorname{Hom}(A, F)^{*}\left(T r_{V}\right)=\operatorname{Hom}(F, A)^{*}\left(T r_{V}\right)$. Then

$$
\begin{aligned}
\operatorname{Hom}(A, F)^{*}\left(\left(k^{*}\right)^{-1}\left(e\left(I d_{V}\right)\right)\right) & =\operatorname{Hom}(F, A)^{*}\left(\left(k^{*}\right)^{-1}\left(e\left(I d_{V}\right)\right)\right) \\
\left(k^{*}\right)^{-1}\left(e\left(\operatorname{Hom}(F, A)\left(I d_{V}\right)\right)\right) & =\left(k^{*}\right)^{-1}\left(e\left(\operatorname{Hom}(A, F)\left(I d_{V}\right)\right)\right) \\
\left(\left(k^{*}\right)^{-1} \circ e\right)(A \circ F) & =\left(\left(k^{*}\right)^{-1} \circ e\right)(F \circ A),
\end{aligned}
$$

so $A \circ F=F \circ A$ for all $A$, and so $F=\lambda \cdot I d_{V}$ by Claim 0.51 . The converse follows from Lemma 2.6.

Proposition 2.19. ([G] $]$ §IV.7) Suppose $\operatorname{Tr}_{V}\left(I d_{V}\right) \neq 0$, and that the operator $\Omega \in \operatorname{End}(\operatorname{End}(V))$ satisfies $\Omega(A \circ B)=(\Omega(A)) \circ(\Omega(B))$ for all $A, B$, and $\Omega\left(I d_{V}\right)=$ $I d_{V}$. Then $\operatorname{Tr}_{V}(\Omega(H))=\operatorname{Tr}_{V}(H)$ for all $H \in \operatorname{End}(V)$.

Proof.

$$
\begin{aligned}
\operatorname{Tr}_{V}(\Omega(A \circ B)) & \left.=\operatorname{Tr}_{V}((\Omega(A)) \circ(\Omega(B)))\right) \\
& =\operatorname{Tr}_{V}((\Omega(B)) \circ(\Omega(A))) \\
& =\operatorname{Tr}_{V}(\Omega(B \circ A)),
\end{aligned}
$$

so Proposition 2.18 applies to $\Omega^{*}\left(\operatorname{Tr}_{V}\right)$ and $\operatorname{Tr}_{V}(\Omega(H))=\lambda \cdot \operatorname{Tr}_{V}(H)$. The second property of $\Omega$ implies $\operatorname{Tr}_{V}\left(\Omega\left(I d_{V}\right)\right)=\operatorname{Tr}_{V}\left(I d_{V}\right)=\lambda \cdot \operatorname{Tr}_{V}\left(I d_{V}\right)$, so either $\operatorname{Tr}_{V}\left(I d_{V}\right)=0$, or $\lambda=1$ and $\operatorname{Tr}_{V}(\Omega(H))=\operatorname{Tr}_{V}(H)$ for all $H$.

Remark 2.20. The following Proposition is a generalization of Example 2.7, motivated by a property of a "line bundle."

Proposition 2.21. Suppose that $L$ is a finite-dimensional vector space, and that the evaluation map $E v_{L}: L^{*} \otimes L \rightarrow \mathbb{K}$ is invertible. Then $\operatorname{Tr}_{L}\left(I_{L}\right)=1$.

Proof. $k=k_{L L}$ and $e=e_{L L}$ are invertible. $E v_{L} \neq 0_{\left(L^{*} \otimes L\right)^{*}}$, so $I d_{L}=$ $e^{-1}\left(E v_{L}\right) \neq 0_{\operatorname{End}(L)} . \operatorname{Tr}_{L}=E v_{L} \circ k^{-1}$ is invertible, so $\operatorname{Tr}_{L}\left(I d_{L}\right) \neq 0$, and Example 2.9 applies. In particular, there is some $\beta \in \mathbb{K}$ so that $\beta \cdot \operatorname{Tr}_{L}\left(I d_{L}\right)=1$, and a map $Q_{1}^{\beta}: \mathbb{K} \rightarrow \operatorname{End}(L): \gamma \mapsto \beta \cdot \gamma \cdot I d_{L}$ as in Equation (2.3) so that $\operatorname{Tr}_{L} \circ Q_{1}^{\beta}=I d_{\mathbb{K}}$. It follows that

$$
\left(E v_{L} \circ k^{-1}\right) \circ Q_{1}^{\beta}=I d_{\mathbb{K}} \Longrightarrow Q_{1}^{\beta} \circ E v_{L}=k
$$

There is also some $v \in L$, and there is some $\phi \in L^{*}$, so that $E v_{L}(\phi \otimes v) \neq 0$, and so $\phi(v) \neq 0$, and $v \neq 0_{L}$. Then,

$$
k(\phi \otimes v)=\left(Q_{1}^{\beta} \circ E v_{L}\right)(\phi \otimes v)=\beta \cdot \phi(v) \cdot I d_{L}
$$

so

$$
(k(\phi \otimes v))(v)=\phi(v) \cdot v=\left(\beta \cdot \phi(v) \cdot I d_{L}\right)(v)=\beta \cdot \phi(v) \cdot v
$$

which implies $\beta=1$.
Remark 2.22. The following Proposition is proved in a different way by [AS $\left.{ }^{2}\right]$.
Proposition 2.23. Given $V$ finite-dimensional and any positive integer $\nu$, if $P_{1}: V \rightarrow V$ and $P_{2}: V \rightarrow V$ are any idempotents, then

$$
\operatorname{Tr}_{V}\left(\left(P_{1}-P_{2}\right)^{2 \nu+1}\right)=\operatorname{Tr}_{V}\left(P_{1}-P_{2}\right)
$$

Proof. The odd power refers to a composite $\left(P_{1}-P_{2}\right) \circ \cdots \circ\left(P_{1}-P_{2}\right)$. It can be shown by induction on $\nu$ that there exist constants $\alpha_{\nu, \iota} \in \mathbb{K}, \iota=1, \ldots, \nu$, so that the composite expands:

$$
\left(P_{1}-P_{2}\right)^{2 \nu+1}=P_{1}-P_{2}+\sum_{\iota=1}^{\nu} \alpha_{\nu, \iota} \cdot\left(\left(P_{1} \circ P_{2}\right)^{\iota} \circ P_{1}-\left(P_{2} \circ P_{1}\right)^{\iota} \circ P_{2}\right)
$$

The claim then follows from Lemma 2.6.

### 2.2. The generalized trace

An analogue of the trace $\operatorname{Tr}_{V}: \operatorname{End}(V) \rightarrow \mathbb{K}$ is the generalized trace, a map

$$
T r_{V ; U, W}: \operatorname{Hom}(V \otimes U, V \otimes W) \rightarrow \operatorname{Hom}(U, W)
$$

constructed in Definition 2.24.

### 2.2.1. Defining the generalized trace.

The following particular cases of the canonical $j$ maps will be used repeatedly:
$j_{1}: \operatorname{End}(V)^{*} \otimes \operatorname{End}(\operatorname{Hom}(U, W)) \rightarrow \operatorname{Hom}(\operatorname{End}(V) \otimes \operatorname{Hom}(U, W), \mathbb{K} \otimes \operatorname{Hom}(U, W))$

$$
j_{2}: \operatorname{End}(V) \otimes \operatorname{Hom}(U, W) \rightarrow \operatorname{Hom}(V \otimes U, V \otimes W)
$$

If $V$ is finite-dimensional, then both $j_{1}$ and $j_{2}$ are invertible, by Claim 1.33. Denote by $l_{1}$ the scalar multiplication map $\mathbb{K} \otimes \operatorname{Hom}(U, W) \rightarrow \operatorname{Hom}(U, W)$. The domain of $j_{1}$ contains the distinguished element $T r_{V} \otimes I d_{\operatorname{Hom}(U, W)}$.

Definition 2.24. For finite-dimensional $V$, define

$$
\operatorname{Tr}_{V ; U, W}=\left(\operatorname{Hom}\left(j_{2}^{-1}, l_{1}\right) \circ j_{1}\right)\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}(U, W)}\right)
$$

Note that the finite-dimensionality of $V$ is used in the Definition, since $j_{2}$ must be invertible, but $U$ and $W$ may be arbitrary vector spaces.

Example 2.25. A map of the form $j_{2}(A \otimes B): V \otimes U \rightarrow V \otimes W$, for $A: V \rightarrow V$ and $B: U \rightarrow W$, has trace
$\operatorname{Tr}_{V ; U, W}\left(j_{2}(A \otimes B)\right)=l_{1}\left(\left(j_{1}\left(\operatorname{Tr}_{V} \otimes I d_{\mathrm{Hom}(U, W)}\right)\right)(A \otimes B)\right)=\operatorname{Tr}_{V}(A) \cdot B$.
In the $V=\mathbb{K}$ case, the trace is an invertible map. Denote scalar multiplication maps $l_{W}: \mathbb{K} \otimes W \rightarrow W$ and $l_{U}: \mathbb{K} \otimes U \rightarrow U$.

Theorem 2.26. For any vector spaces $U, W$,

$$
T r_{\mathbb{K} ; U, W}=\operatorname{Hom}\left(l_{U}^{-1}, l_{W}\right): \operatorname{Hom}(\mathbb{K} \otimes U, \mathbb{K} \otimes W) \rightarrow \operatorname{Hom}(U, W)
$$

Proof. For any $\phi \in \mathbb{K}^{*}, F \in \operatorname{Hom}(U, W)$, the equation $(\phi(1) \cdot F) \circ l_{U}=$ $l_{W} \circ[\phi \otimes F]$ from Lemma 1.37 can be rewritten using $j_{2}: \mathbb{K}^{*} \otimes \operatorname{Hom}(U, W) \rightarrow$ $\operatorname{Hom}(\mathbb{K} \otimes U, \mathbb{K} \otimes W)$,

$$
\operatorname{Hom}\left(l_{U}^{-1}, l_{W}\right) \circ j_{2}=l_{1} \circ\left(j_{1}\left(\left(d_{\mathbb{K}}(1)\right) \otimes I d_{\operatorname{Hom}(U, W)}\right)\right): \phi \otimes F \mapsto \phi(1) \cdot F
$$

The equality follows from Example 2.7, where $\operatorname{Tr}_{\mathbb{K}}=d_{\mathbb{K}}(1)$ :

$$
\operatorname{Hom}\left(l_{U}^{-1}, l_{W}\right)=l_{1} \circ\left(j_{1}\left(\left(d_{\mathbb{K}}(1)\right) \otimes I d_{\operatorname{Hom}(U, W)}\right)\right) \circ j_{2}^{-1}=T r_{\mathbb{K} ; U, W}
$$

In the $U=W=\mathbb{K}$ case, the generalized trace is related to the scalar trace as in the following Theorem.

Theorem 2.27. For finite-dimensional $V$, the scalar multiplication map $l_{V}$ : $V \otimes \mathbb{K} \rightarrow V$, and any $H \in \operatorname{End}(V)$,

$$
\left(\operatorname{Tr}_{V ; \mathbb{K}, \mathbb{K}}\left(l_{V}^{-1} \circ H \circ l_{V}\right)\right)(1)=\operatorname{Tr}_{V}(H)
$$

Equivalently,

$$
\begin{equation*}
\operatorname{Tr}_{V ; \mathbb{K}, \mathbb{K}}\left(l_{V}^{-1} \circ H \circ l_{V}\right)=\operatorname{Tr}_{V}(H) \cdot I d_{\mathbb{K}} . \tag{2.6}
\end{equation*}
$$

Proof. In the following diagram,

the horizontal arrows are

$$
\begin{aligned}
a_{1} & =\left[I d_{\operatorname{End}(V)^{*}} \otimes \operatorname{Hom}\left(m, I d_{\mathbb{K}^{*}}\right)\right] \\
a_{2} & =\operatorname{Hom}\left(\left[I d_{\operatorname{End}(V)} \otimes m\right], I d_{\mathbb{K} \otimes \mathbb{K}^{*}}\right) \\
a_{3} & =\operatorname{Hom}\left(\left[I d_{\operatorname{End}(V)} \otimes m\right], I d_{\mathbb{K}^{*}}\right) \\
a_{4} & =\operatorname{Hom}\left(\operatorname{Hom}\left(I d_{V \otimes \mathbb{K}}, l_{V}\right), I d_{\mathbb{K}^{*}}\right) \\
a_{5} & =\left[I d_{\operatorname{End}(V)^{*}} \otimes \operatorname{Hom}\left(I d_{\mathbb{K}}, m\right)\right] \\
a_{6} & =\operatorname{Hom}\left(\operatorname{Hom}\left(l_{V}, I d_{V}\right), I d_{\mathbb{K}^{*}}\right),
\end{aligned}
$$

for $m: \mathbb{K} \rightarrow \mathbb{K}^{*}$ as in Definition 1.19, so that $m(\alpha): \lambda \mapsto \lambda \cdot \alpha$. So there is not much going on besides scalar multiplication, including the map $l_{2}: \operatorname{End}(V) \otimes \mathbb{K} \rightarrow$ $\operatorname{End}(V)$.

Starting with the element $\operatorname{Tr}_{V} \otimes I d_{\mathbb{K}^{*}}$ in the space in the upper left corner, its output under the composite map going downward and then right to the lower right corner is, using Definition 2.24, $\operatorname{Tr} r_{V ; \mathbb{K}, \mathbb{K}} \circ \operatorname{Hom}\left(l_{V}, l_{V}^{-1}\right)$, as in the LHS of the claim (2.6). The output in the path going right and then downward is
$k_{\operatorname{End}(V), \mathbb{K}^{*}}\left(\operatorname{Tr}_{V} \otimes\left(m^{-1} \circ I d_{\mathbb{K}^{*}} \circ m\right)\right)=k_{\operatorname{End}(V), \mathbb{K}^{*}}\left(\operatorname{Tr}_{V} \otimes I d_{\mathbb{K}}\right): H \mapsto \operatorname{Tr}_{V}(H) \cdot I d_{\mathbb{K}}$,
corresponding to the RHS of the claim. The claimed equality follows from just the commutativity of the diagram, without using any special properties of the trace $\operatorname{Tr}_{V}$.

The upper left block is commutative by Lemma 1.36 and the middle left block is commutative by Lemma 1.6. For the commutativity of the lower block, it is enough, by Lemma 1.6, to check this equality, for $A \in \operatorname{End}(V), \alpha, \beta \in \mathbb{K}, v \in V$ :

$$
\begin{aligned}
& \operatorname{Hom}\left(I d_{V \otimes \mathbb{K}}, l_{V}\right) \circ j_{2} \circ\left[I d_{\operatorname{End}(V)} \otimes m\right]: \\
A \otimes \alpha \mapsto & l_{V} \circ[A \otimes(m(\alpha))]: v \otimes \beta \mapsto l_{V}((A(v)) \otimes(\beta \cdot \alpha))=\beta \cdot \alpha \cdot A(v), \\
& \operatorname{Hom}\left(l_{V}, I d_{V}\right) \circ l_{2}: \\
A \otimes \alpha \mapsto & (\alpha \cdot A) \circ l_{V}: v \otimes \beta \mapsto(\alpha \cdot A)(\beta \cdot v) .
\end{aligned}
$$

Checking the commutativity of the block on the right, for $\Phi \in \operatorname{End}(V)^{*}, \phi \in \mathbb{K}^{*}$,

$$
\begin{aligned}
& \operatorname{Hom}\left(I d_{\operatorname{End}(V) \otimes \mathbb{K}}, l_{1}\right) \circ j_{3} \circ\left[I d_{\operatorname{End}(V)^{*}} \otimes \operatorname{Hom}\left(I d_{\mathbb{K}}, m\right)\right]: \\
& \Phi \otimes \phi \quad \mapsto \quad l_{1} \circ[\Phi \otimes(m \circ \phi)]: \\
& A \otimes \alpha \mapsto(\Phi(A)) \cdot(m(\phi(\alpha))): \beta \mapsto(\Phi(A)) \cdot \beta \cdot \phi(\alpha), \\
& \operatorname{Hom}\left(l_{2}, I d_{\mathbb{K}^{*}}\right) \circ k_{\operatorname{End}(V), \mathbb{K}^{*}}: \\
& \Phi \otimes \phi \quad \mapsto\left(k_{\operatorname{End}(V), \mathbb{K}^{*}}(\Phi \otimes \phi)\right) \circ l_{2}: \\
& A \otimes \alpha \mapsto \\
& \hline\left(k_{\operatorname{End}(V), \mathbb{K}^{*}}(\Phi \otimes \phi)\right)(\alpha \cdot A)=(\Phi(\alpha \cdot A)) \cdot \phi: \beta \mapsto(\Phi(\alpha \cdot A)) \cdot \phi(\beta) .
\end{aligned}
$$

### 2.2.2. Properties of the generalized trace.

The next Theorems in this Section are straightforward linear algebra identities for the generalized trace.

REmARK 2.28. Versions of some of the results in this Section are stated in a more general context of category theory, and given different proofs, in [Maltsiniotis] $\S 3.5$ or $[\mathbf{J S V}] \S 2$. The result of Theorem 2.26 is related to a property called "vanishing" by [JSV], and Theorem 2.29 and Theorem 2.30 are "naturality" properties ([JSV]).

An analogue of Lemma 2.6 applies to maps $A: V \rightarrow V^{\prime}$ and $B: V^{\prime} \otimes U \rightarrow$ $V \otimes W$, using the canonical maps

$$
\begin{aligned}
j_{U} & : \quad \operatorname{Hom}\left(V, V^{\prime}\right) \otimes \operatorname{End}(U) \rightarrow \operatorname{Hom}\left(V \otimes U, V^{\prime} \otimes U\right) \\
j_{W} & : \operatorname{Hom}\left(V, V^{\prime}\right) \otimes \operatorname{End}(W) \rightarrow \operatorname{Hom}\left(V \otimes W, V^{\prime} \otimes W\right)
\end{aligned}
$$

Theorem 2.29. For finite-dimensional $V, V^{\prime}$,

$$
\operatorname{Tr}_{V ; U, W}\left(B \circ\left(j_{U}\left(A \otimes I d_{U}\right)\right)\right)=\operatorname{Tr}_{V^{\prime} ; U, W}\left(\left(j_{W}\left(A \otimes I d_{W}\right)\right) \circ B\right) .
$$

Proof. In the following diagram,

the objects are

$$
\begin{aligned}
& M_{11}=\operatorname{End}(V)^{*} \otimes \operatorname{End}(\operatorname{Hom}(U, W)) \\
& M_{21}=\operatorname{Hom}(\operatorname{End}(V) \otimes \operatorname{Hom}(U, W), \mathbb{K} \otimes \operatorname{Hom}(U, W)) \\
& M_{31}=\operatorname{Hom}(\operatorname{Hom}(V \otimes U, V \otimes W), \operatorname{Hom}(U, W)) \\
& M_{12}=\operatorname{Hom}\left(V^{\prime}, V\right)^{*} \otimes \operatorname{End}(\operatorname{Hom}(U, W)) \\
& M_{22}=\operatorname{Hom}\left(\operatorname{Hom}\left(V^{\prime}, V\right) \otimes \operatorname{Hom}(U, W), \mathbb{K} \otimes \operatorname{Hom}(U, W)\right) \\
& M_{32}=\operatorname{Hom}\left(\operatorname{Hom}\left(V^{\prime} \otimes U, V \otimes W\right), \operatorname{Hom}(U, W)\right) \\
& M_{13}=\operatorname{End}\left(V^{\prime}\right)^{*} \otimes \operatorname{End}(\operatorname{Hom}(U, W)) \\
& M_{23}=\operatorname{Hom}\left(\operatorname{End}\left(V^{\prime}\right) \otimes \operatorname{Hom}(U, W), \mathbb{K} \otimes \operatorname{Hom}(U, W)\right) \\
& M_{33}=\operatorname{Hom}\left(\operatorname{Hom}\left(V^{\prime} \otimes U, V^{\prime} \otimes W\right), \operatorname{Hom}(U, W)\right),
\end{aligned}
$$

where the left and right columns are the maps from the definition of trace and the horizontal arrows in the diagram are

$$
\begin{aligned}
& a_{1}=\left[\operatorname{Hom}\left(A, I d_{V}\right)^{*} \otimes I d_{\operatorname{End}(\operatorname{Hom}(U, W))}\right] \\
& a_{2}=\left[\operatorname{Hom}\left(I d_{V^{\prime}}, A\right)^{*} \otimes I d_{\operatorname{End}(\operatorname{Hom}(U, W))}\right] \\
& a_{3}=\operatorname{Hom}\left(\left[\operatorname{Hom}\left(A, I d_{V}\right) \otimes I d_{\operatorname{Hom}(U, W)}\right], I d_{\mathbb{K} \otimes \operatorname{Hom}(U, W)}\right) \\
& a_{4}=\operatorname{Hom}\left(\left[\operatorname{Hom}\left(I d_{V^{\prime}}, A\right) \otimes I d_{\operatorname{Hom}(U, W)}\right], I d_{\mathbb{K} \otimes \operatorname{Hom}(U, W)}\right) \\
& a_{5}=\operatorname{Hom}\left(\operatorname{Hom}\left(j_{U}\left(A \otimes I d_{U}\right), I d_{V \otimes W)}\right), I d_{\operatorname{Hom}(U, W)}\right) \\
& a_{6}=\operatorname{Hom}\left(\operatorname{Hom}\left(I d_{V^{\prime} \otimes U}, j_{W}\left(A \otimes I d_{W}\right)\right), I d_{\operatorname{Hom}(U, W)}\right) .
\end{aligned}
$$

The two quantities in the statement of the Theorem are

$$
\begin{aligned}
\operatorname{Tr}_{V ; U, W}\left(B \circ\left(j_{U}\left(A \otimes I d_{U}\right)\right)\right) & =\left(a_{5}\left(\operatorname{Tr}_{V ; U, W}\right)\right)(B), \\
\operatorname{Tr}_{V^{\prime} ; U, W}\left(\left(j_{W}\left(A \otimes I d_{W}\right)\right) \circ B\right) & =\left(a_{6}\left(\operatorname{Tr}_{V^{\prime} ; U, W}\right)\right)(B) .
\end{aligned}
$$

Each of the squares in the diagram is commutative, by Lemma 1.6 and Lemma 1.36. By Lemma 2.6, $\operatorname{Hom}\left(A, I d_{V}\right)^{*}\left(\operatorname{Tr}_{V}\right)=\operatorname{Hom}\left(I d_{V^{\prime}}, A\right)^{*}\left(T r_{V^{\prime}}\right)$, so

$$
\begin{aligned}
a_{1}\left(T r_{V} \otimes I d_{\operatorname{Hom}(U, W)}\right) & =\left(\operatorname{Hom}\left(A, I d_{V}\right)^{*}\left(T r_{V}\right)\right) \otimes I d_{\operatorname{Hom}(U, W)} \\
& =\left(\operatorname{Hom}\left(I d_{V^{\prime}}, A\right)^{*}\left(\operatorname{Tr}_{V^{\prime}}\right)\right) \otimes I d_{\operatorname{Hom}(U, W)} \\
& =a_{2}\left(\operatorname{Tr}_{V^{\prime}} \otimes I d_{\operatorname{Hom}(U, W)}\right) .
\end{aligned}
$$

The Theorem follows from the commutativity of the diagram:

$$
\begin{aligned}
a_{5}\left(T r_{V ; U, W}\right) & =\left(a_{5} \circ \operatorname{Hom}\left(j_{2}^{-1}, l_{1}\right) \circ j_{1}\right)\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}(U, W)}\right) \\
& =\left(\operatorname{Hom}\left(\left(j_{2}^{\prime \prime}\right)^{-1}, l_{1}\right) \circ j_{1}^{\prime \prime} \circ a_{1}\right)\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}(U, W)}\right) \\
& =\left(\operatorname{Hom}\left(\left(j_{2}^{\prime \prime}\right)^{-1}, l_{1}\right) \circ j_{1}^{\prime \prime} \circ a_{2}\right)\left(\operatorname{Tr}_{V^{\prime}} \otimes I d_{\operatorname{Hom}(U, W)}\right) \\
& =\left(a_{6} \circ \operatorname{Hom}\left(\left(j_{2}^{\prime}\right)^{-1}, l_{1}\right) \circ j_{1}^{\prime}\right)\left(\operatorname{Tr}_{V^{\prime}} \otimes I d_{\operatorname{Hom}(U, W)}\right) \\
& =a_{6}\left(\operatorname{Tr}_{V^{\prime} ; U, W}\right) .
\end{aligned}
$$

The general strategy for the preceding proof will be repeated in some subsequent proofs. To derive an equality involving the generalized trace, a diagram is set up with the maps from Definition 2.24 on the left and right. The lowest row will be the desired theorem, and the top row is the "key step," which is either obvious, or which uses the previously derived properties of the scalar valued trace. There will be little choice in selecting canonical maps as horizontal arrows, and the commutativity of the diagram will give the theorem as a consequence of the key step. We remark that the canonical maps $m$, $n$, and $q$ will not be needed until Section 2.3.

THEOREM 2.30. If $V$ is finite-dimensional, then for any maps $A: V \otimes U \rightarrow$ $V \otimes W, B: W \rightarrow W^{\prime}$, and $C: U^{\prime} \rightarrow U$, the composite $\left[I d_{V} \otimes B\right] \circ A \circ\left[I d_{V} \otimes C\right]:$ $V \otimes U^{\prime} \rightarrow V \otimes W^{\prime}$ has trace

$$
\operatorname{Tr}_{V ; U^{\prime}, W^{\prime}}\left(\left[I d_{V} \otimes B\right] \circ A \circ\left[I d_{V} \otimes C\right]\right)=B \circ\left(\operatorname{Tr}_{V ; U, W}(A)\right) \circ C .
$$

Proof. In the following diagram,

the objects are

$$
\begin{aligned}
& M_{11}=\operatorname{End}(V)^{*} \otimes \operatorname{End}(\operatorname{Hom}(U, W)) \\
& M_{21}=\operatorname{Hom}(\operatorname{End}(V) \otimes \operatorname{Hom}(U, W), \mathbb{K} \otimes \operatorname{Hom}(U, W)) \\
& M_{31}=\operatorname{Hom}(\operatorname{Hom}(V \otimes U, V \otimes W), \operatorname{Hom}(U, W)) \\
& M_{12}=\operatorname{End}(V)^{*} \otimes \operatorname{Hom}\left(\operatorname{Hom}(U, W), \operatorname{Hom}\left(U^{\prime}, W^{\prime}\right)\right) \\
& M_{22}=\operatorname{Hom}\left(\operatorname{End}(V) \otimes \operatorname{Hom}(U, W), \mathbb{K} \otimes \operatorname{Hom}\left(U^{\prime}, W^{\prime}\right)\right) \\
& M_{32}=\operatorname{Hom}\left(\operatorname{Hom}(V \otimes U, V \otimes W), \operatorname{Hom}\left(U^{\prime}, W^{\prime}\right)\right) \\
& M_{13}=\operatorname{End}(V)^{*} \otimes \operatorname{End}\left(\operatorname{Hom}\left(U^{\prime}, W^{\prime}\right)\right) \\
& M_{23}=\operatorname{Hom}\left(\operatorname{End}(V) \otimes \operatorname{Hom}\left(U^{\prime}, W^{\prime}\right), \mathbb{K} \otimes \operatorname{Hom}\left(U^{\prime}, W^{\prime}\right)\right) \\
& M_{33}=\operatorname{Hom}\left(\operatorname{Hom}\left(V \otimes U^{\prime}, V \otimes W^{\prime}\right), \operatorname{Hom}\left(U^{\prime}, W^{\prime}\right)\right),
\end{aligned}
$$

where the left and right columns are the maps from the definition of trace and the horizontal arrows in the diagram are

$$
\begin{aligned}
a_{1} & =\left[I d_{\operatorname{End}(V)^{*}} \otimes \operatorname{Hom}\left(I d_{\operatorname{Hom}(U, W)}, \operatorname{Hom}(C, B)\right)\right] \\
a_{2} & =\left[I d_{\operatorname{End}(V)^{*}} \otimes \operatorname{Hom}\left(\operatorname{Hom}(C, B), I d_{\operatorname{Hom}\left(U^{\prime}, W^{\prime}\right)}\right)\right] \\
a_{3} & =\operatorname{Hom}\left(I d_{\operatorname{End}(V) \otimes \operatorname{Hom}(U, W)},\left[I d_{\mathbb{K}} \otimes \operatorname{Hom}(C, B)\right]\right) \\
a_{4} & =\operatorname{Hom}\left(\left[I d_{\operatorname{End}(V)} \otimes \operatorname{Hom}(C, B)\right], I d_{\mathbb{K} \otimes \operatorname{Hom}\left(U^{\prime}, W^{\prime}\right)}\right) \\
a_{5} & =\operatorname{Hom}\left(I d_{\operatorname{Hom}(V \otimes U, V \otimes W)}, \operatorname{Hom}(C, B)\right) \\
a_{6} & =\operatorname{Hom}\left(\operatorname{Hom}\left(\left[I d_{V} \otimes C\right],\left[I d_{V} \otimes B\right]\right), I d_{\operatorname{Hom}\left(U^{\prime}, W^{\prime}\right)}\right) .
\end{aligned}
$$

The two quantities in the statement of the Theorem are

$$
\begin{aligned}
\operatorname{Tr}_{V ; U^{\prime}, W^{\prime}}\left(\left[I d_{V} \otimes B\right] \circ A \circ\left[I d_{V} \otimes C\right]\right) & =\left(a_{6}\left(\operatorname{Tr}_{V ; U^{\prime}, W^{\prime}}\right)\right)(A) \\
B \circ\left(\operatorname{Tr}_{V ; U, W}(A)\right) \circ C & =\left(a_{5}\left(\operatorname{Tr}_{V ; U, W}\right)\right)(A) .
\end{aligned}
$$

Squares except the lower left commute by Lemma 1.6 and Lemma 1.36; for the remaining square, let $\lambda \in \mathbb{K}, E \in \operatorname{Hom}(U, W)$ :

$$
\begin{aligned}
\left(l_{1}^{\prime} \circ\left[I d_{\mathbb{K}} \otimes \operatorname{Hom}(C, B)\right]\right)(\lambda \otimes E) & =l_{1}^{\prime}(\lambda \otimes(B \circ E \circ C))=\lambda \cdot(B \circ E \circ C) \\
\left(\operatorname{Hom}(C, B) \circ l_{1}\right)(\lambda \otimes E) & =B \circ(\lambda \cdot E) \circ C=\lambda \cdot(B \circ E \circ C) .
\end{aligned}
$$

The "key step" uses a property of the identity map, and not any properties of the trace:

$$
a_{1}\left(T r_{V} \otimes I d_{\operatorname{Hom}(U, W)}\right)=T r_{V} \otimes \operatorname{Hom}(C, B)=a_{2}\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}\left(U^{\prime}, W^{\prime}\right)}\right)
$$

The Theorem follows from the commutativity of the diagram:

$$
\begin{aligned}
a_{5}\left(\operatorname{Tr}_{V ; U, W}\right) & =\left(a_{5} \circ \operatorname{Hom}\left(j_{2}^{-1}, l_{1}\right) \circ j_{1}\right)\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}(U, W)}\right) \\
& =\left(\operatorname{Hom}\left(j_{2}^{-1}, l_{1}^{\prime}\right) \circ j_{1}^{\prime \prime} \circ a_{1}\right)\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}(U, W)}\right) \\
& =\left(\operatorname{Hom}\left(j_{2}^{-1}, l_{1}^{\prime}\right) \circ j_{1}^{\prime \prime} \circ a_{2}\right)\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}\left(U^{\prime}, W^{\prime}\right)}\right) \\
& =\left(a_{6} \circ \operatorname{Hom}\left(\left(j_{2}^{\prime}\right)^{-1}, l_{1}^{\prime}\right) \circ j_{1}^{\prime}\right)\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}\left(U^{\prime}, W^{\prime}\right)}\right) \\
& =a_{6}\left(\operatorname{Tr}_{V ; U^{\prime}, W^{\prime}}\right)
\end{aligned}
$$

Corollary 2.31. If $V$ and $V^{\prime}$ are finite-dimensional then for any maps $A$ : $V \rightarrow V^{\prime}, B: W \rightarrow W^{\prime}, C: U^{\prime} \rightarrow U$, the following diagram is commutative.


Proof. This follows from Theorem 2.29 and Theorem 2.30.

Lemma 2.32. The following diagram is commutative.

$$
\begin{aligned}
& V_{1}^{*} \otimes V_{2}^{*} \otimes W_{1} \otimes W_{2} \longrightarrow V_{1}^{*} \otimes W_{1} \otimes V_{2}^{*} \otimes W_{2} \\
& \downarrow\left[j \otimes I d_{\left.W_{1} \otimes W_{2}\right]} \quad \downarrow^{\left[k_{V_{1} W_{1}} \otimes k_{V_{2} W_{2}}\right]}\right. \\
& \operatorname{Hom}\left(V_{1} \otimes V_{2}, \mathbb{K} \otimes \mathbb{K}\right) \otimes W_{1} \otimes W_{2} \quad \operatorname{Hom}\left(V_{1}, W_{1}\right) \otimes \operatorname{Hom}\left(V_{2}, W_{2}\right) \\
& \begin{array}{c}
\downarrow \begin{array}{l}
{\left[\operatorname{Hom}\left(I d_{V_{1} \otimes V_{2}}, l\right) \otimes I d_{W_{1} \otimes W_{2}}\right]}
\end{array} \\
\left(V_{1} \otimes V_{2}\right)^{*} \otimes W_{1} \otimes W_{2} \xrightarrow{k_{V_{1} \otimes V_{2}, W_{1} \otimes W_{2}}} \boldsymbol{H} \xrightarrow{j} \operatorname{Hom}\left(V_{1} \otimes V_{2}, W_{1} \otimes W_{2}\right)
\end{array}
\end{aligned}
$$

Proof. The map $s$ switches the middle two factors of the tensor product (as in Example 1.28), and $l$ is multiplication of elements of $\mathbb{K}$.

$$
\begin{aligned}
\phi_{1} \otimes \phi_{2} \otimes w_{1} \otimes w_{2} & \mapsto\left(j \circ\left[k_{V_{1} W_{1}} \otimes k_{V_{2} W_{2}}\right] \circ s\right)\left(\phi_{1} \otimes \phi_{2} \otimes w_{1} \otimes w_{2}\right) \\
& =\left[\left(k_{V_{1} W_{1}}\left(\phi_{1} \otimes w_{1}\right)\right) \otimes\left(k_{V_{2} W_{2}}\left(\phi_{2} \otimes w_{2}\right)\right)\right]: \\
v_{1} \otimes v_{2} & \mapsto\left(\left(\phi\left(v_{1}\right)\right) \cdot w_{1}\right) \otimes\left(\left(\phi_{2}\left(v_{2}\right)\right) \cdot w_{2}\right), \\
\phi_{1} \otimes \phi_{2} \otimes w_{1} \otimes w_{2} & \mapsto k_{V_{1} \otimes V_{2}, W_{1} \otimes W_{2}}\left(\left(l \circ\left[\phi_{1} \otimes \phi_{2}\right]\right) \otimes w_{1} \otimes w_{2}\right): \\
v_{1} \otimes v_{2} & \mapsto \phi_{1}\left(v_{1}\right) \cdot \phi_{2}\left(v_{2}\right) \cdot w_{1} \otimes w_{2} .
\end{aligned}
$$

REmARK 2.33. The above result appears in $[\mathbf{K}] \S$ II.2, and is related to a matrix algebra equation in [Magnus] §3.6.

Theorem 2.34. For finite-dimensional $V$ and $U$, and $A: V \otimes U \rightarrow V \otimes U$,

$$
\operatorname{Tr}_{U}\left(\operatorname{Tr}_{V ; U, U}(A)\right)=\operatorname{Tr}_{V \otimes U}(A)
$$

Proof. As in Lemma 2.6, the maps $k_{V V}$ and $k_{U U}$ are abbreviated $k$ and $k^{\prime}$, and the corresponding map for $V \otimes U$ is denoted $k^{\prime \prime}:(V \otimes U)^{*} \otimes V \otimes U \rightarrow \operatorname{End}(V \otimes U)$. By Lemma 2.32, these $k$ maps are related by the following commutative diagram.


The composite of maps in the left column is abbreviated $a_{1}$. In particular, since $U$ and $V$ are assumed finite-dimensional, all the arrows in the square are invertible.

In the following diagram,

the horizontal arrows are

$$
\begin{aligned}
a_{2} & =\left[k^{*} \otimes \operatorname{Hom}\left(k^{\prime},\left(k^{\prime}\right)^{-1}\right)\right] \\
a_{2}^{-1} & =\left[\left(k^{*}\right)^{-1} \otimes \operatorname{Hom}\left(\left(k^{\prime}\right)^{-1}, k^{\prime}\right)\right] \\
a_{3} & =\operatorname{Hom}\left(\left[k \otimes k^{\prime}\right],\left[I d_{\mathbb{K}} \otimes\left(k^{\prime}\right)^{-1}\right]\right) \\
a_{4} & =\operatorname{Hom}\left(k^{\prime \prime}, I d_{\operatorname{End}(U)}\right),
\end{aligned}
$$

and the statement of the Theorem is that

$$
\operatorname{Hom}\left(I d_{\operatorname{End}(V \otimes U)}, T r_{U}\right)\left(T r_{V ; U, U}\right)=\operatorname{Tr}_{V \otimes U}
$$

The upper square is commutative by Lemma 1.36, and Lemma 1.6 applies easily to the commutativity of the lower square, and to that of the middle square using $k^{\prime \prime} \circ a_{1}=j_{2} \circ\left[k \otimes k^{\prime}\right]$, from the first diagram, and $l_{1} \circ\left[I d_{\mathbb{K}} \otimes k^{\prime}\right]=k^{\prime} \circ l_{1}^{\prime}$, by Lemma 1.37.

The commutativity of this square,


$$
\begin{aligned}
\left(E v_{V \otimes U} \circ a_{1}\right)(\phi \otimes v \otimes \xi \otimes u) & =E v_{V \otimes U}((l \circ[\phi \otimes \xi]) \otimes v \otimes u) \\
& =\phi(v) \cdot \xi(u) \\
\left(E v_{U} \circ l_{1}^{\prime} \circ\left(j_{1}^{\prime}\left(E v_{V} \otimes I d_{U^{*} \otimes U}\right)\right)\right)(\phi \otimes v \otimes \xi \otimes u) & =E v_{U}(\phi(v) \cdot \xi \otimes u) \\
& =\phi(v) \cdot \xi(u),
\end{aligned}
$$

implies that the distinguished elements $E v_{V} \otimes I d_{U^{*} \otimes U}$ and $E v_{V \otimes U}$ are related by the right column of maps in the second diagram:

$$
\begin{aligned}
E v_{V} \otimes I d_{U^{*} \otimes U} & \mapsto T r_{U} \circ k^{\prime} \circ l_{1}^{\prime} \circ\left(j_{1}^{\prime}\left(E v_{V} \otimes I d_{U^{*} \otimes U}\right)\right) \circ a_{1}^{-1} \\
& =E v_{U} \circ l_{1}^{\prime} \circ\left(j_{1}^{\prime}\left(E v_{V} \otimes I d_{U^{*} \otimes U}\right)\right) \circ a_{1}^{-1} \\
& =E v_{V \otimes U} .
\end{aligned}
$$

The above equation used the definition of $T r_{U}$. Along the top row, the key step uses the definition of $T r_{V}$ :

$$
a_{2}^{-1}\left(E v_{V} \otimes I d_{U^{*} \otimes U}\right)=\left(\left(k^{*}\right)^{-1}\left(E v_{V}\right)\right) \otimes\left(k^{\prime} \circ I d_{U^{*} \otimes U} \circ\left(k^{\prime}\right)^{-1}\right)=T r_{V} \otimes I d_{\operatorname{End}(U)}
$$

The Theorem follows:

$$
\begin{aligned}
T r_{U} \circ T r_{V ; U, U} & =\left(\operatorname{Hom}\left(I d_{\operatorname{End}(V \otimes U)}, T r_{U}\right) \circ \operatorname{Hom}\left(j_{2}^{-1}, l_{1}\right) \circ j_{1}\right)\left(T r_{V} \otimes I d_{\operatorname{End}(U)}\right) \\
& =\left(\operatorname{Hom}\left(\operatorname{Id} d_{\operatorname{End}(V \otimes U)}, T r_{U}\right) \circ \operatorname{Hom}\left(j_{2}^{-1}, l_{1}\right) \circ j_{1} \circ a_{2}^{-1}\right)\left(E v_{V} \otimes I d_{U^{*} \otimes U}\right) \\
& =\left(k^{\prime \prime *}\right)^{-1}\left(E v_{V \otimes U}\right) \\
& =\operatorname{Tr}_{V \otimes U}
\end{aligned}
$$

Remark 2.35. The previous Theorem appears in slightly different form in [K] §II.3. The following Corollary is a well-known identity for the (scalar valued) trace ([B] §II.4.4, [Magnus] §1.10, [K] §II.6).

Corollary 2.36. For $A: V \rightarrow V, B: U \rightarrow U$,

$$
\operatorname{Tr}_{V \otimes U}\left(j_{2}(A \otimes B)\right)=\operatorname{Tr}_{V}(A) \cdot \operatorname{Tr}_{U}(B)
$$

Proof. As in Example 2.25,

$$
\begin{aligned}
\operatorname{Tr}_{V \otimes U}\left(j_{2}(A \otimes B)\right) & =\operatorname{Tr}_{U}\left(\operatorname{Tr}_{V ; U, U}\left(j_{2}(A \otimes B)\right)\right) \\
& =\operatorname{Tr}_{U}\left(\operatorname{Tr}_{V}(A) \cdot B\right) \\
& =\operatorname{Tr}_{V}(A) \cdot \operatorname{Tr}_{U}(B) .
\end{aligned}
$$

The result of Corollary 2.36 could also be proved directly using methods similar to the previous proof, and could be stated as the equality

$$
j_{2}^{*}\left(T r_{V \otimes U}\right)=\left(\operatorname{Hom}\left(I d_{\operatorname{End}(V) \otimes \operatorname{End}(U)}, l\right) \circ j\right)\left(\operatorname{Tr}_{V} \otimes \operatorname{Tr}_{U}\right) \in(\operatorname{End}(V) \otimes \operatorname{End}(U))^{*}
$$

or

$$
T r_{V \otimes U} \circ j_{2}=l \circ\left[\operatorname{Tr}_{V} \otimes \operatorname{Tr}_{U}\right]
$$

Corollary 2.37. ([ $\left.\mathbf{G}_{2}\right] \S$ I.5) For $A: V \rightarrow V, B: U \rightarrow U$,

$$
\operatorname{Tr}_{\operatorname{Hom}(V, U)}(\operatorname{Hom}(A, B))=\operatorname{Tr}_{V}(A) \cdot \operatorname{Tr}_{U}(B)
$$

Proof. By Lemma 1.57, $\operatorname{Hom}(A, B)=k_{V U} \circ\left[A^{*} \otimes B\right] \circ k_{V U}^{-1}$, so Lemma 2.6, Corollary 2.36 , and Lemma 2.5 apply:

$$
\begin{aligned}
\operatorname{Tr}_{\operatorname{Hom}(V, U)}(\operatorname{Hom}(A, B)) & =\operatorname{Tr}_{\operatorname{Hom}(V, U)}\left(k_{V U} \circ\left[A^{*} \otimes B\right] \circ k_{V U}^{-1}\right) \\
& =\operatorname{Tr}_{V^{*} \otimes U}\left(\left[A^{*} \otimes B\right]\right) \\
& =\operatorname{Tr}_{V^{*}}\left(A^{*}\right) \cdot \operatorname{Tr}_{U}(B) \\
& =\operatorname{Tr}_{V}(A) \cdot \operatorname{Tr}_{U}(B) .
\end{aligned}
$$

Theorem 2.38. For finite-dimensional $V$ and $V^{\prime}$, and $A: V \otimes V^{\prime} \otimes U \rightarrow$ $V \otimes V^{\prime} \otimes W$,

$$
\operatorname{Tr}_{V \otimes V^{\prime} ; U, W}(A)=\operatorname{Tr}_{V^{\prime} ; U, W}\left(\operatorname{Tr}_{V ; V^{\prime} \otimes U, V^{\prime} \otimes W}(A)\right)
$$

Proof. In the following diagram,

the objects are

$$
\begin{aligned}
& M_{11}=\operatorname{End}\left(V^{\prime}\right)^{*} \otimes \operatorname{End}(\operatorname{Hom}(U, W)) \\
& M_{21}=\operatorname{Hom}\left(\operatorname{End}\left(V^{\prime}\right) \otimes \operatorname{Hom}(U, W), \mathbb{K} \otimes \operatorname{Hom}(U, W)\right) \\
& M_{31}=\operatorname{Hom}\left(\operatorname{Hom}\left(V^{\prime} \otimes U, V^{\prime} \otimes W\right), \operatorname{Hom}(U, W)\right) \\
& M_{12}=\operatorname{End}\left(V \otimes V^{\prime}\right)^{*} \otimes \operatorname{End}(\operatorname{Hom}(U, W)) \\
& M_{22}=\operatorname{Hom}\left(\operatorname{End}\left(V \otimes V^{\prime}\right) \otimes \operatorname{Hom}(U, W), \mathbb{K} \otimes \operatorname{Hom}(U, W)\right) \\
& M_{32}=\operatorname{Hom}\left(\operatorname{Hom}\left(V \otimes V^{\prime} \otimes U, V \otimes V^{\prime} \otimes W\right), \operatorname{Hom}(U, W)\right)
\end{aligned}
$$

the horizontal arrows are

$$
\begin{aligned}
a_{1} & =\left[\left(\operatorname{Tr}_{V ; V^{\prime}, V^{\prime}}\right)^{*} \otimes I d_{\operatorname{End}(\operatorname{Hom}(U, W))}\right] \\
a_{2} & =\operatorname{Hom}\left(\left[\operatorname{Tr}_{V ; V^{\prime}, V^{\prime}} \otimes I d_{\operatorname{Hom}(U, W)}\right], I d_{\mathbb{K} \otimes \operatorname{Hom}(U, W)}\right) \\
a_{3} & =\operatorname{Hom}\left(\operatorname{Tr}_{V ; V^{\prime} \otimes U, V^{\prime} \otimes W}, \operatorname{Id} d_{\operatorname{Hom}(U, W)}\right),
\end{aligned}
$$

and the statement of the Theorem is that

$$
a_{3}\left(\operatorname{Tr}_{V^{\prime} ; U, W}\right)=\operatorname{Tr}_{V \otimes V^{\prime} ; U, W}
$$

The commutativity of this square,

is easy to check, and together with that of the diagram:


$$
\begin{aligned}
D \otimes E \otimes F & \mapsto\left(j_{2}^{\prime} \circ\left[\left(\operatorname{Tr}_{V ; V^{\prime}, V^{\prime}} \circ j_{2}^{\prime \prime \prime}\right) \otimes I d_{\operatorname{Hom}(U, W)}\right]\right)(D \otimes E \otimes F) \\
& =j_{2}^{\prime}\left(\left(\operatorname{Tr}_{V ; V^{\prime}, V^{\prime}}\left(j_{2}^{\prime \prime \prime}(D \otimes E)\right)\right) \otimes F\right) \\
& =\left(\operatorname{Tr}_{V}(D)\right) \cdot j_{2}^{\prime}(E \otimes F) \\
D \otimes E \otimes F & \mapsto\left(l_{1}^{\prime} \circ\left(j\left(T r_{V} \otimes j_{2}^{\prime}\right)\right)\right)(D \otimes E \otimes F) \\
& =l_{1}^{\prime}\left(\left(\operatorname{Tr}_{V}(D)\right) \otimes\left(j_{2}^{\prime}(E \otimes F)\right)\right) \\
& =\left(\operatorname{Tr}_{V}(D)\right) \cdot j_{2}^{\prime}(E \otimes F)
\end{aligned}
$$

implies

$$
\begin{aligned}
\operatorname{Tr}_{V ; V^{\prime} \otimes U, V^{\prime} \otimes W} \circ j_{2}^{\prime \prime}= & l_{1}^{\prime} \circ\left(j_{1}\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}\left(V^{\prime} \otimes U, V^{\prime} \otimes W\right)}\right)\right) \circ j_{2}^{-1} \circ j_{2}^{\prime \prime} \\
= & l_{1}^{\prime} \circ\left(j_{1}\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}\left(V^{\prime} \otimes U, V^{\prime} \otimes W\right)}\right)\right) \\
& \circ\left[\operatorname{Id}_{\operatorname{End}(V)} \otimes j_{2}^{\prime}\right] \circ\left[\left(j_{2}^{\prime \prime \prime}\right)^{-1} \otimes I d_{\operatorname{Hom}(U, W)}\right] \\
= & j_{2}^{\prime} \circ\left[\operatorname{Tr}_{V ; V^{\prime}, V^{\prime}} \otimes I d_{\operatorname{Hom}(U, W)}\right]
\end{aligned}
$$

which is what is needed to show that the lower square of the first diagram is commutative. Its upper square is commutative by Lemma 1.36, and the distinguished elements in the top row are related by Theorem 2.34:
$a_{1}\left(\operatorname{Tr}_{V^{\prime}} \otimes I d_{\mathrm{Hom}(U, W)}\right)=\left(\operatorname{Tr}_{V^{\prime}} \circ \operatorname{Tr}_{V ; V^{\prime}, V^{\prime}}\right) \otimes I d_{\mathrm{Hom}(U, W)}=\operatorname{Tr}_{V \otimes V^{\prime}} \otimes I d_{\mathrm{Hom}(U, W)}$.
The Theorem follows:

$$
\begin{aligned}
a_{3}\left(\operatorname{Tr}_{V ; U, W}\right) & =\left(a_{3} \circ \operatorname{Hom}\left(\left(j_{2}^{\prime}\right)^{-1}, l_{1}\right) \circ j_{1}^{\prime}\right)\left(\operatorname{Tr}_{V^{\prime}} \otimes I d_{\operatorname{Hom}(U, W)}\right) \\
& =\left(\operatorname{Hom}\left(\left(j_{2}^{\prime \prime}\right)^{-1}, l_{1}\right) \circ j_{1}^{\prime \prime} \circ a_{1}\right)\left(\operatorname{Tr}_{V^{\prime}} \otimes I d_{\operatorname{Hom}(U, W)}\right) \\
& =\left(\operatorname{Hom}\left(\left(j_{2}^{\prime \prime}\right)^{-1}, l_{1}\right) \circ j_{1}^{\prime \prime}\right)\left(\operatorname{Tr}_{V \otimes V^{\prime}} \otimes I d_{\operatorname{Hom}(U, W)}\right) \\
& =\operatorname{Tr}_{V \otimes V^{\prime} ; U, W} .
\end{aligned}
$$

Remark 2.39. The result of the above Theorem is another "vanishing" property of the generalized trace ([JSV]).

The maps

$$
\begin{aligned}
j_{3} & : \operatorname{Hom}\left(V_{1} \otimes U_{1}, V_{1} \otimes W_{1}\right) \otimes \operatorname{Hom}\left(V_{2} \otimes U_{2}, V_{2} \otimes W_{2}\right) \\
& \rightarrow \operatorname{Hom}\left(V_{1} \otimes U_{1} \otimes V_{2} \otimes U_{2}, V_{1} \otimes W_{1} \otimes V_{2} \otimes W_{2}\right), \\
j_{4} & : \operatorname{Hom}\left(U_{1}, W_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, W_{2}\right) \rightarrow \operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)
\end{aligned}
$$

appear in the following Theorem comparing the trace of a tensor product to the tensor product of traces. There are also some switching maps, as in Theorem 2.34,

$$
\begin{array}{r}
s_{1}: V_{1} \otimes W_{1} \otimes V_{2} \otimes W_{2} \rightarrow V_{1} \otimes V_{2} \otimes W_{1} \otimes W_{2} \\
\quad s_{2}: V_{1} \otimes V_{2} \otimes U_{1} \otimes U_{2} \rightarrow V_{1} \otimes U_{1} \otimes V_{2} \otimes U_{2} .
\end{array}
$$

THEOREM 2.40. For finite-dimensional $V_{1}, V_{2}$, and maps $A: V_{1} \otimes U_{1} \rightarrow V_{1} \otimes W_{1}$ and $B: V_{2} \otimes U_{2} \rightarrow V_{2} \otimes W_{2}$,
$\operatorname{Tr}_{V_{1} \otimes V_{2} ; U_{1} \otimes U_{2}, W_{1} \otimes W_{2}}\left(s_{1} \circ\left(j_{3}(A \otimes B)\right) \circ s_{2}\right)=j_{4}\left(\left(\operatorname{Tr}_{V_{1} ; U_{1}, W_{1}}(A)\right) \otimes\left(\operatorname{Tr}_{V_{2} ; U_{2}, W_{2}}(B)\right)\right)$.

Proof. In the following diagram,

the objects are

$$
\begin{aligned}
M_{11}= & \operatorname{End}\left(V_{1} \otimes V_{2}\right)^{*} \otimes \operatorname{End}\left(\operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)\right) \\
M_{21}= & \operatorname{Hom}\left(\operatorname{End}\left(V_{1} \otimes V_{2}\right) \otimes \operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)\right. \\
& \left.\mathbb{K} \otimes \operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)\right) \\
M_{31}= & \operatorname{Hom}\left(\operatorname{Hom}\left(V_{1} \otimes V_{2} \otimes U_{1} \otimes U_{2}, V_{1} \otimes V_{2} \otimes W_{1} \otimes W_{2}\right)\right. \\
& \left.\operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)\right) \\
M_{12}= & \left(\operatorname{End}\left(V_{1}\right) \otimes \operatorname{End}\left(V_{2}\right)\right)^{*} \otimes \\
& \operatorname{Hom}\left(\operatorname{Hom}\left(U_{1}, W_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, W_{2}\right), \operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)\right) \\
M_{22}= & \operatorname{Hom}\left(\operatorname{End}\left(V_{1}\right) \otimes \operatorname{End}\left(V_{2}\right) \otimes \operatorname{Hom}\left(U_{1}, W_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, W_{2}\right),\right. \\
& \left.\mathbb{K} \otimes \operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)\right) \\
M_{32}= & \operatorname{Hom}\left(\operatorname{Hom}\left(V_{1} \otimes U_{1}, V_{1} \otimes W_{1}\right) \otimes \operatorname{Hom}\left(V_{2} \otimes U_{2}, V_{2} \otimes W_{2}\right),\right. \\
& \left.\operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)\right) \\
M_{13}= & \operatorname{Hom}\left(\operatorname{End}\left(V_{1}\right) \otimes \operatorname{End}\left(V_{2}\right), \mathbb{K} \otimes \mathbb{K}\right) \otimes \operatorname{End}\left(\operatorname{Hom}\left(U_{1}, W_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, W_{2}\right)\right) \\
M_{23}= & \operatorname{Hom}\left(\operatorname{End}\left(V_{1}\right) \otimes \operatorname{End}\left(V_{2}\right) \otimes \operatorname{Hom}\left(U_{1}, W_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, W_{2}\right),\right. \\
& \left.\mathbb{K} \otimes \mathbb{K} \otimes \operatorname{Hom}\left(U_{1}, W_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, W_{2}\right)\right) \\
M_{33}= & \operatorname{Hom}\left(\operatorname{Hom}\left(V_{1} \otimes U_{1}, V_{1} \otimes W_{1}\right) \otimes \operatorname{Hom}\left(V_{2} \otimes U_{2}, V_{2} \otimes W_{2}\right),\right. \\
& \left.\operatorname{Hom}\left(U_{1}, W_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, W_{2}\right)\right) \\
M_{14}= & \operatorname{End}\left(V_{1}\right)^{*} \otimes \operatorname{End}\left(\operatorname{Hom}\left(U_{1}, W_{1}\right)\right) \otimes \operatorname{End}\left(V_{2}\right)^{*} \otimes \operatorname{End}\left(\operatorname{Hom}\left(U_{2}, W_{2}\right)\right) \\
M_{24}= & \operatorname{Hom}\left(\operatorname{End}\left(V_{1}\right) \otimes \operatorname{Hom}\left(U_{1}, W_{1}\right), \mathbb{K} \otimes \operatorname{Hom}\left(U_{1}, W_{1}\right)\right) \otimes \\
& \operatorname{Hom}\left(\operatorname{End}\left(V_{2}\right) \otimes \operatorname{Hom}\left(U_{2}, W_{2}\right), \mathbb{K} \otimes \operatorname{Hom}\left(U_{2}, W_{2}\right)\right) \\
M_{34}= & \operatorname{Hom}\left(\operatorname{Hom}\left(V_{1} \otimes U_{1}, V_{1} \otimes W_{1}\right), \operatorname{Hom}\left(U_{1}, W_{1}\right)\right) \otimes \\
& \operatorname{Hom}\left(\operatorname{Hom}\left(V_{2} \otimes U_{2}, V_{2} \otimes W_{2}\right), \operatorname{Hom}\left(U_{2}, W_{2}\right)\right) ;
\end{aligned}
$$

the left, right columns define $\operatorname{Tr}_{V_{1} \otimes V_{2} ; U_{1} \otimes U_{2}, W_{1} \otimes W_{2}}$ and $\operatorname{Tr}_{V_{1} ; U_{1}, W_{1}} \otimes \operatorname{Tr}_{V_{2} ; U_{2}, W_{2}}$. The arrows are

$$
\begin{aligned}
& a_{1}=\left[\left(j_{2}^{\prime}\right)^{*} \otimes \operatorname{Hom}\left(j_{4}, \operatorname{Id} d_{\operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)}\right)\right] \\
& a_{2}=\left[\operatorname{Hom}\left(I d_{\operatorname{End}\left(V_{1}\right) \otimes \operatorname{End}\left(V_{2}\right)}, l_{\mathbb{K}}\right) \otimes \operatorname{Hom}\left(I d_{\operatorname{Hom}\left(U_{1}, W_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, W_{2}\right)}, j_{4}\right)\right] \\
& a_{3}=\operatorname{Hom}\left(\left[j_{2}^{\prime} \otimes j_{4}\right], I d_{\mathbb{K} \otimes \operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)}\right) \\
& a_{4}=\operatorname{Hom}\left(I d_{\left.\operatorname{End}\left(V_{1}\right) \otimes \operatorname{End}\left(V_{2}\right) \otimes \operatorname{Hom}\left(U_{1}, W_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, W_{2}\right),\left[l_{\mathbb{K}} \otimes j_{4}\right]\right)}^{\operatorname{Han}}\right. \\
& a_{5}=\operatorname{Hom}\left(j_{2}, l_{1}^{-1}\right) \\
& a_{6}=\operatorname{Hom}\left(\left[j_{2}^{1} \otimes j_{2}^{2}\right] \circ s_{4}, l_{1}^{-1}\right) \\
& a_{7}=\operatorname{Hom}\left(\left[j_{2}^{1} \otimes j_{2}^{2}\right] \circ s_{4},(l \circ l)^{-1}\right) \\
& a_{8}=\left[\operatorname{Hom}\left(j_{2}^{1},\left(l_{1}^{1}\right)^{-1}\right) \otimes \operatorname{Hom}\left(j_{2}^{2},\left(l_{1}^{2}\right)^{-1}\right)\right] \\
& a_{9}=\operatorname{Hom}\left(\operatorname{Hom}\left(s_{2}, s_{1}\right) \circ j_{3}, I d_{\operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)}\right) \\
& a_{10}=\operatorname{Hom}\left(\operatorname{Id}_{\operatorname{Hom}\left(V_{1} \otimes U_{1}, V_{1} \otimes W_{1}\right) \otimes \operatorname{Hom}\left(V_{2} \otimes U_{2}, V_{2} \otimes W_{2}\right)}, j_{4}\right) .
\end{aligned}
$$

The Theorem claims the two maps

$$
\begin{aligned}
T r_{V_{1} \otimes V_{2} ; U_{1} \otimes U_{2}, W_{1} \otimes W_{2}} \circ \operatorname{Hom}\left(s_{2}, s_{1}\right) \circ j_{3} & =a_{9}\left(\operatorname{Tr}_{V_{1} \otimes V_{2} ; U_{1} \otimes U_{2}, W_{1} \otimes W_{2}}\right), \\
j_{4} \circ\left(j_{8}\left(\operatorname{Tr}_{V_{1} ; U_{1}, W_{1}} \otimes T r_{V_{2} ; U_{2}, W_{2}}\right)\right) & =\left(a_{10} \circ j_{8}\right)\left(\operatorname{Tr}_{V_{1} ; U_{1}, W_{1}} \otimes T r_{V_{2} ; U_{2}, W_{2}}\right)
\end{aligned}
$$

are equal. The diagram is commutative - all six squares are easy to check, for example, the upper left and upper middle follow from Lemma 1.36, and each of the remaining four involves two arrows with switching maps. The equality along the top row,

$$
\begin{aligned}
& a_{1}: \quad \operatorname{Tr}_{V_{1} \otimes V_{2}} \otimes I d_{\operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)} \mapsto\left(T r_{V_{1} \otimes V_{2}} \circ j_{2}^{\prime}\right) \otimes j_{4}, \\
& a_{2} \circ[j \otimes j] \circ s_{3}: \quad \operatorname{Tr}_{V_{1}} \otimes I d_{\operatorname{Hom}\left(U_{1}, W_{1}\right)} \otimes T r_{V_{2}} \otimes I d_{\operatorname{Hom}\left(U_{2}, W_{2}\right)} \\
& \mapsto \\
&\left(l_{\mathbb{K}} \circ\left[T r_{V_{1}} \otimes T r_{V_{2}}\right]\right) \otimes j_{4},
\end{aligned}
$$

follows from Corollary 2.36. This key step, together with the commutativity of the diagram, proves the Theorem:

```
\(a_{9} \quad: \quad\left(\operatorname{Tr}_{V_{1} \otimes V_{2} ; U_{1} \otimes U_{2}, W_{1} \otimes W_{2}}\right)\)
    \(\mapsto \quad\left(a_{9} \circ a_{5}^{-1} \circ j_{1}\right)\left(\operatorname{Tr}_{V_{1} \otimes V_{2}} \otimes I d_{\operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)}\right)\)
    \(=\left(a_{6}^{-1} \circ j_{5} \circ a_{1}\right)\left(\operatorname{Tr}_{V_{1} \otimes V_{2}} \otimes I d_{\operatorname{Hom}\left(U_{1} \otimes U_{2}, W_{1} \otimes W_{2}\right)}\right)\)
    \(=\left(a_{6}^{-1} \circ j_{5} \circ a_{2} \circ[j \otimes j] \circ s_{3}\right)\left(T r_{V_{1}} \otimes I d_{\operatorname{Hom}\left(U_{1}, W_{1}\right)} \otimes T r_{V_{2}} \otimes I d_{\operatorname{Hom}\left(U_{2}, W_{2}\right)}\right)\)
    \(=\left(a_{10} \circ j_{8} \circ a_{8}^{-1} \circ\left[j_{1}^{1} \otimes j_{1}^{2}\right]\right)\left(\operatorname{Tr}_{V_{1}} \otimes I d_{\operatorname{Hom}\left(U_{1}, W_{1}\right)} \otimes \operatorname{Tr}{V_{2}} \otimes I d_{\operatorname{Hom}\left(U_{2}, W_{2}\right)}\right)\)
    \(=\left(a_{10} \circ j_{8}\right)\left(\operatorname{Tr}_{V_{1} ; U_{1}, W_{1}} \otimes \operatorname{Tr}_{V_{2} ; U_{2}, W_{2}}\right)\).
```

Remark 2.41. The maps $j_{4}$, from the previous Theorem, and

$$
j_{0}: \operatorname{Hom}\left(V \otimes U_{1}, V \otimes W_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, W_{2}\right) \rightarrow \operatorname{Hom}\left(V \otimes U_{1} \otimes U_{2}, V \otimes W_{1} \otimes W_{2}\right)
$$

appear in the following Corollary about the compatibility of the trace and the tensor product, related to a "superposing" identity of [JSV].

Corollary 2.42. For $A: V \otimes U_{1} \rightarrow V \otimes W_{1}$ and $B: U_{2} \rightarrow W_{2}$,

$$
\operatorname{Tr}_{V ; U_{1} \otimes U_{2}, W_{1} \otimes W_{2}}\left(j_{0}(A \otimes B)\right)=j_{4}\left(\left(\operatorname{Tr}_{V ; U_{1}, W_{1}}(A)\right) \otimes B\right) .
$$

Proof. It can be checked that the following diagram is commutative.


Theorem 2.29, the diagram, the previous Theorem, and finally Theorem 2.26 apply:

$$
\begin{aligned}
L H S & =\operatorname{Tr}_{V ; U_{1} \otimes U_{2}, W_{1} \otimes W_{2}}\left(\left(j_{0}(A \otimes B)\right) \circ\left[l_{V} \otimes I d_{U_{1} \otimes U_{2}}\right] \circ\left[l_{V}^{-1} \otimes I d_{U_{1} \otimes U_{2}}\right]\right) \\
& =\operatorname{Tr}_{V \otimes \mathbb{K} ; U_{1} \otimes U_{2}, W_{1} \otimes W_{2}}\left(\left[l_{V}^{-1} \otimes I d_{W_{1} \otimes W_{2}}\right] \circ\left(j_{0}(A \otimes B)\right) \circ\left[l_{V} \otimes I d_{U_{1} \otimes U_{2}}\right]\right) \\
& =\operatorname{Tr}_{V \otimes \mathbb{K} ; U_{1} \otimes U_{2}, W_{1} \otimes W_{2}}\left(s_{1} \circ\left(j_{3}\left(A \otimes\left(l_{W_{2}}^{-1} \circ B \circ l_{U_{2}}\right)\right)\right) \circ s_{2}\right) \\
& =j_{4}\left(\left(\operatorname{Tr}_{V ; U_{1}, W_{1}}(A)\right) \otimes\left(\operatorname{Tr}_{\mathbb{K} ; U_{2}, W_{2}}\left(\operatorname{Hom}\left(l_{U_{2}}, l_{W_{2}}^{-1}\right)(B)\right)\right)\right) \\
& =j_{4}\left(\left(\operatorname{Tr}_{V ; U_{1}, W_{1}}(A)\right) \otimes B\right) .
\end{aligned}
$$

Notation 2.43. Denote the composite maps

$$
\begin{array}{ccc}
\tilde{\jmath}_{U}=\operatorname{Hom}\left(I d_{V \otimes U}, l\right) \circ j & : & V^{*} \otimes U^{*} \rightarrow(V \otimes U)^{*} \\
\tilde{\jmath}_{W}=\operatorname{Hom}\left(I d_{V \otimes W}, l\right) \circ j & : & V^{*} \otimes W^{*} \rightarrow(V \otimes W)^{*}
\end{array}
$$

where $l$ is multiplication $\mathbb{K} \otimes \mathbb{K} \rightarrow \mathbb{K}$.
If $V$ is finite-dimensional then these $\tilde{\jmath}$ maps are invertible. They appear in the next Theorem, relating the trace of the transpose to the transpose of the trace, and already appeared in Lemma 2.32. Such composites appear again in the next Chapter, but the tilde notation will only be used when abbreviating is more useful than not.

Theorem 2.44. For finite-dimensional $V, H: V \otimes U \rightarrow V \otimes W$, and $t_{U V}$, $t_{V \otimes U, V \otimes W}$ as in Notation 1.9,

$$
\operatorname{Tr}_{V^{*} ; W^{*}, U^{*}}\left(\tilde{\jmath}_{U}^{-1} \circ\left(t_{V \otimes U, V \otimes W}(H)\right) \circ \tilde{\jmath}_{W}\right)=t_{U W}\left(\operatorname{Tr}_{V ; U, W}(H)\right)
$$

Proof. In the following diagram,

the objects are

$$
\begin{aligned}
& M_{11}=\operatorname{End}(V)^{*} \otimes \operatorname{End}(\operatorname{Hom}(U, W)) \\
& M_{21}=\operatorname{Hom}(\operatorname{End}(V) \otimes \operatorname{Hom}(U, W), \mathbb{K} \otimes \operatorname{Hom}(U, W)) \\
& M_{31}=\operatorname{Hom}(\operatorname{Hom}(V \otimes U, V \otimes W), \operatorname{Hom}(U, W)) \\
& M_{12}=\operatorname{End}(V)^{*} \otimes \operatorname{Hom}\left(\operatorname{Hom}(U, W), \operatorname{Hom}\left(W^{*}, U^{*}\right)\right) \\
& M_{22}=\operatorname{Hom}\left(\operatorname{End}(V) \otimes \operatorname{Hom}(U, W), \mathbb{K} \otimes \operatorname{Hom}\left(W^{*}, U^{*}\right)\right) \\
& M_{32}=\operatorname{Hom}\left(\operatorname{Hom}(V \otimes U, V \otimes W), \operatorname{Hom}\left(W^{*}, U^{*}\right)\right) \\
& M_{13}=\operatorname{End}\left(V^{*}\right)^{*} \otimes \operatorname{End}\left(\operatorname{Hom}\left(W^{*}, U^{*}\right)\right) \\
& M_{23}=\operatorname{Hom}\left(\operatorname{End}\left(V^{*}\right) \otimes \operatorname{Hom}\left(W^{*}, U^{*}\right), \mathbb{K} \otimes \operatorname{Hom}\left(W^{*}, U^{*}\right)\right) \\
& M_{33}=\operatorname{Hom}\left(\operatorname{Hom}\left(V^{*} \otimes W^{*}, V^{*} \otimes U^{*}\right), \operatorname{Hom}\left(W^{*}, U^{*}\right)\right)
\end{aligned}
$$

the arrows are

$$
\begin{aligned}
& a_{1}=\left[I d_{\operatorname{End}(V)^{*}} \otimes \operatorname{Hom}\left(I d_{\operatorname{Hom}(U, W)}, t_{U W}\right)\right] \\
& a_{2}=\left[t_{V V}^{*} \otimes \operatorname{Hom}\left(t_{U W}, I d_{\operatorname{Hom}\left(W^{*}, U^{*}\right)}\right)\right] \\
& a_{3}=\operatorname{Hom}\left(I d_{\operatorname{End}(V) \otimes \operatorname{Hom}(U, W)},\left[I d_{\mathbb{K}} \otimes t_{U W}\right]\right) \\
& a_{4}=\operatorname{Hom}\left(\left[t_{V V} \otimes t_{U W}\right], I d_{\mathbb{K} \otimes \operatorname{Hom}\left(W^{*}, U^{*}\right)}\right) \\
& a_{5}=\operatorname{Hom}\left(I d_{\operatorname{Hom}(V \otimes U, V \otimes W)}, t_{U W}\right) \\
& a_{6}=\operatorname{Hom}\left(\operatorname{Hom}\left(\tilde{\jmath}_{W}, \tilde{\jmath}_{U}-1\right) \circ t_{V \otimes U, V \otimes W}, I d_{\operatorname{Hom}\left(W^{*}, U^{*}\right)}\right),
\end{aligned}
$$

and the two quantities in the statement of the Theorem are

$$
\begin{aligned}
t_{U W}\left(\operatorname{Tr}_{V ; U, W}(H)\right) & =\left(a_{5}\left(\operatorname{Tr}_{V ; U, W}\right)\right)(H) \\
\operatorname{Tr}_{V^{*} ; W^{*}, U^{*}}\left(\operatorname{Hom}\left(\tilde{\jmath}_{W}, \tilde{\jmath}_{U}^{-1}\right)\left(t_{V \otimes U, V \otimes W}(H)\right)\right) & =\left(a_{6}\left(\operatorname{Tr}_{V^{*} ; W^{*}, U^{*}}\right)\right)(H)
\end{aligned}
$$

The diagram is commutative, for example, the lower right square:

$$
\begin{aligned}
E \otimes F & \mapsto\left(\operatorname{Hom}\left(I d_{V^{*}} \otimes W^{*}, \tilde{\jmath}_{U}\right) \circ j_{2}^{\prime} \circ\left[t_{V V} \otimes t_{U W}\right]\right)(E \otimes F) \\
& =\tilde{\jmath}_{U} \circ\left(j_{2}^{\prime}\left(\left(t_{V V}(E)\right) \otimes\left(t_{U W}(F)\right)\right)\right): \\
\phi \otimes \xi & \mapsto \tilde{\jmath}_{U}\left(\left(E^{*}(\phi)\right) \otimes\left(F^{*}(\xi)\right)\right): \\
v \otimes u & \mapsto \phi(E(v)) \cdot \xi(F(u)), \\
E \otimes F & \mapsto\left(\operatorname{Hom}\left(\tilde{\jmath}_{W}, I d_{V^{*} \otimes U^{*}}\right) \circ t_{V \otimes U, V \otimes W} \circ j_{2}\right)(E \otimes F) \\
& =\left(t_{V \otimes U, V \otimes W}\left(j_{2}(E \otimes F)\right)\right) \circ \tilde{\jmath}_{W}: \\
\phi \otimes \xi & \mapsto\left(\tilde{\jmath}_{W}(\phi \otimes \xi)\right) \circ\left(j_{2}(E \otimes F)\right): \\
v \otimes u & \mapsto \phi(E(v)) \cdot \xi(F(u)) .
\end{aligned}
$$

Lemma 2.5 implies the equality of the outputs of the distinguished elements in the top row:

$$
\begin{aligned}
a_{1}\left(T r_{V} \otimes I d_{\operatorname{Hom}(U, W)}\right) & =\operatorname{Tr}_{V} \otimes t_{U W} \\
a_{2}\left(T r_{V^{*}} \otimes I d_{\operatorname{Hom}\left(W^{*}, U^{*}\right)}\right) & =\left(t_{V V}^{*}\left(\operatorname{Tr}_{V^{*}}\right)\right) \otimes t_{U W} \\
& =\operatorname{Tr}_{V} \otimes t_{U W}
\end{aligned}
$$

and the Theorem follows from the commutativity of the diagram:

$$
\begin{aligned}
a_{5}\left(\operatorname{Tr}_{V ; U, W}\right) & =\left(a_{5} \circ \operatorname{Hom}\left(j_{2}^{-1}, l_{1}\right) \circ j_{1}\right)\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}(U, W)}\right) \\
& =\left(\operatorname{Hom}\left(j_{2}^{-1}, l_{1}^{\prime}\right) \circ j_{1}^{\prime \prime} \circ a_{1}\right)\left(\operatorname{Tr}_{V} \otimes \operatorname{Id} d_{\operatorname{Hom}(U, W)}\right) \\
& =\left(\operatorname{Hom}\left(j_{2}^{-1}, l_{1}^{\prime}\right) \circ j_{1}^{\prime \prime} \circ a_{2}\right)\left(\operatorname{Tr}_{V^{*}} \otimes \operatorname{Id} d_{\operatorname{Hom}\left(W^{*}, U^{*}\right)}\right) \\
& =\left(a_{6} \circ \operatorname{Hom}\left(\left(j_{2}^{\prime}\right)^{-1}, l_{1}^{\prime}\right) \circ j_{1}^{\prime}\right)\left(\operatorname{Tr}_{V^{*}} \otimes I d_{\operatorname{Hom}\left(W^{*}, U^{*}\right)}\right) \\
& =a_{6}\left(\operatorname{Tr}_{V^{*} ; W^{*}, U^{*}}\right) .
\end{aligned}
$$

ExERCISE 2.45. Given a direct sum $V=V_{1} \oplus V_{2}$, and $A: V_{1} \otimes U \rightarrow V_{1} \otimes W$, and $B: V_{2} \otimes U \rightarrow V_{2} \otimes W$, define $A \oplus B: V \otimes U \rightarrow V \otimes W$ using the projections and inclusions from Example 1.75:

$$
A \oplus B=\left[Q_{1} \otimes I d_{W}\right] \circ A \circ\left[P_{1} \otimes I d_{U}\right]+\left[Q_{2} \otimes I d_{W}\right] \circ B \circ\left[P_{2} \otimes I d_{U}\right]
$$

If $V$ is finite-dimensional, then

$$
\operatorname{Tr}_{V ; U, W}(A \oplus B)=\operatorname{Tr}_{V_{1} ; U, W}(A)+\operatorname{Tr}_{V_{2} ; U, W}(B)
$$

Hint. The proof proceeds exactly as in Proposition 2.12, using Theorem 2.29.

Exercise 2.46. For $V=V_{1} \oplus V_{2}$ as above, and $K: V \otimes U \rightarrow V \otimes W$,

$$
\begin{aligned}
\operatorname{Tr}_{V ; U, W}(K)= & \operatorname{Tr}_{V_{1} ; U, W}\left(\left[P_{1} \otimes I d_{W}\right] \circ K \circ\left[Q_{1} \otimes I d_{U}\right]\right) \\
& +\operatorname{Tr}_{V_{2} ; U, W}\left(\left[P_{2} \otimes I d_{W}\right] \circ K \circ\left[Q_{2} \otimes I d_{U}\right]\right)
\end{aligned}
$$

Hint. Using Theorem 2.29 and Lemma 1.35,
$\operatorname{Tr}_{V_{i} ; U, W}\left(\left[P_{i} \otimes I d_{W}\right] \circ K \circ\left[Q_{i} \otimes I d_{U}\right]\right)=\operatorname{Tr}_{V ; U, W}\left(\left[\left(Q_{i} \circ P_{i}\right) \otimes I d_{W}\right] \circ K\right)$.
The proof proceeds exactly as in Proposition 2.13.
Proposition 2.47. For finite-dimensional $V_{1}, V_{2}$, maps $A: V_{1} \otimes U_{1} \rightarrow V_{2} \otimes W_{2}$, $B: V_{2} \otimes U_{2} \rightarrow V_{1} \otimes W_{1}$, and switching maps as in the following diagrams,

the traces of the composites are equal:

$$
\begin{aligned}
& \operatorname{Tr}_{V_{1} ; U_{2} \otimes U_{1}, W_{1} \otimes W_{2}}\left(\left[B \otimes I d_{W_{2}}\right] \circ s_{2} \circ\left[A \otimes I d_{U_{2}}\right] \circ s_{1}\right) \\
= & \operatorname{Tr}_{V_{2} ; U_{2} \otimes U_{1}, W_{1} \otimes W_{2}}\left(s_{4} \circ\left[A \otimes I d_{W_{1}}\right] \circ s_{3} \circ\left[B \otimes I d_{U_{1}}\right]\right) .
\end{aligned}
$$

Proof. Since $j: \operatorname{Hom}\left(V_{2}, V_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, W_{1}\right) \rightarrow \operatorname{Hom}\left(V_{2} \otimes U_{2}, V_{1} \otimes W_{1}\right)$ is invertible by the finite-dimensionality hypothesis and Claim 1.33, it is enough, by the linearity of the above expressions, to check the claim for maps $B$ of the form $j\left(B_{1} \otimes B_{2}\right)$, for $B_{1}: V_{2} \rightarrow V_{1}, B_{2}: U_{2} \rightarrow W_{1}$.

The following easily checked diagram shows the $B_{2}$ factor commutes with $A$.


Using Theorem 2.29,

## LHS

$=\operatorname{Tr}_{V_{1} ; U_{2} \otimes U_{1}, W_{1} \otimes W_{2}}\left(\left[\left[B_{1} \otimes B_{2}\right] \otimes I d_{W_{2}}\right] \circ s_{2} \circ\left[A \otimes I d_{U_{2}}\right] \circ s_{1}\right)$
$=\operatorname{Tr}_{V_{1} ; U_{2} \otimes U_{1}, W_{1} \otimes W_{2}}\left(\left[B_{1} \otimes I d_{W_{1} \otimes W_{2}}\right] \circ\left[I d_{V_{2}} \otimes\left[B_{2} \otimes I d_{W_{2}}\right]\right] \circ s_{2} \circ\left[A \otimes I d_{U_{2}}\right] \circ s_{1}\right)$
$=\operatorname{Tr}_{V_{1} ; U_{2} \otimes U_{1}, W_{1} \otimes W_{2}}\left(\left[B_{1} \otimes I d_{W_{1} \otimes W_{2}}\right] \circ s_{4} \circ\left[A \otimes I d_{W_{1}}\right] \circ s_{3} \circ\left[I d_{V_{1}} \otimes\left[B_{2} \otimes I d_{U_{1}}\right]\right]\right)$
$=\operatorname{Tr}_{V_{2} ; U_{2} \otimes U_{1}, W_{1} \otimes W_{2}}\left(s_{4} \circ\left[A \otimes I d_{W_{1}}\right] \circ s_{3} \circ\left[I d_{V_{1}} \otimes\left[B_{2} \otimes I d_{U_{1}}\right]\right] \circ\left[B_{1} \otimes I d_{U_{2} \otimes U_{1}}\right]\right)$
$=\operatorname{Tr}_{V_{2} ; U_{2} \otimes U_{1}, W_{1} \otimes W_{2}}\left(s_{4} \circ\left[A \otimes I d_{W_{1}}\right] \circ s_{3} \circ\left[\left[B_{1} \otimes B_{2}\right] \otimes I d_{U_{1}}\right]\right)$
$=R H S$.

Exercise 2.48. Using various switching maps, Proposition 2.47 can be used to prove related identities. For example, given maps:

$$
\begin{aligned}
A^{\prime}: U_{1} \otimes V_{1} & \rightarrow V_{2} \otimes W_{2} \\
B^{\prime}: U_{2} \otimes V_{2} & \rightarrow V_{1} \otimes W_{1} \\
s_{5}: V_{1} \otimes U_{2} \otimes U_{1} & \rightarrow U_{2} \otimes U_{1} \otimes V_{1} \\
s_{6}: V_{2} \otimes U_{2} \otimes U_{1} & \rightarrow U_{1} \otimes U_{2} \otimes V_{2},
\end{aligned}
$$

the following identity can be proved as a consequence of Proposition 2.47:

$$
\begin{align*}
& T r_{V_{1} ; U_{2} \otimes U_{1}, W_{1} \otimes W_{2}}\left(\left[B^{\prime} \otimes I d_{W_{2}}\right] \circ\left[I d_{U_{2}} \otimes A^{\prime}\right] \circ s_{5}\right) \\
= & T r_{V_{2} ; U_{2} \otimes U_{1}, W_{1} \otimes W_{2}}\left(s_{4} \circ\left[A^{\prime} \otimes I d_{W_{1}}\right] \circ\left[I d_{U_{1}} \otimes B^{\prime}\right] \circ s_{6}\right) . \tag{2.7}
\end{align*}
$$

Hint. Let $A=A^{\prime} \circ s$ and $B=B^{\prime} \circ s$ for appropriate switching maps $s$.

Remark 2.49. Equation (2.7) is related to [PS] Proposition 2.7, on the "cyclicity" of the generalized trace.

### 2.3. Vector valued trace

In analogy with Definition 2.24, but with no space $U$, the "vector valued" or " $W$-valued" trace of a map $V \rightarrow V \otimes W$ should be an element of $W$. The results on the generalized trace have analogues in this case, but the construction uses different canonical maps.

### 2.3.1. Defining the vector valued trace.

The following Definition 2.50 applies to an arbitrary vector space $W$ and a finite-dimensional space $V$ to define the $W$-valued trace $\operatorname{Tr}_{V ; W}: \operatorname{Hom}(V, V \otimes W) \rightarrow$ $W$, in terms of the previously defined (scalar) trace $\operatorname{Tr}_{V}$, and canonical maps

$$
\begin{aligned}
& n: \\
& \operatorname{End}_{1}(V) \otimes W \rightarrow \operatorname{Hom}(V, V \otimes W) \\
& j_{1}^{\prime}: \\
& \operatorname{End}(V)^{*} \otimes \operatorname{End}(W) \rightarrow \operatorname{Hom}(\operatorname{End}(V) \otimes W, \mathbb{K} \otimes W),
\end{aligned}
$$

where $j_{1}^{\prime}$ is another canonical $j$ map in analogy with $j_{1}$ from Definition 2.24, and $n$ is invertible by Lemma 1.42.

Definition 2.50. $\operatorname{Tr} r_{V ; W}=\left(\operatorname{Hom}\left(n^{-1}, l_{W}\right) \circ j_{1}^{\prime}\right)\left(\operatorname{Tr}_{V} \otimes I d_{W}\right)$.
Example 2.51. A map of the form $n(A \otimes w): V \rightarrow V \otimes W$, for $A: V \rightarrow V$ and $w \in W$, has trace

$$
\operatorname{Tr}_{V ; W}(n(A \otimes w))=l_{W}\left(\left(j_{1}^{\prime}\left(\operatorname{Tr}_{V} \otimes I d_{W}\right)\right)(A \otimes w)\right)=\operatorname{Tr}_{V}(A) \cdot w
$$

A map $q: \operatorname{Hom}(V, \operatorname{Hom}(U, V \otimes W)) \rightarrow \operatorname{Hom}(V \otimes U, V \otimes W)$ from Definition 1.43 and a map $n^{\prime}: V \otimes \operatorname{Hom}(U, W) \rightarrow \operatorname{Hom}(U, V \otimes W)$ as in Notation 1.39 are used in the following Theorem relating Definition 2.50 to Definition 2.24. Consider the vector valued trace, in the case where $W$ is replaced by the vector space $\operatorname{Hom}(U, W)$.

ThEOREM 2.52. For finite-dimensional $V$, and a map $K: V \rightarrow V \otimes \operatorname{Hom}(U, W)$,

$$
\operatorname{Tr}_{V ; \operatorname{Hom}(U, W)}(K)=\operatorname{Tr}_{V ; U, W}\left(q\left(n^{\prime} \circ K\right)\right)
$$

Proof. In the following diagram,
the objects are

$$
\begin{aligned}
& M_{11}=\operatorname{Hom}(\operatorname{End}(V) \otimes \operatorname{Hom}(U, W), \mathbb{K} \otimes \operatorname{Hom}(U, W)) \\
& M_{21}=\operatorname{Hom}(\operatorname{Hom}(V \otimes U, V \otimes W), \operatorname{Hom}(U, W)) \\
& M_{12}=\operatorname{Hom}(\operatorname{Hom}(V, V \otimes \operatorname{Hom}(U, W)), \operatorname{Hom}(U, W)) \\
& M_{22}=\operatorname{Hom}(\operatorname{Hom}(V, \operatorname{Hom}(U, V \otimes W)), \operatorname{Hom}(U, W))
\end{aligned}
$$

The square is commutative since

$$
\begin{aligned}
E \otimes F & \mapsto\left(q \circ \operatorname{Hom}\left(I d_{V}, n^{\prime}\right) \circ n\right)(E \otimes F)=q\left(n^{\prime} \circ(n(E \otimes F))\right): \\
v \otimes u & \mapsto\left(n^{\prime}((n(E \otimes F))(v))\right)(u) \\
& =\left(n^{\prime}((E(v)) \otimes F)\right)(u) \\
& =(E(v)) \otimes(F(u)) \\
& =\left(j_{2}(E \otimes F)\right)(v \otimes u)
\end{aligned}
$$

Definitions 2.24 and 2.50 are related in this case by $l_{W}=l_{1}$ and $j_{1}^{\prime}=j_{1}$. The Theorem follows:

$$
\begin{aligned}
T r_{V ; \operatorname{Hom}(U, W)} & =\left(\operatorname{Hom}\left(n^{-1}, l_{1}\right) \circ j_{1}\right)\left(T r_{V} \otimes I d_{\operatorname{Hom}(U, W)}\right) \\
& =\left(\operatorname{Hom}\left(j_{2}^{-1} \circ q \circ \operatorname{Hom}\left(I d_{V}, n^{\prime}\right), l_{1}\right) \circ j_{1}\right)\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}(U, W)}\right) \\
& =\operatorname{Hom}\left(q \circ \operatorname{Hom}\left(I d_{V}, n^{\prime}\right), I d_{\operatorname{Hom}(U, W)}\right)\left(\operatorname{Tr}_{V ; U, W}\right) .
\end{aligned}
$$

Definition 2.50 is related to the original definition of trace when $W=\mathbb{K}$.

Theorem 2.53. For $H: V \rightarrow V \otimes \mathbb{K}, \operatorname{Tr}_{V}\left(l_{V} \circ H\right)=T r_{V ; \mathbb{K}}(H)$.
Proof. Let $l_{2}: \operatorname{End}(V)^{*} \otimes \mathbb{K} \rightarrow \operatorname{End}(V)^{*}$ be another scalar multiplication map. The following diagram is commutative.


For $\lambda, \mu \in \mathbb{K}, \Phi \in \operatorname{End}(V)^{*}, A \in \operatorname{End}(V)$,

$$
\begin{aligned}
\Phi \otimes \lambda & \mapsto\left(j _ { 1 } ^ { \prime } \circ \left[I d_{\left.\left.\operatorname{End}(V)^{*} \otimes m\right]\right)}(\Phi \otimes \lambda)=j_{1}^{\prime}(\Phi \otimes(m(\lambda))):\right.\right. \\
A \otimes \mu & \mapsto(\Phi(A)) \otimes(\mu \cdot \lambda), \\
\Phi \otimes \lambda & \mapsto\left(\operatorname{Hom}\left(n, l_{\mathbb{K}}^{-1}\right) \circ \operatorname{Hom}\left(I d_{V}, l_{V}\right)^{*} \circ l_{2}\right)(\Phi \otimes \lambda) \\
& =l_{\mathbb{K}}^{-1} \circ\left((\lambda \cdot \Phi) \circ \operatorname{Hom}\left(I d_{V}, l_{V}\right)\right) \circ n: \\
A \otimes \mu & \mapsto l_{\mathbb{K}}^{-1}\left((\lambda \cdot \Phi)\left(l_{V} \circ(n(A \otimes \mu))\right)\right)=1 \otimes(\lambda \cdot \Phi(\mu \cdot A)),
\end{aligned}
$$

since $\left(l_{V} \circ(n(A \otimes \mu))\right): v \mapsto l_{V}((A(v)) \otimes \mu)=(\mu \cdot A)(v)$. The Theorem follows from $\left[I d_{\operatorname{End}(V)^{*}} \otimes m\right]\left(\operatorname{Tr}_{V} \otimes 1\right)=\operatorname{Tr}_{V} \otimes I d_{\mathbb{K}}:$

$$
\begin{aligned}
\operatorname{Hom}\left(I d_{V}, l_{V}\right)^{*}\left(T r_{V}\right) & =\left(\operatorname{Hom}\left(I d_{V}, l_{V}\right)^{*} \circ l_{2}\right)\left(\operatorname{Tr}_{V} \otimes 1\right) \\
& =\left(\operatorname{Hom}\left(n^{-1}, l_{\mathbb{K}}\right) \circ j_{1}^{\prime} \circ\left[I d_{\operatorname{End}(V)^{*}} \otimes m\right]\right)\left(\operatorname{Tr}_{V} \otimes 1\right) \\
& =\operatorname{Tr}_{V ; \mathbb{K}} .
\end{aligned}
$$

Definition 2.24 and Definition 2.50 are related in the case $U=\mathbb{K}$ :
Theorem 2.54. For $H: V \rightarrow V \otimes W, \operatorname{Tr}_{V ; \mathbb{K}, W}\left(H \circ l_{V}\right): 1 \mapsto \operatorname{Tr}_{V ; W}(H)$.
Proof. The following diagram is commutative:

where the horizontal arrows are

$$
\begin{aligned}
a_{1} & =\left[I d_{\operatorname{End}(V)^{*}} \otimes \operatorname{Hom}\left(m, m^{-1}\right)\right] \\
a_{2} & =\operatorname{Hom}\left(\left[\operatorname{Id} d_{\operatorname{End}(V)} \otimes m\right],\left[I d_{\mathbb{K}} \otimes m^{-1}\right]\right) \\
a_{3} & =\operatorname{Hom}\left(\operatorname{Hom}\left(l_{V}, I d_{V \otimes W}\right), m^{-1}\right) .
\end{aligned}
$$

The statement of the Theorem becomes

$$
a_{3}\left(\operatorname{Tr}_{V ; \mathbb{K}, W}\right)=\operatorname{Tr}_{V ; W}
$$

The top square is commutative by Lemma 1.36. The lower square is commutative by Lemma 1.6, Lemma 1.37, and Lemma 1.41. The Theorem follows from $a_{1}\left(\operatorname{Tr}_{V} \otimes\right.$ $\left.I d_{\text {Hom }(\mathbb{K}, W)}\right)=T r_{V} \otimes I d_{W}:$

$$
\begin{aligned}
a_{3}\left(\operatorname{Tr}_{V ; \mathbb{K}, W}\right) & =\left(a_{3} \circ \operatorname{Hom}\left(j_{2}^{-1}, l_{1}\right) \circ j_{1}\right)\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}(\mathbb{K}, W)}\right) \\
& =\left(\operatorname{Hom}\left(n^{-1}, l_{W}\right) \circ j_{1}^{\prime} \circ a_{1}\right)\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}(\mathbb{K}, W)}\right) \\
& =\left(\operatorname{Hom}\left(n^{-1}, l_{W}\right) \circ j_{1}^{\prime}\right)\left(\operatorname{Tr}_{V} \otimes I d_{W}\right) \\
& =\operatorname{Tr}_{V ; W} .
\end{aligned}
$$

Exercise 2.55. The result of Theorem 2.27,

$$
\operatorname{Tr}_{V}(H)=\left(\operatorname{Tr}_{V ; \mathbb{K}, \mathbb{K}}\left(l_{V}^{-1} \circ H \circ l_{V}\right)\right)(1)
$$

can be given a different proof using the vector valued trace as an intermediate step.
Hint. By Theorem 2.53 and Theorem 2.54,

$$
T r_{V}=\operatorname{Hom}\left(I d_{V}, l_{V}^{-1}\right)^{*}\left(\operatorname{Hom}\left(\operatorname{Hom}\left(l_{V}, I d_{V \otimes \mathbb{K}}\right), m^{-1}\right)\left(\operatorname{Tr}_{V ; \mathbb{K}, \mathbb{K}}\right)\right)
$$

Corollary 2.56. For $H: \mathbb{K} \rightarrow \mathbb{K} \otimes W$, $\operatorname{Tr}_{\mathbb{K} ; W}(H)=l_{W}(H(1))$.
Proof. Theorem 2.54 applies, with $l_{\mathbb{K}}: \mathbb{K} \otimes \mathbb{K} \rightarrow \mathbb{K}$ :

$$
\operatorname{Tr}_{\mathbb{K} ; W}(H)=\left(\operatorname{Tr}_{\mathbb{K} ; \mathbb{K}, W}\left(H \circ l_{\mathbb{K}}\right)\right)(1) .
$$

By Theorem 2.26, this quantity is equal to

$$
\left(\operatorname{Hom}\left(l_{\mathbb{K}}^{-1}, l_{W}\right)\left(H \circ l_{\mathbb{K}}\right)\right)(1)=l_{W}(H(1))
$$

### 2.3.2. Properties of the vector valued trace.

The following results on the $W$-valued trace are corollaries of results from Section 2.2. In most cases, Theorem 2.54 applies, leading to a straightforward calculation.

Corollary 2.57. For $A: V \rightarrow V^{\prime}, B: V^{\prime} \rightarrow V \otimes W$,

$$
\operatorname{Tr}_{V ; W}(B \circ A)=\operatorname{Tr}_{V^{\prime} ; W}\left(\left(j_{W}\left(A \otimes I d_{W}\right)\right) \circ B\right) .
$$

Proof. Theorem 2.29 and Theorem 2.54 apply, using the map $l_{V^{\prime}}: V^{\prime} \otimes \mathbb{K} \rightarrow$ $V^{\prime}$, and the equation $A \circ l_{V}=l_{V^{\prime}} \circ\left(j_{\mathbb{K}}\left(A \otimes I d_{\mathbb{K}}\right)\right)$, a version of Lemma 1.37.

$$
\begin{aligned}
\operatorname{Tr}_{V ; W}(B \circ A) & =\left(\operatorname{Tr}_{V^{\prime} ; \mathbb{K}, W}\left(B \circ A \circ l_{V}\right)\right)(1) \\
& =\left(\operatorname{Tr}_{V ; \mathbb{K}, W}\left(B \circ l_{V^{\prime}} \circ\left(j_{\mathbb{K}}\left(A \otimes I d_{\mathbb{K}}\right)\right)\right)\right)(1) \\
& =\left(\operatorname{Tr}_{V^{\prime} ; \mathbb{K}, W}\left(\left(j_{W}\left(A \otimes I d_{W}\right)\right) \circ B \circ l_{V^{\prime}}\right)\right)(1) \\
& =\operatorname{Tr}_{V^{\prime}, W}\left(\left(j_{W}\left(A \otimes I d_{W}\right)\right) \circ B\right) .
\end{aligned}
$$

Corollary 2.58. For $A: V \rightarrow V \otimes W, B: W \rightarrow W^{\prime}$,

$$
\operatorname{Tr}_{V ; W^{\prime}}\left(\left[I d_{V} \otimes B\right] \circ A\right)=B\left(\operatorname{Tr}_{V ; W}(A)\right)
$$

Proof. By Theorem 2.30 and Theorem 2.54,

$$
\begin{aligned}
\operatorname{Tr}_{V ; W^{\prime}}\left(\left[I d_{V} \otimes B\right] \circ A\right) & =\left(\operatorname{Tr}_{V ; \mathbb{K}, W^{\prime}}\left(\left[I d_{V} \otimes B\right] \circ A \circ l_{V}\right)\right)(1) \\
& =\left(B \circ\left(\operatorname{Tr}_{V ; \mathbb{K}, W}\left(A \circ l_{V}\right)\right)\right)(1)=B\left(\operatorname{Tr}_{V ; W}(A)\right) .
\end{aligned}
$$

Corollary 2.59. If $V$ and $V^{\prime}$ are finite-dimensional then for any maps $A$ : $V \rightarrow V^{\prime}, B: W \rightarrow W^{\prime}$, the following diagram is commutative.


Proof. This follows from Corollary 2.57 and Corollary 2.58.
Lemma 2.60. For a direct sum $W=W_{1} \oplus W_{2}$ with operators $P_{i}, Q_{i}$, there is also a direct $\operatorname{sum} \operatorname{Hom}(V, V \otimes W)=\operatorname{Hom}\left(V, V \otimes W_{1}\right) \oplus \operatorname{Hom}\left(V, V \otimes W_{2}\right)$, with projections $\operatorname{Hom}\left(I d_{V},\left[I d_{V} \otimes P_{i}\right]\right)$ and inclusions $\operatorname{Hom}\left(I d_{V},\left[I d_{V} \otimes Q_{i}\right]\right)$ as in Examples 1.75 and 1.76. The map $\operatorname{Tr}_{V ; W}: \operatorname{Hom}(V, V \otimes W) \rightarrow W$ respects the direct sums, and the induced map is equal to the $W_{i}$-valued trace:

$$
\operatorname{Tr}_{V ; W_{i}}=P_{i} \circ \operatorname{Tr}_{V ; W} \circ \operatorname{Hom}\left(I d_{V},\left[I d_{V} \otimes Q_{i}\right]\right): \operatorname{Hom}\left(V, V \otimes W_{i}\right) \rightarrow W_{i}
$$

Proof. Both results follow from Definition 1.82 and Corollary 2.58.

Corollary 2.61. For $A: V \otimes V^{\prime} \rightarrow V \otimes V^{\prime} \otimes W$,

$$
\operatorname{Tr}_{V \otimes V^{\prime} ; W}(A)=\operatorname{Tr}_{V^{\prime} ; W}\left(\operatorname{Tr}_{V ; V^{\prime}, V^{\prime} \otimes W}(A)\right)
$$

Proof. Using Theorem 2.30, Theorem 2.38, and Theorem 2.54, and the scalar multiplication identity $l_{V \otimes V^{\prime}}=\left[I d_{V} \otimes l_{V^{\prime}}\right]: V \otimes V^{\prime} \otimes \mathbb{K} \rightarrow V \otimes V^{\prime}$,

$$
\begin{aligned}
\operatorname{Tr}_{V \otimes V^{\prime} ; W}(A) & =\left(\operatorname{Tr}_{V \otimes V^{\prime} ; \mathbb{K}, W}\left(A \circ l_{V \otimes V^{\prime}}\right)\right)(1) \\
& =\left(\operatorname{Tr}_{V \otimes V^{\prime} ; \mathbb{K}, W}\left(A \circ\left[I d_{V} \otimes l_{V^{\prime}}\right]\right)\right)(1) \\
& =\left(\operatorname{Tr}_{V^{\prime} ; \mathbb{K}, W}\left(\operatorname{Tr}_{V ; V^{\prime} \otimes \mathbb{K}, V^{\prime} \otimes W}\left(A \circ\left[I d_{V} \otimes l_{V^{\prime}}\right]\right)\right)\right)(1) \\
& =\left(\operatorname{Tr}_{V^{\prime} ; \mathbb{K}, W}\left(\left(\operatorname{Tr}_{V^{\prime} ; V^{\prime}, V^{\prime} \otimes W}(A)\right) \circ l_{V^{\prime}}\right)\right)(1) \\
& =\operatorname{Tr}_{V^{\prime} ; W}\left(\operatorname{Tr}_{V ; V^{\prime}, V^{\prime} \otimes W}(A)\right) .
\end{aligned}
$$

Exercise 2.62. Denote by $n^{\prime \prime}$ the map

$$
\begin{aligned}
n^{\prime \prime} & : \quad W \otimes \operatorname{Hom}\left(U, W^{\prime}\right) \rightarrow \operatorname{Hom}\left(U, W \otimes W^{\prime}\right) \\
& : \quad w \otimes E \mapsto(u \mapsto w \otimes(E(u))) .
\end{aligned}
$$

Then, for $A: V \rightarrow V \otimes W, B: U \rightarrow W^{\prime}$,

$$
\operatorname{Tr}_{V ; U, W \otimes W^{\prime}}\left(j_{0}^{\prime}(A \otimes B)\right)=n^{\prime \prime}\left(\left(\operatorname{Tr}_{V ; W}(A)\right) \otimes B\right)
$$

Hint. By Theorem 2.30, Theorem 2.54, Corollary 2.42, and the equations

$$
\begin{aligned}
\left(j_{0}^{\prime}(A \otimes B)\right) \circ\left[I d_{V} \otimes l_{U}\right] & =\left[A \otimes\left(B \circ l_{U}\right)\right]=\left[\left(A \circ l_{V}\right) \otimes B\right], \\
\left(\operatorname{Tr}_{V ; U, W \otimes W^{\prime}}\left(j_{0}^{\prime}(A \otimes B)\right)\right) \circ l_{U} & =\operatorname{Tr}_{V ; \mathbb{K} \otimes U, W \otimes W^{\prime}}\left(\left[A \otimes\left(B \circ l_{U}\right)\right]\right) \\
& =\operatorname{Tr}_{V ; \mathbb{K} \otimes U, W \otimes W^{\prime}}\left(\left[\left(A \circ l_{V}\right) \otimes B\right]\right) \\
& =j_{4}\left(\left(\operatorname{Tr}_{V ; \mathbb{K}, W}\left(A \circ l_{V}\right)\right) \otimes B\right) \\
\Longrightarrow r_{V ; U, W \otimes W^{\prime}}\left(j_{0}^{\prime}(A \otimes B)\right) & =\left(j_{4}\left(\left(\operatorname{Tr}_{V ; \mathbb{K}, W}\left(A \circ l_{V}\right)\right) \otimes B\right)\right) \circ l_{U}^{-1}: \\
u & \mapsto\left(\left(\operatorname{Tr}_{V ; \mathbb{K}, W}\left(A \circ l_{V}\right)\right)(1)\right) \otimes(B(u)) \\
& =\left(\operatorname{Tr}_{V ; W}(A)\right) \otimes(B(u)) \\
& =\left(n^{\prime \prime}\left(\left(\operatorname{Tr}_{V ; W}(A)\right) \otimes B\right)\right)(u) .
\end{aligned}
$$

Corollary 2.63. For finite-dimensional $V_{1}, V_{2}$, maps $A: V_{1} \rightarrow V_{1} \otimes W_{1}$, $B: V_{2} \rightarrow V_{2} \otimes W_{2}$, the switching map $s_{1}$, and a canonical $j$ map, as in Theorem 2.40:
$j_{3}^{\prime}: \operatorname{Hom}\left(V_{1}, V_{1} \otimes W_{1}\right) \otimes \operatorname{Hom}\left(V_{2}, V_{2} \otimes W_{2}\right) \rightarrow \operatorname{Hom}\left(V_{1} \otimes V_{2}, V_{1} \otimes V_{2} \otimes W_{1} \otimes W_{2}\right)$, the following identity holds:
$\operatorname{Tr}_{V_{1} \otimes V_{2} ; W_{1} \otimes W_{2}}\left(s_{1} \circ\left(j_{3}^{\prime}(A \otimes B)\right)\right)=\left(\operatorname{Tr}_{V_{1} ; W_{1}}(A)\right) \otimes\left(\operatorname{Tr}_{V_{2} ; W_{2}}(B)\right) \in W_{1} \otimes W_{2}$.
Proof. In the following diagram,

the objects are

$$
\begin{aligned}
& M_{11}=\operatorname{Hom}\left(V_{1}, V_{1} \otimes W_{1}\right) \otimes \operatorname{Hom}\left(V_{2}, V_{2} \otimes W_{2}\right) \\
& M_{21}=\operatorname{Hom}\left(V_{1} \otimes V_{2}, V_{1} \otimes W_{1} \otimes V_{2} \otimes W_{2}\right) \\
& M_{12}=\operatorname{Hom}\left(V_{1} \otimes \mathbb{K}, V_{1} \otimes W_{1}\right) \otimes \operatorname{Hom}\left(V_{2} \otimes \mathbb{K}, V_{2} \otimes W_{2}\right) \\
& M_{22}=\operatorname{Hom}\left(V_{1} \otimes V_{2} \otimes \mathbb{K}, V_{1} \otimes W_{1} \otimes V_{2} \otimes W_{2}\right) \\
& M_{13}=\operatorname{Hom}\left(V_{1} \otimes \mathbb{K} \otimes V_{2} \otimes \mathbb{K}, V_{1} \otimes W_{1} \otimes V_{2} \otimes W_{2}\right) \\
& M_{23}=\operatorname{Hom}\left(V_{1} \otimes V_{2} \otimes \mathbb{K} \otimes \mathbb{K}, V_{1} \otimes W_{1} \otimes V_{2} \otimes W_{2}\right),
\end{aligned}
$$

and the arrows are

$$
\left.\left.\begin{array}{rl}
a_{1} & =\left[\operatorname { H o m } ( l _ { V _ { 1 } } , I d _ { V _ { 1 } \otimes W _ { 1 } } ) \otimes \operatorname { H o m } \left(l_{V_{2}}, I d_{V_{1}} \otimes W_{2}\right.\right.
\end{array}\right)\right] .
$$

The diagram is commutative, by Lemma 1.36 and a scalar multiplication identity. By Theorem 2.54, Theorem 2.30, Theorem 2.40, and the diagram,

$$
\begin{aligned}
L H S & =\left(\operatorname{Tr}_{V_{1} \otimes V_{2} ; \mathbb{K}, W_{1} \otimes W_{2}}\left(s_{1} \circ\left(j_{3}^{\prime}(A \otimes B)\right) \circ l_{V_{1} \otimes V_{2}}\right)\right)(1) \\
& =\left(\operatorname{Tr}_{V_{1} \otimes V_{2} ; \mathbb{K}, W_{1} \otimes W_{2}}\left(s_{1} \circ\left(j_{3}\left(\left(A \circ l_{V_{1}}\right) \otimes\left(B \circ l_{V_{2}}\right)\right)\right) \circ s_{2} \circ\left[I d_{V_{1} \otimes V_{2}} \otimes l_{\mathbb{K}}^{-1}\right]\right)\right)(1) \\
& =\left(\left(\operatorname{Tr}_{V_{1} \otimes V_{2} ; \mathbb{K} \otimes \mathbb{K}, W_{1} \otimes W_{2}}\left(s_{1} \circ\left(j_{3}\left(\left(A \circ l_{V_{1}}\right) \otimes\left(B \circ l_{V_{2}}\right)\right)\right) \circ s_{2}\right)\right) \circ l_{\mathbb{K}}^{-1}\right)(1) \\
& =\left(j_{4}\left(\left(\operatorname{Tr}_{V_{1} ; \mathbb{K}, W_{1}}\left(A \circ l_{V_{1}}\right)\right) \otimes\left(\operatorname{Tr}_{V_{2} ; \mathbb{K}, W_{2}}\left(B \circ l_{V_{2}}\right)\right)\right)\right)(1 \otimes 1) \\
& =\left(\operatorname{Tr}_{V_{1} ; W_{1}}(A)\right) \otimes\left(\operatorname{Tr}_{V_{2} ; W_{2}}(B)\right)=R H S .
\end{aligned}
$$

ExErcise 2.64. For a direct sum $V=V_{1} \oplus V_{2}$ as in Definition 1.71, and maps $A: V_{1} \rightarrow V_{1} \otimes W, B: V_{2} \rightarrow V_{2} \otimes W$, define $A \oplus B: V \rightarrow V \otimes W$, using the inclusions from Example 1.75:

$$
A \oplus B=\left[Q_{1} \otimes I d_{W}\right] \circ A \circ P_{1}+\left[Q_{2} \otimes I d_{W}\right] \circ B \circ P_{2}
$$

If $V$ is finite-dimensional, then

$$
\operatorname{Tr}_{V ; W}(A \oplus B)=\operatorname{Tr}_{V_{1} ; W}(A)+\operatorname{Tr}_{V_{2} ; W}(B)
$$

Hint. The proof proceeds exactly as in Proposition 2.12, using Corollary 2.57.

Exercise 2.65. For $V=V_{1} \oplus V_{2}$, and $K: V \rightarrow V \otimes W$,
$\operatorname{Tr}_{V ; W}(K)=\operatorname{Tr}_{V_{1} ; W}\left(\left[P_{1} \otimes I d_{W}\right] \circ K \circ Q_{1}\right)+\operatorname{Tr}_{V_{2} ; W}\left(\left[P_{2} \otimes I d_{W}\right] \circ K \circ Q_{2}\right)$.
Hint. Using Corollary 2.57 and Lemma 1.35,

$$
\operatorname{Tr}_{V_{i} ; W}\left(\left[P_{i} \otimes I d_{W}\right] \circ K \circ Q_{i}\right)=\operatorname{Tr}_{V ; W}\left(\left[\left(Q_{i} \circ P_{i}\right) \otimes I d_{W}\right] \circ K\right)
$$

The proof proceeds exactly as in Proposition 2.13.

### 2.4. Equivalence of alternative definitions

In $[\mathbf{J S V}] \S 3$, the canonical trace of a map $F: V \otimes U \rightarrow V \otimes W$ is defined in terms of category theory. In the context and notation of these notes, the definition of $[\mathbf{J S V}]$ can be interpreted as saying that $\operatorname{Tr}_{V ; U, W}(F)$ is the following composite map from $U$ to $W$ :

$$
\begin{equation*}
U \longrightarrow V^{*} \otimes V \otimes U \xrightarrow{\left[I d_{V^{*}} \otimes F\right]} V^{*} \otimes V \otimes W \xrightarrow{l_{W} \circ\left[E v_{V} \otimes I d_{W}\right]} W \tag{2.8}
\end{equation*}
$$

where the first arrow is defined for $u \in U$ by:

$$
u \mapsto\left(k^{-1}\left(I d_{V}\right)\right) \otimes u
$$

As mentioned after Theorem 2.10, this map could be expressed in terms of maps $l_{U}: \mathbb{K} \otimes U \rightarrow U$ and an inclusion $Q_{1}^{1}: \mathbb{K} \rightarrow \operatorname{End}(V): 1 \mapsto I d_{V}$ as in Example 2.9 and Equation (2.4).

Notation 2.66. For finite-dimensional $V, k: V^{*} \otimes V \rightarrow \operatorname{End}(V)$, a switching $\operatorname{map} s: V^{*} \otimes V \rightarrow V \otimes V^{*}$, and the map $Q_{1}^{1}: \mathbb{K} \rightarrow \operatorname{End}(V): 1 \mapsto I d_{V}$, define $\eta_{V}: \mathbb{K} \rightarrow V \otimes V^{*}$ by:

$$
\eta_{V}=s \circ k^{-1} \circ Q_{1}^{1}
$$

The switching map is included for later convenience in Theorem 2.94. The arrow in (2.8) can then be described as follows:

$$
\begin{align*}
{\left[s^{-1} \otimes I d_{U}\right] \circ\left[\eta_{V} \otimes I d_{U}\right] \circ l_{U}^{-1} } & \\
=\left[k^{-1} \otimes I d_{U}\right] \circ\left[Q_{1}^{1} \otimes I d_{U}\right] \circ l_{U}^{-1}: U & \rightarrow V^{*} \otimes V \otimes U  \tag{2.9}\\
: u & \mapsto
\end{align*}\left(k^{-1}\left(I d_{V}\right)\right) \otimes u .
$$

The following Theorem shows that the formula (2.8) for $\operatorname{Tr}_{V ; U, W}(F)$ coincides with Definition 2.24. $V$ must be finite-dimensional, but $U$ and $W$ may be arbitrary.

Theorem 2.67. For finite-dimensional $V, F: V \otimes U \rightarrow V \otimes W$, and $u \in U$,

$$
\left(\operatorname{Tr}_{V ; U, W}(F)\right)(u)=\left(l_{W} \circ\left[E v_{V} \otimes I d_{W}\right] \circ\left[I d_{V^{*}} \otimes F\right] \circ\left[k^{-1} \otimes I d_{U}\right]\right)\left(I d_{V} \otimes u\right)
$$

Proof. The following diagram is commutative, where the top arrow is $a_{1}=$ $\left[I d_{\operatorname{End}\left(V^{*}\right)} \otimes j_{2}\right]$.


The upper and lower squares are easy to check (the maps $d_{U W}, d_{\operatorname{End}(V) \otimes U, W}$ are as in Definition 1.12), and the middle square is commutative by Lemma 1.36. Starting with $I d_{V^{*}} \otimes F$ in the upper left corner, the RHS of the Theorem is the output of the composition in the left column. The top three arrows in the right column come from the construction in Theorem 2.10,

$$
\operatorname{Tr}_{V}(A)=\left(\left(d_{\operatorname{End}(V)}\left(I d_{V}\right)\right) \circ \operatorname{Hom}\left(k^{-1}, E v_{V}\right) \circ j\right)\left(I d_{V^{*}} \otimes A\right)
$$

so that the composite of $a_{1}^{-1}=\left[I d_{\operatorname{End}\left(V^{*}\right)} \otimes j_{2}^{-1}\right]$ with the right column of maps takes $I d_{V^{*}} \otimes F$ to $\operatorname{Tr}_{V ; U, W}(F)=l_{1}\left(\left(j_{1}\left(\operatorname{Tr}_{V} \otimes I d_{\operatorname{Hom}(U, W)}\right)\right)\left(j_{2}^{-1}(F)\right)\right)$. The lowest arrow plugs $u$ into $\operatorname{Tr}_{V ; U, W}(F)$, giving the LHS of the Theorem, so the equality follows directly from the commutativity of the diagram.

Corollary 2.68. For finite-dimensional $V$ and $A: V \rightarrow V \otimes W$,

$$
\operatorname{Tr}_{V ; W}(A)=\left(l_{W} \circ\left[E v_{V} \otimes I d_{W}\right] \circ\left[I d_{V^{*}} \otimes A\right] \circ k^{-1}\right)\left(I d_{V}\right)
$$

Proof. By Theorem 2.67 and Theorem 2.54,

$$
\begin{aligned}
L H S & =\left(\operatorname{Tr}_{V ; \mathbb{K}, W}\left(A \circ l_{V}\right)\right)(1) \\
& =\left(l_{W} \circ\left[E v_{V} \otimes I d_{W}\right] \circ\left[I d_{V^{*}} \otimes\left(A \circ l_{V}\right)\right] \circ\left[k^{-1} \otimes I d_{\mathbb{K}}\right]\right)\left(I d_{V} \otimes 1\right) \\
& =\text { RHS. }
\end{aligned}
$$

This shows, in analogy with Theorem 2.10 and (2.8) from Theorem 2.67, that the $W$-valued trace of $A$ is the output of the distinguished element $k^{-1}\left(I d_{V}\right)$ under the composite map

$$
\begin{equation*}
V^{*} \otimes V \xrightarrow{\left[I d_{V^{*}} \otimes A\right]} V^{*} \otimes V \otimes W \xrightarrow{l_{W} \circ\left[E v_{V} \otimes I d_{W}\right]} W \tag{2.10}
\end{equation*}
$$

So, Corollary 2.68 could be used as an alternative, but equivalent, definition of vector valued trace. This Section continues with some identities for the vector valued trace, some of which (Theorem 2.72, Corollary 2.86, Corollary 2.106) could also be used in alternative approaches to the definition of $\operatorname{Tr}_{V ; W}$.

### 2.4.1. A vector valued canonical evaluation.

Definition 2.69. The distinguished element

$$
E v_{V W} \in \operatorname{Hom}(\operatorname{Hom}(V, W) \otimes V, W)
$$

is the canonical evaluation map, defined by

$$
E v_{V W}(A \otimes v)=A(v)
$$

In the $W=\mathbb{K}$ case, $E v_{V \mathbb{K}}$ is the distinguished element $E v_{V} \in\left(V^{*} \otimes V\right)^{*}$ from Definition 2.2. The scalar evaluation $E v_{V}$ and vector valued evaluation $E v_{V W}$ are related as follows.

Lemma 2.70. For any $V$ and $W$, let $s^{\prime}: V \otimes W \rightarrow W \otimes V$ be a switching map. The following diagram is commutative.


Proof.

$$
\begin{aligned}
\phi \otimes v \otimes w & \mapsto\left(l \circ\left[E v_{V} \otimes I d_{W}\right]\right)(\phi \otimes v \otimes w) \\
& =\phi(v) \cdot w \\
\phi \otimes v \otimes w & \mapsto\left(E v_{V W} \circ\left[k_{V W} \otimes I d_{V}\right] \circ\left[I d_{V^{*}} \otimes s^{\prime}\right]\right)(\phi \otimes v \otimes w) \\
& =E v_{V W}\left(\left(k_{V W}(\phi \otimes w)\right) \otimes v\right) \\
& =\phi(v) \cdot w .
\end{aligned}
$$

The canonical evaluation maps have the following naturality property.
Lemma 2.71. For any vector spaces $U, V, V^{\prime}, W$, and any maps $G: V^{\prime} \rightarrow V$, $B: U \rightarrow W$, the following diagram is commutative.


Proof. For $A \in \operatorname{Hom}(V, U), v \in V^{\prime}$,

$$
\begin{aligned}
& B \circ E v_{V U} \circ\left[I d_{\operatorname{Hom}(V, U)} \otimes G\right]: \\
A \otimes v \quad \mapsto & B\left(E v_{V U}(A \otimes(G(v)))\right)=B(A(G(v))), \\
& E v_{V^{\prime} W} \circ\left[\operatorname{Hom}(G, B) \otimes I d_{V^{\prime}}\right]: \\
A \otimes v \quad \mapsto & E v_{V^{\prime} W}((B \circ A \circ G) \otimes v)=(B \circ A \circ G)(v) .
\end{aligned}
$$

Theorem 2.72. For a map

$$
n^{\prime}: \operatorname{Hom}(V, W) \otimes V \rightarrow \operatorname{Hom}(V, V \otimes W)
$$

if $V$ is finite-dimensional, then

$$
T r_{V ; W} \circ n^{\prime}=E v_{V W}
$$

Proof. The map $n^{\prime}$ is as in Notation 1.39. The conclusion is equivalent to the formula $\operatorname{Tr}_{V ; W}\left(n^{\prime}(A \otimes v)\right)=A(v)$, for $A \in \operatorname{Hom}(V, W)$ and $v \in V$.

The equality $\operatorname{Tr}_{V ; W} \circ n^{\prime}=E v_{V W}$ follows from the commutativity of the diagram.


The left square is Definition 2.50, and the top triangle is Definition 2.3, together with Lemma 1.35 . The right square is exactly Lemma 2.70 . The back square is commutative:

$$
\begin{aligned}
\phi \otimes v \otimes w & \mapsto\left(n \circ\left[k_{V V} \otimes I d_{W}\right]\right)(\phi \otimes v \otimes w) \\
& =n\left(\left(k_{V V}(\phi \otimes v)\right) \otimes w\right): \\
u & \mapsto \phi(u) \cdot v \otimes w, \\
\phi \otimes v \otimes w & \mapsto\left(n^{\prime} \circ\left[k_{V W} \otimes I d_{V}\right] \circ\left[I d_{V^{*}} \otimes s^{\prime}\right]\right)(\phi \otimes v \otimes w) \\
& =n^{\prime}\left(\left(k_{V W}(\phi \otimes w)\right) \otimes v\right): \\
u & \mapsto v \otimes(\phi(u) \cdot w) .
\end{aligned}
$$

Recall the canonical map $e_{V V}^{W}: \operatorname{End}(V) \rightarrow \operatorname{Hom}(\operatorname{Hom}(V, W) \otimes V, W)$ from Definition 1.51. In the following diagram, the left triangle is commutative by Lemma 1.53.

$\operatorname{End}(\operatorname{Hom}(V, W))$
Every space in the diagram contains a distinguished element, giving an analogue of Equation (2.1):

$$
\begin{equation*}
E v_{V W}=q\left(I d_{\operatorname{Hom}(V, W)}\right)=q\left(t_{V V}^{W}\left(I d_{V}\right)\right)=e_{V V}^{W}\left(I d_{V}\right) \tag{2.11}
\end{equation*}
$$

Theorem 2.72 gives this analogue of Equation (2.2) from Lemma 2.5:
$T r_{V ; W}=\left(\left(\operatorname{Hom}\left(n^{\prime}, I d_{W}\right)\right)^{-1} \circ q\right)\left(I d_{\operatorname{Hom}(V, W)}\right)=\left(\left(\operatorname{Hom}\left(n^{\prime}, I d_{W}\right)\right)^{-1} \circ e_{V V}^{W}\right)\left(I d_{V}\right)$.
Using Theorem 2.72 as a definition for the vector valued trace allows some proofs to be simplified and avoids scalar multiplication. For example, the following result re-states Corollary 2.58 but gives a simpler proof.

Corollary 2.73. For any $V, W, W^{\prime}$, if $V$ is finite-dimensional and $B \in$ $\operatorname{Hom}\left(W, W^{\prime}\right)$ then
$\operatorname{Tr}_{V ; W^{\prime}} \circ \operatorname{Hom}\left(I d_{V},\left[I d_{V} \otimes B\right]\right)=B \circ \operatorname{Tr}_{V ; W}: \operatorname{Hom}(V, V \otimes W) \rightarrow W^{\prime}$.
Proof. For $n^{\prime}$ as in Theorem 2.72 and an analogous map $n^{\prime \prime}$, the downward composite in the left column of the following diagram is $\operatorname{Tr}_{V ; W}=E v_{V W} \circ\left(n^{\prime}\right)^{-1}$, and in the right column is $\operatorname{Tr}_{V ; W^{\prime}}$.


The blocks are commutative; the upper by Lemma 1.40 and the lower by Lemma 2.71 (in the case $G=I d_{V}$ ).

Theorem 2.74. For finite-dimensional $V$, let

$$
n_{1}: \operatorname{End}(V) \otimes U \rightarrow \operatorname{Hom}(V, V \otimes U)
$$

Then, for any $F: V \otimes U \rightarrow V \otimes W$ and $u \in U$,

$$
\left(\operatorname{Tr}_{V ; U, W}(F)\right)(u)=T r_{V ; W}\left(F \circ\left(n_{1}\left(I d_{V} \otimes u\right)\right)\right)
$$

Proof. Consider the following diagram.


The composition from $U$ to $W$ along the top row gives $\operatorname{Tr}_{V ; U, W}(F)$ by Theorem 2.67. The left square is from (2.9), and the right block is Lemma 2.70. The $n^{\prime}$ map is also from Theorem 2.72. The commutativity of the middle blocks is easily checked, so the claim follows from Theorem 2.72:

$$
L H S=E v_{V W}\left(\left(n^{\prime}\right)^{-1}\left(F \circ\left(n_{1}\left(I d_{V} \otimes u\right)\right)\right)\right)=R H S .
$$

Corollary 2.68 and Theorem 2.72 are related by the following commutative diagram.


The left square is commutative by Lemma 1.57, and the right block is from the Proof of Theorem 2.74. Starting with $I d_{V} \in \operatorname{End}(V)$, the composition along the top row gives $\operatorname{Tr}_{V ; W}(A) \in W$ as in (2.10) from Corollary 2.68, and along the lowest row gives $E v_{V W}\left(\left(n^{\prime}\right)^{-1}(A)\right)$, which also equals $\operatorname{Tr}_{V ; W}(A)$ by Theorem 2.72.

Lemma 2.75. For any $U, V, W$, the following diagram is commutative.


Proof. Both paths take $u \otimes A \otimes v \in U \otimes \operatorname{Hom}(V, W) \otimes V$ to $u \otimes(A(v)) \in$ $U \otimes W$.

Theorem 2.76. For any $V, U, W$, and $F: V \otimes U \rightarrow V \otimes W$, if $V$ is finitedimensional then the $n$ maps in the following diagram are invertible:

and the diagram is commutative, in the sense that

$$
\begin{aligned}
& F \circ\left[I d_{V} \otimes E v_{V U}\right] \circ\left[n_{2} \otimes I d_{V}\right]^{-1} \\
= & {\left[I d_{V} \otimes E v_{V W}\right] \circ\left[n_{2}^{\prime} \otimes I d_{V}\right]^{-1} \circ\left[\operatorname{Hom}\left(I d_{V}, F\right) \otimes I d_{V}\right] . }
\end{aligned}
$$

Proof. The $n_{2}, n_{2}^{\prime}$ maps are defined as they appear in the diagram, with subscript notation used to avoid duplication with the labels appearing elsewhere in this Section; they are invertible by Lemma 1.42.

By Lemma 2.75 , the upward composite on the left, $\left[I d_{V} \otimes E v_{V U}\right] \circ\left[n_{2} \otimes I d_{V}\right]^{-1}$, is equal to $E v_{V, V \otimes U}$, and similarly the upward composite on the right is equal to $E v_{V, V \otimes W}$. The claim then follows from Lemma 2.71.

Corollary 2.77. For any $V, U, W$, and $F: V \otimes U \rightarrow V \otimes W$, if $V$ is finite-dimensional then the $n$ maps in the following diagram are invertible:

and the diagram is commutative, in the sense that

$$
\begin{aligned}
& F \circ\left[I d_{V} \otimes E v_{V U}\right] \circ\left[I d_{V} \otimes n_{3}\right]^{-1} \circ n_{4}^{-1} \\
= & {\left[I d_{V} \otimes E v_{V W}\right] \circ\left[I d_{V} \otimes n_{3}^{\prime}\right]^{-1} \circ\left(n_{4}^{\prime}\right)^{-1} \circ \operatorname{Hom}\left(I d_{V},\left[F \otimes I d_{V}\right]\right) }
\end{aligned}
$$

Proof. The four $n$ maps are defined as they appear in the diagram, with subscript notation used to avoid duplication with the labels appearing elsewhere in this Section; they are invertible by Lemma 1.42. The left column of the following diagram matches the left column from the diagram in the Theorem; the notation $V=V_{1}=V_{2}=V_{3}$ is introduced to track the action of the switching maps.


The commutativity of the blocks on the right is easily checked, and the upper left block is commutative by Lemma 1.35 and Lemma 2.70. For the lower left block, start with $v, w \in V, \phi \in V^{*}, u \in U$ :

$$
\begin{align*}
v \otimes \phi \otimes u \otimes w & \mapsto k_{V, V \otimes U \otimes V}(\phi \otimes v \otimes u \otimes w):  \tag{2.12}\\
x & \mapsto \phi(x) \cdot v \otimes u \otimes w \\
v \otimes \phi \otimes u \otimes w & \mapsto n_{4}\left(v \otimes\left(n_{3}\left(\left(k_{V U}(\phi \otimes u)\right) \otimes w\right)\right)\right): \\
x & \mapsto v \otimes(\phi(x) \cdot u) \otimes w
\end{align*}
$$

So, the diagram is commutative, and a similar result holds when $U$ is replaced by $W$, corresponding to the right column of the diagram of the Theorem. The claim of the Theorem is reduced to the commutativity of the following diagram.


The upper block is commutative by Lemma 1.37, the next lower block is commutative by Lemma 1.35, and the lowest block is commutative by Lemma 1.57. The remaining block is easily checked, the $k$ maps are invertible by Lemma 1.59 , and the claim follows.

Lemma 2.78. For a switching map $s: V \otimes V \rightarrow V \otimes V$, if $k: V^{*} \otimes V \rightarrow \operatorname{End}(V)$ is invertible, then the following map:

$$
v \mapsto\left(l_{V} \circ\left[E v_{V} \otimes I d_{V}\right] \circ\left[I d_{V^{*}} \otimes s\right] \circ\left[k^{-1} \otimes I d_{V}\right]\right)\left(I d_{V} \otimes v\right)
$$

is equal to the identity map $I d_{V}$.
Proof. For the special case of Lemma 2.70 with $W=V, s^{\prime}=s$, the above composite map is $E v_{V V}$, so the given expression is

$$
v \mapsto E v_{V V}\left(I d_{V} \otimes v\right)=I d_{V}(v)=v
$$

Example 2.79. If $V$ is finite-dimensional, then the generalized trace of the switching map $s: V \otimes V \rightarrow V \otimes V$ is:

$$
\begin{equation*}
\operatorname{Tr}_{V ; V, V}(s)=I d_{V} \tag{2.13}
\end{equation*}
$$

by the formula from Theorem 2.67 and Lemma 2.78:
$\operatorname{Tr}_{V ; V, V}(s): v \mapsto\left(l_{V} \circ\left[E v_{V} \otimes I d_{V}\right] \circ\left[I d_{V^{*}} \otimes s\right] \circ\left[k^{-1} \otimes I d_{V}\right]\right)\left(I d_{V} \otimes v\right)=v$.
REMARK 2.80. Equation (2.13) is related to the "yanking" property of [JSV].
The following Lemma is analogous to Lemma 2.78.
Lemma 2.81. For a switching involution

$$
s^{\prime \prime}: V^{*} \otimes V \otimes V^{*} \rightarrow V^{*} \otimes V \otimes V^{*}: \phi \otimes v \otimes \psi \mapsto \psi \otimes v \otimes \phi
$$

if $k: V^{*} \otimes V \rightarrow \operatorname{End}(V)$ is invertible, then the following map:

$$
\phi \mapsto\left(l_{V^{*}} \circ\left[E v_{V} \otimes I d_{V}\right] \circ s^{\prime \prime} \circ\left[k^{-1} \otimes I d_{V^{*}}\right]\right)\left(I d_{V} \otimes \phi\right)
$$

is equal to the identity map $I d_{V^{*}}$.

Proof. The following diagram is commutative; the calculation is similar that in the Proof of Lemma 2.70. Abbreviate $t=t_{V V}$ as in Lemma 2.5.


Starting with $I d_{V} \otimes \phi$, the commutativity of the diagram and the existence of $k^{-1}$ give:

$$
\begin{align*}
& \left(l_{V^{*}} \circ\left[E v_{V} \otimes I d_{V}\right] \circ s^{\prime \prime} \circ\left[k^{-1} \otimes I d_{V^{*}}\right]\right)\left(I d_{V} \otimes \phi\right)  \tag{2.14}\\
= & E v_{V^{*} V^{*}}\left(\left(t\left(I d_{V}\right)\right) \otimes \phi\right)=I d_{V}^{*}(\phi)=\phi .
\end{align*}
$$

Theorem 2.82. If $k: V^{*} \otimes V \rightarrow \operatorname{End}(V)$ is invertible, then $d_{V}: V \rightarrow V^{* *}$ is invertible.

Proof. The following map, temporarily denoted $B: V^{* *} \rightarrow V$, is an inverse:

$$
B: \Phi \mapsto l_{V}\left(\left[\Phi \otimes I d_{V}\right]\left(k^{-1}\left(I d_{V}\right)\right)\right)
$$

For any $V, W$, and $v \in V$, the following diagram is commutative (the two paths $V^{*} \otimes W \rightarrow W$ are equal compositions).


In the case $W=V$, starting with $I d_{V}$ in the top middle gives the following equality:

$$
\begin{aligned}
\left(B \circ d_{V}\right)(v) & =l_{V}\left(\left[\left(d_{V}(v)\right) \otimes I d_{V}\right]\left(k^{-1}\left(I d_{V}\right)\right)\right) \\
& =E v_{V V}\left(I d_{V} \otimes v\right)=v
\end{aligned}
$$

To check the composite in the other order, in the second diagram, $s^{\prime \prime \prime}$ is another switching map as indicated in the diagram, $\eta_{V}$ and $s$ are as in (2.9), the block is commutative, and the composition in the left column acts as the identity map, by
(2.14) from Lemma 2.81 .


The conclusion is:

$$
\begin{aligned}
\Phi(\phi) & =\left(E v_{V} \circ\left[I d_{V^{*}} \otimes l_{V}\right] \circ s^{\prime \prime \prime} \circ\left[\left[\Phi \otimes I d_{V}\right] \otimes I d_{V^{*}}\right]\right)\left(\left(k^{-1}\left(I d_{V}\right)\right) \otimes \phi\right) \\
& =E v_{V}\left(\phi \otimes\left(l_{V}\left(\left[\Phi \otimes I d_{V}\right]\left(k^{-1}\left(I d_{V}\right)\right)\right)\right)\right) \\
& =\phi\left(l_{V}\left(\left[\Phi \otimes I d_{V}\right]\left(k^{-1}\left(I d_{V}\right)\right)\right)\right) \\
& =\phi(B(\Phi))=\left(\left(d_{V} \circ B\right)(\Phi)\right)(\phi) .
\end{aligned}
$$

Proposition 2.83. Given $U, V, W$, a map $G: U \rightarrow \operatorname{Hom}(V, W)$, and the canonical map

$$
q: \operatorname{Hom}(U, \operatorname{Hom}(V, W)) \rightarrow \operatorname{Hom}(U \otimes V, W)
$$

if $V$ is finite-dimensional then

$$
\begin{equation*}
q(G)=T r_{V ; W} \circ n^{\prime} \circ\left[G \otimes I d_{V}\right] \tag{2.15}
\end{equation*}
$$

Proof. $q$ is as in Definition 1.43, and $n^{\prime}$ is as in Theorem 2.72, which gives, for $u \otimes v \in U \otimes V$,

$$
\begin{aligned}
\left(T r_{V ; W} \circ n^{\prime} \circ\left[G \otimes I d_{V}\right]\right)(u \otimes v) & =\left(E v_{V W} \circ\left[G \otimes I d_{V}\right]\right)(u \otimes v) \\
& =(G(u))(v) \\
& =(q(G))(u \otimes v) .
\end{aligned}
$$

Equation (2.15) from Proposition 2.83 can also be re-written, for $F=q(G) \in$ $\operatorname{Hom}(U \otimes V, W)$,

$$
F=E v_{V W} \circ\left[\left(q^{-1}(F)\right) \otimes I d_{V}\right]=T r_{V ; W} \circ n^{\prime} \circ\left[\left(q^{-1}(F)\right) \otimes I d_{V}\right]
$$

Theorem 2.84. For finite-dimensional $V$, and maps

$$
\begin{aligned}
n_{2}: \operatorname{Hom}(U, \operatorname{Hom}(V, W)) \otimes V & \rightarrow \operatorname{Hom}(U, \operatorname{Hom}(V, W) \otimes V) \\
n_{3}: \operatorname{Hom}(V \otimes U, W) \otimes V & \rightarrow \operatorname{Hom}(V \otimes U, V \otimes W) \\
q: \operatorname{Hom}(U, \operatorname{Hom}(V, W)) & \rightarrow \operatorname{Hom}(V \otimes U, W) \\
F: V \otimes U & \rightarrow V \otimes W
\end{aligned}
$$

the following diagram is commutative.


Proof. $n_{3}$ is invertible by Lemma 1.42. The claim follows from the commutativity of this diagram.


Starting with $A \otimes v_{1} \in \operatorname{Hom}(U, \operatorname{Hom}(V, W)) \otimes V$,

$$
\begin{aligned}
\left(\operatorname{Hom}\left(I d_{V}, E v_{V W}\right) \circ n_{2}\right)\left(A \otimes v_{1}\right): u & \mapsto E v_{V W}\left(\left(n_{2}\left(A \otimes v_{1}\right)\right)(u)\right) \\
& =E v_{V W}\left((A(u)) \otimes v_{1}\right)=(A(u))\left(v_{1}\right) .
\end{aligned}
$$

Going the other way around the diagram,

$$
\begin{aligned}
\operatorname{Tr}_{V ; U, W}\left(n_{3}\left((q(A)) \otimes v_{1}\right)\right): u & \mapsto \operatorname{Tr}_{V ; W}\left(\left(n_{3}\left((q(A)) \otimes v_{1}\right)\right) \circ\left(n_{1}\left(I d_{V} \otimes u\right)\right)\right) \\
& =\operatorname{Tr}_{V ; W}\left(n^{\prime}\left((A(u)) \otimes v_{1}\right)\right) \\
& =(A(u))\left(v_{1}\right)
\end{aligned}
$$

The first step uses Theorem 2.74 and its $n_{1}$ map, and the last step uses Theorem 2.72 and its $n^{\prime}$ map. The middle step uses the following calculation:

$$
\begin{aligned}
\left(n_{3}\left((q(A)) \otimes v_{1}\right)\right) \circ\left(n_{1}\left(I d_{V} \otimes u\right)\right): v_{2} & \mapsto\left(n_{3}\left((q(A)) \otimes v_{1}\right)\right)\left(v_{2} \otimes u\right) \\
& =v_{1} \otimes\left((q(A))\left(v_{2} \otimes u\right)\right) \\
& =v_{1} \otimes\left((A(u))\left(v_{2}\right)\right) \\
& =\left(n^{\prime}\left((A(u)) \otimes v_{1}\right)\right)\left(v_{2}\right)
\end{aligned}
$$

Theorem 2.85. For finite-dimensional $V$ and any vector space $Z$, let $s_{1}$ : $V \otimes V \rightarrow V \otimes V$ be the switching map and let

$$
n: \operatorname{End}(V) \otimes V \otimes Z \rightarrow \operatorname{Hom}(V, V \otimes V \otimes Z)
$$

Then, for any $B \in V \otimes Z$,

$$
\operatorname{Tr}_{V ; V \otimes Z}\left(\left[s_{1} \otimes I d_{Z}\right] \circ\left(n\left(I d_{V} \otimes B\right)\right)\right)=B
$$

Proof. It is straightforward to check that the following diagram is commutative.


So the LHS of the claim is:

$$
\begin{aligned}
& \operatorname{rr}_{V, V \otimes Z}\left(\left[s_{1} \otimes I d_{Z}\right] \circ\left(n\left(I d_{V} \otimes B\right)\right)\right) \\
= & \left(\operatorname{Tr}_{V ; V \otimes Z} \circ \operatorname{Hom}\left(I d_{V},\left[s_{1} \otimes I d_{Z}\right]\right) \circ n\right)\left(I d_{V} \otimes B\right) \\
= & \left(T r_{V ; V \otimes Z} \circ n \circ\left[k_{V V} \otimes I d_{V \otimes Z}\right]\right. \\
& \left.\circ\left[\left[I d_{V^{*}} \otimes s_{1}\right] \otimes I d_{Z}\right] \circ\left[k_{V V}^{-1} \otimes I d_{V \otimes Z}\right]\right)\left(I d_{V} \otimes B\right) .
\end{aligned}
$$

Let $s_{3}: V \otimes Z \rightarrow Z \otimes V$ be another switching, and denote $V_{1}=V_{2}=V$, so that the labels explain the switching

$$
s_{2}=\left[I d_{V^{*}} \otimes s_{4}\right]: V^{*} \otimes V_{1} \otimes\left(V_{2} \otimes Z\right) \rightarrow V^{*} \otimes\left(V_{2} \otimes Z\right) \otimes V_{1}
$$

Using $W=V \otimes Z$ and this $s_{4}$ in the role of $s^{\prime}$ from the diagram from the Proof of Theorem 2.72, the commutativity of that diagram continues the chain of equalities:

$$
\begin{aligned}
= & \left(E v_{V, V \otimes Z} \circ\left[k_{V, V \otimes Z} \otimes I d_{V}\right] \circ\left[I d_{V^{*}} \otimes s_{4}\right]\right. \\
& \left.\circ\left[\left[I d_{V^{*}} \otimes s_{1}\right] \otimes I d_{Z}\right] \circ\left[k_{V V}^{-1} \otimes I d_{V \otimes Z}\right]\right)\left(I d_{V} \otimes B\right) \\
= & \left(E v_{V, V \otimes Z} \circ\left[k_{V, V \otimes Z} \otimes I d_{V}\right] \circ\left[I d_{V^{*} \otimes V} \circ s_{3}\right] \circ\left[k_{V V}^{-1} \otimes I d_{V \otimes Z}\right]\right)\left(I d_{V} \otimes B\right) \\
= & \left(E v_{V, V \otimes Z} \circ\left[k_{V, V \otimes Z} \otimes I d_{V}\right] \circ\left[k_{V V}^{-1} \circ s_{3}\right]\right)\left(I d_{V} \otimes B\right) .
\end{aligned}
$$

The commutativity of the following diagram:

leads the equalities to the conclusion:

$$
=\left[E v_{V, V} \otimes I d_{Z}\right]\left(I d_{V} \otimes B\right)=B
$$

The switching $s_{3}: V \otimes Z \rightarrow Z \otimes V$ from Theorem 2.85 appears in the following Corollaries, which are related to constructions in [Stolz-Teichner].

Corollary 2.86. Given $V$ finite-dimensional and a map $A: V \rightarrow V \otimes W$, if there exist a vector space $Z$ and a factorization of the form

$$
A=\left[I d_{V} \otimes B_{2}\right] \circ\left[B_{1} \otimes I d_{V}\right] \circ l^{-1}
$$

for $l: \mathbb{K} \otimes V \rightarrow V, B_{1}: \mathbb{K} \rightarrow V \otimes Z$, and $B_{2}: Z \otimes V \rightarrow W$, then

$$
\operatorname{Tr}_{V ; W}(A)=\left(B_{2} \circ s_{3} \circ B_{1}\right)(1)
$$

Proof. It is straightforward to check that the following diagram is commutative. The $s_{1}$ is the switching from Theorem 2.85, and as in the above Proof, denote $V_{1}=V_{2}=V$, to keep track of switching, so that $s_{4}: V_{1} \otimes\left(V_{2} \otimes Z\right) \rightarrow\left(V_{2} \otimes Z\right) \otimes V_{1}$.


The following equalities use the commutativity of the diagram, Corollary 2.58 (or Corollary 2.73) twice, and Theorem 2.85 applied to $B=B_{1}(1) \in V \otimes Z$.

$$
\begin{aligned}
\operatorname{Tr}_{V ; W}(A) & =\operatorname{Tr}_{V ; W}\left(\left[I d_{V} \otimes B_{2}\right] \circ\left[B_{1} \otimes I d_{V}\right] \circ l^{-1}\right) \\
& =B_{2}\left(\operatorname{Tr}_{V ; Z \otimes V}\left(\left[B_{1} \otimes I d_{V}\right] \circ l^{-1}\right)\right) \\
& =B_{2}\left(\operatorname{Tr}_{V ; Z \otimes V}\left(\left[I d_{V} \otimes s_{3}\right] \circ\left[s_{1} \otimes I d_{Z}\right] \circ\left(n\left(I d_{V} \otimes\left(B_{1}(1)\right)\right)\right)\right)\right) \\
& =\left(B_{2} \circ s_{3}\right)\left(\operatorname{Tr}_{V ; V \otimes Z}\left(\left[s_{1} \otimes I d_{Z}\right] \circ\left(n\left(I d_{V} \otimes\left(B_{1}(1)\right)\right)\right)\right)\right) \\
& =\left(B_{2} \circ s_{3}\right)\left(B_{1}(1)\right) .
\end{aligned}
$$

Corollary 2.87. Given $V$ finite-dimensional and a map $A: V \rightarrow V$, if there exist a vector space $Z$ and a factorization of the form

$$
A=l_{V} \circ\left[I d_{V} \otimes B_{2}\right] \circ\left[B_{1} \otimes I d_{V}\right] \circ l^{-1}
$$

for $l_{V}: V \otimes \mathbb{K} \rightarrow V, l: \mathbb{K} \otimes V \rightarrow V, B_{1}: \mathbb{K} \rightarrow V \otimes Z$, and $B_{2}: Z \otimes V \rightarrow \mathbb{K}$, then

$$
\operatorname{Tr}_{V}(A)=\left(B_{2} \circ s_{3} \circ B_{1}\right)(1) .
$$

Proof. Theorem 2.53 and Corollary 2.86 apply.
Corollary 2.88. Given $V$ finite-dimensional and a map $A: V \otimes U \rightarrow V \otimes W$, if there exist a vector space $Z$ and a factorization of the form

$$
A=\left[I d_{V} \otimes B_{2}\right] \circ\left[B_{1} \otimes I d_{V}\right] \circ s_{5}
$$

for $s_{5}: V \otimes U \rightarrow U \otimes V, B_{1}: U \rightarrow V \otimes Z$, and $B_{2}: Z \otimes V \rightarrow W$, then

$$
\operatorname{Tr}_{V ; U, W}(A)=B_{2} \circ s_{3} \circ B_{1}
$$

Proof. Theorem 2.30 applies:

$$
\begin{aligned}
\operatorname{Tr}_{V ; U, W}(A) & =\operatorname{Tr}_{V ; U, W}\left(\left[I d_{V} \otimes B_{2}\right] \circ\left[B_{1} \otimes I d_{V}\right] \circ s_{5}\right) \\
& =B_{2} \circ\left(\operatorname{Tr}_{V ; U, Z \otimes V}\left(\left[B_{1} \otimes I d_{V}\right] \circ s_{5}\right)\right),
\end{aligned}
$$

so to prove the claim it is enough to check

$$
\begin{equation*}
\operatorname{Tr}_{V ; U, Z \otimes V}\left(\left[B_{1} \otimes I d_{V}\right] \circ s_{5}\right)=s_{3} \circ B_{1} \tag{2.16}
\end{equation*}
$$

for $B_{1} \in \operatorname{Hom}(U, V \otimes Z)$. In the following diagram, temporarily denote by $a_{1}$ the following map,

$$
\begin{aligned}
a_{1} & =j \circ\left[I d_{\operatorname{Hom}(U, V \otimes Z)} \otimes Q_{1}^{1}\right] \circ l_{\operatorname{Hom}(U, V \otimes Z)}^{-1}: \\
B_{1} & \mapsto\left[B_{1} \otimes I d_{V}\right],
\end{aligned}
$$

for $Q_{1}^{1}: \mathbb{K} \rightarrow \operatorname{End}(V)$ as in Example 2.9.


The maps $n^{\prime \prime}, n^{\prime}, n_{1}$, as in Definition 1.38 and Notation 1.39, are all invertible, by the finite-dimensionality of $V$ and Lemma 1.42. The commutativity of the top block, with the switching maps, is easily checked. The commutativity of the lower right triangle is Theorem 2.52. So, the claim of (2.16) is that the lower left triangle is commutative, and this will follow from showing that the outer part of the diagram is commutative, starting with $v_{0} \otimes B_{3} \in V \otimes \operatorname{Hom}(U, Z)$.

For $v \in V, u \in U$, the following maps are equal. The first step uses the formula for the inverse of the canonical map $q$ from Lemma 1.44.

$$
\begin{aligned}
\left(q^{-1}\left(\left(a_{1}\left(n^{\prime \prime}\left(v_{0} \otimes B_{3}\right)\right)\right) \circ s_{5}\right)\right)(v): u & \mapsto\left(\left(a_{1}\left(n^{\prime \prime}\left(v_{0} \otimes B_{3}\right)\right)\right) \circ s_{5}\right)(v \otimes u) \\
& =\left[\left(n^{\prime \prime}\left(v_{0} \otimes B_{3}\right)\right) \otimes I d_{V}\right](u \otimes v) \\
& =v_{0} \otimes\left(B_{3}(u)\right) \otimes v, \\
n^{\prime}\left(\left[I d_{V} \otimes n_{1}\right]\left(v_{0} \otimes B_{3} \otimes v\right)\right): u & \mapsto v_{0} \otimes\left(\left(n_{1}\left(B_{3} \otimes v\right)\right)(u)\right) \\
7) & =v_{0} \otimes\left(B_{3}(u)\right) \otimes v .
\end{aligned}
$$

Denote, as in Definition 1.19,

$$
m\left(v_{0} \otimes B_{3}\right): \mathbb{K} \rightarrow V \otimes \operatorname{Hom}(U, Z): 1 \mapsto v_{0} \otimes B_{3}
$$

so that

$$
v_{0} \otimes B_{3} \otimes v=\left(\left[\left(m\left(v_{0} \otimes B_{3}\right)\right) \otimes I d_{V}\right] \circ l^{-1}\right)(v)
$$

and from (2.17),

$$
q^{-1}\left(\left(a_{1}\left(n^{\prime \prime}\left(v_{0} \otimes B_{3}\right)\right)\right) \circ s_{5}\right)=n^{\prime} \circ\left[I d_{V} \otimes n_{1}\right] \circ\left[\left(m\left(v_{0} \otimes B_{3}\right)\right) \otimes I d_{V}\right] \circ l^{-1}
$$

The conclusion uses Corollary 2.86:

$$
\begin{aligned}
v_{0} \otimes B_{3} & \mapsto T r_{V ; \operatorname{Hom}(U, Z \otimes V)}\left(\left(n^{\prime}\right)^{-1} \circ\left(q^{-1}\left(\left(a_{1}\left(n^{\prime \prime}\left(v_{0} \otimes B_{3}\right)\right)\right) \circ s_{5}\right)\right)\right) \\
& =T r_{V ; \operatorname{Hom}(U, Z \otimes V)}\left(\left[I d_{V} \otimes n_{1}\right] \circ\left[\left(m\left(v_{0} \otimes B_{3}\right)\right) \otimes I d_{V}\right] \circ l^{-1}\right) \\
& =\left(n_{1} \circ s_{3}^{\prime} \circ\left(m\left(v_{0} \otimes B_{3}\right)\right)\right)(1)=\left(n_{1} \circ s_{3}^{\prime}\right)\left(v_{0} \otimes B_{3}\right) .
\end{aligned}
$$

Example 2.89. Consider $V=V_{1}=V_{2}$ and $s_{4}: V_{1} \otimes\left(V_{2} \otimes Z\right) \rightarrow\left(V_{2} \otimes Z\right) \otimes V_{1}$ as in the diagram from the Proof of Corollary 2.86. Then

$$
\operatorname{Tr}_{V ; V \otimes Z, Z \otimes V}\left(s_{4}\right)=s_{3}
$$

This is a special case of Corollary 2.88 , with $U=V \otimes Z, W=Z \otimes V, s_{5}=s_{4}$, $B_{1}=I d_{V \otimes Z}$, and $B_{2}=I d_{Z \otimes V}$.

Example 2.90. Using Theorem 2.30 and Example 2.89,

$$
\begin{aligned}
\operatorname{Tr}_{V ; Z \otimes V, V \otimes Z}\left(s_{4}^{-1}\right) & =\operatorname{Tr}_{V ; Z \otimes V, V \otimes Z}\left(\left[I d_{V} \otimes s_{3}^{-1}\right] \circ s_{4} \circ\left[I d_{V} \otimes s_{3}^{-1}\right]\right) \\
& =s_{3}^{-1} \circ\left(\operatorname{Tr}_{V ; V \otimes Z, Z \otimes V}\left(s_{4}\right)\right) \circ s_{3}^{-1} \\
& =s_{3}^{-1}
\end{aligned}
$$

Example 2.91. Formula (2.13) from Example 2.79 also follows as a special case; for the switching map $s_{1}: V \otimes V \rightarrow V \otimes V$ as in Theorem 2.85, $\operatorname{Tr}_{V ; V, V}\left(s_{1}\right)=$ $I d_{V}$. This is the case of Corollary 2.88 with $U=V, Z=\mathbb{K}, B_{1}=l_{V}^{-1}, B_{2}=l$, $A=s_{1}=s_{5}=\left[I d_{V} \otimes l\right] \circ\left[l_{V}^{-1} \otimes I d_{V}\right] \circ s_{5}$, and $s_{3}: V \otimes \mathbb{K} \rightarrow \mathbb{K} \otimes V$, so

$$
\operatorname{Tr}_{V ; V, V}\left(s_{5}\right)=l \circ s_{3} \circ l_{V}^{-1}=I d_{V}
$$

THEOREM 2.92. For finite-dimensional $V$ and $U$, a switching map $s: W \otimes U \rightarrow$ $U \otimes W$, and $A: V \otimes U \rightarrow V \otimes W$,

$$
\operatorname{Tr}_{V ; U, W}(A)=\operatorname{Tr}_{V \otimes U ; U, W}\left(\left[I d_{V} \otimes s\right] \circ\left[A \otimes I d_{U}\right]\right)
$$

Proof. Using Theorem 2.38, Theorem 2.30, Corollary 2.42, an easily checked equality relating the switching maps $s$ and $s^{\prime}: U \otimes U \rightarrow U \otimes U$, Theorem 2.30 again, and finally Example 2.79,

$$
\begin{aligned}
R H S & =\operatorname{Tr}_{U ; U, W}\left(\operatorname{Tr}_{V ; U \otimes U, U \otimes W}\left(\left[I d_{V} \otimes s\right] \circ\left[A \otimes I d_{U}\right]\right)\right) \\
& =\operatorname{Tr}_{U ; U, W}\left(s \circ\left(\operatorname{Tr}_{V ; U \otimes U, W \otimes U}\left(\left[A \otimes I d_{U}\right]\right)\right)\right) \\
& =\operatorname{Tr}_{U ; U, W}\left(s \circ\left[\left(\operatorname{Tr}_{V ; U, W}(A)\right) \otimes I d_{U}\right]\right) \\
& =\operatorname{Tr}_{U ; U, W}\left(\left[I d_{U} \otimes\left(\operatorname{Tr}_{V ; U, W}(A)\right)\right] \circ s^{\prime}\right) \\
& =\left(\operatorname{Tr}_{V ; U, W}(A)\right) \circ\left(\operatorname{Tr}_{U ; U, U}\left(s^{\prime}\right)\right) \\
& =\operatorname{Tr}_{V ; U, W}(A) .
\end{aligned}
$$

Exercise 2.93. For finite-dimensional $V$ and $W$, a switching map $s: W \otimes U \rightarrow$ $U \otimes W$, and $A: V \otimes U \rightarrow V \otimes W$,

$$
\operatorname{Tr}_{V ; U, W}(A)=\operatorname{Tr}_{V \otimes W ; U, W}\left(\left[A \otimes I d_{W}\right] \otimes\left[I d_{V} \otimes s\right]\right)
$$

Hint. The steps are analogous to the steps in the Proof of Theorem 2.92. If $U$ and $W$ are both finite-dimensional, then the equality of the RHS of this equation with the RHS from Theorem 2.92 follows directly from Theorem 2.29.

### 2.4.2. Coevaluation and dualizability.

THEOREM 2.94. For finite-dimensional $V, \eta_{V}: \mathbb{K} \rightarrow V \otimes V^{*}$ as in Notation 2.66, and scalar multiplication maps $l_{V}: \mathbb{K} \otimes V \rightarrow V, l_{V^{*}}: \mathbb{K} \otimes V^{*} \rightarrow V^{*}$, $l_{1}: V \otimes \mathbb{K} \rightarrow V, l_{2}: V^{*} \otimes \mathbb{K} \rightarrow V^{*}$,

$$
l_{1} \circ\left[I d_{V} \otimes E v_{V}\right] \circ\left[\eta_{V} \otimes I d_{V}\right] \circ l_{V}^{-1}=I d_{V}
$$

and

$$
l_{V^{*}} \circ\left[E v_{V} \otimes I d_{V^{*}}\right] \circ\left[I d_{V^{*}} \otimes \eta_{V}\right] \circ l_{2}^{-1}=I d_{V^{*}}
$$

Proof. In the following two diagrams, $V=V_{1}=V_{2}=V_{3}$ — the subscripts are added just to track the action of the switchings and other canonical maps. In the first diagram, the upper left square uses the formula (2.9) with $k^{-1}$ from Notation 2.66 , and is commutative by Lemma 1.35 . The $s_{5}$ notation in the right half is from Corollary 2.88 and Example 2.91. The first claim is that the lower left part of the diagram is commutative.


The commutativity of the right half of the diagram is easy to check. The first claim follows from checking that the identity map is equal to the composite of maps starting at $V$ and going clockwise. Lemma 2.78 applies.

$$
\begin{align*}
& l_{1} \circ\left[I d_{V} \otimes E v_{V}\right] \circ\left[\eta_{V} \otimes I d_{V}\right] \circ l_{V}^{-1} \\
= & l_{V} \circ\left[E v_{V} \otimes I d_{V}\right] \circ\left[I d_{V^{*}} \otimes s_{5}\right] \circ\left[k^{-1} \otimes I d_{V}\right] \circ\left[Q_{1}^{1} \otimes I d_{V}\right] \circ l_{V}^{-1}  \tag{2.18}\\
= & I d_{V}
\end{align*}
$$

The expression (2.18) is also equal to $\operatorname{Tr}_{V ; V, V}\left(s_{5}\right)=I d_{V}$ as in Examples 2.79 and 2.91.

For the second claim, consider the second diagram, where $s^{\prime \prime}$ is the switching involution from Lemma 2.81 and $s^{\prime \prime \prime \prime}$ is another switching map so that the upper
block is easily seen to be commutative.


As in the first diagram, the definition of $\eta_{V}$ is used in the left square, and the second claim is that the lower left part of the second diagram is commutative. The calculation is again to check the clockwise composition, and Lemma 2.81 applies.

$$
\begin{aligned}
& l_{V^{*}} \circ\left[E v_{V} \otimes I d_{V^{*}}\right] \circ\left[I d_{V^{*}} \otimes \eta_{V}\right] \circ l_{2}^{-1} \\
= & l_{V^{*}} \circ\left[E v_{V} \otimes I d_{V^{*}}\right] \circ s^{\prime \prime} \circ\left[k^{-1} \otimes I d_{V^{*}}\right] \circ s^{\prime \prime \prime \prime} \circ\left[I d_{V^{*}} \otimes Q_{1}^{1}\right] \circ l_{2}^{-1} \\
= & l_{V^{*}} \circ\left[E v_{V} \otimes I d_{V^{*}}\right] \circ s^{\prime \prime} \circ\left[k^{-1} \otimes I d_{V^{*}}\right] \circ\left[Q_{1}^{1} \otimes I d_{V^{*}}\right] \circ l_{V^{*}}^{-1} \\
= & I d_{V^{*}} .
\end{aligned}
$$

Definition 2.95. A vector space $V$ is dualizable means: there exists $(D, \epsilon, \eta)$, where $D$ is a vector space, and $\epsilon: D \otimes V \rightarrow \mathbb{K}$ and $\eta: \mathbb{K} \rightarrow V \otimes D$ are linear maps such that the following diagrams (involving various scalar multiplication maps) are commutative.


Example 2.96. Given $V$ as in Theorem 2.94, the space $D=V^{*}$ and the maps $\epsilon=E v_{V}$ and $\eta=\eta_{V}=s \circ k^{-1} \circ Q_{1}^{1}$ satisfy the identities from Definition 2.95.

REMARK 2.97. In category theory and other generalizations of this construction ( $[$ Stolz-Teichner $],[\mathbf{P S}]$ ), $\eta$ is called a coevaluation map. A more general notion, with left and right duals, is considered by [Maltsiniotis].

Lemma 2.98. If $V$ is dualizable, with duality data $(D, \epsilon, \eta)$, then there is an invertible map $D \rightarrow V^{*}$.

Proof. It is equivalent, by Example 1.27 and Lemma 1.21, to show there is an invertible map $\operatorname{Hom}(\mathbb{K}, D) \rightarrow \operatorname{Hom}(\mathbb{K} \otimes V, \mathbb{K})$. Denote:

$$
\begin{align*}
A: \operatorname{Hom}(\mathbb{K}, D) & \rightarrow \operatorname{Hom}(\mathbb{K} \otimes V, \mathbb{K})  \tag{2.19}\\
\delta & \mapsto(\lambda \otimes v \mapsto \epsilon((\delta(\lambda)) \otimes v)), \\
B: \operatorname{Hom}(\mathbb{K} \otimes V, \mathbb{K}) & \rightarrow \operatorname{Hom}(\mathbb{K}, D) \\
\phi & \mapsto\left(\lambda \mapsto\left(l \circ\left[\phi \otimes I d_{D}\right] \circ l^{-1} \circ \eta\right)(\lambda)\right),
\end{align*}
$$

where $l$ denotes various scalar multiplications. The following diagrams are commutative, where unlabeled arrows are scalar multiplications or their inverses.


In the left diagram, the top square is easily checked and the lower triangle uses the formula for $A$. The composition in the right column gives the identity map for $D$ by Definition 2.95, so $I d_{D} \circ \delta=B(A(\delta)): \mathbb{K} \rightarrow D$.

In the right diagram, the left column gives the identity map for $\mathbb{K} \otimes V$ by Definition 2.95. For $\lambda \otimes v \in \mathbb{K} \otimes V$,

$$
\begin{aligned}
(A \circ B)(\phi): \lambda \otimes v & \mapsto \epsilon(((B(\phi))(\lambda)) \otimes v) \\
& =\epsilon\left(\left(\left(l \circ\left[\phi \otimes I d_{D}\right] \circ l^{-1} \circ \eta\right)(\lambda)\right) \otimes v\right) \\
& =\left(\epsilon \circ\left[\left(l \circ\left[\phi \otimes I d_{D}\right] \circ l^{-1} \circ \eta\right) \otimes I d_{V}\right]\right)(\lambda \otimes v) \\
& =\left(\phi \circ I d_{\mathbb{K} \otimes V}\right)(\lambda \otimes v)
\end{aligned}
$$

Lemma 2.99. Suppose $V$ is dualizable, with two triples of duality data as in Definition 2.95: $\left(D_{1}, \epsilon_{1}, \eta_{1}\right)$ and $\left(D_{2}, \epsilon_{2}, \eta_{2}\right)$. Then the map $a_{12}: D_{1} \rightarrow D_{2}$,

$$
D_{1} \longrightarrow D_{1} \otimes \mathbb{K} \xrightarrow{\left[I d_{D_{1}} \otimes \eta_{2}\right]} D_{1} \otimes V \otimes D_{2} \xrightarrow{\left[\epsilon_{1} \otimes I d_{D_{2}}\right]} \mathbb{K} \otimes D_{2} \longrightarrow D_{2}
$$

has inverse given by the map $a_{21}: D_{2} \rightarrow D_{1}$ :

$$
D_{2} \longrightarrow D_{2} \otimes \mathbb{K} \xrightarrow{\left[I d_{D_{2}} \otimes \eta_{1}\right]} D_{2} \otimes V \otimes D_{1} \xrightarrow{\left[\epsilon_{2} \otimes I d_{D_{1}}\right]} \mathbb{K} \otimes D_{1} \longrightarrow D_{1}
$$

and $a_{12}$ satisfies the identities $\left[I d_{V} \otimes a_{12}\right] \circ \eta_{1}=\eta_{2}$ and $\epsilon_{2} \circ\left[a_{12} \otimes I d_{V}\right]=\epsilon_{1}$.

Proof. Some of the arrows in the following diagram are left unlabeled, but they involve only identity maps, scalar multiplications and their inverses, and the given $\eta_{1}, \eta_{2}, \epsilon_{1}, \epsilon_{2}$ maps.


The composition in the left column gives the identity map $D_{1} \rightarrow D_{1}$, and the middle left block is commutative, involving the composite $\left[I d_{V} \otimes \epsilon_{2}\right] \circ\left[\eta_{2} \otimes I d_{V}\right]$. The commutativity of the upper, right, and lower blocks is easy to check. The composite $D_{1} \rightarrow D_{2} \rightarrow D_{1}$ clockwise from the top is equal to $a_{21} \circ a_{12}$, and the commutativity of the diagram establishes the claim that $a_{21} \circ a_{12}=I d_{D_{1}}$; checking the inverse in the other order follows from relabeling the subscripts.

For the identity $\left[I d_{V} \otimes a_{12}\right] \circ \eta_{1}=\eta_{2}$, consider the following diagram.


The lower block uses the definition of $a_{12}$. The right block involves $\eta_{1}$ and $\epsilon_{1}$ so that one of the identities from Definition 2.95 applies. The claim is that the left triangle is commutative, and this follows from the easily checked commutativity of the outer rectangle.

Similarly for the identity $\epsilon_{2} \circ\left[a_{12} \otimes I d_{V}\right]=\epsilon_{1}$, consider the following diagram.


The left block uses the definition of $a_{12}$. The top block involves $\eta_{2}$ and $\epsilon_{2}$ so that one of the identities from Definition 2.95 applies. The claim is that the right triangle is commutative, and this follows from the easily checked commutativity of the outer rectangle.

In the case $D=V^{*}$ from Example 2.96, the maps from Lemma 2.98 and 2.99 agree (up to composition with trivial invertible maps as in the following Exercise) and so they are canonical.

Exercise 2.100. Applying Lemma 2.98 to the triple $\left(V^{*}, E v_{V}, \eta_{V}\right)$ from Example 2.96 gives a map $A$ such that the left diagram is commutative. If $V$ is also dualizable with $\left(D_{2}, \epsilon_{2}, \eta_{2}\right)$, then the maps $B$ from Lemma 2.98 and $a_{12}$ from Lemma 2.99 make the right diagram commutative.


Hint. The first claim is left as an exercise. For the second claim, consider $\phi \in V^{*}, \lambda \in \mathbb{K}$; the following quantities agree, showing the right diagram is commutative.

$$
\begin{aligned}
\left(m \circ a_{12}\right)(\phi): \lambda & \mapsto\left(m\left(a_{12}(\phi)\right)\right)(\lambda)=\lambda \cdot a_{12}(\phi) \\
& =\lambda \cdot\left(l \circ\left[E v_{V} \otimes I d_{D_{2}}\right] \circ\left[I d_{V^{*}} \otimes \eta_{2}\right] \circ l^{-1}\right)(\phi) \\
& =\lambda \cdot\left(l \circ\left[E v_{V} \otimes I d_{D_{2}}\right]\right)\left(\phi \otimes\left(\eta_{2}(1)\right)\right), \\
\left(B \circ \operatorname{Hom}\left(l, I d_{\mathbb{K}}\right)\right)(\phi): \lambda & \mapsto(B(\phi \circ l))(\lambda) \\
& =\left(l \circ\left[(\phi \circ l) \otimes I d_{D_{2}}\right] \circ l^{-1} \circ \eta_{2}\right)(\lambda) \\
& =\left(l \circ\left[(\phi \circ l) \otimes I d_{D_{2}}\right]\right)\left(1 \otimes\left(\eta_{2}(\lambda)\right)\right) \\
& =\left(l \circ\left[\phi \otimes I d_{D_{2}}\right]\right)\left(\eta_{2}(\lambda)\right) .
\end{aligned}
$$

Lemma 2.101. If $V$ is dualizable, with $(D, \epsilon, \eta)$, then $D$ is dualizable, with duality data $(V, \epsilon \circ s, s \circ \eta)$, where $s: V \otimes D \rightarrow D \otimes V$ is a switching map.

Proof. In the following diagram, $V=V_{1}=V_{2}$.


Unlabeled arrows are obvious switching or scalar multiplication. The $s_{1}, s_{2}$ switchings are as indicated by the subscripts. The lower left square is commutative, by the first identity from Definition 2.95, and the other small squares are easy to check, so the large square is commutative, which is the second identity for $(V, \epsilon \circ s, s \circ \eta)$ from Definition 2.95 applied to $D$.

Similarly, in the following diagram, $D=D_{1}=D_{2}$.


Again, the lower left square is commutative by hypothesis, and the commutativity of the large square is the first identity for $(V, \epsilon \circ s, s \circ \eta)$ from Definition 2.95 applied to $D$.

Lemma 2.102. If $V$ is dualizable, then $d_{V}$ is invertible.
Proof. Let $a_{1}: D \rightarrow V^{*}$ be the invertible map from Lemma 2.98, defined in terms of $\epsilon$ and $A_{1}=A$ from (2.19). The transposes of these maps appear in the right square of the diagram.

By Lemma 2.101, $D$ is also dualizable, with an evaluation map $\epsilon \circ s$, which defines $A_{2}$ as in (2.19) and an invertible map $a_{2}: V \rightarrow D^{*}$ from Lemma 2.98 again. These maps appear in the top square of the diagram.


The two squares in the diagram are commutative by construction. The following calculation checks that $a_{1}^{*} \circ d_{V}: V \rightarrow D^{*}$ is equal to $a_{2}$.

$$
\begin{aligned}
l_{D}^{*} \circ a_{1}^{*} \circ d_{V} & =l_{D}^{*} \circ m_{D}^{*} \circ A_{1}^{*} \circ\left(l_{V}^{* *}\right)^{-1} \circ d_{V} \\
& =\left(\left(l_{V}^{-1}\right)^{*} \circ A_{1} \circ m_{D} \circ l_{D}\right)^{*} \circ d_{V}: \\
v & \mapsto\left(d_{V}(v)\right) \circ\left(\left(l_{V}^{-1}\right)^{*} \circ A_{1} \circ m_{D} \circ l_{D}\right): \\
\lambda \otimes u & \mapsto\left(d_{V}(v)\right)\left(\left(A_{1}\left(m_{D}(\lambda \cdot u)\right)\right) \circ l_{V}^{-1}\right) \\
& =\left(A_{1}\left(m_{D}(\lambda \cdot u)\right)(1 \otimes v)\right. \\
& =\epsilon\left(\left(\left(m_{D}(\lambda \cdot u)\right)(1)\right) \otimes v\right) \\
& =\epsilon((\lambda \cdot u) \otimes v), \\
A_{2} \circ m_{V}: v & \mapsto A_{2}\left(m_{V}(v)\right): \\
\lambda \otimes u & \mapsto(\epsilon \circ s)\left(\left(\left(m_{V}(v)\right)(\lambda)\right) \otimes u\right) \\
& =(\epsilon \circ s)((\lambda \cdot v) \otimes u) \\
& =\epsilon(u \otimes(\lambda \cdot v)) .
\end{aligned}
$$

It follows that $d_{V}=\left(a_{1}^{*}\right)^{-1} \circ a_{2}$ is invertible.
Theorem 2.103. Given $V$, the following are equivalent.
(1) $k: V^{*} \otimes V \rightarrow \operatorname{End}(V)$ is invertible.
(2) $V$ is dualizable.
(3) $d: V \rightarrow V^{* *}$ is invertible.
(4) $V$ is finite-dimensional.

Proof. The Proof of Theorem 2.94 only used the property that $k$ is invertible to show that $V$ is dualizable, with $D=V^{*}, \epsilon=E v_{V}$, and $\eta=\eta_{V}=s \circ k^{-1} \circ Q_{1}^{1}$; this is the implication $(1) \Longrightarrow(2)$. Lemma 2.102 just showed $(2) \Longrightarrow$ (3), and Theorem 2.82 showed directly that $(1) \Longrightarrow$ (3). The implication (3) $\Longrightarrow$ (4) was stated without proof in Claim 1.15 and the implication $(4) \Longrightarrow(1)$ was stated in Lemma 1.59, which was proved using Claim 1.33.

REmark 2.104. In the special case where $(D, \epsilon, \eta)=\left(V^{*}, E v_{V}, \eta_{V}\right)$ from Example 2.96, the map $a_{1}$ from Lemma 2.102 is $I d_{V^{*}}$ as in Exercise 2.100, and the map $a_{2}$ is exactly $d_{V}$. This shows that Lemma 2.98 (establishing that $A_{2}$ has an inverse, $B$ ) is related to Theorem 2.82 (showing that $d_{V}$ has an inverse); the second diagram from the Proof of Theorem 2.82 is similar to the right diagram from the Proof of Lemma 2.98.

The following result is a generalization of Theorem 2.67.
Theorem 2.105. If $V$ is dualizable, with any triple $\left(D_{2}, \epsilon_{2}, \eta_{2}\right)$ as in Definition 2.95, and $s_{2}: V \otimes D_{2} \rightarrow D_{2} \otimes V$ is the switching map, then for any $F: V \otimes U \rightarrow$ $V \otimes W$,

$$
\left(\operatorname{Tr}_{V ; U, W}(F)\right)(u)=\left(l_{W} \circ\left[\epsilon_{2} \otimes I d_{W}\right] \circ\left[I d_{D_{2}} \otimes F\right] \circ\left[\left(s_{2} \circ \eta_{2}\right) \otimes I d_{U}\right] \circ l_{U}^{-1}\right)(u)
$$

Proof. By Theorem 2.103, $V$ must be finite-dimensional, so the trace exists. By Theorem 2.94 (the Proof of which uses Theorem 2.67) and Example 2.96, there is another triple $\left(D_{1}, \epsilon_{1}, \eta_{1}\right)=\left(V^{*}, E v_{V}, \eta_{V}\right)$ satisfying Definition 2.95. There is
an invertible map $a_{12}: V^{*} \rightarrow D_{2}$ by Lemma 2.99. Consider the following diagram.


The composition from $U$ to $W$ along the top row gives $\operatorname{Tr}_{V ; U, W}(F)$ by Theorem 2.67. The left square is from Theorem 2.94 and the left and right triangles are commutative by Lemma 2.99. The RHS of the Theorem is the path from $U$ to $W$ along the lowest row, so the claimed equality follows from the easily checked commutativity of the middle block.

Corollary 2.106. If $V$ is dualizable, with any triple $(D, \epsilon, \eta)$ as in Definition 2.95, and $s: V \otimes D \rightarrow D \otimes V$ is the switching map, then for any $A: V \rightarrow V \otimes W$,

$$
\operatorname{Tr}_{V ; W}(A)=\left(l_{W} \circ\left[\epsilon \otimes I d_{W}\right] \circ\left[I d_{D} \otimes A\right] \circ s \circ \eta\right)(1) .
$$

Proof. This follows from Theorem 2.105 in the same way that Corollary 2.68 follows from Theorem 2.67. By Theorem 2.54,

$$
\begin{aligned}
L H S & =\left(\operatorname{Tr}_{V ; \mathbb{K}, W}\left(A \circ l_{V}\right)\right)(1) \\
& =\left(l_{W} \circ\left[\epsilon \otimes I d_{W}\right] \circ\left[I d_{D} \otimes\left(A \circ l_{V}\right)\right] \circ\left[(s \circ \eta) \otimes I d_{\mathbb{K}}\right] \circ l_{\mathbb{K}}^{-1}\right)(1) \\
& =R H S .
\end{aligned}
$$

This generalizes Corollary 2.68 by showing that, for any duality data $(D, \epsilon, \eta)$, the $W$-valued trace of $A$ is the output of 1 under the composite map

$$
\mathbb{K} \xrightarrow{\eta} V \otimes D \xrightarrow{s} D \otimes V \xrightarrow{\left[I d_{D} \otimes A\right]} D \otimes V \otimes W \xrightarrow{l_{W} \circ\left[\epsilon \otimes I d_{W}\right]} W
$$

Corollary 2.107. If $V$ is dualizable, with any triple $(D, \epsilon, \eta)$ as in Definition 2.95, and $s: V \otimes D \rightarrow D \otimes V$ is the switching map, then for any $A: V \rightarrow V$,

$$
\operatorname{Tr}_{V}(A)=\left(\epsilon \circ\left[I d_{D} \otimes A\right] \circ s \circ \eta\right)(1)
$$

Proof. By Theorem 2.53 and Corollary 2.106,

$$
\begin{aligned}
L H S & =\operatorname{Tr}_{V ; \mathbb{K}}\left(l_{V}^{-1} \circ A\right) \\
& =\left(l_{\mathbb{K}} \circ\left[\epsilon \otimes I d_{\mathbb{K}}\right] \circ\left[I d_{D} \otimes\left(l_{V}^{-1} \circ A\right)\right] \circ s \circ \eta\right)(1) \\
& =R H S .
\end{aligned}
$$

This generalizes Theorem 2.10 and the map $\mathbb{K} \rightarrow \mathbb{K}$ from (2.6) by showing that for any $(D, \epsilon, \eta)$, the trace of $A \in \operatorname{End}(V)$ is the output of 1 under the composite map

$$
\mathbb{K} \xrightarrow{\eta} V \otimes D \xrightarrow{s} D \otimes V \xrightarrow{\left[I d_{D} \otimes A\right]} D \otimes V \xrightarrow{\epsilon} \mathbb{K} .
$$

As mentioned at the beginning of this Section, the above results can be used as definitions of the trace: Theorem 2.105 for $\operatorname{Tr}_{V ; U, W}$, Corollary 2.106 for $\operatorname{Tr}_{V ; W}$, and Corollary 2.107 for $\operatorname{Tr}_{V}$. The proofs that these formulas are equivalent to the definitions from the previous Sections show that the trace can be calculated using any choice of duality data $(D, \epsilon, \eta)$, and that the output does not depend on the choice. Using this approach can also lead to simpler proofs of some properties of the trace.

Exercise 2.108. The result of Theorem 2.27,

$$
\operatorname{Tr}_{V}(H)=\left(\operatorname{Tr}_{V ; \mathbb{K}, \mathbb{K}}\left(l_{V}^{-1} \circ H \circ l_{V}\right)\right)(1),
$$

can be given a different (and simpler) proof using a choice of duality $(D, \epsilon, \eta)$.
Hint. In the following diagram,

the lower row is copied from Corollary 2.107, corresponding to $\operatorname{Tr}_{V}(H) \cdot I d_{\mathbb{K}}$ as in (2.6) from Theorem 2.27. The clockwise path from $\mathbb{K}$ to $\mathbb{K}$ is $\operatorname{Tr}_{V ; \mathbb{K}, \mathbb{K}}\left(l_{V}^{-1} \circ H \circ l_{V}\right)$, by Theorem 2.105, in the case $U=W=\mathbb{K}$. The middle block in the diagram is commutative by Lemma 1.35, and the left and right blocks by versions of Lemma 1.37, and the claim follows from the commutativity of the diagram.

Remark 2.109. Theorem 2.27, Exercise 2.55, and Exercise 2.108 give some details omitted from $\left[\mathbf{C}_{2}\right]$ Example 2.13.

Big Exercise 2.110. Theorem 2.30, and some of the other results of Section 2.2 .2 , can be proved starting with Theorem 2.105 as a definition of the generalized trace.

Exercise 2.111. For any spaces $D, U, V$, the arrows in this diagram are invertible.


If $V$ is dualizable with data $(D, \epsilon, \eta)$, then on the right, there is a distinguished element $\left[I d_{U} \otimes \epsilon\right] \in \operatorname{Hom}(U \otimes D \otimes V, U \otimes \mathbb{K})$. In the case $(D, \epsilon, \eta)=\left(V^{*}, E v_{V}, \eta_{V}\right)$ from Example 2.96, there is a distinguished element $k_{V U} \in \operatorname{Hom}\left(V^{*} \otimes U, \operatorname{Hom}(V, U)\right)$ on
the left, and the two elements are related by the composition of arrows in the path.

Big Exercise 2.112. For a dualizable space $V$, define (as in [PS] §2) the mate of a map $A: V \otimes U \rightarrow V \otimes W$ with respect to duality data $(D, \epsilon, \eta)$ as the map $A^{m}: D \otimes U \rightarrow D \otimes W$ given by the composition in the following diagram.


Then (as in [PS] §7),

$$
\operatorname{Tr}_{D ; U, W}\left(A^{m}\right)=\operatorname{Tr}_{V ; U, W}(A)
$$

In particular, LHS does not depend on the choice of $(D, \epsilon, \eta)$.
Hint. By Lemma 2.101, $D$ is dualizable, so by Theorem 2.105, LHS exists. The formula from Theorem 2.105 does not depend on the choice of duality data for $D$; it is convenient to choose to use $(V, \epsilon \circ s, s \circ \eta)$ from Lemma 2.101. In the following diagram, the lower middle block uses maps from the above definition of $A^{m}$, including

$$
a=\left[I d_{V} \otimes\left[I d_{D} \otimes\left[A \otimes I d_{D}\right]\right]\right] .
$$



By Theorem 2.105, the path from $U$ to $W$ along the top row is $\operatorname{Tr}_{V ; U, W}(A)$, and from $U$ to $W$ along the lowest row is $\operatorname{Tr}_{D ; U, W}\left(A^{m}\right)$. The claimed equality follows from the commutativity of the diagram. The maps in the top middle block are as in the next diagram, with notation $D=D_{1}=D_{2}$ and $V=V_{1}=V_{2}=V_{3}$ to indicate various switching maps.


The above diagram is commutative; the middle block involving both $\eta$ and $\epsilon$ uses one of the properties from Definition 2.95. Using these maps as specified in the above right column, it is also easy to check that the right block from the big diagram is commutative.

To check that the left block from the big diagram is commutative, note that the path going up from $U$ to $D \otimes V \otimes U$ takes input $u$ to output $((s \circ \eta)(1)) \otimes u$, and the downward path also takes $u$ to $((s \circ \eta)(1)) \otimes u$. So, it is enough to check that $((s \circ \eta)(1)) \otimes u$ has the same output along the two paths leading to $V \otimes D \otimes V \otimes U \otimes D$. This is shown in the next diagram, where the numbering $V=V_{1}=V_{2}$ and $D=$ $D_{1}=D_{2}$ is chosen to match the left column of the previous diagram.


All the blocks in the last diagram are commutative, except for the center right block. However, starting with $(\eta(1)) \otimes u \in V \otimes D \otimes U$ in the lower right corner, all paths leading upward to $V \otimes D \otimes V \otimes U \otimes D$ give the same output. The upward right column, and the clockwise path around the left side, correspond, respectively, to the lower half and the upper half of the left block in the big diagram.

## CHAPTER 3

## Bilinear Forms

As a special case of Definition 1.22 , consider a bilinear function $V \times V \rightsquigarrow \mathbb{K}$, which takes as input an ordered pair of elements of a vector space $V$ and gives as output an element of $\mathbb{K}$ (a scalar), so that it is $\mathbb{K}$-linear in either input when the other is fixed. Definition 3.1 encodes this idea in a convenient way using linear maps, as described in Example 1.50. This Chapter examines the trace of a bilinear form on a finite-dimensional space $V$, with respect to a metric $g$ on $V$.

### 3.1. Symmetric bilinear forms

Definition 3.1. A bilinear form $h$ on a vector space $V$ is a $\mathbb{K}$-linear map $h: V \rightarrow V^{*}$.

For vectors $u, v \in V$, a bilinear form $h$ acts on $u$ to give an element of the dual, $h(u) \in V^{*}$, which then acts on $v$ to give $(h(u))(v) \in \mathbb{K}$.

Definition 3.2. The transpose operator, $T_{V} \in \operatorname{End}\left(\operatorname{Hom}\left(V, V^{*}\right)\right)$, is defined by $T_{V}=\operatorname{Hom}\left(d_{V}, I d_{V^{*}}\right) \circ t_{V V^{*}}: h \mapsto h^{*} \circ d_{V}$.

Lemma 3.3. $T_{V}$ is an involution.
Proof. The effect of the operator $T_{V}$ is to switch the two inputs:

$$
\begin{equation*}
\left(\left(T_{V}(h)\right)(u)\right)(v)=\left(\left(h^{*} \circ d_{V}\right)(u)\right)(v)=\left(d_{V}(u)\right)(h(v))=(h(v))(u) \tag{3.1}
\end{equation*}
$$

so the claim is obvious from Equation (3.1). This is also a corollary of Lemma 4.4 from Section 4.1, which considers some other approaches to bilinear forms and the definition of transpose, using different spaces and canonical maps.

Definition 3.4. A bilinear form $h$ is symmetric means: $h=T_{V}(h) . h$ is antisymmetric means: $h=-T_{V}(h)$.

If $h$ is symmetric, then $(h(u))(v)=(h(v))(u)$, and if $h$ is antisymmetric, then $(h(u))(v)=-(h(v))(u)$.

Notation 3.5. If $\frac{1}{2} \in \mathbb{K}$, then the involution $T_{V}$ on $\operatorname{Hom}\left(V, V^{*}\right)$ produces, as in Lemma 1.112, a direct sum of the subspaces of symmetric and antisymmetric forms on $V$, denoted $\operatorname{Hom}\left(V, V^{*}\right)=\operatorname{Sym}(V) \oplus \operatorname{Alt}(V)$.

In particular, any bilinear form $h$ is canonically the sum of a symmetric form and an antisymmetric form,

$$
\begin{equation*}
h=\frac{1}{2} \cdot\left(h+T_{V}(h)\right)+\frac{1}{2} \cdot\left(h-T_{V}(h)\right) \tag{3.2}
\end{equation*}
$$

Lemma 3.6. If $\frac{1}{2} \in \mathbb{K}$, then the canonical map $k_{U U^{*}}: U^{*} \otimes U^{*} \rightarrow \operatorname{Hom}\left(U, U^{*}\right)$ respects the direct sums:

$$
k_{U U^{*}}: S^{2}\left(U^{*}\right) \oplus \Lambda^{2}\left(U^{*}\right) \rightarrow \operatorname{Sym}(U) \oplus \operatorname{Alt}(U)
$$

Proof. The direct sums are from Example 1.116, produced by the involution $s$ on $U^{*} \otimes U^{*}$, and Notation 3.5, produced by the involution $T_{U}$. It is easily checked that the following diagram is commutative.


So $k_{U U^{*}}$ respects the direct sums by Lemma 1.118.
Definition 3.7. For a map $H: U \rightarrow V$, and a bilinear form $h: V \rightarrow V^{*}$, the map $H^{*} \circ h \circ H$ is a bilinear form on $U$, called the pullback of $h$.

Lemma 3.8. For any vector spaces $U, V$, and any map $H: U \rightarrow V$, the following diagram is commutative.


If, further, $\frac{1}{2} \in \mathbb{K}$, then the map $h \mapsto H^{*} \circ h \circ H$ respects the direct sums:

$$
\operatorname{Hom}\left(H, H^{*}\right): \operatorname{Sym}(V) \oplus \operatorname{Alt}(V) \rightarrow \operatorname{Sym}(U) \oplus \operatorname{Alt}(U)
$$

Proof. Using Lemma 1.6 and Lemma 1.13, the transpose of the pullback of a bilinear form $h: V \rightarrow V^{*}$ is the pullback of the transpose:

$$
\begin{aligned}
T_{U}\left(H^{*} \circ h \circ H\right) & =\left(H^{*} \circ h \circ H\right)^{*} \circ d_{U}=H^{*} \circ h^{*} \circ H^{* *} \circ d_{U} \\
& =H^{*} \circ h^{*} \circ d_{V} \circ H=H^{*} \circ\left(T_{V}(h)\right) \circ H
\end{aligned}
$$

The claim about the direct sums from Notation 3.5 follows from Lemma 1.118.
So, if $h \in \operatorname{Sym}(V)$, then its pullback satisfies $H^{*} \circ h \circ H \in \operatorname{Sym}(U)$. The pullback of an antisymmetric form is similarly antisymmetric

Notation 3.9. If an arbitrary vector space $V$ is a direct sum of $V_{1}$ and $V_{2}$, as in Definition 1.71, and $h_{1}: V_{1} \rightarrow V_{1}^{*}, h_{2}: V_{2} \rightarrow V_{2}^{*}$, then

$$
\begin{equation*}
P_{1}^{*} \circ h_{1} \circ P_{1}+P_{2}^{*} \circ h_{2} \circ P_{2}: V \rightarrow V^{*} \tag{3.3}
\end{equation*}
$$

will be called the direct sum $h_{1} \oplus h_{2}$ of the bilinear forms $h_{1}$ and $h_{2}$.
The expression (3.3) is the same construction as in Lemma 1.80, applied to the direct sum $V^{*}=V_{1}^{*} \oplus V_{2}^{*}$ from Example 1.78.

THEOREM 3.10. $T_{V}\left(h_{1} \oplus h_{2}\right)=\left(T_{V_{1}}\left(h_{1}\right)\right) \oplus\left(T_{V_{2}}\left(h_{2}\right)\right)$.
Proof.

$$
\begin{aligned}
L H S & =\left(P_{1}^{*} \circ h_{1} \circ P_{1}\right)^{*} \circ d_{V}+\left(P_{2}^{*} \circ h_{2} \circ P_{2}\right)^{*} \circ d_{V} \\
& =P_{1}^{*} \circ h_{1}^{*} \circ P_{1}^{* *} \circ d_{V}+P_{2}^{*} \circ h_{2}^{*} \circ P_{2}^{* *} \circ d_{V} \\
& =P_{1}^{*} \circ h_{1}^{*} \circ d_{V_{1}} \circ P_{1}+P_{2}^{*} \circ h_{2}^{*} \circ d_{V_{2}} \circ P_{2} \\
& =P_{1}^{*} \circ\left(T_{V_{1}}\left(h_{1}\right)\right) \circ P_{1}+P_{2}^{*} \circ\left(T_{V_{2}}\left(h_{2}\right)\right) \circ P_{2}=R H S
\end{aligned}
$$

using Lemma 1.6 and Lemma 1.13.
It follows that the direct sum of symmetric forms is symmetric, and that the direct sum of antisymmetric forms is antisymmetric.

The following Lemma will be convenient in some of the theorems about the tensor product of symmetric forms.

Lemma 3.11. ([B] §II.4.4) For $A: U_{1} \rightarrow U_{2}$ and $B: V_{1} \rightarrow V_{2}$, the following diagram is commutative.


Proof. The scalar multiplication $\mathbb{K} \otimes \mathbb{K} \rightarrow \mathbb{K}$ is denoted $l$. The top square is commutative by Lemma 1.36, and the lower one by Lemma 1.6.

Theorem 3.12. If $h_{1}: U \rightarrow U^{*}$ and $h_{2}: V \rightarrow V^{*}$, then

$$
\operatorname{Hom}\left(I d_{U \otimes V}, l\right) \circ j \circ\left[h_{1} \otimes h_{2}\right]:(U \otimes V) \rightarrow(U \otimes V)^{*}
$$

is a bilinear form such that

$$
T_{U \otimes V}\left(\operatorname{Hom}\left(I d_{U \otimes V}, l\right) \circ j \circ\left[h_{1} \otimes h_{2}\right]\right)
$$

is equal to

$$
\operatorname{Hom}\left(I d_{U \otimes V}, l\right) \circ j \circ\left[\left(T_{U}\left(h_{1}\right)\right) \otimes\left(T_{V}\left(h_{2}\right)\right)\right]
$$

Proof. First, for any $U, V$, the following diagram is commutative:


$$
\begin{aligned}
u \otimes v & \mapsto\left(j^{*} \circ \operatorname{Hom}\left(I d_{U \otimes V}, l\right)^{*} \circ d_{U \otimes V}\right)(u \otimes v): \\
\phi \otimes \xi & \mapsto\left(d_{U \otimes V}(u \otimes v)\right)\left(\operatorname{Hom}\left(I d_{U \otimes V}, l\right)([\phi \otimes \xi])\right) \\
& =l([\phi \otimes \xi](u \otimes v)) \\
& =\phi(u) \cdot \xi(v), \\
u \otimes v & \mapsto\left(\operatorname{Hom}\left(I d_{U^{*} \otimes V}, l\right) \circ j \circ\left[d_{U} \otimes d_{V}\right]\right)(u \otimes v) \\
& =l \circ\left[\left(d_{U}(u)\right) \otimes\left(d_{V}(v)\right)\right]: \\
\phi \otimes \xi & \mapsto \phi(u) \cdot \xi(v) .
\end{aligned}
$$

Note that the bottom row of the diagram is one of the columns of the diagram in Lemma 3.11 in the case $U_{2}=U^{*}, V_{2}=V^{*}$. The statement of the Theorem follows, using the above commutativity and Lemma 3.11.

$$
\begin{aligned}
T_{U \otimes V}\left(h_{1} \otimes h_{2}\right) & =\left(\operatorname{Hom}\left(I d_{U \otimes V}, l\right) \circ j \circ\left[h_{1} \otimes h_{2}\right]\right)^{*} \circ d_{U \otimes V} \\
& =\left[h_{1} \otimes h_{2}\right]^{*} \circ j^{*} \circ \operatorname{Hom}\left(I d_{U \otimes V}, l\right)^{*} \circ d_{U \otimes V} \\
& =\left[h_{1} \otimes h_{2}\right]^{*} \circ \operatorname{Hom}\left(I d_{U^{*} \otimes V^{*}}, l\right) \circ j \circ\left[d_{U} \otimes d_{V}\right] \\
& =\operatorname{Hom}\left(I d_{U \otimes V}, l\right) \circ j \circ\left[h_{1}^{*} \otimes h_{2}^{*}\right] \circ\left[d_{U} \otimes d_{V}\right] \\
& =\operatorname{Hom}\left(I d_{U \otimes V}, l\right) \circ j \circ\left[\left(T_{U}\left(h_{1}\right)\right) \otimes\left(T_{V}\left(h_{2}\right)\right)\right] .
\end{aligned}
$$

Notation 3.13. The bilinear form $\operatorname{Hom}\left(I d_{U \otimes V}, l\right) \circ j \circ\left[h_{1} \otimes h_{2}\right]$ from the above Theorem will be called the tensor product of bilinear forms, and denoted $\left\{h_{1} \otimes h_{2}\right\}$, in analogy with the bracket notation. As defined, the tensor product bilinear form acts as

$$
\left(\left\{h_{1} \otimes h_{2}\right\}\left(u_{1} \otimes v_{1}\right)\right)\left(u_{2} \otimes v_{2}\right)=\left(h_{1}\left(u_{1}\right)\right)\left(u_{2}\right) \cdot\left(h_{2}\left(v_{1}\right)\right)\left(v_{2}\right)
$$

When $h_{1}$ and $h_{2}$ are symmetric forms, it is clear from this formula that $\left\{h_{1} \otimes h_{2}\right\}$ is also symmetric, but the above proof, using Definition 3.4, makes explicit the roles of the symmetry and the scalar multiplication. It also follows that the tensor product of antisymmetric forms is symmetric.

There is a distributive law for the direct sum and tensor product of bilinear forms. Let $V$ be a direct sum of $V_{1}$ and $V_{2}$, and recall, from Example 1.75, that $V \otimes U$ is a direct sum of $V_{1} \otimes U$ and $V_{2} \otimes U$, with projection maps $\left[P_{i} \otimes I d_{U}\right]$.

Theorem 3.14. For bilinear forms $h_{1}, h_{2}, g$ on arbitrary vector spaces $V_{1}, V_{2}$, $U$, the following bilinear forms on $V \otimes U$ are equal:

$$
\left\{\left(h_{1} \oplus h_{2}\right) \otimes g\right\}=\left\{h_{1} \otimes g\right\} \oplus\left\{h_{2} \otimes g\right\}
$$

Proof. Unraveling the definitions, and applying Lemma 3.11 and Lemma 1.35 gives the claimed equality:

$$
\begin{aligned}
R H S= & {\left[P_{1} \otimes I d_{U}\right]^{*} \circ \operatorname{Hom}\left(I d_{V_{1} \otimes U}, l\right) \circ j \circ\left[h_{1} \otimes g\right] \circ\left[P_{1} \otimes I d_{U}\right] } \\
& +\left[P_{2} \otimes I d_{U}\right]^{*} \circ \operatorname{Hom}\left(I d_{V_{2} \otimes U}, l\right) \circ j \circ\left[h_{2} \otimes g\right] \circ\left[P_{2} \otimes I d_{U}\right] \\
= & \operatorname{Hom}\left(I d_{V \otimes U}, l\right) \circ j \circ\left[P_{1}^{*} \otimes I d_{U}\right] \circ\left[h_{1} \otimes g\right] \circ\left[P_{1} \otimes I d_{U}\right] \\
& +\operatorname{Hom}\left(I d_{V \otimes U}, l\right) \circ j \circ\left[P_{2}^{*} \otimes I d_{U}\right] \circ\left[h_{2} \otimes g\right] \circ\left[P_{2} \otimes I d_{U}\right] \\
= & \operatorname{Hom}\left(I d_{V \otimes U}, l\right) \circ j \circ\left[\left(P_{1}^{*} \circ h_{1} \circ P_{1}+P_{2}^{*} \circ h_{2} \circ P_{2}\right) \otimes g\right] \\
= & \text { LHS. }
\end{aligned}
$$

### 3.2. Metrics

Definition 3.15. A metric $g$ on $V$ is a symmetric, invertible map $g: V \rightarrow V^{*}$.
The invertibility of a metric as in Definition 3.15 implies a non-degeneracy condition: for each non-zero $v \in V$, there exists a vector $u \in V$ so that $(g(v))(u) \neq$ 0 . Also, by the following Theorem, a metric exists only on finite-dimensional vector spaces.

THEOREM 3.16. Given a symmetric (or antisymmetric) bilinear form $g: V \rightarrow$ $V^{*}$, the following are equivalent.
(1) $V$ is finite-dimensional and there exists $P: V^{*} \rightarrow V$ such that $P \circ g=I d_{V}$.
(2) $V$ is finite-dimensional and there exists $Q: V^{*} \rightarrow V$ such that $g \circ Q=$ $I d_{V^{*}}$.
(3) $g$ is invertible.

Proof. Let $g$ be symmetric; the antisymmetric case is similar.
If $g$ is invertible, then from $g^{*} \circ d_{V}=g$ and Lemma 1.11,

$$
\left(g^{-1}\right)^{*} \circ g=\left(g^{*}\right)^{-1} \circ g=d_{V}
$$

is invertible, so $V$ is finite-dimensional by Claim 1.15, which implies (1) and (2).
Assuming (1) and using Claim 1.15,

$$
I d_{V^{*}}=I d_{V}^{*}=(P \circ g)^{*}=g^{*} \circ P^{*}=g \circ d_{V}^{-1} \circ P^{*}
$$

so $g$ has a left inverse and a right inverse, and (3) follows, as in Exercise 0.48. Similarly, assuming (2),

$$
I d_{V^{* *}}=I d_{V^{*}}^{*}=(g \circ Q)^{*}=Q^{*} \circ g^{*}=Q^{*} \circ g \circ d_{V}^{-1}
$$

so $d_{V}=Q^{*} \circ g \Longrightarrow I d_{V}=d_{V}^{-1} \circ Q^{*} \circ g$, and $g$ has a left inverse and a right inverse.

THEOREM 3.17. Given a metric $g$ on $V$, the bilinear form $d_{V} \circ g^{-1}: V^{*} \rightarrow V^{* *}$ is a metric on $V^{*}$.

Proof. To show $d_{V} \circ g^{-1}$ is symmetric, use the definition of $T_{V^{*}}$ and Lemma 1.16:

$$
T_{V^{*}}\left(d_{V} \circ g^{-1}\right)=\left(d_{V} \circ g^{-1}\right)^{*} \circ d_{V^{*}}=\left(g^{-1}\right)^{*} \circ d_{V}^{*} \circ d_{V^{*}}=\left(g^{*}\right)^{-1}=d_{V} \circ g^{-1}
$$

The last step uses the symmetry of $g$. This map is invertible by Theorem 3.16 and Claim 1.15.

The bilinear form $d_{V} \circ g^{-1}$ could be called the metric induced by $g$ on $V^{*}$, or the dual metric. It acts on elements $\phi, \xi \in V^{*}$ as

$$
\left(\left(d_{V} \circ g^{-1}\right)(\phi)\right)(\xi)=\xi\left(g^{-1}(\phi)\right) .
$$

COROLLARY 3.18. If $g_{1}$ is a metric on $V_{1}$ and $g_{2}$ is a metric on $V_{2}$, then $g_{1} \oplus g_{2}$ is a metric on $V=V_{1} \oplus V_{2}$.

Proof. The direct sum $g_{1} \oplus g_{2}$ as in Notation 3.9 is symmetric by Theorem 3.10, and is invertible by Lemma 1.80. Specifically, the inclusion maps $Q_{1}, Q_{2}$ are used to construct an inverse to the expression (3.3):

$$
\begin{align*}
& \left(Q_{1} \circ g_{1}^{-1} \circ Q_{1}^{*}+Q_{2} \circ g_{2}^{-1} \circ Q_{2}^{*}\right) \circ\left(P_{1}^{*} \circ g_{1} \circ P_{1}+P_{2}^{*} \circ g_{2} \circ P_{2}\right)=I d_{V}  \tag{3.4}\\
& \left(P_{1}^{*} \circ g_{1} \circ P_{1}+P_{2}^{*} \circ g_{2} \circ P_{2}\right) \circ\left(Q_{1} \circ g_{1}^{-1} \circ Q_{1}^{*}+Q_{2} \circ g_{2}^{-1} \circ Q_{2}^{*}\right)=I d_{V^{*}}
\end{align*}
$$

Corollary 3.19. If $g_{1}$ and $g_{2}$ are metrics on $U$ and $V$, then $\left\{g_{1} \otimes g_{2}\right\}$ is a metric on $U \otimes V$.

Proof. The bilinear form

$$
\left\{g_{1} \otimes g_{2}\right\}=\operatorname{Hom}\left(I d_{U \otimes V}, l\right) \circ j \circ\left[g_{1} \otimes g_{2}\right]
$$

as in Notation 3.13 is symmetric by Theorem 3.12, $j$ is invertible by the finitedimensionality (Claim 1.33), and the inverse of $\operatorname{Hom}\left(I d_{U \otimes V}, l\right) \circ j \circ\left[g_{1} \otimes g_{2}\right]$ : $U \otimes V \rightarrow(U \otimes V)^{*}$ is

$$
\left[g_{1}^{-1} \otimes g_{2}^{-1}\right] \circ j^{-1} \circ \operatorname{Hom}\left(I d_{U \otimes V}, l^{-1}\right)
$$

ExERCISE 3.20. If $h_{1}, h_{2}$, and $g$ are metrics on $V_{1}, V_{2}$, and $U$, and $h=h_{1} \oplus h_{2}$ is the direct sum bilinear form on $V=V_{1} \oplus V_{2}$, then the induced tensor product metric $\{h \otimes g\}$ on $V \otimes U$ coincides with the induced direct sum metric on $\left(V_{1} \otimes U\right) \oplus\left(V_{2} \otimes U\right)$, as in Theorem 3.14.

### 3.3. Isometries

Example 3.21. If $h$ is a metric on $V$, and $H: U \rightarrow V$ is invertible, then the pullback $H^{*} \circ h \circ H$ (as in Definition 3.7) is a metric on $U$, since it is symmetric by Lemma 3.8, and has inverse $H^{-1} \circ h^{-1} \circ\left(H^{*}\right)^{-1}$.

REmARK 3.22. The pullback of a metric $h$ by an arbitrary linear map $H$ need not be a metric, for example, the case where $H$ is the inclusion of a lightlike line in Minkowski space. See also Definition 3.105.

Definition 3.23. A $\mathbb{K}$-linear map $H: U \rightarrow V$ is an isometry, with respect to metrics $g$ on $U$ and $h$ on $V$, means: $H$ is invertible, and $g=H^{*} \circ h \circ H$, so the diagram is commutative.


This means that the metric $g$ is equal to the pullback of $h$ by $H$, and that for elements of $U$,

$$
\left(g\left(u_{1}\right)\right)\left(u_{2}\right)=\left(h\left(H\left(u_{1}\right)\right)\right)\left(H\left(u_{2}\right)\right) .
$$

It follows immediately from the definition that the composite of isometries is an isometry, that the inverse of an isometry is an isometry, and that $I d_{V}$ and $-I d_{V}$ are isometries.

REmark 3.24. The equation $g=H^{*} \circ h \circ H$ does not itself require that $H^{-1}$ exists, and one could consider non-surjective "isometric embeddings," but invertibility will be assumed as part of Definition 3.23, just for convenience.

ExERCISE 3.25. If $h: V \rightarrow V^{*}$ and $H: U \rightarrow V$, and $H^{*} \circ h \circ H: U \rightarrow U^{*}$ is invertible, then $H$ is a linear monomorphism.

THEOREM 3.26. Any metric $g: U \rightarrow U^{*}$ is an isometry with respect to itself, $g$, and the dual metric, $d_{U} \circ g^{-1}$.

Proof. The pullback by $g$ of the dual metric is

$$
g^{*} \circ d_{U} \circ g^{-1} \circ g=g
$$

by the symmetry of $g$.
Theorem 3.27. Given a metric $g$ on $U, d_{U}: U \rightarrow U^{* *}$ is an isometry with respect to $g$ and the dual of the dual metric $d_{U^{*}} \circ\left(d_{U} \circ g^{-1}\right)^{-1}=d_{U^{*}} \circ g \circ d_{U}^{-1}$ on $U^{* *}$.

Proof. By the identity $d_{U}^{*} \circ d_{U^{*}}=I d_{U^{*}}$ from Lemma 1.16,

$$
g=d_{U}^{*} \circ d_{U^{*}} \circ g \circ d_{U}^{-1} \circ d_{U}
$$

Theorem 3.28. Given metrics $g_{1}, g_{2}, h_{1}$, and $h_{2}$ on $U_{1}, U_{2}, V_{1}$, and $V_{2}$, if $A: U_{1} \rightarrow U_{2}$ and $B: V_{1} \rightarrow V_{2}$ are isometries, then $[A \otimes B]: U_{1} \otimes V_{1} \rightarrow U_{2} \otimes V_{2}$ is an isometry with respect to the induced metrics.

Proof. The statement of the Theorem is that

$$
\left\{g_{1} \otimes h_{1}\right\}=[A \otimes B]^{*} \circ\left\{g_{2} \otimes h_{2}\right\} \circ[A \otimes B] .
$$

The RHS can be expanded, and then Lemma 3.11 applies:

$$
\begin{aligned}
R H S & =[A \otimes B]^{*} \circ \operatorname{Hom}\left(I d_{U_{2} \otimes V_{2}}, l\right) \circ j \circ\left[g_{2} \otimes h_{2}\right] \circ[A \otimes B] \\
& =\operatorname{Hom}\left(I d_{U_{1} \otimes V_{1}}, l\right) \circ j \circ\left[A^{*} \otimes B^{*}\right] \circ\left[g_{2} \otimes h_{2}\right] \circ[A \otimes B] \\
& =\operatorname{Hom}\left(I d_{U_{1} \otimes V_{1}}, l\right) \circ j \circ\left[g_{1} \otimes h_{1}\right]=L H S .
\end{aligned}
$$

The last step uses Lemma 1.35 and $g_{1}=A^{*} \circ g_{2} \circ A, h_{1}=B^{*} \circ h_{2} \circ B$.
Lemma 3.29. If $V_{1}$ is finite-dimensional, then for any maps $F: V_{1} \rightarrow V_{2}^{*}$, $E: U_{1}^{*} \rightarrow U_{2}$, the following diagram is commutative.


Proof. The $p$ maps are as in Notation 1.66.

$$
\begin{aligned}
\phi \otimes v & \mapsto\left(p_{V_{2} U_{2}} \circ\left[\left(F \circ d_{V_{1}}^{-1}\right) \otimes E\right] \circ p_{U_{1} V_{1}}\right)(\phi \otimes v) \\
& =\left(p_{V_{2} U_{2}} \circ\left[\left(F \circ d_{V_{1}}^{-1}\right) \otimes E\right]\right)\left(\left(d_{V_{1}}(v)\right) \otimes \phi\right) \\
& =p_{V_{2} U_{2}}((F(v)) \otimes(E(\phi))) \\
& =\left(d_{U_{2}}(E(\phi))\right) \otimes(F(v))=\left[\left(d_{U_{2}} \circ E\right) \otimes F\right](\phi \otimes v) .
\end{aligned}
$$

Theorem 3.30. Given metrics $g$ and $h$ on $U$ and $V$, the canonical map $f_{U V}$ : $U^{*} \otimes V \rightarrow\left(V^{*} \otimes U\right)^{*}$ is an isometry with respect to the induced metrics.

Proof. The diagram is commutative, where the compositions in the left and right columns define the induced metrics.


The lower triangle is commutative by Lemma 1.65. The two blocks with $f$ and $p$ maps are commutative by Lemma 1.68, and the block in the middle is commutative by Lemma 3.29.

Lemma 3.31. Given metrics $g$ and $h$ on $U$ and $V$, let $U=U_{1} \oplus U_{2}$, with operators $Q_{i}, P_{i}$, and let $V=V_{1} \oplus V_{2}$, with operators $Q_{i}^{\prime}$, $P_{i}^{\prime}$. Suppose that for $i=1$ or 2 , the bilinear form $\left(Q_{i}^{\prime}\right)^{*} \circ h \circ Q_{i}^{\prime}$ is a metric on $V_{i}$. If $H: U \rightarrow V$ is an isometry that respects the direct sums, then the bilinear form $Q_{i}^{*} \circ g \circ Q_{i}$ is a metric on $U_{i}$, and the induced map $P_{i}^{\prime} \circ H \circ Q_{i}: U_{i} \rightarrow V_{i}$ is an isometry.

Proof. The induced map $P_{i}^{\prime} \circ H \circ Q_{i}$ is invertible, as in Lemma 1.83. The following calculation (which uses the property that $H$ respects the direct sums) shows that the bilinear form $Q_{i}^{*} \circ g \circ Q_{i}$ is equal to the pullback of $\left(Q_{i}^{\prime}\right)^{*} \circ h \circ Q_{i}^{\prime}$ by the map $P_{i}^{\prime} \circ H \circ Q_{i}$, so it is a metric as in Example 3.21, and $P_{i}^{\prime} \circ H \circ Q_{i}$ is an isometry, by Definition 3.23.

$$
\begin{aligned}
& \left(P_{i}^{\prime} \circ H \circ Q_{i}\right)^{*} \circ\left(\left(Q_{i}^{\prime}\right)^{*} \circ h \circ Q_{i}^{\prime}\right) \circ\left(P_{i}^{\prime} \circ H \circ Q_{i}\right) \\
= & Q_{i}^{*} \circ H^{*} \circ\left(P_{i}^{\prime}\right)^{*} \circ\left(Q_{i}^{\prime}\right)^{*} \circ h \circ Q_{i}^{\prime} \circ P_{i}^{\prime} \circ H \circ Q_{i} \\
= & \left(Q_{i}^{\prime} \circ P_{i}^{\prime} \circ H \circ Q_{i}\right)^{*} \circ h \circ Q_{i}^{\prime} \circ P_{i}^{\prime} \circ H \circ Q_{i} \\
= & \left(H \circ Q_{i} \circ P_{i} \circ Q_{i}\right)^{*} \circ h \circ H \circ Q_{i} \circ P_{i} \circ Q_{i} \\
= & Q_{i}^{*} \circ H^{*} \circ h \circ H \circ Q_{i} \\
= & Q_{i}^{*} \circ g \circ Q_{i} .
\end{aligned}
$$

### 3.4. Trace with respect to a metric

Definition 3.32. With respect to a metric $g$ on $V$, the trace of a bilinear form $h$ on $V$ is defined by

$$
T r_{g}(h)=\operatorname{Tr}_{V}\left(g^{-1} \circ h\right)
$$

By Lemma 2.6, this is the same as $\operatorname{Tr}_{V^{*}}\left(h \circ g^{-1}\right)$, and another way to write the definition is

$$
T r_{g}=\operatorname{Hom}\left(I d_{V}, g^{-1}\right)^{*}\left(T r_{V}\right) \in \operatorname{Hom}\left(V, V^{*}\right)^{*}
$$

Theorem 3.33. Given a metric $g$ on $V$, if $h$ is any bilinear form on $V$, then $\operatorname{Tr}_{g}\left(T_{V}(h)\right)=T r_{g}(h)$.

Proof.

$$
\begin{aligned}
\operatorname{Tr}_{g}\left(h^{*} \circ d_{V}\right) & =\operatorname{Tr}_{V^{*}}\left(h^{*} \circ d_{V} \circ g^{-1}\right)=\operatorname{Tr}_{V^{*}}\left(h^{*} \circ\left(g^{-1}\right)^{*}\right) \\
& =\operatorname{Tr}_{V^{*}}\left(\left(g^{-1} \circ h\right)^{*}\right)=\operatorname{Tr}_{V}\left(g^{-1} \circ h\right)=\operatorname{Tr}_{g}(h)
\end{aligned}
$$

using the symmetry of $g$ and Lemma 2.5.
Corollary 3.34. If $\frac{1}{2} \in \mathbb{K}$, then the trace of an antisymmetric form is 0 with respect to any metric $g$.

Theorem 3.35. Given a metric $g$ on $V$, if $\operatorname{Tr}_{V}\left(\operatorname{Id}_{V}\right) \neq 0$, then $\operatorname{Hom}\left(V, V^{*}\right)=$ $\mathbb{K} \oplus \operatorname{ker}\left(T r_{g}\right)$.

Proof. Since $\operatorname{Tr}_{g}(g)=\operatorname{Tr}_{V}\left(I d_{V}\right) \neq 0$, Lemmas 1.94 and 1.95 apply. For any $h: V \rightarrow V^{*}$ there is a canonical decomposition of $h$ into two terms: one that is a scalar multiple of $g$ and the other that has trace zero with respect to $g$ :

$$
h=\frac{\operatorname{Tr}_{g}(h)}{\operatorname{Tr}_{V}\left(I d_{V}\right)} \cdot g+\left(h-\frac{\operatorname{Tr}_{g}(h)}{\operatorname{Tr}_{V}\left(I d_{V}\right)} \cdot g\right) .
$$

Corollary 3.36. Given a metric $g$ on $V$, if both $\frac{1}{2} \in \mathbb{K}$ and $\operatorname{Tr}_{V}\left(\operatorname{Id}_{V}\right) \neq 0$, then $\operatorname{Hom}\left(V, V^{*}\right)$ admits a direct sum $\mathbb{K} \oplus \operatorname{Sym}_{0}(V, g) \oplus \operatorname{Alt}(V)$, where $\operatorname{Sym}_{0}(V, g)$ is the kernel of the restriction of $\operatorname{Tr}_{g}$ to $\operatorname{Sym}(V)$.

Proof. Using Theorem 3.33, Theorem 1.117 applies. The canonical decomposition of any bilinear form $h$ into three terms, corresponding to (1.11) with $w=v=g$, is:

$$
h=\frac{\operatorname{Tr}_{g}(h)}{\operatorname{Tr}_{V}\left(I d_{V}\right)} \cdot g+\left(\frac{1}{2}\left(h+T_{V}(h)\right)-\frac{T r_{g}(h)}{\operatorname{Tr}_{V}\left(I d_{V}\right)} \cdot g\right)+\frac{1}{2}\left(h-T_{V}(h)\right)
$$

Proposition 3.37. Given a metric $g$ on $V$, the trace is "invariant under pullback," that is, for an invertible map $H: U \rightarrow V$,

$$
\operatorname{Tr}_{H^{*} \circ g \circ H}\left(H^{*} \circ h \circ H\right)=\operatorname{Tr}_{g}(h)
$$

Proof.

$$
\begin{aligned}
\operatorname{Tr}_{H^{*} \circ g \circ H}\left(H^{*} \circ h \circ H\right) & =\operatorname{Tr}_{U}\left(H^{-1} \circ g^{-1} \circ\left(H^{*}\right)^{-1} \circ H^{*} \circ h \circ H\right) \\
& =\operatorname{Tr}_{U}\left(H^{-1} \circ g^{-1} \circ h \circ H\right) \\
& =\operatorname{Tr}_{V}\left(g^{-1} \circ h\right)=\operatorname{Tr}_{g}(h),
\end{aligned}
$$

by Lemma 2.6.

Proposition 3.38. Given metrics $g_{1}, g_{2}$ on $V_{1}, V_{2}$, if $V=V_{1} \oplus V_{2}$, then for any bilinear forms $h_{1}: V_{1} \rightarrow V_{1}^{*}, h_{2}: V_{2} \rightarrow V_{2}^{*}$,

$$
T r_{g_{1} \oplus g_{2}}\left(h_{1} \oplus h_{2}\right)=T r_{g_{1}}\left(h_{1}\right)+T r_{g_{2}}\left(h_{2}\right)
$$

Proof. Using the formula (3.4) for $\left(g_{1} \oplus g_{2}\right)^{-1}$ from Corollary 3.18, and Lemma 2.6,

$$
\begin{aligned}
L H S & =\operatorname{Tr}_{V}\left(\left(Q_{1} \circ g_{1}^{-1} \circ Q_{1}^{*}+Q_{2} \circ g_{2}^{-1} \circ Q_{2}^{*}\right) \circ\left(P_{1}^{*} \circ h_{1} \circ P_{1}+P_{2}^{*} \circ h_{2} \circ P_{2}\right)\right) \\
& =\operatorname{Tr}_{V}\left(Q_{1} \circ g_{1}^{-1} \circ h_{1} \circ P_{1}+Q_{2} \circ g_{2}^{-1} \circ h_{2} \circ P_{2}\right) \\
& =\operatorname{Tr}_{V_{1}}\left(P_{1} \circ Q_{1} \circ g_{1}^{-1} \circ h_{1}\right)+\operatorname{Tr}_{V_{2}}\left(P_{2} \circ Q_{2} \circ g_{2}^{-1} \circ h_{2}\right)=R H S
\end{aligned}
$$

Proposition 3.39. Given metrics $g$ and $h$ on $U$ and $V$, for bilinear forms $E: U \rightarrow U^{*}$ and $F: V \rightarrow V^{*}$,

$$
\operatorname{Tr}_{\{g \otimes h\}}(\{E \otimes F\})=\operatorname{Tr}_{g}(E) \cdot \operatorname{Tr}_{h}(F)
$$

Proof. Using the formula from Corollary 3.19, there is a convenient cancellation, and then Corollary 2.36 applies:

$$
\begin{aligned}
\operatorname{Tr}_{\{g \otimes h\}}(\{E \otimes F\})= & \operatorname{Tr}_{U \otimes V}\left(\left[g^{-1} \otimes h^{-1}\right] \circ j^{-1} \circ \operatorname{Hom}\left(I d_{U \otimes V}, l^{-1}\right)\right. \\
& \left.\circ \operatorname{Hom}\left(I d_{U \otimes V}, l\right) \circ j \circ[E \otimes F]\right) \\
= & \operatorname{Tr}_{U \otimes V}\left(j_{2}\left(\left(g^{-1} \circ E\right) \otimes\left(h^{-1} \circ F\right)\right)\right) \\
= & \operatorname{Tr}_{g}(E) \cdot \operatorname{Tr}_{h}(F)
\end{aligned}
$$

### 3.5. The induced metric on $\operatorname{Hom}(U, V)$

Definition 3.40. Given metrics $g$ and $h$ on $U$ and $V$, define a bilinear form $b$ on $\operatorname{Hom}(U, V)$, acting on elements $A, B: U \rightarrow V$ as:

$$
(b(B))(A)=\operatorname{Tr}_{V}\left(A \circ g^{-1} \circ B^{*} \circ h\right)
$$

$b$ can be written as a composite:

$$
b=\operatorname{Hom}\left(I d_{\operatorname{Hom}(U, V)}, T r_{V}\right) \circ t_{V U}^{V} \circ \operatorname{Hom}\left(h, g^{-1}\right) \circ t_{U V}
$$

using the generalized transpose $t_{V U}^{V}$ from Definition 1.7. By Lemma 2.6, $b$ can also be written as a trace with respect to $g$ :

$$
(b(B))(A)=\operatorname{Tr}_{U}\left(g^{-1} \circ B^{*} \circ h \circ A\right)=\operatorname{Tr}_{g}\left(B^{*} \circ h \circ A\right) .
$$

Theorem 3.41. Given metrics $g$ and $h$ on $U$ and $V$, the induced tensor product metric on $U^{*} \otimes V$ is equal to the pullback of the bilinear form $b$ by the canonical map $k_{U V}$.

Proof. The diagram is commutative, where the composition in the left column defines the induced metric (as in Theorem 3.30), and the composition in the right column defines the bilinear form $b$.


The three squares in the upper half of the diagram are commutative, by Lemma 3.29, Lemma 1.69, and Lemma 1.57 (with $h \circ d_{V}^{-1}=h^{*}$ because $h$ is symmetric). The left triangle in the lower half is commutative by Lemma 1.68, and the middle triangle is just the definition $f_{V U}=e_{V U} \circ k_{V U}$ from Notation 1.63. Checking the lower right triangle, starting with $D \in \operatorname{Hom}(V, U)$, uses $\left(k_{U V}(\phi \otimes v)\right) \circ D=k_{V V}\left(\left(D^{*}(\phi)\right) \otimes v\right)$, which follows from Lemma 1.57:

$$
\operatorname{Hom}\left(D, I d_{V}\right) \circ k_{U V}=k_{V V} \circ\left[D^{*} \otimes I d_{V}\right]
$$

and the definition of the trace (Definition 2.24):

$$
\begin{aligned}
D & \mapsto\left(k_{U V}^{*} \circ \operatorname{Hom}\left(\operatorname{Id}_{\operatorname{Hom}(U, V)}, \operatorname{Tr}_{V}\right) \circ t_{V U}^{V}\right)(D) \\
& =\operatorname{Tr}_{V} \circ\left(t_{V U}^{V}(D)\right) \circ k_{U V}: \\
\phi \otimes v & \mapsto \operatorname{Tr}_{V}\left(\left(t_{V U}^{V}(D)\right)\left(k_{U V}(\phi \otimes v)\right)\right) \\
& =\operatorname{Tr}_{V}\left(\left(k_{U V}(\phi \otimes v)\right) \circ D\right) \\
& =\left(\left(k_{V V}^{-1}\right)^{*}\left(E v_{V}\right)\right)\left(k_{V V}\left(\left(D^{*}(\phi)\right) \otimes v\right)\right) \\
& =E v_{V}((\phi \circ D) \otimes v) \\
& =\phi(D(v))=\left(e_{V U}(D)\right)(\phi \otimes v)
\end{aligned}
$$

In particular, the pullback $k_{U V}^{*} \circ b \circ k_{U V}=\left\{\left(d_{U} \circ g^{-1}\right) \otimes h\right\}$ from Theorem 3.41 acts on $\phi, \psi \in U^{*}$ and $v, w \in V$ as:

$$
\begin{align*}
\psi\left(g^{-1}(\phi)\right) \cdot(h(v))(w) & =\left(\left\{\left(d_{U} \circ g^{-1}\right) \otimes h\right\}(\phi \otimes v)\right)(\psi \otimes w) \\
& =\left(b\left(k_{U V}(\phi \otimes v)\right)\right)\left(k_{U V}(\psi \otimes w)\right)  \tag{3.5}\\
& =\operatorname{Tr}_{U}\left(g^{-1} \circ\left(k_{U V}(\phi \otimes v)\right)^{*} \circ h \circ\left(k_{U V}(\psi \otimes w)\right)\right) .
\end{align*}
$$

Corollary 3.42. Given metrics $g$ and $h$ on $U$ and $V, b$ is a metric on $\operatorname{Hom}(U, V)$.

Proof. This follows from Example 3.21, where $k_{U V}^{-1}$ is the invertible map relating the metric on $U^{*} \otimes V$ to the bilinear form $b$, proving that $b$ is symmetric and invertible, and $k_{U V}$ and $k_{U V}^{-1}$ are isometries.

Corollary 3.43. Given metrics $g$ and $h$ on $U$ and $V$, the canonical map $e_{U V}: \operatorname{Hom}(U, V) \rightarrow\left(V^{*} \otimes U\right)^{*}$ is an isometry with respect to the induced metrics.

Proof. This follows from Theorem 3.30, since $e_{U V}=f_{U V} \circ k_{U V}^{-1}$.
Remark 3.44. Historically, the $b$ metric involving the trace has been called the "Hilbert-Schmidt" metric; we will just refer to it as the metric on $\operatorname{Hom}(U, V)$ induced by metrics on $U$ and $V$ and will usually use the $b$ notation. The relationship between the metric $b$ and the tensor product metric seems to be well-known, although possibly not in this generality. A special case of a Hermitian version of Theorem 3.41 appears in [Bhatia] §I.4, and a positive definite version for endomorphisms in $\left[\mathbf{G}_{2}\right]$ §III.4. Matrix versions of Theorem 3.41 appear in [Neudecker], $[\mathbf{L}]$, and $[\mathbf{H J}] \S 4.2$.

THEOREM 3.45. If $A: U_{2} \rightarrow U_{1}$ is an isometry with respect to metrics $g_{2}, g_{1}$, and $B: V_{1} \rightarrow V_{2}$ is an isometry with respect to metrics $h_{1}, h_{2}$, then $\operatorname{Hom}(A, B)$ : $\operatorname{Hom}\left(U_{1}, V_{1}\right) \rightarrow \operatorname{Hom}\left(U_{2}, V_{2}\right)$ is an isometry with respect to the induced metrics.

Proof. The hypotheses are $h_{1}=B^{*} \circ h_{2} \circ B$, and $g_{2}=A^{*} \circ g_{1} \circ A$. For $E$, $F \in \operatorname{Hom}\left(U_{1}, V_{2}\right)$, the pullback of the induced metric on $\operatorname{Hom}\left(U_{2}, V_{2}\right)$ is

$$
\begin{aligned}
(b(B \circ F \circ A))(B \circ E \circ A) & =\operatorname{Tr}_{V_{2}}\left(B \circ E \circ A \circ g_{2}^{-1} \circ A^{*} \circ F^{*} \circ B^{*} \circ h_{2}\right) \\
& =\operatorname{Tr}_{V_{1}}\left(E \circ g_{1}^{-1} \circ F^{*} \circ B^{*} \circ h_{2} \circ B\right) \\
& =\operatorname{Tr}_{V_{1}}\left(E \circ g_{1}^{-1} \circ F^{*} \circ h_{1}\right) .
\end{aligned}
$$

THEOREM 3.46. With respect to the $b$ metrics induced by $g_{1}, g_{2}, h_{1}, h_{2}$ on $U_{1}$, $U_{2}, V_{1}, V_{2}$, the map $j: \operatorname{Hom}\left(U_{1}, V_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, V_{2}\right) \rightarrow \operatorname{Hom}\left(U_{1} \otimes U_{2}, V_{1} \otimes V_{2}\right)$ is an isometry.

Proof. For $A_{1}, B_{1}: U_{1} \rightarrow V_{1}, A_{2}, B_{2}: U_{2} \rightarrow V_{2}$, the statement of the Theorem is that the tensor product metric and pullback metric are equal:

$$
\left(b\left(B_{1}\right)\right)\left(A_{1}\right) \cdot\left(b\left(B_{2}\right)\right)\left(A_{2}\right)=\left(b\left(j\left(B_{1} \otimes B_{2}\right)\right)\right)\left(j\left(A_{1} \otimes A_{2}\right)\right)
$$

Computing the RHS, using the metrics $\left\{g_{1} \otimes g_{2}\right\}$, and $\left\{h_{1} \otimes h_{2}\right\}$, gives:

$$
\begin{aligned}
R H S= & \operatorname{Tr}_{V_{1} \otimes V_{2}}\left(\left[A_{1} \otimes A_{2}\right] \circ\left[g_{1}^{-1} \otimes g_{2}^{-1}\right] \circ j^{-1} \circ \operatorname{Hom}\left(I d_{U_{1} \otimes U_{2}}, l^{-1}\right)\right. \\
& \left.\circ\left[B_{1} \otimes B_{2}\right]^{*} \circ \operatorname{Hom}\left(I d_{V_{1} \otimes V_{2}}, l\right) \circ j \circ\left[h_{1} \otimes h_{2}\right]\right) \\
= & \operatorname{Tr}_{V_{1} \otimes V_{2}}\left(\left[A_{1} \otimes A_{2}\right] \circ\left[g_{1}^{-1} \otimes g_{2}^{-1}\right] \circ\left[B_{1}^{*} \otimes B_{2}^{*}\right] \circ\left[h_{1} \otimes h_{2}\right]\right) \\
= & \left.\operatorname{Tr}_{V_{1} \otimes V_{2}}\left[\left(A_{1} \circ g_{1}^{-1} \circ B_{1}^{*} \circ h_{1}\right) \otimes\left(A_{2} \circ g_{2}^{-1} \circ B_{2}^{*} \circ h_{2}\right)\right]\right) \\
= & \operatorname{Tr}_{V_{1}}\left(A_{1} \circ g_{1}^{-1} \circ B_{1}^{*} \circ h_{1}\right) \cdot \operatorname{Tr}_{V_{2}}\left(A_{2} \circ g_{2}^{-1} \circ B_{2}^{*} \circ h_{2}\right) .
\end{aligned}
$$

The first step uses Lemma 3.11, and the second step uses Lemma 1.35, and finally Corollary 2.36 gives a product of traces equal to LHS.

Theorem 3.47. Given metrics $g$ and $h$ on $U$ and $V$, the map $t_{U V}: \operatorname{Hom}(U, V) \rightarrow$ $\operatorname{Hom}\left(V^{*}, U^{*}\right)$ is an isometry with respect to the induced metrics.

Proof. Calculating the pullback, for $A, B \in \operatorname{Hom}(U, V)$ gives

$$
\begin{aligned}
\left(b\left(B^{*}\right)\right)\left(A^{*}\right) & =\operatorname{Tr}_{U^{*}}\left(A^{*} \circ\left(d_{V} \circ h^{-1}\right)^{-1} \circ B^{* *} \circ d_{U} \circ g^{-1}\right) \\
& =\operatorname{Tr}_{U^{*}}\left(A^{*} \circ h \circ d_{V}^{-1} \circ B^{* *} \circ d_{U} \circ g^{-1}\right) \\
& =\operatorname{Tr}_{U^{*}}\left(A^{*} \circ h \circ B \circ g^{-1}\right) \\
& =\operatorname{Tr}_{V}\left(B \circ g^{-1} \circ A^{*} \circ h\right) \\
& =(b(B))(A) .
\end{aligned}
$$

Corollary 3.48. Given a metric $g$ on $V, T_{V}: \operatorname{Hom}\left(V, V^{*}\right) \rightarrow \operatorname{Hom}\left(V, V^{*}\right)$ is an isometry with respect to the induced $b$ metric.

Proof. By Definition $3.2, T_{V}=\operatorname{Hom}\left(d_{V}, I d_{V^{*}}\right) \circ t_{V V^{*}}$, which is a composition of isometries, by Theorem 3.27, Theorem 3.45, and Theorem 3.47.

### 3.6. Orthogonal direct sums

DEfinition 3.49. A direct sum $U=U_{1} \oplus U_{2} \oplus \cdots \oplus U_{\nu}$, with inclusion maps $Q_{i}$, is orthogonal with respect to a metric $g$ on $U$ means: $Q_{I}^{*} \circ g \circ Q_{i}=0_{\operatorname{Hom}\left(U_{i}, U_{I}^{*}\right)}$ for $i \neq I$.

Equivalently, the direct sum is orthogonal if and only if $g: U \rightarrow U^{*}$ respects the direct sums (as in Definition 1.82), where the direct sum structure on $U^{*}$ is as in Example 1.78.

LEMMA 3.50. Given $U$ with a metric $g$, if $U=U_{1} \oplus U_{2}$ and $U=U_{1}^{\prime} \oplus U_{2}^{\prime}$ are equivalent direct sums, and one is orthogonal with respect to $g$, then so is the other.

Proof. This follows from Lemma 1.92.

Example 3.51. Given metrics $g_{1}, g_{2}$ on $U_{1}, U_{2}$, if $U=U_{1} \oplus U_{2}$, then the direct sum is orthogonal with respect to the induced metric from Corollary 3.18, $g=g_{1} \oplus g_{2}=P_{1}^{*} \circ g_{1} \circ P_{1}+P_{2}^{*} \circ g_{2} \circ P_{2}$.

Theorem 3.52. Given a metric $g$ on $U$, if $\operatorname{Tr}_{U}\left(\operatorname{Id}_{U}\right) \neq 0$, then any direct sum $\operatorname{End}(U)=\mathbb{K} \oplus \operatorname{End}_{0}(U)$ from Example 2.9 is orthogonal with respect to the $b$ metric induced by $g$.

Proof. As noted in Lemma 1.94 and Example 2.9, any such direct sum is technically not unique, but equivalent to any other choice, so the non-uniqueness does not affect the claimed orthogonality by Lemma 3.50.

If $A \in \operatorname{End}_{0}(U)=\operatorname{ker}\left(\operatorname{Tr}_{U}\right)$, then the $b$ metric applied to $A$ and any element of the line spanned by $I d_{U}$ is $\operatorname{Tr}_{U}\left(A \circ g^{-1} \circ\left(\lambda \cdot I d_{U}\right)^{*} \circ g\right)=\lambda \cdot \operatorname{Tr}_{U}(A)=0$.

ThEOREM 3.53. Given a metric $g$ on $U$, if $\operatorname{Tr}_{U}\left(I d_{U}\right) \neq 0$, then the direct sum $\operatorname{Hom}\left(U, U^{*}\right)=\mathbb{K} \oplus \operatorname{ker}\left(T r_{g}\right)$ from Theorem 3.35 is orthogonal with respect to the induced metric.

Proof. Such a direct sum is as in Lemmas 1.94 and 1.95.
If $E \in \operatorname{ker}\left(\operatorname{Tr}_{g}\right)$, then the $b$ metric applied to $E$ and any scalar multiple of $g$ is $\operatorname{Tr}_{U^{*}}\left(E \circ g^{-1} \circ(\lambda \cdot g)^{*} \circ d_{U} \circ g^{-1}\right)=\lambda \cdot \operatorname{Tr}_{U^{*}}\left(E \circ g^{-1}\right)=0$.

Lemma 3.54. Given a metric $g$ on $U$, if $U=U_{1} \oplus U_{2}$ is an orthogonal direct sum with respect to $g$, then the involution on $U$ from Example 1.114, $K=Q_{1} \circ$ $P_{1}-Q_{2} \circ P_{2}$, and similarly $-K$, are isometries with respect to $g$.

Proof. Using the orthogonality,

$$
\begin{aligned}
( \pm K)^{*} \circ g \circ( \pm K) & =\left(Q_{1} \circ P_{1}-Q_{2} \circ P_{2}\right)^{*} \circ g \circ\left(Q_{1} \circ P_{1}-Q_{2} \circ P_{2}\right) \\
& =\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right)^{*} \circ g \circ\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right)=g
\end{aligned}
$$

Lemma 3.55. Given a metric $g$ on $U$, if $\frac{1}{2} \in \mathbb{K}$ and $K \in \operatorname{End}(U)$ is an involution and an isometry with respect to $g$, then the direct sum produced by $K$, as in Lemma 1.112, is orthogonal.

Proof. Using the isometry property, $K^{*} \circ g \circ K=g$, so using the involution property, $K^{*} \circ g=g \circ K$. To check that $g$ respects the direct sum, as in Definition 1.82, use $Q_{i} \circ P_{i}=\frac{1}{2} \cdot\left(I d_{U} \pm K\right)$ as in Lemma 1.112:
$g \circ Q_{i} \circ P_{i}=g \circ \frac{1}{2} \cdot\left(I d_{U} \pm K\right)=\frac{1}{2} \cdot\left(I d_{U^{*}} \pm K^{*}\right) \circ g=\left(Q_{i} \circ P_{i}\right)^{*} \circ g=P_{i}^{*} \circ Q_{i}^{*} \circ g$.

Theorem 3.56. Given a metric $g$ on $U$, if $\frac{1}{2} \in \mathbb{K}$, then the direct sum

$$
\operatorname{Hom}\left(U, U^{*}\right)=\operatorname{Sym}(U) \oplus \operatorname{Alt}(U)
$$

is orthogonal with respect to the induced metric.
Proof. This follows from Lemma 3.55, Lemma 3.3, and Corollary 3.48.
Corollary 3.57. Given a metric $g$ on $U$, If $\frac{1}{2} \in \mathbb{K}$ and $\operatorname{Tr}_{U}\left(I d_{U}\right) \neq 0$, then the direct sum

$$
\operatorname{Hom}\left(U, U^{*}\right)=\mathbb{K} \oplus \operatorname{Sym}_{0}(U, g) \oplus \operatorname{Alt}(U)
$$

is orthogonal with respect to the induced metric.

There is a converse to the construction of Example 3.51: if a direct sum is orthogonal with respect to a given metric $g$, then metrics are induced on the summands.

Theorem 3.58. Given a metric $g$ on $U$ and a direct sum $U=U_{1} \oplus U_{2}$ with projection and inclusion operators $P_{i}, Q_{i}$, if the direct sum is orthogonal with respect to $g$, then each of the maps $g_{i}=Q_{i}^{*} \circ g \circ Q_{i}: U_{i} \rightarrow U_{i}^{*}$ is a metric, and $g=g_{1} \oplus g_{2}$.

Proof. The pullback $g_{i}$ has inverse $P_{i} \circ g^{-1} \circ P_{i}^{*}$ by Lemma 1.83 , and is symmetric by Lemma 3.8, so it is a metric. Since $g$ respects the direct sums, $P_{i}^{*} \circ Q_{i}^{*} \circ g=g \circ Q_{i} \circ P_{i}$, so using the definition of direct sum of bilinear forms,

$$
\begin{aligned}
g_{1} \oplus g_{2} & =P_{1}^{*} \circ Q_{1}^{*} \circ g \circ Q_{1} \circ P_{1}+P_{2}^{*} \circ Q_{2}^{*} \circ g \circ Q_{2} \circ P_{2} \\
& =g \circ\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right)=g .
\end{aligned}
$$

Example 3.59. Theorem 3.58, applied to the above direct sums, demonstrates that under suitable hypotheses, a metric $g$ on $U$ induces metrics on $\operatorname{End}_{0}(U)$, $\operatorname{ker}\left(\operatorname{Tr}_{g}\right), \operatorname{Sym}(U), \operatorname{Sym}_{0}(U, g)$, and $\operatorname{Alt}(U)$.

Theorem 3.60. Given metrics $g$ and $h$ on $U$ and $V$, if $U=U_{1} \oplus U_{2}$ is an orthogonal direct sum with respect to $g$, then the direct sum $U \otimes V=\left(U_{1} \otimes V\right) \oplus$ $\left(U_{2} \otimes V\right)$, as in Example 1.75, is orthogonal with respect to the tensor product metric $\{g \otimes h\}$, and the metric on $U_{i} \otimes V$ induced by the direct sum coincides with $\left\{g_{i} \otimes h\right\}$.

Proof. Using Lemma 3.11, and the inclusion operators $\left[Q_{i} \otimes I d_{V}\right]: U_{i} \otimes V \rightarrow$ $U \otimes V$,

$$
\begin{aligned}
& {\left[Q_{I} \otimes I d_{V}\right]^{*} \circ \operatorname{Hom}\left(I d_{U \otimes V}, l\right) \circ j \circ[g \otimes h] \circ\left[Q_{i} \otimes I d_{V}\right] } \\
= & \operatorname{Hom}\left(I d_{U_{I} \otimes V}, l\right) \circ j \circ\left[Q_{I}^{*} \otimes I d_{V}^{*}\right] \circ[g \otimes h] \circ\left[Q_{i} \otimes I d_{V}\right] \\
= & \operatorname{Hom}\left(I d_{U_{I} \otimes V}, l\right) \circ j \circ\left[\left(Q_{I}^{*} \circ g \circ Q_{i}\right) \otimes h\right] .
\end{aligned}
$$

For $i \neq I$, the result is zero, showing the direct sum is orthogonal, and for $i=I$, the calculation shows that the tensor product of the induced metric $g_{i}=Q_{i}^{*} \circ g \circ Q_{i}$ and $h$ is equal to the metric induced by $\{g \otimes h\}$ and $\left[Q_{i} \otimes I d_{V}\right]$ on $U_{i} \otimes V$.

Theorem 3.61. Given metrics $g$ and $h$ on $U$ and $V$, if $V=V_{1} \oplus V_{2}$, with operators $Q_{i}^{\prime}, P_{i}^{\prime}$, is an orthogonal direct sum with respect to $h$, and $U=U_{1} \oplus U_{2}$, and $H: U \rightarrow V$ is an isometry with respect to $g$ and $h$ which respects the direct sums, then the direct sum $U_{1} \oplus U_{2}$ is orthogonal with respect to $g$, and $P_{i}^{\prime} \circ H \circ Q_{i}$ : $U_{i} \rightarrow V_{i}$ is an isometry with respect to the induced metrics.

Proof. It is straightforward to check that $H^{*}: V^{*} \rightarrow U^{*}$ respects the direct sums. It follows that $g=H^{*} \circ h \circ H$ is a composite of maps that respect the direct sums, so $U_{1} \oplus U_{2}$ is orthogonal with respect to $g$. The induced metrics on $U_{i}$ and $V_{i}$ are as in Theorem 3.58, and the last claim is a special case of Lemma 3.31.

### 3.7. Topics and applications

The following facts about the trace, metrics, and direct sums are left as exercises; their proofs are short and lend themselves to the methods and notation of the previous Sections. Some of the results generalize well-known properties of metrics on real vector spaces that appear in topics in geometry, algebra, or applications. A few of the results, labeled Lemmas, will be needed later.

### 3.7.1. Foundations of geometry.

Proposition 3.62. Let $U$ and $V$ be vector spaces, and let $h: V \rightarrow V^{*}$ be an invertible $\mathbb{K}$-linear map. Suppose $H$ is just a function with domain $U$ and target $V$, which is not necessarily linear, but which is right cancellable. If there is some $\mathbb{K}$-linear map $g: U \rightarrow U^{*}$ so that

$$
((h \circ H)(u)) \circ H=g(u)
$$

for all $u \in U$, then $H$ is $\mathbb{K}$-linear.
Proof. The right cancellable property in the category of sets is as in Exercise 6.18: $A \circ H=B \circ H \Longrightarrow A=B$, for any, not necessarily linear, functions $A$ and $B$.

For $\mathbb{K}$-linearity, two equations must hold. First, for any $\lambda \in \mathbb{K}, u \in U$,

$$
\begin{aligned}
((h \circ H)(\lambda \cdot u)) \circ H=g(\lambda \cdot u) & =\lambda \cdot g(u)=\lambda \cdot((h \circ H)(u)) \circ H \\
\Longrightarrow(h \circ H)(\lambda \cdot u) & =\lambda \cdot(h \circ H)(u) \\
\Longrightarrow h(H(\lambda \cdot u)) & =h(\lambda \cdot H(u)) \\
\Longrightarrow H(\lambda \cdot u) & =\lambda \cdot H(u)
\end{aligned}
$$

Second, for any $u_{1}, u_{2} \in U$,

$$
\begin{aligned}
\left((h \circ H)\left(u_{1}+u_{2}\right)\right) \circ H=g\left(u_{1}+u_{2}\right) & =g\left(u_{1}\right)+g\left(u_{2}\right) \\
& =\left((h \circ H)\left(u_{1}\right)\right) \circ H+\left((h \circ H)\left(u_{2}\right)\right) \circ H \\
& =\left((h \circ H)\left(u_{1}\right)+(h \circ H)\left(u_{2}\right)\right) \circ H \\
\Longrightarrow(h \circ H)\left(u_{1}+u_{2}\right) & =(h \circ H)\left(u_{1}\right)+(h \circ H)\left(u_{2}\right) \\
\Longrightarrow h\left(H\left(u_{1}+u_{2}\right)\right) & =h\left(H\left(u_{1}\right)+H\left(u_{2}\right)\right) \\
\Longrightarrow H\left(u_{1}+u_{2}\right) & =H\left(u_{1}\right)+H\left(u_{2}\right) .
\end{aligned}
$$

Proposition 3.63. Let $U$ and $V$ be vector spaces, and let $g: U \rightarrow U^{*}, h$ : $V \rightarrow V^{*}$ be symmetric bilinear forms. Suppose $H$ is just a function with domain $U$ and target $V$, which is not necessarily linear. If $\frac{1}{2} \in \mathbb{K}$ and $H\left(0_{U}\right)=0_{V}$ and $H$ satisfies

$$
(h(H(v)-H(u)))(H(v)-H(u))=(g(v-u))(v-u)
$$

for all $u, v \in U$, then $H$ also satisfies

$$
((h \circ H)(u)) \circ H=g(u)
$$

for all $u \in U$.
Proof. Expanding the RHS of the hypothesis identity using the symmetric property of $g$,

$$
\begin{aligned}
(g(v-u))(v-u) & =(g(v))(v)-(g(v))(u)-(g(u))(v)+(g(u))(u) \\
& =(g(v))(v)-2(g(u))(v)+(g(u))(u)
\end{aligned}
$$

Expanding the LHS, using the symmetric property of $h$ and $H\left(0_{U}\right)=0_{V}$,

$$
\begin{aligned}
& (h(H(v)-H(u)))(H(v)-H(u)) \\
= & (h(H(v)))(H(v))-(h(H(v)))(H(u))-(h(H(u)))(H(v))+(h(H(u)))(H(u)) \\
= & \left(h\left(H(v)-H\left(0_{U}\right)\right)\right)\left(H(v)-H\left(0_{U}\right)\right)-2(h(H(u)))(H(v)) \\
& +\left(h\left(H(u)-H\left(0_{U}\right)\right)\right)\left(H(u)-H\left(0_{U}\right)\right) \\
= & \left(g\left(v-0_{U}\right)\right)\left(v-0_{U}\right)-2(h(H(u)))(H(v))+\left(g\left(u-0_{U}\right)\right)\left(u-0_{U}\right) .
\end{aligned}
$$

Setting the above quantities equal, cancelling like terms, and using $\frac{1}{2} \in \mathbb{K}$, the conclusion follows.

Proposition 3.64. Let $U$ and $V$ be vector spaces, and let $g: U \rightarrow U^{*}$ be a metric on $U$. Suppose $h$ is just a function with domain $V$ and target $V^{*}$, which is not necessarily linear. If $\frac{1}{2} \in \mathbb{K}$ and $H: U \rightarrow V$ is a $\mathbb{K}$-linear map satisfying

$$
((h \circ H)(u))(H(u))=(g(u))(u)
$$

for all $u \in U$, then $H$ satisfies

$$
(h(H(v)-H(u)))(H(v)-H(u))=(g(v-u))(v-u)
$$

for all $u, v \in U$, and $\operatorname{ker}(H)=\left\{0_{U}\right\}$.
Proof. To establish the claimed identity, use the linearity of $H$ :

$$
L H S=(h(H(v-u)))(H(v-u))=R H S
$$

Suppose $H(u)=0_{V}$. Then, for any $v \in U$,

$$
\begin{aligned}
((h \circ H)(v))(H(v)) & =(h(H(v)-H(u)))(H(v)-H(u)) \\
& =(g(v-u))(v-u) \\
& =(g(v))(v)-(g(v))(u)-(g(u))(v)+(g(u))(u) \\
& =((h \circ H)(v))(H(v))-2(g(u))(v)+((h \circ H)(u))(H(u)),
\end{aligned}
$$

the last step using the symmetric property of $g$. Using $h(H(u)) \in V^{*}$ and $H(u)=$ $0_{V}$, the last term is 0 , so cancelling like terms and using $\frac{1}{2} \in \mathbb{K}$, the conclusion is that $(g(u))(v)=0$. Since this holds for all $v, g(u)=0_{U^{*}}$, and $g$ is invertible, so $u=0_{U}$.

Corollary 3.65. Given a vector space $V$ and metrics $g$ and $h$ on $V$, if $\frac{1}{2} \in \mathbb{K}$ and $H$ is just a function with domain $V$ and target $V$, which is not necessarily linear, then the following are equivalent.
(1) $H: V \rightsquigarrow V$ is right cancellable, and for all $u \in V$,

$$
((h \circ H)(u)) \circ H=g(u) .
$$

(2) $H: V \rightsquigarrow V$ is right cancellable, $H\left(0_{V}\right)=0_{V}$, and for all $u, v \in V$,

$$
(h(H(v)-H(u)))(H(v)-H(u))=(g(v-u))(v-u) .
$$

(3) $H: V \rightarrow V$ is $\mathbb{K}$-linear, and for all $u \in V$,

$$
((h \circ H)(u))(H(u))=(g(u))(u)
$$

(4) $H: V \rightarrow V$ is an isometry with respect to $g$ and $h$.

Proof. For $(1) \Longrightarrow(3)$, the linearity is Proposition 3.62 and the identity obviously follows. Since $V$ is finite-dimensional, a $\mathbb{K}$-linear map $V \rightarrow V$ with trivial kernel must be invertible by Claim 0.50 (and therefore right cancellable), so Proposition 3.64 gives $(3) \Longrightarrow(2)$. $(2) \Longrightarrow(1)$ is Proposition 3.63. It is immediate from Definition 3.23 that $(4) \quad \Longrightarrow \quad(1)$, and also (4) $\quad \Longrightarrow \quad$ (3). Finally, the linearity of (3), the identity of (1), and the above mentioned invertibility together imply (4). The implications (1) $\Longleftrightarrow(4) \Longrightarrow$ (3) did not require $\frac{1}{2} \in \mathbb{K}$.

### 3.7.2. More isometries.

Exercise 3.66. Given metrics on $U$ and $V$, the switching map $s: U \otimes V \rightarrow$ $V \otimes U: u \otimes v \mapsto v \otimes u$, as in Example 1.28, is an isometry with respect to the induced tensor product metrics.

Lemma 3.67. Every map $h: \mathbb{K} \rightarrow \mathbb{K}^{*}$ is of the form $h^{\nu}$, where for $\nu \in \mathbb{K}$, $\left(h^{\nu}(\lambda)\right)(\mu)=\nu \cdot \lambda \cdot \mu$. If $\nu=0$ then $h=0_{\operatorname{Hom}\left(\mathbb{K}, \mathbb{K}^{*}\right)}$. If $\nu \neq 0$, then $h^{\nu}$ is a metric on $\mathbb{K}$, with inverse map $\frac{1}{\nu} \cdot \operatorname{Tr}_{\mathbb{K}}$.

Proof. For any $h$, let $\nu=(h(1))(1)$; then $(h(\lambda))(\mu)=\lambda \cdot \mu \cdot(h(1))(1)$. For any $\nu, h^{\nu}=\nu \cdot h^{1}$, and $h^{\nu}$ is clearly symmetric. If $\nu \neq 0$, then $h^{\nu}$ is invertible, with inverse $\frac{1}{\nu} \cdot T r_{\mathbb{K}}$, by Example 2.7:

$$
\begin{gathered}
\left(\left(\frac{1}{\nu} \cdot \operatorname{Tr}_{\mathbb{K}}\right) \circ h^{\nu}\right)(\lambda)=\frac{1}{\nu} \cdot \operatorname{Tr}_{\mathbb{K}}\left(h^{\nu}(\lambda)\right)=\frac{1}{\nu} \cdot\left(h^{\nu}(\lambda)\right)(1)=\frac{1}{\nu} \cdot \nu \cdot \lambda \cdot 1=\lambda . \\
\left(h^{\nu} \circ\left(\frac{1}{\nu} \cdot \operatorname{Tr}_{\mathbb{K}}\right)\right)(A)=h^{\nu}\left(\frac{1}{\nu} \cdot A(1)\right): \mu \mapsto \nu \cdot \frac{1}{\nu} \cdot A(1) \cdot \mu=A(\mu)
\end{gathered}
$$

A canonical such metric on $\mathbb{K}$ is $h^{1}=\left(T r_{\mathbb{K}}\right)^{-1}$. $h^{1}$ is also equal to the map $m: \mathbb{K} \rightarrow \operatorname{Hom}(\mathbb{K}, \mathbb{K})$.

ExERCISE 3.68. For three copies of the scalar field, $\mathbb{K}_{\alpha}, \mathbb{K}_{\beta}$, $\mathbb{K}_{\gamma}$, with metrics $h^{\alpha}, h^{\beta}, h^{\gamma}$, if $\beta=\alpha \cdot \gamma \in \mathbb{K}$, then the map $T r_{\mathbb{K}}: \operatorname{Hom}\left(\mathbb{K}_{\alpha}, \mathbb{K}_{\beta}\right) \rightarrow \mathbb{K}_{\gamma}$ is an isometry with respect to the induced $b$ metric and $h^{\gamma}$.

Hint. For $A, B \in \operatorname{End}(\mathbb{K})$, the pullback metric is, by Example 2.7,

$$
\left(h^{\gamma}\left(\operatorname{Tr}_{\mathbb{K}}(A)\right)\right)\left(\operatorname{Tr}_{\mathbb{K}}(B)\right)=\left(h^{\gamma}(A(1))\right)(B(1))=\gamma \cdot A(1) \cdot B(1) .
$$

The induced metric $b$ on $\operatorname{Hom}\left(\mathbb{K}_{\alpha}, \mathbb{K}_{\beta}\right)$ gives

$$
\begin{aligned}
\operatorname{Tr}_{\mathbb{K}}\left(A \circ\left(h^{\alpha}\right)^{-1} \circ B^{*} \circ h^{\beta}\right) & =\left(A \circ\left(h^{\alpha}\right)^{-1} \circ B^{*} \circ h^{\beta}\right)(1) \\
& =A\left(\alpha^{-1} \cdot \operatorname{Tr}_{\mathbb{K}}\left(B^{*}\left(h^{\beta}(1)\right)\right)\right) \\
& =A\left(\alpha^{-1} \cdot\left(h^{\beta}(1)\right)(B(1))\right) \\
& =A\left(\alpha^{-1} \cdot \beta \cdot 1 \cdot B(1)\right) \\
& =\frac{\beta}{\alpha} \cdot A(1) \cdot B(1) .
\end{aligned}
$$

Lemma 3.69. Given a metric $g$ on $U$, the scalar multiplication map $l_{U}: U \otimes$ $\mathbb{K} \rightarrow U$ is an isometry, with respect to the tensor product metric $\left\{g \otimes h^{\nu}\right\}$ and $\nu \cdot g$.

Proof. Calculating the pullback of $\nu \cdot g$ gives:

$$
\left(\nu \cdot g\left(l_{U}\left(u_{1} \otimes \lambda\right)\right)\right)\left(l_{U}\left(u_{2} \otimes \mu\right)\right)=\lambda \cdot \mu \cdot \nu \cdot\left(g\left(u_{1}\right)\right)\left(u_{2}\right),
$$

and the tensor product metric is

$$
\left(\left\{g \otimes h^{\nu}\right\}\left(u_{1} \otimes \lambda\right)\right)\left(u_{2} \otimes \mu\right)=\nu \cdot \lambda \cdot \mu \cdot\left(g\left(u_{1}\right)\right)\left(u_{2}\right)
$$

ExERCISE 3.70. Given a metric $g$ on $U$, the canonical map $m: U \rightarrow \operatorname{Hom}(\mathbb{K}, U)$, $m(u): \lambda \mapsto \lambda \cdot u$, is an isometry with respect to $g$ and the metric $b$ induced by $h^{1}$ and $g$.

Hint. The pullback of the metric $b$ induced by the more general map $h^{\nu}$ is, using Lemma 3.67,

$$
\begin{aligned}
\left(b\left(m\left(u_{1}\right)\right)\right)\left(m\left(u_{2}\right)\right) & =\operatorname{Tr}_{\mathbb{K}}\left(\left(h^{\nu}\right)^{-1} \circ\left(m\left(u_{1}\right)\right)^{*} \circ g \circ\left(m\left(u_{1}\right)\right)\right) \\
& =\left(h^{\nu}\right)^{-1}\left(\left(m\left(u_{1}\right)\right)^{*}\left(g\left(\left(m\left(u_{2}\right)\right)(1)\right)\right)\right) \\
& =\nu^{-1} \cdot \operatorname{Tr}_{\mathbb{K}}\left(\left(g\left(\left(m\left(u_{2}\right)\right)(1)\right)\right) \circ\left(m\left(u_{1}\right)\right)\right) \\
& =\nu^{-1} \cdot\left(g\left(\left(m\left(u_{2}\right)\right)(1)\right)\right)\left(\left(m\left(u_{1}\right)\right)(1)\right) \\
& =\nu^{-1} \cdot\left(g\left(u_{2}\right)\right)\left(u_{1}\right) .
\end{aligned}
$$

If $U \neq\left\{0_{U}\right\}$, then $\nu=1$ is necessary for equality.
Lemma 3.71. Given a metric $g$ on $V$, and a direct sum $V=\mathbb{K} \oplus U$ with inclusion operators $Q_{i}$, if the direct sum is orthogonal with respect to $g$, then the induced metric $Q_{1}^{*} \circ g \circ Q_{1}$ on $\mathbb{K}$ is equal to $h^{\nu}$, for $\nu=\left(g\left(Q_{1}(1)\right)\right)\left(Q_{1}(1)\right)$.

Proof. $Q_{1}^{*} \circ g \circ Q_{1}=h^{\nu}$ for some $\nu \neq 0$, by Lemma 3.67 and Theorem 3.58.

$$
\nu=\left(h^{\nu}(1)\right)(1)=\left(\left(Q_{1}^{*} \circ g \circ Q_{1}\right)(1)\right)(1)=\left(g\left(Q_{1}(1)\right)\right)\left(Q_{1}(1)\right) .
$$

ExERCISE 3.72. Given a metric $g$ on $V$ and an orthogonal direct sum $V=\mathbb{K} \oplus U$ as in Lemma 3.71, if $\alpha \in \mathbb{K}$ satisfies

$$
\left(g\left(Q_{1}(\alpha)\right)\right)\left(Q_{1}(\alpha)\right)=1
$$

then

$$
d_{\mathbb{K} U}(\alpha): \operatorname{Hom}(\mathbb{K}, U) \rightarrow U: A \mapsto A(\alpha)
$$

is an isometry with respect to the induced metrics.
Hint. Let $h^{\nu}$ and $g_{U}$ be the metrics induced by $g$ on $\mathbb{K}$ and $U$ from Lemma 3.71, so $\nu=\left(g\left(Q_{1}(1)\right)\right)\left(Q_{1}(1)\right)$. For $A, B \in \operatorname{Hom}(\mathbb{K}, U)$, the pullback of $g_{U}$ by $d_{\mathbb{K} U}(\alpha)$ gives:

$$
\begin{aligned}
\left(g_{U}\left(\left(d_{\mathbb{K} U}(\alpha)\right)(A)\right)\right)\left(\left(d_{\mathbb{K} U}(\alpha)\right)(B)\right) & =\left(g_{U}(A(\alpha))\right)(B(\alpha)) \\
& =\alpha^{2} \cdot\left(g_{U}(A(1))\right)(B(1)) .
\end{aligned}
$$

The calculation for the induced metric on $\operatorname{Hom}(\mathbb{K}, U)$ is:

$$
\begin{aligned}
(b(A))(B) & =\operatorname{Tr}_{\mathbb{K}}\left(\left(h^{\nu}\right)^{-1} \circ A^{*} \circ g_{U} \circ B\right) \\
& =\left(h^{\nu}\right)^{-1}\left(\left(g_{U}(B(1))\right) \circ A\right) \\
& =\nu^{-1} \cdot\left(g_{U}(B(1))\right)(A(1)) .
\end{aligned}
$$

If $\alpha^{2} \nu=1$, then the outputs are equal; the converse holds for $U \neq\left\{0_{U}\right\}$. The above calculation works for any metric on $U$, and is similar to that from Exercise 3.70.

Lemma 3.73. Given metrics on $U$ and $V$, the canonical map $n: \operatorname{Hom}(U, V) \otimes$ $W \rightarrow \operatorname{Hom}(U, V \otimes W)$ is an isometry with respect to the induced metrics.

Proof. This follows from the fact that $j, l_{U}$, and $m$ are isometries, Lemma 1.41, where $n=\left[I d_{\operatorname{Hom}(U, V)} \otimes m^{-1}\right] \circ j \circ \operatorname{Hom}\left(l_{U}, I d_{V \otimes W}\right)$, and Theorems 3.28 and 3.45. It could also be checked directly.

ExERCISE 3.74. Given a metric $g$ on $U$, the dual metric on $U^{*}$ and the metric $b$ on $\operatorname{Hom}(U, \mathbb{K})$, induced by $g$ and $h^{1}$, coincide.

Hint. For $\phi \in U^{*}$, and the more general metric $h^{\nu}$ on $\mathbb{K}$, the identity

$$
\left(\left(h^{\nu}(1)\right) \circ \phi\right)(\lambda)=\nu \cdot 1 \cdot \phi(\lambda)=(\nu \cdot \phi)(\lambda)
$$

is used in computing the $b$ metric for $\phi, \xi \in U^{*}$ :

$$
\begin{aligned}
\operatorname{Tr}_{\mathbb{K}}\left(\xi \circ g^{-1} \circ \phi^{*} \circ h^{\nu}\right) & =\xi\left(g^{-1}\left(\phi^{*}\left(h^{\nu}(1)\right)\right)\right)=\xi\left(g^{-1}\left(\left(h^{\nu}(1)\right) \circ \phi\right)\right) \\
& =\xi\left(g^{-1}(\nu \cdot \phi)\right)=\nu \cdot \xi\left(g^{-1}(\phi)\right) .
\end{aligned}
$$

The dual metric on $U^{*}$ results in the quantity $\xi\left(g^{-1}(\phi)\right)$, so $\nu=1$ is necessary for equality in the case $U \neq\left\{0_{U}\right\}$, and, in general, if $h^{\nu}$ is the metric on $\mathbb{K}$, then the $b$ metric on $\operatorname{Hom}(U, \mathbb{K})$ is equal to $\nu \cdot d_{U} \circ g^{-1}$.

EXERCISE 3.75. Given metrics on $U_{1}$ and $U_{2}$, if $A: U_{2} \rightarrow U_{1}$ is an isometry, then $A^{*}: U_{1}^{*} \rightarrow U_{2}^{*}$ is an isometry with respect to the dual metrics.

Exercise 3.76. Given metrics on $U$ and $V$, the map $p: U \otimes V \rightarrow V^{* *} \otimes U$, as in Notation 1.66, is an isometry with respect to the induced tensor product metrics.

Exercise 3.77. Given metrics $g, h$, and $y$ on $U, V$, and $W$, the map $q$ : $\operatorname{Hom}(V, \operatorname{Hom}(U, W)) \rightarrow \operatorname{Hom}(V \otimes U, W)$, as in Definition 1.43, is an isometry with respect to the induced metrics.

Hint. All the maps in the following commutative diagram are isometries.


Proposition 3.78. Given finite-dimensional vector spaces $V$ and $L$, if, as in Proposition 2.21, $E v_{L}: L^{*} \otimes L \rightarrow \mathbb{K}$ is invertible, then $d_{V L}: V \rightarrow \operatorname{Hom}(\operatorname{Hom}(V, L), L)$ is invertible. If, further, there is some metric $y$ on $L$, and $E v_{L}$ is an isometry with respect to the induced metric on $L^{*} \otimes L$ and $h^{1}$ on $\mathbb{K}$, then $d_{V L}$ is an isometry with respect to any metric $g$ on $V$, and the induced metric on $\operatorname{Hom}(\operatorname{Hom}(V, L), L)$.

Proof. Recall $d_{V L}$ from Definition 1.12.


The lower triangle is commutative, as in Proposition 2.21, and so is the top part of the diagram:

$$
\begin{aligned}
v & \mapsto\left(q \circ \operatorname{Hom}\left(I d_{V^{*}}, Q_{1}^{1}\right) \circ d_{V}\right)(v) \\
& =q\left(Q_{1}^{1} \circ\left(d_{V}(v)\right)\right): \\
\phi \otimes u & \mapsto\left(Q_{1}^{1}(\phi(v))\right)(u)=\left(\phi(v) \cdot I d_{L}\right)(u)=\phi(v) \cdot u, \\
v & \mapsto\left(\operatorname{Hom}\left(k_{V L}, I d_{L}\right) \circ d_{V L}\right)(v) \\
& =\left(d_{V L}(v)\right) \circ k_{V L}: \\
\phi \otimes u & \mapsto\left(k_{V L}(\phi \otimes u)\right)(v)=\phi(v) \cdot u .
\end{aligned}
$$

$d_{V L}$ is invertible because all the other maps in the rectangle are invertible. By Theorem 3.45, $\operatorname{Hom}\left(I d_{V^{*}}, E v_{L}\right)$ is an isometry with respect to the $b$ metric on $\operatorname{Hom}\left(V^{*}, L^{*} \otimes L\right)$, and the $b$ metric on $V^{* *}=\operatorname{Hom}\left(V^{*}, \mathbb{K}\right)$, induced by $d_{V} \circ g^{-1}$ on $V^{*}$ and $h^{1}$ on $\mathbb{K} . d_{V}$ is an isometry from $V$ to $V^{* *}$ with respect to the dual metric, which by Exercise 3.74 , is the same as the $b$ metric on $\operatorname{Hom}\left(V^{*}, \mathbb{K}\right)$. So, $d_{V L}$ is a composite of isometries.

### 3.7.3. Antisymmetric forms and symplectic forms.

Exercise 3.79. Given a bilinear form $g: V \rightarrow V^{*}$, if $g$ satisfies $(g(v))(v)=0$ for all $v \in V$, then $g$ is antisymmetric. If $\frac{1}{2} \in \mathbb{K}$, then, conversely, an antisymmetric form $g$ satisfies $(g(v))(v)=0$.

Big Exercise 3.80. Given a bilinear form $g: V \rightarrow V^{*}$, the following are equivalent.
(1) For all $u, v \in V$, if $(g(u))(v)=0$, then $(g(v))(u)=0$.
(2) $g \in \operatorname{Sym}(V) \cup \operatorname{Alt}(V)$.

Hint. $(2) \Longrightarrow(1)$ is easy; a proof of the well-known converse is given by $[\mathbf{J}]$ $\S 6.1$. A bilinear form satisfying either equivalent condition is variously described by the literature as "orthosymmetric" or "reflexive."

Definition 3.81. A bilinear form $h: U \rightarrow U^{*}$ is a symplectic form means: $h$ is antisymmetric and invertible.

Recall from Theorem 3.16 that the invertibility implies $U$ is finite-dimensional.
ExErcise 3.82. Given a symplectic form $h$ on $V$, the bilinear form $d_{V} \circ h^{-1}$ : $V^{*} \rightarrow V^{* *}$ is a symplectic form on $V^{*}$.

Hint. This is an analogue of Theorem 3.17. The antisymmetric property implies the equality $d_{V} \circ h^{-1}=-\left(h^{*}\right)^{-1}$.

Given a symplectic form $h$ on $V$, the above Exercise suggests there are two opposite ways $h$ could induce a symplectic form on $V^{*}$ :

$$
\begin{align*}
d_{V} \circ h^{-1} & =-\left(h^{*}\right)^{-1}  \tag{3.6}\\
-d_{V} \circ h^{-1} & =\left(h^{*}\right)^{-1} \tag{3.7}
\end{align*}
$$

Exercise 3.83. The tensor product of symplectic forms is a metric.
The following Definition is analogous to Definition 3.23.
Definition 3.84. A map $H: U \rightarrow V$ is a symplectic isometry, with respect to symplectic forms $g$ on $U$, and $h$ on $V$, means: $H$ is invertible, and $g=H^{*} \circ h \circ H$.

LEMMA 3.85. A symplectic form $h: U \rightarrow U^{*}$ is a symplectic isometry with respect to itself and the symplectic form $-d_{V} \circ h^{-1}$ from (3.7).

ExERCISE 3.86. Given $V$ with metric $g$ and symplectic form $h$, the following are equivalent.
(1) $g$ is a symplectic isometry with respect to $h$ and the symplectic form $d_{V} \circ h^{-1}$ from (3.6).
(2) $h^{-1} \circ g \in \operatorname{End}(V)$ is an involution.

Exercise 3.87. Given $V$ with metric $g$ and symplectic form $h$, the following are equivalent.
(1) $g$ is a symplectic isometry with respect to $h$ and the symplectic form $-d_{V} \circ h^{-1}$ from (3.7).
(2) $h$ is an isometry with respect to $g$ and the dual metric $d_{V} \circ g^{-1}$.
(3) $g^{-1} \circ h \in \operatorname{End}(V)$ is an isometry with respect to $g$.
(4) $g^{-1} \circ h \in \operatorname{End}(V)$ is a symplectic isometry with respect to $h$.

Hint. The equivalence of (2) and (3) follows from Theorem 3.26.
Exercise 3.88. Given a symplectic form $h$ on $U$, using either method (3.6) or (3.7) to induce a symplectic form on the dual space, the double dual $U^{* *}$ has a canonical symplectic form

$$
d_{U^{*}} \circ\left(d_{U} \circ h^{-1}\right)^{-1}=-d_{U^{*}} \circ\left(-d_{U} \circ h^{-1}\right)^{-1}=d_{U^{*}} \circ h \circ d_{U}^{-1}
$$

The map $d_{U}: U \rightarrow U^{* *}$ is a symplectic isometry with respect to $h$ and the above symplectic form.

Big Exercise 3.89. Several more of the elementary results on metrics can be adapted to symplectic forms.

### 3.7.4. More direct sums.

Exercise 3.90. Given linear maps $H: U \rightarrow V$ and $h: V \rightarrow V^{*}$, if $H^{*} \circ h \circ H:$ $U \rightarrow U^{*}$ is invertible, then there is a direct sum $V=U \oplus \operatorname{ker}\left(H^{*} \circ h\right)$. If, in addition, $h$ is symmetric (or antisymmetric), then $h: V \rightarrow V^{*}$ respects the induced direct sums and $H^{*} \circ h \circ H: U \rightarrow U^{*}$ is a metric (respectively, symplectic form) on $U$. If, further, $h$ is invertible, then $h$ also induces a metric (respectively, symplectic form) on $\operatorname{ker}\left(H^{*} \circ h\right)$.

Hint. $H$ is a linear monomorphism as in Exercise 3.25. Let $Q_{1}=H$, and let $P_{1}=\left(H^{*} \circ h \circ H\right)^{-1} \circ H^{*} \circ h$. Then $P_{1} \circ Q_{1}=I d_{U}$, and $Q_{1} \circ P_{1}=H \circ\left(H^{*} \circ h \circ\right.$ $H)^{-1} \circ H^{*} \circ h$ is an idempotent on $V$. The kernel of $Q_{1} \circ P_{1}$ is equal to the kernel of $H^{*} \circ h$; let $Q_{2}$ denote the inclusion of this subspace in $V$, and define the projection $P_{2}$ onto this subspace as in Example 1.107: $P_{2}=I d_{V}-Q_{1} \circ P_{1}=Q_{2} \circ P_{2}$.

The direct sum $V=U \oplus \operatorname{ker}\left(H^{*} \circ h\right)$ induces a direct sum $V^{*}=U^{*} \oplus\left(\operatorname{ker}\left(H^{*} \circ\right.\right.$ $h))^{*}$ as in Example 1.78. If $h$ is symmetric (or antisymmetric), then $H^{*} \circ h \circ H$ is also symmetric (respectively, antisymmetric) by Lemma 3.8, and a metric (respectively, symplectic form) on $U$, so $U$ is finite-dimensional and $d_{U}$ is invertible. Consider the two expressions:

$$
\begin{aligned}
h \circ Q_{1} \circ P_{1} & =h \circ H \circ\left(H^{*} \circ h \circ H\right)^{-1} \circ H^{*} \circ h, \\
P_{1}^{*} \circ Q_{1}^{*} \circ h & =h^{*} \circ H^{* *} \circ\left(H^{*} \circ h^{*} \circ H^{* *}\right)^{-1} \circ H^{*} \circ h .
\end{aligned}
$$

If $h= \pm h^{*} \circ d_{V}$, then, using Lemma 1.13,

$$
\begin{aligned}
h \circ Q_{1} \circ P_{1} & = \pm h^{*} \circ d_{V} \circ H \circ\left(H^{*} \circ\left( \pm h^{*} \circ d_{V}\right) \circ H\right)^{-1} \circ H^{*} \circ h \\
& =h^{*} \circ H^{* *} \circ d_{U} \circ\left(H^{*} \circ h^{*} \circ H^{* *} \circ d_{U}\right)^{-1} \circ H^{*} \circ h
\end{aligned}
$$

so $h \circ Q_{1} \circ P_{1}=P_{1}^{*} \circ Q_{1}^{*} \circ h$, and $h$ respects the direct sums.
If, further, $h$ is invertible, then $h$ is a metric (respectively, symplectic form) that respects the direct sums $V \rightarrow V^{*}$, so $V=U \oplus \operatorname{ker}\left(H^{*} \circ h\right)$ is an orthogonal direct sum with respect to $h$, and Theorem 3.58 applies.

ExERCISE 3.91. Given $V=V_{1} \oplus V_{2}, U=U_{1} \oplus U_{2}$, with projection and inclusion maps $P_{i}, Q_{i}$ on $V, P_{i}^{\prime}, Q_{i}^{\prime}$ on $U$, if $A: U_{1} \rightarrow V_{1}$ and $B: U_{2} \rightarrow V_{2}$ are isometries with respect to metrics $g_{i}$ on $U_{i}, h_{i}$ on $V_{i}$, then

$$
A \oplus B=Q_{1} \circ A \circ P_{1}^{\prime}+Q_{2} \circ B \circ P_{2}^{\prime}: U \rightarrow V
$$

is an isometry with respect to the induced metrics.

Hint. The invertibility is by Lemma 1.80. The rest of the claim is that

$$
g_{1} \oplus g_{2}=(A \oplus B)^{*} \circ\left(h_{1} \oplus h_{2}\right) \circ(A \oplus B)
$$

The RHS can be expanded:

$$
\begin{aligned}
R H S= & \left(P_{1}^{\prime *} \circ A^{*} \circ Q_{1}^{*}+P_{2}^{\prime *} \circ B^{*} \circ Q_{2}^{*}\right) \\
& \circ\left(P_{1}^{*} \circ h_{1} \circ P_{1}+P_{2}^{*} \circ h_{2} \circ P_{2}\right) \\
& \circ\left(Q_{1} \circ A \circ P_{1}^{\prime}+Q_{2} \circ B \circ P_{2}^{\prime}\right) \\
= & P_{1}^{\prime *} \circ A^{*} \circ h_{1} \circ A \circ P_{1}^{\prime}+P_{2}^{\prime *} \circ B^{*} \circ h_{2} \circ B \circ P_{2}^{\prime} \\
= & P_{1}^{\prime *} \circ g_{1} \circ P_{1}^{\prime}+P_{2}^{\prime *} \circ g_{2} \circ P_{2}^{\prime}=L H S .
\end{aligned}
$$

The last step uses $g_{1}=A^{*} \circ h_{1} \circ A, g_{2}=B^{*} \circ h_{2} \circ B$.
ExErcise 3.92. Given metrics $g_{1}$ and $g_{2}$ on $V_{1}$ and $V_{2}$, if $V=V_{1} \oplus V_{2}$ and $W=V_{1} \oplus V_{2}$ are direct sums with operators $P_{i}^{\prime}, Q_{i}^{\prime}$ and $P_{i}, Q_{i}$, respectively, then the map $Q_{1}^{\prime} \circ P_{1}+Q_{2}^{\prime} \circ P_{2}: W \rightarrow V$ is an isometry with respect to the direct sum metrics from Corollary 3.18.

Hint. This is a special case of Exercise 3.91. The construction of the invertible $\operatorname{map} Q_{1}^{\prime} \circ P_{1}+Q_{2}^{\prime} \circ P_{2}: W \rightarrow V$ is a special case of the map from Lemma 1.80.

ExERCISE 3.93. Given metrics $g_{1}$ and $g_{2}$ on $V_{1}$ and $V_{2}$, if $V=V_{1} \oplus V_{2}$, then the dual of the metric $g_{1} \oplus g_{2}$ from Corollary 3.18 is $d_{V} \circ\left(g_{1} \oplus g_{2}\right)^{-1}: V^{*} \rightarrow V^{* *}$, as in Theorem 3.17. For the direct sum $V^{*}=V_{1}^{*} \oplus V_{2}^{*}$ from Example 1.78, the direct sum of the dual metrics is $\left(d_{V_{1}} \circ g_{1}^{-1}\right) \oplus\left(d_{V_{2}} \circ g_{2}^{-1}\right)$. These two metrics on $V^{*}$ are equal.

Hint. Lemma 1.13 applies to the direct sum formula (3.3) and the inverse (3.4).

Example 3.94. Given $\frac{1}{2} \in \mathbb{K}$, and given $V$ with metric $g$ and an involution $K_{1}: V \rightarrow V$, producing a direct sum $V_{1} \oplus V_{2}$ as in Lemma 1.112, suppose the bilinear forms $Q_{i}^{*} \circ g \circ Q_{i}$ are metrics for $i=1,2$ (this is the case, for example, when $K_{1}$ is an isometry, by Lemma 3.55 and Theorem 3.58). If $K_{2}$ is another involution on $V$ that is an isometry and anticommutes with $K_{1}$, then $K_{2}$ respects the direct sums $V_{1} \oplus V_{2} \rightarrow V_{2} \oplus V_{1}$ as in Lemma 1.119, and the induced maps $P_{2} \circ K_{2} \circ Q_{1}: V_{1} \rightarrow V_{2}$ and $P_{1} \circ K_{2} \circ Q_{2}: V_{2} \rightarrow V_{1}$, as in Theorem 1.128, are isometries by Lemma 3.31.

Lemma 3.95. Given $\frac{1}{2} \in \mathbb{K}$, and given $V$ with metric $g$ and an involution $K: V \rightarrow V$, producing a direct sum $V=V_{1} \oplus V_{2}$ with operators $P_{i}, Q_{i}$ as in Lemma 1.112, suppose the direct sum is orthogonal with respect to $g$ (this is the case, for example, when $K$ is an isometry, by Lemma 3.55). Let $K^{\prime}$ be another involution on $V$ that is an isometry and anticommutes with $K$, and which produces $a$ direct sum $V=V_{1}^{\prime} \oplus V_{2}^{\prime}$, with operators $P_{i}^{\prime}, Q_{i}^{\prime}$. If $\beta \in \mathbb{K}$ satisfies $\beta^{2}=2$, then for $i=1,2, I=1,2$, the map $\beta \cdot P_{I}^{\prime} \circ Q_{i}: V_{i} \rightarrow V_{I}^{\prime}$ is an isometry.

Proof. The map $\beta \cdot P_{I}^{\prime} \circ Q_{i}: V_{i} \rightarrow V_{I}^{\prime}$ is invertible by Theorem 1.129. The induced metric on $V_{i}$ is $Q_{i}^{*} \circ g \circ Q_{i}$ and on $V_{I}^{\prime}$ is $\left(Q_{I}^{\prime}\right)^{*} \circ g \circ Q_{I}^{\prime}$, by Lemma 3.55 and

Theorem 3.58. From the Proof of Lemma 3.55, $g \circ Q_{I}^{\prime} \circ P_{I}^{\prime}=\left(P_{I}^{\prime}\right)^{*} \circ\left(Q_{I}^{\prime}\right)^{*} \circ g$.

$$
\begin{aligned}
& \left(\beta \cdot P_{I}^{\prime} \circ Q_{i}\right)^{*} \circ\left(\left(Q_{I}^{\prime}\right)^{*} \circ g \circ Q_{I}^{\prime}\right) \circ\left(\beta \cdot P_{I}^{\prime} \circ Q_{i}\right) \\
= & \beta^{2} \cdot Q_{i}^{*} \circ\left(P_{I}^{\prime}\right)^{*} \circ\left(Q_{I}^{\prime}\right)^{*} \circ g \circ Q_{I}^{\prime} \circ P_{I}^{\prime} \circ Q_{i} \\
= & \beta^{2} \cdot Q_{i}^{*} \circ g \circ Q_{I}^{\prime} \circ P_{I}^{\prime} \circ Q_{i} \\
= & \beta^{2} \cdot Q_{i}^{*} \circ g \circ \frac{1}{2} \cdot\left(I d_{V} \pm K^{\prime}\right) \circ Q_{i} .
\end{aligned}
$$

By hypothesis, $g$ respects the direct sum $V_{1} \oplus V_{2}$, but $K^{\prime}$ reverses the direct sum as in Lemma 1.119. So, $Q_{i}^{*} \circ g \circ K^{\prime} \circ Q_{i}=0_{\operatorname{Hom}\left(V_{i}, V_{i}^{*}\right)}$ and the second term in the last line drops out.

Exercise 3.96. Given metrics $g$ and $h$ on $U$ and $V$, let $U=U_{1} \oplus U_{2}$ and $V=V_{1} \oplus V_{2}$ be orthogonal direct sums with operators $P_{i}, Q_{i}, P_{i}^{\prime}, Q_{i}^{\prime}$. If $H: U \rightarrow V$ is an isometry such that $P_{2}^{\prime} \circ H \circ Q_{1}=0_{\operatorname{Hom}\left(U_{1}, V_{2}\right)}$, and $P_{1}^{\prime} \circ H \circ Q_{1}$ is a linear epimorphism, then $P_{1}^{\prime} \circ H \circ Q_{2}=0_{\operatorname{Hom}\left(U_{2}, V_{1}\right)}$, so $H$ respects the direct sums.

Hint.

$$
\begin{aligned}
0_{\operatorname{Hom}\left(U_{1}, U_{2}^{*}\right)} & =Q_{2}^{*} \circ g \circ Q_{1} \\
& =Q_{2}^{*} \circ H^{*} \circ h \circ H \circ Q_{1} \\
& =Q_{2}^{*} \circ H^{*} \circ\left(Q_{1}^{\prime} \circ P_{1}^{\prime}+Q_{2}^{\prime} \circ P_{2}^{\prime}\right)^{*} \circ h \circ\left(Q_{1}^{\prime} \circ P_{1}^{\prime}+Q_{2}^{\prime} \circ P_{2}^{\prime}\right) \circ H \circ Q_{1} \\
& =\left(P_{1}^{\prime} \circ H \circ Q_{2}\right)^{*} \circ Q_{1}^{\prime *} \circ h \circ Q_{1}^{\prime} \circ P_{1}^{\prime} \circ H \circ Q_{1} .
\end{aligned}
$$

$Q_{1}^{\prime *} \circ h \circ Q_{1}^{\prime}$ is invertible by Theorem 3.58 , so $P_{1}^{\prime} \circ H \circ Q_{2}=0_{\operatorname{Hom}\left(U_{2}, V_{1}\right)}$ by the linear epimorphism property (Definition 0.46 ).

ExERCISE 3.97. If $U_{1}=V_{1}$ in Exercise 3.96, then the epimorphism property is not needed in the hypothesis.

Hint.

$$
\begin{aligned}
\left(P_{1} \circ H^{-1} \circ Q_{1}^{\prime}\right) \circ\left(P_{1}^{\prime} \circ H \circ Q_{1}\right) & =P_{1} \circ H^{-1} \circ\left(Q_{1}^{\prime} \circ P_{1}^{\prime}+Q_{2}^{\prime} \circ P_{2}^{\prime}\right) \circ H \circ Q_{1} \\
& =P_{1} \circ Q_{1}=I d_{V_{1}} .
\end{aligned}
$$

Claim 0.50 applies.
EXERCISE 3.98. Given any vector space $V$, if $U=U_{1} \oplus U_{2}$ is a direct sum with projection operators $P_{i}$ and inclusion operators $Q_{i}$, then as in Example 1.77, $\operatorname{Hom}(U, V)=\operatorname{Hom}\left(U_{1}, V\right) \oplus \operatorname{Hom}\left(U_{2}, V\right)$, with projection operators $\operatorname{Hom}\left(Q_{i}, I d_{V}\right)$ and inclusion operators $\operatorname{Hom}\left(P_{i}, I d_{V}\right)$. Given metrics $g$ and $h$ on $U$ and $V$, if $U_{1} \oplus U_{2}$ is an orthogonal direct sum, then $\operatorname{Hom}\left(U_{1}, V\right) \oplus \operatorname{Hom}\left(U_{2}, V\right)$ is an orthogonal direct sum with respect to the induced $b$ metric.

Hint. Consider $A: U_{i} \rightarrow V, B: U_{I} \rightarrow V$.

$$
\begin{aligned}
\left(\left(\operatorname{Hom}\left(P_{I}, I d_{V}\right)^{*} \circ b \circ \operatorname{Hom}\left(P_{i}, I d_{V}\right)\right)(A)\right)(B) & =\left(b\left(A \circ P_{i}\right)\right)\left(B \circ P_{I}\right) \\
& =\operatorname{Tr}_{V}\left(B \circ P_{I} \circ g^{-1} \circ\left(A \circ P_{i}\right)^{*} \circ h\right) \\
& =\operatorname{Tr}_{V}\left(B \circ P_{I} \circ g^{-1} \circ P_{i}^{*} \circ A^{*} \circ h\right) .
\end{aligned}
$$

By Lemma 1.83 , since $g: U \rightarrow U^{*}$ respects the direct sums, so does $g^{-1}: U^{*} \rightarrow U$, so for $i \neq I, P_{I} \circ g^{-1} \circ P_{i}^{*}=0_{\operatorname{Hom}\left(U_{i}^{*}, U_{I}\right)}$. This makes $\left(b\left(A \circ P_{i}\right)\right)\left(B \circ P_{I}\right)$ equal to zero, proving orthogonality.

Exercise 3.99. Given any vector space $U$, if $V=V_{1} \oplus V_{2}$ is a direct sum with projection operators $P_{i}$ and inclusion operators $Q_{i}$, then as in Example 1.76, $\operatorname{Hom}(U, V)=\operatorname{Hom}\left(U, V_{1}\right) \oplus \operatorname{Hom}\left(U, V_{2}\right)$, with projection operators $\operatorname{Hom}\left(I d_{U}, P_{i}\right)$ and inclusion operators $\operatorname{Hom}\left(I d_{U}, Q_{i}\right)$. Given metrics $g$ and $h$ on $U$ and $V$, if $V_{1} \oplus V_{2}$ is an orthogonal direct sum, then $\operatorname{Hom}\left(U, V_{1}\right) \oplus \operatorname{Hom}\left(U, V_{2}\right)$ is an orthogonal direct sum with respect to the induced $b$ metric.

Hint. Consider $A: U \rightarrow V_{i}, B: U \rightarrow V_{I}$.

$$
\begin{aligned}
\left(\left(\operatorname{Hom}\left(I d_{U}, Q_{I}\right)^{*} \circ b \circ \operatorname{Hom}\left(I d_{U}, Q_{i}\right)\right)(A)\right)(B) & =\left(b\left(Q_{i} \circ A\right)\right)\left(Q_{I} \circ B\right) \\
& =\operatorname{Tr}_{V}\left(Q_{I} \circ B \circ g^{-1} \circ\left(Q_{i} \circ A\right)^{*} \circ h\right) \\
& =\operatorname{Tr}_{V_{I}}\left(B \circ g^{-1} \circ A^{*} \circ Q_{i}^{*} \circ h \circ Q_{I}\right)
\end{aligned}
$$

For $i \neq I$, this quantity is zero.
ExErcise 3.100. Given a metric $g$ on $U$, if $U=U_{1} \oplus U_{2}$ is an orthogonal direct sum with operators $Q_{i}, P_{i}$, and $g_{1}, g_{2}$ are the metrics induced on $U_{1}, U_{2}$ (from Theorem 3.58), and $K: U \rightarrow U^{*}$, then

$$
\operatorname{Tr}_{g}(K)=\operatorname{Tr}_{g_{1}}\left(Q_{1}^{*} \circ K \circ Q_{1}\right)+\operatorname{Tr}_{g_{2}}\left(Q_{2}^{*} \circ K \circ Q_{2}\right)
$$

Hint. By Theorem 3.58, $g_{i}^{-1}=P_{i} \circ g^{-1} \circ P_{i}^{*}$, and from the hint for Exercise 3.98, $P_{I} \circ g^{-1} \circ P_{i}^{*}=0_{\operatorname{Hom}\left(U_{i}^{*}, U_{I}\right)}$ for $i \neq I$. Using Lemma 2.6,

$$
\begin{aligned}
\operatorname{Tr}_{g}(K)= & \operatorname{Tr}_{V}\left(g^{-1} \circ\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right)^{*} \circ K \circ\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right)\right) \\
= & \operatorname{Tr}_{V_{1}}\left(P_{1} \circ g^{-1} \circ\left(P_{1}^{*} \circ Q_{1}^{*}+P_{2}^{*} \circ Q_{2}^{*}\right) \circ K \circ Q_{1}\right) \\
& +\operatorname{Tr}_{V_{2}}\left(P_{2} \circ g^{-1} \circ\left(P_{1}^{*} \circ Q_{1}^{*}+P_{2}^{*} \circ Q_{2}^{*}\right) \circ K \circ Q_{2}\right) \\
= & \operatorname{Tr}_{V_{1}}\left(P_{1} \circ g^{-1} \circ P_{1}^{*} \circ Q_{1}^{*} \circ K \circ Q_{1}\right) \\
& +\operatorname{Tr}_{V_{2}}\left(P_{2} \circ g^{-1} \circ P_{2}^{*} \circ Q_{2}^{*} \circ K \circ Q_{2}\right) \\
= & \operatorname{Tr}_{V_{1}}\left(g_{1}^{-1} \circ Q_{1}^{*} \circ K \circ Q_{1}\right)+\operatorname{Tr}_{V_{2}}\left(g_{2}^{-1} \circ Q_{2}^{*} \circ K \circ Q_{2}\right) .
\end{aligned}
$$

Lemma 3.101. Let $V=U \oplus U^{*}$, with operators $P_{i}, Q_{i}$. The direct sum induces a symmetric form on $V$,

$$
\begin{equation*}
P_{1}^{*} \circ P_{2}+P_{2}^{*} \circ d_{U} \circ P_{1} \tag{3.8}
\end{equation*}
$$

If $U$ is finite-dimensional, then this symmetric form is a metric.
Proof.

$$
\begin{aligned}
\left(P_{1}^{*} \circ P_{2}+P_{2}^{*} \circ d_{U} \circ P_{1}\right)^{*} \circ d_{V} & =P_{2}^{*} \circ P_{1}^{* *} \circ d_{V}+P_{1}^{*} \circ d_{U}^{*} \circ P_{2}^{* *} \circ d_{V} \\
& =P_{2}^{*} \circ d_{U} \circ P_{1}+P_{1}^{*} \circ d_{U}^{*} \circ d_{U^{*}} \circ P_{2} \\
& =P_{1}^{*} \circ P_{2}+P_{2}^{*} \circ d_{U} \circ P_{1} . \\
\left(P_{1}^{*} \circ P_{2}+P_{2}^{*} \circ d_{U} \circ P_{1}\right) \circ\left(Q_{1} \circ d_{U}^{-1} \circ Q_{2}^{*}+Q_{2} \circ Q_{1}^{*}\right) & =P_{2}^{*} \circ Q_{2}^{*}+P_{1}^{*} \circ Q_{1}^{*} \\
& =I d_{V^{*}} \\
\left(Q_{1} \circ d_{U}^{-1} \circ Q_{2}^{*}+Q_{2} \circ Q_{1}^{*}\right) \circ\left(P_{1}^{*} \circ P_{2}+P_{2}^{*} \circ d_{U} \circ P_{1}\right) & =Q_{1} \circ P_{1}+Q_{2} \circ P_{2} \\
& =I d_{V} .
\end{aligned}
$$

Example 3.102. Given a metric $g_{U}$ on $U$, if $V=U \oplus U^{*}$, with operators $P_{i}$, $Q_{i}$, then the direct sum of the metric $g_{U}$ and its dual $d_{U} \circ g_{U}^{-1}$ is a metric on $V$ :

$$
g_{U} \oplus g_{U^{*}}=P_{1}^{*} \circ g_{U} \circ P_{1}+P_{2}^{*} \circ d_{U} \circ g_{U}^{-1} \circ P_{2}
$$

as in Theorem 3.17 and Corollary 3.18.
The map $K=Q_{2} \circ g_{U} \circ P_{1}+Q_{1} \circ g_{U}^{-1} \circ P_{2}$ is an involution on $V$, as in Equation (1.17) from Theorem 1.128, and it is an isometry with respect to both the above induced metric $g_{U} \oplus g_{U^{*}}$, and the canonical metric $g_{V}$ from (3.8) in Lemma 3.101. In particular, if $\frac{1}{2} \in \mathbb{K}$, then Lemma 3.55 applies, so that the direct sum $V=V_{1} \oplus V_{2}$, where

$$
\begin{aligned}
P_{1}^{\prime} & =\frac{1}{2}\left(I d_{V}+K\right)=\frac{1}{2}\left(I d_{V}+Q_{2} \circ g_{U} \circ P_{1}+Q_{1} \circ g_{U}^{-1} \circ P_{2}\right) \\
P_{2}^{\prime} & =\frac{1}{2}\left(I d_{V}-K\right)=\frac{1}{2}\left(I d_{V}-Q_{2} \circ g_{U} \circ P_{1}-Q_{1} \circ g_{U}^{-1} \circ P_{2}\right)
\end{aligned}
$$

is orthogonal with respect to both metrics on $V$. Each of the two metrics on $V$ induces a metric on $V_{1}$ and on $V_{2}$.

Exercise 3.103. For $V=U \oplus U^{*}$ and $V=V_{1} \oplus V_{2}$ as in the above Example, the two induced metrics on $V_{1}$ are identical, while those on $V_{2}$ are opposite.

Hint. It is more convenient to check the equality of the inverses of the induced metrics on $V_{1}$, using (3.4) from Corollary 3.18 and the formulas from Theorem 3.58:

$$
\begin{aligned}
& P_{1}^{\prime} \circ g_{V}^{-1} \circ\left(P_{1}^{\prime}\right)^{*} \\
= & \frac{1}{2}\left(I d_{V}+K\right) \circ\left(Q_{1} \circ d_{U}^{-1} \circ Q_{2}^{*}+Q_{2} \circ Q_{1}^{*}\right) \circ \frac{1}{2}\left(I d_{V}+K\right)^{*} \\
= & P_{1}^{\prime} \circ\left(g_{U} \oplus g_{U^{*}}\right)^{-1} \circ\left(P_{1}^{\prime}\right)^{*} \\
= & \frac{1}{2}\left(I d_{V}+K\right) \circ\left(Q_{1} \circ g_{U}^{-1} \circ Q_{1}^{*}+Q_{2} \circ g_{U} \circ d_{U}^{-1} \circ Q_{2}^{*}\right) \circ \frac{1}{2}\left(I d_{V}+K\right)^{*} \\
= & \frac{1}{2}\left(Q_{1} \circ g_{U}^{-1} \circ Q_{1}^{*}+Q_{2} \circ g_{U}^{*} \circ Q_{2}^{*}+Q_{2} \circ Q_{1}^{*}+Q_{1} \circ d_{U}^{-1} \circ Q_{2}^{*}\right) \\
= & \frac{1}{2}\left(g_{V}^{-1}+\left(g_{U} \oplus g_{U^{*}}\right)^{-1}\right) .
\end{aligned}
$$

The calculations for the metrics induced on $V_{2}$ are similar.
Example 3.104. Let $V=U \oplus U^{*}$, with operators $P_{i}, Q_{i}$. The direct sum induces an antisymmetric form on $V$,

$$
\begin{equation*}
P_{2}^{*} \circ d_{U} \circ P_{1}-P_{1}^{*} \circ P_{2} . \tag{3.9}
\end{equation*}
$$

If $U$ is finite-dimensional, then this antisymmetric form is symplectic (Definition 3.81). The construction is similar to the induced symmetric form (3.8) from Lemma 3.101, and canonical up to sign (as in (3.6), (3.7)). The inverse of the symplectic form is $Q_{1} \circ d_{U}^{-1} \circ Q_{2}^{*}-Q_{2} \circ Q_{1}^{*}$.

### 3.7.5. Isotropic maps and graphs.

Definition 3.105. Given a bilinear form $g: V \rightarrow V^{*}$, a linear map $A: U \rightarrow V$ is isotropic with respect to $g$ means that the pullback of $g$ by $A$ is zero:

$$
A^{*} \circ g \circ A=0_{\operatorname{Hom}\left(U, U^{*}\right)}
$$

Exercise 3.106. Given $V=V_{1} \oplus V_{2}$ with projection and inclusion operators $\left(P_{1}, P_{2}\right),\left(Q_{1}, Q_{2}\right)$, and a bilinear form $h: V \rightarrow V^{*}$, the following are equivalent.
(1) $Q_{1}$ and $Q_{2}$ are both isotropic with respect to $h$.
(2) The involution $K=Q_{1} \circ P_{1}-Q_{2} \circ P_{2}$ satisfies $h=-K^{*} \circ h \circ K$.

If, further, $\frac{1}{2} \in \mathbb{K}$ and $K \in \operatorname{End}(V)$ is any involution satisfying $h=-K^{*} \circ h \circ K$, then the direct sum produced by $K$ has both of the above equivalent properties.

Hint. The expression $Q_{1} \circ P_{1}-Q_{2} \circ P_{2}$ is as in Example 1.114.
ExERCISE 3.107. Given $V=V_{1} \oplus V_{2}$ with inclusion operators $Q_{i}$, bilinear forms $g_{1}: V_{1} \rightarrow V_{1}^{*}, g_{2}: V_{2} \rightarrow V_{2}^{*}$, and a map $A: V_{1} \rightarrow V_{2}$, the following are equivalent.
(1) $g_{1}=A^{*} \circ g_{2} \circ A$.
(2) The map $Q_{1}+Q_{2} \circ A: V_{1} \rightarrow V$ is isotropic with respect to the bilinear form $g_{1} \oplus\left(-g_{2}\right)$.

Hint. The first property is that $g_{1}$ is the pullback of $g_{2}$ by $A$ as in Definition 3.7; special cases include $A$ being an isometry (Definition 3.23) or a symplectic isometry (Definition 3.84).

The second property refers to the direct sum of bilinear forms as in (3.3) from Notation 3.9. The expression $Q_{1}+Q_{2} \circ A$ is from the notion that a "graph" of a linear map can be defined in terms of a direct sum, as in Exercise 1.101.

ExERCISE 3.108. ([ $\mathbf{L P}])$ Let $V=U \oplus U^{*}$. Given maps $E: W \rightarrow U$ and $h: U \rightarrow W^{*}$, the following are equivalent.
(1) The bilinear form $h \circ E: W \rightarrow W^{*}$ is antisymmetric.
(2) The map $Q_{1} \circ E+Q_{2} \circ h^{*} \circ d_{W}: W \rightarrow V$ is isotropic with respect to the symmetric form (3.8) on $V$ from Lemma 3.101.
Further, if $E$ is a linear monomorphism, then so is $Q_{1} \circ E+Q_{2} \circ h^{*} \circ d_{W}$.
Hint. By Definition 3.105, the second property is that the pullback of the symmetric form (3.8) on $V=U \oplus U^{*}$ from Lemma 3.101 by the map $Q_{1} \circ E+Q_{2} \circ$ $h^{*} \circ d_{W}: W \rightarrow V$ is $0_{\operatorname{Hom}\left(W, W^{*}\right)}$. The transpose $T_{W}(h \circ E)$ is $E^{*} \circ h^{*} \circ d_{W}$.

$$
\begin{aligned}
& \left(Q_{1} \circ E+Q_{2} \circ h^{*} \circ d_{W}\right)^{*} \circ\left(P_{1}^{*} \circ P_{2}+P_{2}^{*} \circ d_{U} \circ P_{1}\right) \circ\left(Q_{1} \circ E+Q_{2} \circ h^{*} \circ d_{W}\right) \\
= & E^{*} \circ h^{*} \circ d_{W}+d_{W}^{*} \circ h^{* *} \circ d_{U} \circ E \\
= & E^{*} \circ h^{*} \circ d_{W}+h \circ E .
\end{aligned}
$$

For any maps $F, G$, if

$$
\left(Q_{1} \circ E+Q_{2} \circ h^{*} \circ d_{W}\right) \circ F=\left(Q_{1} \circ E+Q_{2} \circ h^{*} \circ d_{W}\right) \circ G,
$$

then

$$
\begin{aligned}
P_{1} \circ\left(Q_{1} \circ E+Q_{2} \circ h^{*} \circ d_{W}\right) \circ F & =P_{1} \circ\left(Q_{1} \circ E+Q_{2} \circ h^{*} \circ d_{W}\right) \circ G \\
=E \circ F & =E \circ G,
\end{aligned}
$$

so if $E$ is a linear monomorphism (Definition 0.42 ), then $F=G$, proving the second claim.

If $W=U$ and $E=I d_{U}$, then this construction is exactly the graph of $h^{*} \circ d_{U}$, as in Exercise 1.101. A generalization of the construction appears in Section 4.2.

Exercise 3.109. ([LP]) Let $V=U \oplus U^{*}$. Given maps $E: W \rightarrow U$ and $h: U \rightarrow W^{*}$, the following are equivalent.
(1) The bilinear form $h \circ E: W \rightarrow W^{*}$ is symmetric.
(2) The map $Q_{1} \circ E+Q_{2} \circ h^{*} \circ d_{W}: W \rightarrow V$ is isotropic with respect to the antisymmetric form (3.9) from Example 3.104.

### 3.7.6. The adjoint.

Definition 3.110. Metrics $g, h$, on $U, V$ induce an adjoint map,

$$
\begin{equation*}
\operatorname{Hom}\left(h, g^{-1}\right) \circ t_{U V}: \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}(V, U): A \mapsto g^{-1} \circ A^{*} \circ h \tag{3.10}
\end{equation*}
$$

Exercise 3.111. Given metrics $g$ and $h$ on $U$ and $V$, the map (3.10) is an isometry with respect to the induced $b$ metrics. Also, if $A: U \rightarrow V$ is an isometry, then its adjoint is an isometry $V \rightarrow U$.

Hint. The first assertion follows from the fact that $g, h$, and $t_{U V}$ are isometries. The second claim follows from the following equation, which uses the symmetry of $g$ and $h$, and Lemma 1.13:

$$
\begin{equation*}
\left(g^{-1} \circ A^{*} \circ h\right)^{*}=h^{*} \circ A^{* *} \circ\left(g^{-1}\right)^{*}=h \circ d_{V}^{-1} \circ A^{* *} \circ d_{U} \circ g^{-1}=h \circ A \circ g^{-1} \tag{3.11}
\end{equation*}
$$

and the hypothesis $g=A^{*} \circ h \circ A$ :

$$
\begin{aligned}
\left(g^{-1} \circ A^{*} \circ h\right)^{*} \circ g \circ\left(g^{-1} \circ A^{*} \circ h\right) & =\left(h \circ A \circ g^{-1}\right) \circ A^{*} \circ h \\
& =h \circ A \circ A^{-1}=h
\end{aligned}
$$

Lemma 3.112. Given metrics $g$ and $h$ on $U$ and $V$, the composite of adjoint maps,

$$
\left(\operatorname{Hom}\left(g, h^{-1}\right) \circ t_{V U}\right) \circ\left(\operatorname{Hom}\left(h, g^{-1}\right) \circ t_{U V}\right): \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}(U, V)
$$

is the identity. In particular, the adjoint map $\operatorname{Hom}\left(g, g^{-1}\right) \circ t_{U U}: \operatorname{End}(U) \rightarrow$ $\operatorname{End}(U)$ is an involution.

Proof. Using (3.11),

$$
h^{-1} \circ\left(g^{-1} \circ A^{*} \circ h\right)^{*} \circ g=h^{-1} \circ\left(h \circ A \circ g^{-1}\right) \circ g=A .
$$

ExERCISE 3.113. Given a metric $g$ on $U$, if $\operatorname{Tr}_{U}\left(I d_{U}\right) \neq 0$, then the adjoint $\operatorname{map} \operatorname{Hom}\left(g, g^{-1}\right) \circ t_{U U}$ respects any direct $\operatorname{sum} \operatorname{End}(U)=\mathbb{K} \oplus \operatorname{End}_{0}(U)$ as in Example 2.9. The restriction of the adjoint map to $\operatorname{End}_{0}(U)$ is an involution and an isometry.

Hint. The direct sum refers to the construction of Example 2.9, and it is easily checked that $P_{I} \circ \operatorname{Hom}\left(g, g^{-1}\right) \circ t_{U U} \circ Q_{i}$ is zero for $i \neq I$. The direct sum is orthogonal as in Theorem 3.52, and Theorem 3.61 applies to the map induced by the adjoint on $\operatorname{End}_{0}(U)$.

Theorem 3.114. Given a metric $g$ on $U$, the following diagram is commutative, where $s$ and $s^{\prime}$ are switching involutions.


All the horizontal compositions of arrows define involutions, and if $\frac{1}{2} \in \mathbb{K}$, then they produce orthogonal direct sums on the spaces in the left column.

Proof. The composite in the third row is $T_{U}$, and the second square from the top does not involve the metric $g$ - it was considered in Lemma 3.6.

The composite in the fifth row, $\left[g^{*} \otimes g^{-1}\right] \circ p$, is the only involution not considered earlier. The commutativity of all the squares is easy to check.

The direct sums are produced by the involutions as in Lemma 1.112. The orthogonality of the direct sum for $\operatorname{Hom}\left(U, U^{*}\right)$ was checked in Theorem 3.56, and the orthogonality of the other direct sums similarly follows from Lemma 3.55 since all the horizontal arrows are isometries and involutions, or from Theorem 3.61 since all the vertical arrows are isometries which respect the direct sums, by Lemma 1.118. In particular, the direct sum $U^{*} \otimes U^{*}=S^{2}\left(U^{*}\right) \oplus \Lambda^{2}\left(U^{*}\right)$ from Lemma 3.6 is orthogonal.

Definition 3.115. Given a metric $g$ on $U$, if $\frac{1}{2} \in \mathbb{K}$, then the orthogonal direct sum on $\operatorname{End}(U)$, produced by the involution $\operatorname{Hom}\left(g, g^{-1}\right) \circ t$ as in Theorem 3.114, defines subspaces of self-adjoint $\left(A=g^{-1} \circ A^{*} \circ g\right)$ and skew-adjoint $(A=$ $-g^{-1} \circ A^{*} \circ g$ ) endomorphisms.

Example 3.116. Given a metric $g$ on $U$, if $\frac{1}{2} \in \mathbb{K}$, then the bilinear form $h: U \rightarrow U^{*}$ is a symmetric (or, antisymmetric) form if and only if $g^{-1} \circ h \in \operatorname{End}(U)$ is self-adjoint (respectively, skew-adjoint). This is the action of the middle left vertical arrow, and its inverse, from Theorem 3.114, respecting the direct sums $\operatorname{Hom}\left(U, U^{*}\right) \rightarrow \operatorname{End}(U)$.

Exercise 3.117. Given metrics $g, h$ on $U, V$, if $\frac{1}{2} \in \mathbb{K}$ then for any map $A: U \rightarrow V$,

$$
\operatorname{Hom}\left(g^{-1} \circ A^{*} \circ h, A\right): \operatorname{End}(U) \rightarrow \operatorname{End}(V)
$$

respects the direct sum from Definition 3.115.

Hint. The following diagram is commutative, so Lemma 1.118 applies.


Exercise 3.118. Given a metric $g$ on $V$, if $\frac{1}{2} \in \mathbb{K}$, then a skew-adjoint $A \in$ $\operatorname{End}(V)$ satisfies $\operatorname{Tr}_{V}(A)=0$. If, further, $\operatorname{Tr}_{V}\left(I d_{V}\right) \neq 0$, then any $A \in \operatorname{End}(V)$ can be written as a sum of three terms,

$$
A=\frac{\operatorname{Tr}_{V}(A)}{\operatorname{Tr}_{V}\left(I d_{V}\right)} \cdot I d_{V}+A_{1}+A_{2}
$$

where $A_{1}$ and $A_{2}$ have trace $0, A_{1}$ is self-adjoint, and $A_{2}$ is skew-adjoint.
Hint. The first claim follows from Lemma 2.5 and Lemma 2.6. The second claim is an analogue of Corollary 3.36. Apply Theorem 1.117 to $\operatorname{Tr}_{V}$ and the involution $\operatorname{Hom}\left(g, g^{-1}\right) \circ t$ on $\operatorname{End}(V)$ to get a direct sum decomposition.

Exercise 3.119. Given a metric $g$ on $U$, any scalar $\alpha \in \mathbb{K}$, and any vector $u \in U$, the endomorphism

$$
\alpha \cdot k_{U U}((g(u)) \otimes u) \in \operatorname{End}(U)
$$

is self-adjoint. If, further, $\alpha \cdot(g(u))(u)=1$, then $\alpha \cdot k_{U U}((g(u)) \otimes u)$ is an idempotent.
Hint. From the commutativity of the diagram in Theorem 3.114,

$$
\begin{aligned}
& \left(\operatorname{Hom}\left(g, g^{-1}\right) \circ t_{U U}\right)\left(k_{U U}((g(u)) \otimes u)\right) \\
= & \left(\operatorname{Hom}\left(g, g^{-1}\right) \circ t_{U U} \circ k_{U U} \circ\left[g \otimes I d_{U}\right]\right)(u \otimes u) \\
= & \left(k_{U U} \circ\left[g \otimes I d_{U}\right] \circ s\right)(u \otimes u) \\
= & k_{U U}((g(u)) \otimes u) .
\end{aligned}
$$

The easily checked idempotent property is related to Exercise 2.15.
Exercise 3.120. Given metrics $g, h$ on $U, V$, any vector $u \in U$, and any map $A: U \rightarrow V$, the two self-adjoint endomorphisms from Exercise 3.119 are related by the map from Exercise 3.117:

$$
\operatorname{Hom}\left(g^{-1} \circ A^{*} \circ h, A\right)\left(k_{U U}((g(u)) \otimes u)\right)=k_{V V}((h(A(u))) \otimes(A(u)))
$$

Hint. The left square is commutative by Lemma 1.35, and the right square is commutative by Lemma 1.57 and Equation (3.11).


The equality follows from the case where $B=A$, and starting with $u \otimes u \in U \otimes U$.

Exercise 3.121. Given a metric $g$ on $U$, and an endomorphism $A \in \operatorname{End}(U)$, any pair of two of the following three statements implies the remaining third statement.
(1) $A$ is an involution.
(2) $A$ is self-adjoint.
(3) $A$ is an isometry.

### 3.7.7. Some formulas from applied mathematics.

Remark 3.122. The following few statements are related to the Householder reflection $R$.

ExErcise 3.123. Given a metric $g$ on $U$, and an element $u \in U$, if $(g(u))(u) \neq$ 0 , then the endomorphism

$$
R=I d_{U}-\frac{2}{(g(u))(u)} \cdot k_{U U}((g(u)) \otimes u)
$$

is self-adjoint, an involution, and an isometry.
Hint. The second term is from Exercise 3.119. Lemma 1.115 and Exercise 3.121 apply.

Proposition 3.124. Given a metric $g$ on $V$ and $\frac{1}{2} \in \mathbb{K}$, if $u, v \in V$ satisfy $(g(u))(u)=(g(v))(v) \neq 0$, then there exists an isometry $H \in \operatorname{End}(V)$ such that $H(u)=v$.

Proof. Such an isometry may not be unique; the following construction is not canonical, it depends on two cases.

Case 1. If $(g(u+v))(u+v) \neq 0$, then consider the isometry from Exercise 3.123, applied to the vector $u+v$ :

$$
\begin{aligned}
R & =I d_{V}-\frac{2}{(g(u+v))(u+v)} \cdot k_{V V}((g(u+v)) \otimes(u+v)): \\
u & \mapsto u-\frac{2}{(g(u+v))(u+v)} \cdot(g(u+v))(u) \cdot(u+v) \\
& =u-\frac{2}{2 \cdot(g(u))(u)+2 \cdot(g(u))(v)} \cdot((g(u))(u)+(g(v))(u)) \cdot(u+v) \\
& =-v .
\end{aligned}
$$

Let $H=-R$.
Case 2. If $(g(u+v))(u+v)=0$, the calculation

$$
(g(u+v))(u+v)+(g(u-v))(u-v)=4 \cdot(g(u))(u)
$$

and the assumption $\frac{1}{2} \in \mathbb{K}$, imply that $(g(u-v))(u-v) \neq 0$, so we can use the isometry from Exercise 3.123, applied to the vector $u-v$ :

$$
\begin{aligned}
H=R & =I d_{V}-\frac{2}{(g(u-v))(u-v)} \cdot k_{V V}((g(u-v)) \otimes(u-v)): \\
u & \mapsto u-\frac{2}{(g(u-v))(u-v)} \cdot(g(u-v))(u) \cdot(u-v) \\
& =u-\frac{2}{2 \cdot(g(u))(u)-2 \cdot(g(u))(v)} \cdot((g(u))(u)-(g(v))(u)) \cdot(u-v) \\
& =v
\end{aligned}
$$

Exercise 3.125. Given a metric $g$ on $V$ and $v \in V$, if $(g(v))(v) \neq 0$, then there exists a direct sum $V=\mathbb{K} \oplus \operatorname{ker}(g(v))$ such that any direct sum equivalent to it has the properties that it is orthogonal and for any $A \in \operatorname{End}(V)$,

$$
\operatorname{Tr}_{V}\left(Q_{1} \circ P_{1} \circ A\right)=\frac{(g(v))(A(v))}{(g(v))(v)}
$$

If, further, $\frac{1}{2} \in \mathbb{K}$, then the direct sum produced by the involution $-R$, for $R$ as in Exercise 3.123, is such an equivalent direct sum.

Hint. Since $g(v) \neq 0_{V^{*}}$, Lemmas 1.94 and 1.95 give a direct sum $V=\mathbb{K} \oplus$ $\operatorname{ker}(g(v))$, which is canonical up to equivalence, as follows. Let $Q_{2}^{\prime}$ be the inclusion of the subspace $\operatorname{ker}(g(v))$ in $V$. For any $\alpha, \beta \in \mathbb{K}$ with $\alpha \cdot \beta \cdot(g(v))(v)=1$, define

$$
\begin{aligned}
Q_{1}^{\beta}: \mathbb{K} & \rightarrow V: \gamma \mapsto \beta \cdot \gamma \cdot v, \\
P_{1}^{\alpha}=\alpha \cdot g(v): V & \rightarrow \mathbb{K}, \\
P_{2}^{\prime}=I d_{V}-Q_{1}^{\beta} \circ P_{1}^{\alpha}: V & \rightarrow \operatorname{ker}(g(v)) .
\end{aligned}
$$

For the orthogonality of the direct sum, it is straightforward to check, using the symmetric property of $g$, that $\left(P_{1}^{\alpha}\right)^{*} \circ\left(Q_{1}^{\beta}\right)^{*} \circ g=g \circ Q_{1}^{\beta} \circ P_{1}^{\alpha}$, or that $\left(Q_{1}^{\beta}\right)^{*} \circ g \circ Q_{2}^{\prime}$ and $\left(Q_{2}^{\prime}\right)^{*} \circ g \circ Q_{1}^{\beta}$ are both zero. This is also a special case of Exercise 3.90 with $h=g$ and $H=Q_{1}^{\beta}$.

It is also easy to check that

$$
\begin{equation*}
Q_{1}^{\beta} \circ P_{1}^{\alpha} \circ A=k_{V V}(\beta \cdot \alpha \cdot((g(v)) \circ A) \otimes v) \in \operatorname{End}(V), \tag{3.12}
\end{equation*}
$$

so by the definition of trace,

$$
\begin{align*}
\operatorname{Tr}_{V}\left(Q_{1}^{\beta} \circ P_{1}^{\alpha} \circ A\right) & =E v_{V}(\beta \cdot \alpha \cdot((g(v)) \circ A) \otimes v)  \tag{3.13}\\
& =\beta \cdot \alpha \cdot(g(v))(A(v))=\frac{(g(v))(A(v))}{(g(v))(v)} \tag{3.14}
\end{align*}
$$

where the RHS of (3.14) does not depend on the choice of $\alpha, \beta$. Further, if operators $P_{i}, Q_{i}$ define any direct sum equivalent to the above orthogonal direct sum, then that direct sum is also orthogonal by Lemma 3.50, and $Q_{1}^{\beta} \circ P_{1}^{\alpha}=Q_{1} \circ P_{1}$ as in Lemma 1.89, so the LHS of (3.13) is invariant under equivalent direct sums.

Finally, setting $A=I d_{V}$ in (3.12) gives $R=I d_{V}-2 \cdot Q_{1}^{\beta} \circ P_{1}^{\alpha}$. If $\frac{1}{2} \in \mathbb{K}$, then the direct sum produced by $-R$ as in Lemma 1.112 has $Q_{1} \circ P_{1}=\frac{1}{2} \cdot\left(I d_{V}+(-R)\right)=$ $Q_{1}^{\beta} \circ P_{1}^{\alpha}$ and the direct sums are equivalent. The $A=I d_{V}$ case of (3.14) also gives the formula from Example 2.8.

The above steps did not use the invertibility of $g$, although the notion of orthogonal direct sum was defined only with respect to an invertible metric $g$.

EXERCISE 3.126. Given a metric $g$ on $V$ and a direct sum of the form $V=\mathbb{K} \oplus U$ with projections $\left(P_{1}, P_{2}\right)$ and inclusions $\left(Q_{1}, Q_{2}\right)$, let $v=Q_{1}(1)$. If the direct sum is orthogonal with respect to $g$, then it is equivalent to a direct sum $V=\mathbb{K} \oplus \operatorname{ker}(g(v))$ from Exercise 3.125. The involution from Lemma 3.54,

$$
-K=-Q_{1} \circ P_{1}+Q_{2} \circ P_{2}
$$

coincides with the involution from Exercise 3.123,

$$
\begin{aligned}
R & =I d_{V}-\frac{2}{(g(v))(v)} \cdot k_{V V}((g(v)) \otimes v) \\
& =I d_{V}-\frac{2}{\left(\left(g \circ Q_{1}\right)(1)\right)\left(Q_{1}(1)\right)} \cdot k_{V V}\left(\left(\left(g \circ Q_{1}\right)(1)\right) \otimes\left(Q_{1}(1)\right)\right) \in \operatorname{End}(V)
\end{aligned}
$$

Hint. First, Lemma 3.71 applies to the orthogonal direct sum: $(g(v))(v)=$ $\left(g\left(Q_{1}(1)\right)\right)\left(Q_{1}(1)\right)=\nu \neq 0$. Using orthogonality again, $g \circ Q_{1} \circ P_{1}=P_{1}^{*} \circ Q_{1}^{*} \circ g$, so for any $w \in V$,

$$
\begin{aligned}
g\left(Q_{1}\left(P_{1}(w)\right)\right) & =P_{1}^{*}\left(Q_{1}^{*}(g(w))\right) \\
=P_{1}(w) \cdot g\left(Q_{1}(1)\right)=P_{1}(w) \cdot g(v) & =g(w) \circ Q_{1} \circ P_{1}: v \mapsto \\
P_{1}(w) \cdot(g(v))(v) & =(g(w))\left(Q_{1}\left(P_{1}(v)\right)\right)=(g(w))\left(P_{1}(v) \cdot Q_{1}(1)\right) \\
& =P_{1}\left(Q_{1}(1)\right) \cdot(g(w))(v)=(g(w))(v) \\
\Longrightarrow P_{1}(w) & =\frac{(g(w))(v)}{(g(v))(v)} .
\end{aligned}
$$

The equivalence of the direct sums follows, using the symmetric property of $g$ :

$$
\begin{aligned}
\left(Q_{1} \circ P_{1}\right)(w) & =P_{1}(w) \cdot Q_{1}(1)=\frac{(g(w))(v)}{(g(v))(v)} \cdot v \\
\left(Q_{1}^{\beta} \circ P_{1}^{\alpha}\right)(w) & =\alpha \cdot \beta \cdot(g(v))(w) \cdot v=\frac{(g(v))(w)}{(g(v))(v)} \cdot v
\end{aligned}
$$

The claimed equality also follows, as in (3.12):

$$
-K=I d_{V}-2 \cdot Q_{1} \circ P_{1}=I d_{V}-2 \cdot Q_{1}^{\beta} \circ P_{1}^{\alpha}=R
$$

ExErcise 3.127. Given a metric $g$ on $V$, if $\operatorname{Tr}_{V}\left(I_{V}\right) \neq 0$, then for an orthogonal direct sum $\operatorname{End}(V)=\mathbb{K} \oplus \operatorname{End}_{0}(V)$ with inclusion operator $Q_{1}^{\beta}$ as in Example 2.9 and Theorem 3.52, the induced metric on $\mathbb{K}$ is $h^{\nu}$, where $\nu=\beta^{2} \cdot \operatorname{Tr}_{V}\left(I d_{V}\right)$ does not depend on $g$. The involution $R$ on $\operatorname{End}(V)$ from Exercise 3.126 does not depend on $g$ or $\beta$, and reverses the trace: for any $A \in \operatorname{End}(V), \operatorname{Tr}_{V}(R(A))=-\operatorname{Tr}_{V}(A)$.

Hint. Using Lemma 3.71,

$$
\nu=\left(b\left(Q_{1}^{\beta}(1)\right)\right)\left(Q_{1}^{\beta}(1)\right)=\operatorname{Tr}_{V}\left(\beta \cdot I d_{V} \circ g^{-1} \circ\left(\beta \cdot I d_{V}\right)^{*} \circ g\right)=\beta^{2} \cdot \operatorname{Tr}_{V}\left(I d_{V}\right)
$$

For $A \in \operatorname{End}(V)$,

$$
\begin{aligned}
R(A) & =A-\frac{2}{\nu} \cdot\left(b\left(Q_{1}^{\beta}(1)\right)\right)(A) \cdot Q_{1}^{\beta}(1) \\
& =A-\frac{2}{\nu} \cdot \operatorname{Tr}_{V}\left(A \circ g^{-1} \circ\left(\beta \cdot I d_{V}\right)^{*} \circ g\right) \cdot \beta \cdot I d_{V} \\
& =A-\frac{2 \cdot \operatorname{Tr}_{V}(A) \cdot \beta^{2}}{\beta^{2} \cdot \operatorname{Tr}_{V}\left(I d_{V}\right)} \cdot I d_{V}
\end{aligned}
$$

Remark 3.128. The following few exercises are related to the block vec operation from $[\mathbf{O}]$.

In the following diagram,

$s_{1}, s_{2}$, and $s_{3}=s_{2} \circ s_{1}$ are switching maps, and the various $\tilde{\jmath}$ maps are as in Notation 2.43. The top block is commutative, it is similar to the diagram from Lemma 2.32.

Notation 3.129. If three of the four spaces $U, V, W, X$ are finite-dimensional, then all of the arrows in the above diagram are invertible. Define the map

$$
: \operatorname{Hom}\left(U \otimes V,(W \otimes X)^{*}\right) \rightarrow \operatorname{Hom}\left(V \otimes X,(U \otimes W)^{*}\right)
$$

to equal the composite going counter-clockwise around the lower right square in the diagram.

Exercise 3.130. ([O] Theorem 1) If three of the four spaces $U, V, W, X$ are finite-dimensional, then for any $A \in \operatorname{Hom}\left(U \otimes V,(W \otimes X)^{*}\right)$, the following are equivalent.
(1) There exist $h_{1} \in \operatorname{Hom}\left(U, W^{*}\right), h_{2} \in \operatorname{Hom}\left(V, X^{*}\right)$ such that

$$
A=\tilde{\jmath} \circ\left[h_{1} \otimes h_{2}\right] .
$$

(2) There exist $\phi_{1} \in(V \otimes X)^{*}$ and $\phi_{2} \in(U \otimes W)^{*}$ such that

$$
\square(A)=k_{V \otimes X,(U \otimes W)^{*}}\left(\phi_{1} \otimes \phi_{2}\right)
$$

In the special case $W=U, X=V,(1)$ can be re-written using Notation 3.13:
(1') There exist $h_{1} \in \operatorname{Hom}\left(U, U^{*}\right), h_{2} \in \operatorname{Hom}\left(V, V^{*}\right)$ such that $A=\left\{h_{1} \otimes h_{2}\right\}$.

Exercise 3.131. ([O] Corollary 1) If $V$ is finite-dimensional, then for any $A \in \operatorname{Hom}\left(V \otimes V,(V \otimes V)^{*}\right)$, the following are equivalent.
(1) There exists $h \in \operatorname{Hom}\left(V, V^{*}\right)$ such that $A=\{h \otimes h\}$.
(2) There exists $\phi \in(V \otimes V)^{*}$ such that $\square(A)=k_{V \otimes V,(V \otimes V)^{*}}(\phi \otimes \phi)$. Either (1) or (2) implies that the bilinear form $\square(A)$ is symmetric.

Remark 3.132. The following two Propositions relating the $b$ metric to a trace on a tensor product space are analogous to a formula involving the "commutation matrix" $K$ (from Remark 1.70), which appears in $[\mathbf{H J}] \S 4.3$, and [Magnus] (exercise 3.9: $\left.\operatorname{tr} K\left(A^{\prime} \otimes B\right)=\operatorname{tr} A^{\prime} B\right)$.

Proposition 3.133. Given metrics $g$ and $h$ on $U$ and $V$, for $A, B \in \operatorname{Hom}(U, V)$,

$$
\operatorname{Tr}_{V^{*} \otimes U}\left(\left[\left(h \circ d_{V}^{-1}\right) \otimes g^{-1}\right] \circ p \circ\left[B^{*} \otimes A\right]\right)=\operatorname{Tr}_{U}\left(g^{-1} \circ B^{*} \circ h \circ A\right)
$$

Proof. In the following diagram,

the arrow $s$ in the top row switches the two $V$ factors, and the abbreviated arrow labels are

$$
\begin{aligned}
a_{1} & =\left[k_{U V} \otimes k_{U V}\right] \\
a_{2} & =\left[k_{U^{*} V^{*}} \otimes k_{U V}\right] \\
a_{3} & =\operatorname{Hom}\left(I d_{V^{*} \otimes U},\left[\left(h \circ d_{V}^{-1}\right) \otimes g^{-1}\right]\right) .
\end{aligned}
$$

The top right square is commutative by Lemmas 1.35 and 1.69. The lower left triangle is commutative by Corollary 2.36, and the triangle above that by the definition of trace. Starting with $\Phi \otimes \phi \otimes \xi \otimes v \in V^{* *} \otimes U^{*} \otimes U^{*} \otimes V$, the lower right square is commutative:

$$
\begin{aligned}
\Phi \otimes \phi \otimes \xi \otimes v & \mapsto\left(a_{3} \circ \operatorname{Hom}\left(I d_{V^{*} \otimes U}, p\right) \circ j \circ a_{2}\right)(\Phi \otimes \phi \otimes \xi \otimes v) \\
& =\left[\left(h \circ d_{V}^{-1}\right) \otimes g^{-1}\right] \circ p \circ\left[\left(k_{U^{*} V^{*}}(\Phi \otimes \phi)\right) \otimes\left(k_{U V}(\xi \otimes v)\right)\right]: \\
\psi \otimes u & \mapsto(h((\xi(u)) \cdot v)) \otimes\left(g^{-1}((\Phi(\psi)) \cdot \phi)\right), \\
\Phi \otimes \phi \otimes \xi \otimes v & \mapsto\left(j_{2} \circ\left[k_{V^{*} V^{*}} \otimes k_{U U}\right] \circ s \circ\left[\left[I d_{V^{* *}} \otimes g^{-1}\right] \otimes\left[I d_{U^{*}} \otimes h\right]\right]\right)(\Phi \otimes \phi \otimes \xi \otimes v) \\
& =\left[\left(k_{V^{*} V^{*}}(\Phi \otimes(h(v)))\right) \otimes\left(k_{U U}\left(\xi \otimes\left(g^{-1}(\phi)\right)\right)\right)\right]: \\
\psi \otimes u & \mapsto(\Phi(\psi) \cdot h(v)) \otimes\left(\xi(u) \cdot g^{-1}(\phi)\right) .
\end{aligned}
$$

Starting with $\phi \otimes w \otimes \xi \otimes v \in U^{*} \otimes V \otimes U^{*} \otimes V$, the upper left square is commutative:

$$
\begin{aligned}
\phi \otimes w \otimes \xi \otimes v & \mapsto\left(l \circ\left[E v_{V^{*}} \otimes E v_{U}\right] \circ s \circ\left[\left[I d_{V^{* *}} \otimes g^{-1}\right] \otimes\left[I d_{U^{*}} \otimes h\right]\right] \circ\left[p \otimes I d_{U^{*}} \otimes V\right]\right)(\phi \otimes w \otimes \xi \otimes v) \\
& =\left(l \circ\left[E v_{V^{*}} \otimes E v_{U}\right] \circ s\right)\left(\left(d_{V}(w)\right) \otimes\left(g^{-1}(\phi)\right) \otimes \xi \otimes(h(v))\right) \\
& =((h(v))(w)) \cdot\left(\xi\left(g^{-1}(\phi)\right)\right), \\
\phi \otimes w \otimes \xi \otimes v & \mapsto\left(E v _ { U ^ { * } \otimes V ^ { \circ } } \left[\left(\operatorname { H o m } \left(I d_{\left.\left.\left.\left.U^{*} \otimes V, l\right) \circ j \circ\left[\left(d_{U} \circ g^{-1}\right) \otimes h\right]\right) \otimes I d_{U^{*} \otimes V}\right] \circ s\right)(\phi \otimes w \otimes \xi \otimes v)}\right.\right.\right.\right. \\
& =E v_{U^{*} \otimes V}\left(\left(l \circ\left[\left(\left(d_{U} \circ g^{-1}\right)(\phi)\right) \otimes(h(v))\right]\right) \otimes \xi \otimes w\right) \\
& =\left(\xi\left(g^{-1}(\phi)\right)\right) \cdot((h(v))(w)) .
\end{aligned}
$$

This last quantity is also the result of the tensor product metric:

$$
\left(\left\{\left(d_{U} \circ g^{-1}\right) \otimes h\right\}(\phi \otimes w)\right)(\xi \otimes v)=\left(\xi\left(g^{-1}(\phi)\right)\right) \cdot((h(v))(w)),
$$

from Corollary 3.19. So the claimed equality follows from the commutativity of the diagram, and the fact that $k_{U V}^{-1}$ is an isometry (Theorem 3.41). Starting with $B \otimes A \in \operatorname{Hom}(U, V) \otimes \operatorname{Hom}(U, V):$

$$
\begin{aligned}
L H S & =\left(T r_{V^{*} \otimes U} \circ a_{3} \circ \operatorname{Hom}\left(I d_{V^{*} \otimes U}, p\right) \circ j \circ\left[t_{U V} \otimes I d_{\operatorname{Hom}(U, V)}\right]\right)(B \otimes A) \\
& =\left(E v _ { U ^ { * } \otimes V ^ { \circ } } \left[\left(\operatorname { H o m } \left(I d_{\left.\left.\left.\left.U^{*} \otimes V, l\right) \circ j \circ\left[\left(d_{U} \circ g^{-1}\right) \otimes h\right]\right) \otimes I d_{U^{*} \otimes V}\right] \circ s \circ a_{1}^{-1}\right)(B \otimes A)}\right.\right.\right.\right. \\
& =\left(\left\{\left(d_{U} \circ g^{-1}\right) \otimes h\right\}\left(k_{U V}^{-1}(B)\right)\right)\left(k_{U V}^{-1}(A)\right) \\
& =(b(B))(A)=R H S .
\end{aligned}
$$

Proposition 3.134. Given metrics $g$ and $h$ on $U$ and $V$, for $A, B \in \operatorname{Hom}(U, V)$,

$$
\operatorname{Tr}_{\left\{\left(d_{V} \circ h^{-1}\right) \otimes g\right\}}\left(f_{U V} \circ\left[B^{*} \otimes A\right]\right)=\operatorname{Tr}_{g}\left(B^{*} \circ h \circ A\right) .
$$

Proof. By Lemma 1.68 and the previous Proposition,

$$
\begin{aligned}
L H S & =\operatorname{Tr}_{V^{*} \otimes U}\left(\left[\left(d_{V} \circ h^{-1}\right) \otimes g\right]^{-1} \circ j^{-1} \circ \operatorname{Hom}\left(I d_{V^{*} \otimes U}, l\right)^{-1} \circ f_{U V} \circ\left[B^{*} \otimes A\right]\right) \\
& =\operatorname{Tr}_{V^{*} \otimes U}\left(\left[\left(h \circ d_{V}^{-1}\right) \otimes g^{-1}\right] \circ p \circ\left[B^{*} \otimes A\right]\right) \\
& =\operatorname{Tr}_{U}\left(g^{-1} \circ B^{*} \circ h \circ A\right)=R H S .
\end{aligned}
$$

### 3.7.8. Eigenvalues.

ExErcise 3.135. Suppose $h$ and $g$ are bilinear forms on $V$, and $g$ is symmetric. If $h\left(v_{1}\right)=\lambda_{1} \cdot g\left(v_{1}\right)$, and $\left(T_{V}(h)\right)\left(v_{2}\right)=\lambda_{2} \cdot g\left(v_{2}\right)$, then either $\lambda_{1}=\lambda_{2}$, or $\left(g\left(v_{1}\right)\right)\left(v_{2}\right)=0$.

Hint.

$$
\begin{aligned}
\left(\lambda_{1}-\lambda_{2}\right) \cdot\left(g\left(v_{1}\right)\right)\left(v_{2}\right) & =\left(\lambda_{1} \cdot g\left(v_{1}\right)\right)\left(v_{2}\right)-\left(\lambda_{2} \cdot g\left(v_{2}\right)\right)\left(v_{1}\right) \\
& =\left(h\left(v_{1}\right)\right)\left(v_{2}\right)-\left(\left(T_{V}(h)\right)\left(v_{2}\right)\right)\left(v_{1}\right)=0
\end{aligned}
$$

ExERCISE 3.136. Suppose $h$ and $g$ are bilinear forms on $V$, and $g$ is antisymmetric. If $h\left(v_{1}\right)=\lambda_{1} \cdot g\left(v_{1}\right)$, and $\left(T_{V}(h)\right)\left(v_{2}\right)=\lambda_{2} \cdot g\left(v_{2}\right)$, then either $\lambda_{1}=-\lambda_{2}$, or $\left(g\left(v_{1}\right)\right)\left(v_{2}\right)=0$.

EXERCISE 3.137. If $h$ and $g$ are both symmetric forms (or both antisymmetric), and $h\left(v_{1}\right)=\lambda_{1} \cdot g\left(v_{1}\right)$, and $h\left(v_{2}\right)=\lambda_{2} \cdot g\left(v_{2}\right)$, then either $\lambda_{1}=\lambda_{2}$, or $\left(g\left(v_{1}\right)\right)\left(v_{2}\right)=0$.

ExERCISE 3.138. If $g$ is a bilinear form on $V$, and $E$ is an endomorphism of $V$ such that $g \circ E=E^{*} \circ g: V \rightarrow V^{*}$, and $E\left(v_{1}\right)=\lambda_{1} \cdot v_{1}$, and $E\left(v_{2}\right)=\lambda_{2} \cdot v_{2}$, then either $\lambda_{1}=\lambda_{2}$, or $\left(g\left(v_{1}\right)\right)\left(v_{2}\right)=0$.

Hint. When $g$ is a metric, the hypothesis is that $E$ is self-adjoint.

$$
\begin{aligned}
\left(\lambda_{1}-\lambda_{2}\right) \cdot\left(g\left(v_{1}\right)\right)\left(v_{2}\right) & =\left(\lambda_{1} \cdot g\left(v_{1}\right)\right)\left(v_{2}\right)-\left(\lambda_{2} \cdot g\left(v_{1}\right)\right)\left(v_{2}\right) \\
& =\left(g\left(E\left(v_{1}\right)\right)\right)\left(v_{2}\right)-\left(g\left(v_{1}\right)\right)\left(E\left(v_{2}\right)\right) \\
& =\left((g \circ E)\left(v_{1}\right)\right)\left(v_{2}\right)-\left(\left(E^{*} \circ g\right)\left(v_{1}\right)\right)\left(v_{2}\right)=0
\end{aligned}
$$

Exercise 3.139. If $g$ is a bilinear form on $V$, and $E$ is an endomorphism of $V$ such that $g \circ E=-E^{*} \circ g: V \rightarrow V^{*}$, and $E\left(v_{1}\right)=\lambda_{1} \cdot v_{1}$, and $E\left(v_{2}\right)=\lambda_{2} \cdot v_{2}$, then either $\lambda_{1}=-\lambda_{2}$, or $\left(g\left(v_{1}\right)\right)\left(v_{2}\right)=0$. In particular, if $\frac{1}{2} \in \mathbb{K}$, then either $\lambda_{1}=0$, or $\left(g\left(v_{1}\right)\right)\left(v_{1}\right)=0$.

Hint. This is a skew-adjoint version of the previous Exercise.
ExERCISE 3.140. Given a metric $g$ on $U$, a self-adjoint endomorphism $H: U \rightarrow$ $U$, and a nonzero element $v \in U$, there exists $\lambda \in \mathbb{K}$ such that $H(v)=\lambda \cdot v$ if and only if $H$ commutes with the endomorphism $k((g(v)) \otimes v)$ from Exercise 3.119.

Hint. The diagram from Exercise 3.120 gives these two equalities:

$$
\begin{aligned}
H \circ(k((g(v)) \otimes v)) & =k((g(v)) \otimes(H(v))), \\
(k((g(v)) \otimes v)) \circ H & =k((g(H(v))) \otimes v) .
\end{aligned}
$$

If $H(v)=\lambda \cdot v$, then the two quantities are equal. Conversely, if they are equal, then for any $u \in U$,

$$
\begin{aligned}
(k((g(v)) \otimes(H(v))))(u) & =(k((g(H(v))) \otimes v))(u) \\
(g(v))(u) \cdot(H(v)) & =(g(H(v)))(u) \cdot v .
\end{aligned}
$$

Since $v \neq 0_{U}$, the non-degeneracy of $g$ implies there is some $u$ so that $(g(v))(u) \neq 0$. Let $\lambda=\frac{(g(H(v)))(u)}{(g(v))(u)}$.

ExErcise 3.141. If $g$ is a bilinear form on $V$, and $E$ is an endomorphism of $V$ such that $E^{*} \circ g \circ E=g: V \rightarrow V^{*}$, and $E\left(v_{1}\right)=\lambda_{1} \cdot v_{1}$, and $E\left(v_{2}\right)=\lambda_{2} \cdot v_{2}$, then either $\lambda_{1} \cdot \lambda_{2}=1$, or $\left(g\left(v_{1}\right)\right)\left(v_{2}\right)=0$. In particular, either $\lambda_{1}^{2}=1$, or $\left(g\left(v_{1}\right)\right)\left(v_{1}\right)=0$.

Hint.

$$
\begin{aligned}
\left(g\left(v_{1}\right)\right)\left(v_{2}\right) & =\left(\left(E^{*} \circ g \circ E\right)\left(v_{1}\right)\right)\left(v_{2}\right)=\left(g\left(E\left(v_{1}\right)\right)\right)\left(E\left(v_{2}\right)\right) \\
& =\lambda_{1} \cdot \lambda_{2} \cdot\left(g\left(v_{1}\right)\right)\left(v_{2}\right) .
\end{aligned}
$$

### 3.7.9. Canonical metrics.

Example 3.142. Given $V$ finite-dimensional, the canonical invertible map

$$
\left(k^{*}\right)^{-1} \circ e: \operatorname{End}(V) \rightarrow \operatorname{End}(V)^{*}
$$

from Lemma 2.1 is a metric on $\operatorname{End}(V)$. It is symmetric by Lemma 1.13 and Lemma 2.1:
$\left(\left(k^{*}\right)^{-1} \circ e\right)^{*} \circ d_{\operatorname{End}(V)}=e^{*} \circ\left(k^{-1}\right)^{* *} \circ d_{\operatorname{End}(V)}=e^{*} \circ d \circ k^{-1}=\left(k^{*}\right)^{-1} \circ e$.
This metric on $\operatorname{End}(V)$ should be called the canonical metric, to distinguish it from the $b$ metric, induced by a choice of metric on $V$. The non-degeneracy of the metric was considered in Proposition 2.16, where it was also shown that for $A$, $B \in \operatorname{End}(V)$,

$$
\begin{equation*}
\left(\left(\left(k^{*}\right)^{-1} \circ e\right)(A)\right)(B)=\operatorname{Tr}_{V}(A \circ B) \tag{3.15}
\end{equation*}
$$

Example 3.143. Given $V$ finite-dimensional, the canonical map $f: V^{*} \otimes V \rightarrow$ $\left(V^{*} \otimes V\right)^{*}$ is invertible, and is symmetric by Lemma 1.65 , so it is a metric on $V^{*} \otimes V$. The dual metric on $\left(V^{*} \otimes V\right)^{*}$ is $d \circ f^{-1}=\left(f^{*}\right)^{-1}$.

This metric on $V^{*} \otimes V$ is also canonical, and, in general, different from the tensor product metric induced by a choice of metric on $V$. By Lemma 1.68, the metric $f$ is equal to the composite $\operatorname{Hom}\left(I d_{V^{*} \otimes V}, l\right) \circ j \circ p: V^{*} \otimes V \rightarrow\left(V^{*} \otimes V\right)^{*}$.

EXERCISE 3.144. The dual metric $d_{\mathbb{K}} \circ\left(h^{1}\right)^{-1}$ on $\mathbb{K}^{*}$ coincides with the $\left(k^{*}\right)^{-1} \circ e$ metric on $\operatorname{End}(\mathbb{K})$.

Hint. The metric $h^{1}$ is as in Lemma 3.67. For $\phi, \xi \in \mathbb{K}^{*}$,

$$
\begin{aligned}
\left(\left(d_{\mathbb{K}} \circ\left(h^{1}\right)^{-1}\right)(\phi)\right)(\xi) & =\xi\left(\operatorname{Tr}_{\mathbb{K}}(\phi)\right)=\xi(\phi(1))=\phi(1) \cdot \xi(1) \\
\left(\left(\left(k^{*}\right)^{-1} \circ e\right)(\phi)\right)(\xi) & =\operatorname{Tr}_{\mathbb{K}}(\phi \circ \xi)=\phi(\xi(1))=\xi(1) \cdot \phi(1)
\end{aligned}
$$

EXERCISE 3.145. With respect to the canonical metrics $\left(k^{*}\right)^{-1} \circ e$ on $\operatorname{End}(\mathbb{K})$ and $h^{1}$ on $\mathbb{K}, T r_{\mathbb{K}}$ is an isometry.

Hint. The canonical metric, applied to $A, B \in \operatorname{End}(\mathbb{K})$, is:

$$
\left(\left(\left(k^{*}\right)^{-1} \circ e\right)(A)\right)(B)=\operatorname{Tr}_{\mathbb{K}}(A \circ B)=(A \circ B)(1)=A(B(1))=B(1) \cdot A(1) .
$$

This coincides with the pullback:

$$
\left(h^{1}\left(\operatorname{Tr}_{\mathbb{K}}(A)\right)\right)\left(\operatorname{Tr}_{\mathbb{K}}(B)\right)=\left(h^{1}(A(1))\right)(B(1))=A(1) \cdot B(1) .
$$

Exercise 3.146. Given finite-dimensional $V$, the canonical map $k: V^{*} \otimes V \rightarrow$ $\operatorname{End}(V)$ is an isometry with respect to the canonical metrics $f$ and $\left(k^{*}\right)^{-1} \circ e$.

Hint. The pullback of $\left(k^{*}\right)^{-1} \circ e$ by $k$ agrees with $f$ :

$$
k^{*} \circ\left(k^{*}\right)^{-1} \circ e \circ k=f
$$

Exercise 3.147. Given finite-dimensional $V$, the canonical map $e: \operatorname{End}(V) \rightarrow$ $\left(V^{*} \otimes V\right)^{*}$ is an isometry with respect to the canonical metrics $\left(k^{*}\right)^{-1} \circ e$ and $\left(f^{*}\right)^{-1}$.

Hint. The pullback of $\left(f^{*}\right)^{-1}$ by $e$ is:

$$
e^{*} \circ\left(f^{*}\right)^{-1} \circ e=e^{*} \circ\left(e^{*}\right)^{-1} \circ\left(k^{*}\right)^{-1} \circ e=\left(k^{*}\right)^{-1} \circ e .
$$

It follows that $f_{V V}$ is an isometry, but this also follows from Theorem 3.26.
ExERCISE 3.148. ([ $\left.\mathbf{G}_{2}\right] \S$ I.8) Given finite-dimensional $U$, $V$, if $A: U \rightarrow V$ is invertible, then $\operatorname{Hom}\left(A^{-1}, A\right): \operatorname{End}(U) \rightarrow \operatorname{End}(V)$ is an isometry with respect to the $\left(k^{*}\right)^{-1} \circ e$ metrics.

Hint. From the Proof of Lemma 2.6:

$$
\begin{aligned}
\left(k^{* *}\right)^{-1} \circ e^{\prime} & =\left(k^{\prime *}\right)^{-1} \circ e^{\prime} \circ \operatorname{Hom}\left(A, A^{-1}\right) \circ \operatorname{Hom}\left(A^{-1}, A\right) \\
& =\operatorname{Hom}\left(A^{-1}, A\right)^{*} \circ\left(k^{*}\right)^{-1} \circ e \circ \operatorname{Hom}\left(A^{-1}, A\right) .
\end{aligned}
$$

ExERCISE 3.149. For $U, V$, and invertible $A$ as in the previous Exercise, $\left[\left(A^{-1}\right)^{*} \otimes A\right]: U^{*} \otimes U \rightarrow V^{*} \otimes V$ is an isometry with respect to $f_{U U}$ and $f_{V V}$.

Hint. This follows from Lemma 1.57:

$$
\left[\left(A^{-1}\right)^{*} \otimes A\right]=k_{V V}^{-1} \circ \operatorname{Hom}\left(A^{-1}, A\right) \circ k_{U U}
$$

and could also be checked directly.
ExErcise 3.150. Given finite-dimensional $V$, the transpose $t: \operatorname{End}(V) \rightarrow$ $\operatorname{End}\left(V^{*}\right): A \mapsto A^{*}$ is an isometry with respect to the canonical $\left(k^{*}\right)^{-1} \circ e$ metrics.

Hint. From the Proof of Lemma 2.5:

$$
t^{*} \circ\left(k^{*}\right)^{-1} \circ e^{\prime} \circ t=\left(k^{*}\right)^{-1} \circ e
$$

EXERCISE 3.151. Given finite-dimensional $U, V$, the map $j: \operatorname{End}(U) \otimes \operatorname{End}(V) \rightarrow$ $\operatorname{End}(U \otimes V)$ is an isometry with respect to the tensor product of canonical metrics, and the canonical metric on $\operatorname{End}(U \otimes V)$.

Hint. By Corollary 2.36,

$$
\begin{aligned}
\operatorname{Tr}_{U \otimes V}\left(\left(j\left(A_{1} \otimes B_{1}\right)\right) \circ\left(j\left(A_{2} \otimes B_{2}\right)\right)\right) & =\operatorname{Tr}_{U \otimes V}\left(j\left(\left(A_{1} \circ A_{2}\right) \otimes\left(B_{1} \circ B_{2}\right)\right)\right) \\
& =\operatorname{Tr}_{U}\left(A_{1} \circ A_{2}\right) \cdot \operatorname{Tr}_{V}\left(B_{1} \circ B_{2}\right) .
\end{aligned}
$$

Exercise 3.152. Given finite-dimensional $U$, if $\operatorname{Tr}_{U}\left(\operatorname{Id}_{U}\right) \neq 0$, then a direct sum $\operatorname{End}(U)=\mathbb{K} \oplus \operatorname{End}_{0}(U)$ from Example 2.9 is orthogonal with respect to the canonical metric $\left(k^{*}\right)^{-1} \circ e$ on $\operatorname{End}(U)$, and this induces a canonical metric on $\operatorname{End}_{0}(U)$. The involution from Exercise 3.123, defined in terms of the canonical metric and the canonical element $I d_{U}$, is given for $A \in \operatorname{End}(U)$ by:

$$
R: A \mapsto A-2 \cdot \frac{\operatorname{Tr}_{U}(A)}{\operatorname{Tr}_{U}\left(I d_{U}\right)} \cdot I d_{V}
$$

which is the same as the involution $-K$ from Lemma 3.54 and the involution $R$ from Exercise 3.127.

Hint. The orthogonality is easy to check; this is also a special case of Exercises 3.125 and 3.126.

EXERCISE 3.153. Given a metric $g$ on $U$, the adjoint involution $\operatorname{Hom}\left(g, g^{-1}\right) \circ$ $t_{U U}$ on $\operatorname{End}(U)$ is an isometry with respect to the canonical metric. If $\frac{1}{2} \in \mathbb{K}$, then the direct sum decomposition into self-adjoint and skew-adjoint endomorphisms, from Definition 3.115, is orthogonal with respect to the canonical metric. On the space of self-adjoint endomorphisms, the metric induced by the canonical metric coincides with the metric induced by the induced $b$ metric. On the space of skewadjoint endomorphisms, the two induced metrics are opposite.

ExERCISE 3.154. For any bilinear form $g: \operatorname{End}(V) \rightarrow \operatorname{End}(V)^{*}$ (and in particular, any metric $g$ on $\operatorname{End}(V)$ ), there exists $F \in \operatorname{End}(\operatorname{End}(V))$ so that for all $A, B \in \operatorname{End}(V)$,

$$
(g(A))(B)=\operatorname{Tr}_{V}((F(A)) \circ B)
$$

Hint. Define $F=e^{-1} \circ k^{*} \circ g$. Then by Proposition 2.17,

$$
(g(A))(B)=\operatorname{Tr}_{V}\left(\left(e^{-1}\left(k^{*}(g(A))\right)\right) \circ B\right)
$$

The canonical metric on $\operatorname{End}(V)$ from Example 3.142 is the case $F=I d_{\operatorname{End}(V)}$. The $b$ metric from Definition 3.40 induced by a metric $h$ on $V$,

$$
(b(A))(B)=\operatorname{Tr}_{V}\left(h^{-1} \circ A^{*} \circ h \circ B\right)
$$

is the case where $F$ is the adjoint involution from Definition 3.110 and Lemma 3.112 .

Example 3.155. For the generalized transpose from Definition 1.7 and Example 1.48,

$$
t_{U V}^{W} \in \operatorname{Hom}(\operatorname{Hom}(U, V), \operatorname{Hom}(\operatorname{Hom}(V, W), \operatorname{Hom}(U, W))),
$$

and any bilinear form $g: \operatorname{Hom}(U, W) \rightarrow \operatorname{Hom}(U, W)^{*}$, the map

$$
\operatorname{Hom}\left(I d_{\operatorname{Hom}(U, V)}, \operatorname{Hom}\left(I d_{\operatorname{Hom}(V, W)}, g\right)\right)
$$

transforms $t_{U V}^{W}$ to the scalar valued trilinear form
$\operatorname{Hom}\left(I d_{\operatorname{Hom}(V, W)}, g\right) \circ t_{U V}^{W} \in \operatorname{Hom}\left(\operatorname{Hom}(U, V), \operatorname{Hom}\left(\operatorname{Hom}(V, W),(\operatorname{Hom}(U, W))^{*}\right)\right)$.
For $A \in \operatorname{Hom}(U, V), B \in \operatorname{Hom}(V, W)$, and $C \in \operatorname{Hom}(U, W)$,

$$
\begin{aligned}
\operatorname{Hom}\left(I d_{\operatorname{Hom}(V, W)}, g\right) \circ t_{U V}^{W}: A & \mapsto g \circ\left(t_{U V}^{W}(A)\right)=g \circ \operatorname{Hom}\left(A, I d_{U}\right): \\
B & \mapsto g(B \circ A): \\
C & \mapsto(g(B \circ A))(C) .
\end{aligned}
$$

In the special case where $g$ is the metric $b$ from Definition 3.40 induced by metrics $g_{1}$ on $U$ and $g_{2}$ on $W$,

$$
\begin{aligned}
(g(B \circ A))(C) & =\operatorname{Tr}_{U}\left(g_{1}^{-1} \circ(B \circ A)^{*} \circ g_{2} \circ C\right) \\
& =\operatorname{Tr}_{U^{*}}\left(A^{*} \circ B^{*} \circ g_{2} \circ C \circ g_{1}^{-1}\right)
\end{aligned}
$$

In a different special case where $W=U$ and $g$ is the canonical metric $\left(k^{*}\right)^{-1} \circ e$ on $\operatorname{End}(U)$ from Example 3.142,

$$
(g(B \circ A))(C)=T r_{U}(B \circ A \circ C)
$$

Example 3.156. For any metrics $g$ and $h$ on $\operatorname{End}(V)$, consider the $b$ metric from Definition 3.40 induced by $g$ and $h$ on $\operatorname{End}(\operatorname{End}(V))$,

$$
(b(E))(F)=\operatorname{Tr}_{\operatorname{End}(V)}\left(F \circ g^{-1} \circ E^{*} \circ h\right),
$$

for $E, F \in \operatorname{End}(\operatorname{End}(V))$. The canonical metric on $\operatorname{End}(\operatorname{End}(V))$,

$$
\begin{equation*}
\left(k_{\operatorname{End}(V), \operatorname{End}(V)}^{*}\right)^{-1} \circ e_{\operatorname{End}(V), \operatorname{End}(V)}, \tag{3.16}
\end{equation*}
$$

is not necessarily the same as the $b$ metric. The metrics can be shown to be different by example, if there exist $A, B \in \operatorname{End}(V), \Psi, \Phi \in \operatorname{End}(V)^{*}$ such that $(h(A))(B)=0$ and $\Psi(A) \neq 0$ and $\Phi(B) \neq 0$. From Equation (3.5) and Equation (3.15),

$$
\begin{aligned}
& \left(b\left(k_{\operatorname{End}(V), \operatorname{End}(V)}(\Phi \otimes A)\right)\right)\left(k_{\operatorname{End}(V), \operatorname{End}(V)}(\Psi \otimes B)\right) \\
= & \left.\Psi\left(g^{-1}(\Phi)\right)\right) \cdot(h(A))(B)=0 .
\end{aligned}
$$

The canonical metric applied to the same inputs has output

$$
\begin{aligned}
& \operatorname{Tr}_{\operatorname{End}(V)}\left(\left(k_{\operatorname{End}(V), \operatorname{End}(V)}(\Phi \otimes A)\right) \circ\left(k_{\operatorname{End}(V), \operatorname{End}(V)}(\Psi \otimes B)\right)\right) \\
= & \operatorname{Tr}_{\operatorname{End}(V)}\left(\Phi(B) \cdot k_{\operatorname{End}(V), \operatorname{End}(V)}(\Psi \otimes A)\right) \\
= & \Phi(B) \cdot \Psi(A) \neq 0
\end{aligned}
$$

So even for $g$ and $h$ as in Example 3.142, the canonical metric is not the same as the metric canonically induced by canonical metrics!

## CHAPTER 4

## Vector Valued Bilinear Forms

The notion of a bilinear form $h: V \rightarrow V^{*}$ can be generalized from the "scalar valued" case to a "vector valued" (or " $W$-valued," or "twisted") form $h: V \rightarrow$ $\operatorname{Hom}(V, W)$, so that for inputs $v_{1}, v_{2} \in V$, the output $\left(h\left(v_{1}\right)\right)\left(v_{2}\right)$ is an element of $W$. In the same way as Example 1.50 , vector valued bilinear functions $\mathbf{B}$ : $V \times V \rightsquigarrow W$ correspond to $W$-valued bilinear forms on $V$, elements of the space $\operatorname{Hom}(V, \operatorname{Hom}(V, W))$. Most of the properties of the scalar valued case generalize, but some of the canonical maps are different.

### 4.1. Transpose for vector valued forms

There would appear to be multiple ways to use the already considered canonical maps to define a transpose operation that switches the inputs for a $W$-valued form. One way would be to transform $\operatorname{Hom}(V, \operatorname{Hom}(V, W))$ into $\operatorname{Hom}\left(V, V^{*}\right) \otimes W$, and then apply $\left[T_{V} \otimes I d_{W}\right]$, where $T_{V}$ is the transpose for scalar valued forms from Definition 3.2. Another way would be to start from scratch with canonical maps from Chapter 1, which is the approach taken with Lemma 4.1 and Definition 4.2. Of course, these two ways end up with the same result, as shown in Lemma 4.5.

The following Lemma considers a more general domain $\operatorname{Hom}\left(V_{1}, \operatorname{Hom}\left(V_{2}, W\right)\right)$, where $V_{1}$ and $V_{2}$ are not necessarily the same. The $d$ map in the diagram is a generalized double duality from Definition 1.12, the $t$ map is a generalized transpose from Definition 1.7, the canonical $q$ maps are as in Definition 1.43, and $s$ is a switching map.

Lemma 4.1. For any $V_{1}, V_{2}, W$, the following diagram is commutative.


Proof. For $u \in V_{1}, v \in V_{2}$, and $A \in \operatorname{Hom}\left(V_{1}, \operatorname{Hom}\left(V_{2}, W\right)\right)$,
$\left(\operatorname{Hom}\left(s, I d_{W}\right) \circ q_{1}\right)(A):$
$v \otimes u \quad \mapsto \quad\left(\left(q_{1}(A)\right) \circ s\right)(v \otimes u)=\left(q_{1}(A)\right)(u \otimes v)=(A(u))(v)$,
$\left(q_{2} \circ \operatorname{Hom}\left(d_{V_{2} W}, I d_{\operatorname{Hom}\left(V_{1}, W\right)}\right) \circ t_{V_{1}, \operatorname{Hom}\left(V_{2}, W\right)}^{W}\right)(A):$
$v \otimes u \quad \mapsto \quad\left(q_{2}\left(\left(t_{V_{1}, \operatorname{Hom}\left(V_{2}, W\right)}^{W}(A)\right) \circ d_{V_{2} W}\right)\right)(v \otimes u)$
$=\left(\left(t_{V_{1}, \operatorname{Hom}\left(V_{2}, W\right)}^{W}(A)\right)\left(d_{V_{2} W}(v)\right)\right)(u)=\left(\left(d_{V_{2} W}(v)\right) \circ A\right)(u)=(A(u))(v)$.

Definition 4.2. Corresponding to the left column in the above diagram, let

$$
\begin{equation*}
T_{V_{1}, V_{2} ; W}=\operatorname{Hom}\left(d_{V_{2} W}, I d_{\operatorname{Hom}\left(V_{1}, W\right)}\right) \circ t_{V_{1}, \operatorname{Hom}\left(V_{2}, W\right)}^{W} \tag{4.1}
\end{equation*}
$$

Notation 4.3. In the special case $V=V_{1}=V_{2}$, abbreviate $T_{V, V ; W}=T_{V ; W}$. In the case $W=\mathbb{K}, T_{V ; \mathbb{K}}$ is exactly $T_{V}$ from Definition 3.2.

The above expression (4.1) for $T_{V_{1}, V_{2} ; W}$ (and $T_{V ; W}$ ) uses only Hom spaces and maps from Section 1.1, without referring to tensor products, the scalar field $\mathbb{K}$, scalar multiplication, or any dual space like $V^{*}$. The spaces and $s$ and $q$ maps in Lemma 4.1 use tensor products but no scalars.

Lemma 4.4. For any vector spaces $V_{1}, V_{2}, W, T_{V_{1}, V_{2} ; W}$ is invertible. In particular, for $V_{1}=V_{2}, T_{V_{1} ; W}$ is an involution on $\operatorname{Hom}\left(V_{1}, \operatorname{Hom}\left(V_{1}, W\right)\right)$.

Proof. The first claim follows from Lemma 4.1 and the invertibility of the $q$ maps (Lemma 1.44), and the diagram also shows that

$$
\begin{equation*}
T_{V_{2}, V_{1} ; W}=T_{V_{1}, V_{2} ; W}^{-1} \tag{4.2}
\end{equation*}
$$

The second claim is a special case of (4.2). For $h: V_{1} \rightarrow \operatorname{Hom}\left(V_{2}, W\right)$, and $v \in V_{1}$, $u \in V_{2}$, it follows from Definition 4.2 that

$$
\begin{equation*}
\left(\left(T_{V_{1}, V_{2} ; W}(h)\right)(u)\right)(v)=(h(v))(u), \tag{4.3}
\end{equation*}
$$

as in (3.1) from Lemma 3.3. Instead of using Lemma 4.1 or (4.3), Equation (4.2) can be checked directly from Definition 4.2, using Lemma 1.6, Lemma 1.13, and Lemma 1.16:

$$
\begin{aligned}
T_{V_{2}, V_{1} ; W}\left(T_{V_{1}, V_{2} ; W}(h)\right) & =\operatorname{Hom}\left(\left(t_{V_{1}, \operatorname{Hom}\left(V_{2}, W\right)}^{W}(h)\right) \circ d_{V_{2} W}, I d_{W}\right) \circ d_{V_{1} W} \\
& =\operatorname{Hom}\left(d_{V_{2} W}, I d_{W}\right) \circ \operatorname{Hom}\left(\operatorname{Hom}\left(h, I d_{W}\right), I d_{W}\right) \circ d_{V_{1} W} \\
& =\operatorname{Hom}\left(d_{V_{2} W}, I d_{W}\right) \circ d_{\operatorname{Hom}\left(V_{2}, W\right), W} \circ h \\
& =h .
\end{aligned}
$$

Relabeling the subscripts then gives the composite in the other order.
The following Lemma uses a canonical $n$ map from Definition 1.38, so that for $g \otimes w \in \operatorname{Hom}\left(V, V^{*}\right) \otimes W,(n(g \otimes w))(v)=(g(v)) \otimes w$.

Lemma 4.5. For any $V, W$, the following diagram is commutative. If $V$ or $W$ is finite-dimensional, then the $k_{V W}$ and $n$ maps in the diagram are invertible.


Proof. The left triangle is Definition 4.2 for $T_{V ; W}$. For the right part of the diagram, starting with $g \otimes w \in \operatorname{Hom}\left(V, V^{*}\right) \otimes W$,

$$
\begin{aligned}
g \otimes w & \mapsto\left(\operatorname{Hom}\left(d_{V W}, I d_{\operatorname{Hom}(V, W)}\right) \circ t_{V, \operatorname{Hom}(V, W)}^{W} \circ \operatorname{Hom}\left(I d_{V}, k_{V W}\right) \circ n\right)(g \otimes w): \\
v & \mapsto\left(\left(t_{V, \operatorname{Hom}(V, W)}^{W}\left(k_{V W} \circ(n(g \otimes w))\right) \circ d_{V W}\right)(v)\right. \\
& =\left(d_{V W}(v)\right) \circ k_{V W} \circ(n(g \otimes w)): \\
u & \mapsto\left(d_{V W}(v)\right)\left(k_{V W}((g(u)) \otimes w)\right) \\
& =\left(k_{V W}((g(u)) \otimes w)\right)(v)=(g(u))(v) \cdot w, \\
g \otimes w & \mapsto\left(\operatorname{Hom}\left(I d_{V}, k_{V W}\right) \circ n \circ\left[T_{V} \otimes I d_{W}\right]\right)(g \otimes w): \\
v & \mapsto k_{V W}\left(\left(n\left(\left(T_{V}(g)\right) \otimes w\right)\right)(v)\right) \\
& =k_{V W}\left(\left(\left(T_{V}(g)\right)(v)\right) \otimes w\right): \\
u & \mapsto\left(\left(T_{V}(g)\right)(v)\right)(u) \cdot w=(g(u))(v) \cdot w .
\end{aligned}
$$

The invertibility of the canonical maps was stated in Lemma 1.59 and Lemma 1.42 .

Lemma 4.6. For any vector spaces $U_{1}, U_{2}, V_{1}, V_{2}, W_{1}, W_{2}$, and any maps $E: U_{1} \rightarrow V_{1}, F: U_{2} \rightarrow V_{2}, G: W_{1} \rightarrow W_{2}$, the following diagram is commutative.


Proof. The claim could be checked by calculating how the composites act on pairs of input vectors, as in Equation (4.3) from the Proof of Lemma 4.4. The following proof instead shows how the claim follows from only the elementary properties of the $t$ and $d$ maps.

The diagram can be expanded using Definition 4.2 and Lemma 1.6:

where

$$
\begin{aligned}
M_{1} & =\operatorname{Hom}\left(\operatorname{Hom}\left(\operatorname{Hom}\left(V_{2}, W_{2}\right), W_{2}\right), \operatorname{Hom}\left(V_{1}, W_{2}\right)\right) \\
M_{2} & =\operatorname{Hom}\left(\operatorname{Hom}\left(\operatorname{Hom}\left(U_{2}, W_{2}\right), W_{2}\right), \operatorname{Hom}\left(U_{1}, W_{2}\right)\right) \\
a_{1} & =\operatorname{Hom}\left(\operatorname{Hom}\left(\operatorname{Hom}\left(F, I d_{W_{2}}\right), I d_{W_{2}}\right), \operatorname{Hom}\left(E, I d_{W_{2}}\right)\right)
\end{aligned}
$$

The lower left square is commutative by Lemma 1.8. The lower right square is commutative by Lemma 1.6 and Lemma 1.13. These steps are analogous to the steps in the Proof of Lemma 3.8.

The commutativity of the upper block states that for $h: V_{1} \rightarrow \operatorname{Hom}\left(V_{2}, W_{1}\right)$,

$$
T_{V_{1}, V_{2} ; W_{2}}\left(\operatorname{Hom}\left(I d_{V_{2}}, G\right) \circ h\right)=\operatorname{Hom}\left(I d_{V_{1}}, G\right) \circ\left(T_{V_{1}, V_{2} ; W_{1}}(h)\right)
$$

The following diagram expands the upper block of the previous diagram, so that the compositions down the left and right sides are $T_{V_{1}, V_{2} ; W_{1}}$ and $T_{V_{1}, V_{2} ; W_{2}}$ from Definition 4.2, and the claim of the Lemma follows from the commutativity of the diagram.

The inside arrows are:

$$
\begin{aligned}
a_{2} & =\operatorname{Hom}\left(\operatorname{Hom}\left(\operatorname{Hom}\left(I d_{V_{2}}, G\right), I d_{W_{2}}\right), I d_{\operatorname{Hom}\left(V_{1}, W_{2}\right)}\right) \\
a_{3} & =\operatorname{Hom}\left(\operatorname{Hom}\left(\operatorname{Id} d_{\operatorname{Hom}\left(V_{2}, W_{1}\right)}, G\right), I d_{\operatorname{Hom}\left(V_{1}, W_{2}\right)}\right) \\
a_{4} & =\operatorname{Hom}\left(I d_{\operatorname{Hom}\left(\operatorname{Hom}\left(V_{2}, W_{1}\right), W_{1}\right)}, \operatorname{Hom}\left(I d_{V_{1}}, G\right)\right)
\end{aligned}
$$

The upper square and the left square are both commutative by Lemma 1.8. The lower square is commutative by Lemma 1.6. The commutativity of the right block follows from Lemma 1.6 and this special case of Lemma 1.13:

$$
\operatorname{Hom}\left(I d_{\operatorname{Hom}\left(V_{2}, W_{1}\right)}, G\right) \circ d_{V_{2} W_{1}}=\operatorname{Hom}\left(\operatorname{Hom}\left(I d_{V_{2}}, G\right), I d_{W_{2}}\right) \circ d_{V_{2} W_{2}}
$$

Similarly to Lemma 4.5 , the following few Lemmas use canonical $n$ maps all labeled $n$, even when some spaces appear in a different order, as in Notation 1.39 , so their domain, target, and formula are as indicated by their position in the diagram.

Lemma 4.7. For any $U, V_{1}, V_{2}, W$, the following diagram is commutative. If $U$ is finite-dimensional, or $V_{1}$ and $V_{2}$ are both finite-dimensional, then all the maps in the diagram are invertible.


Proof. Replacing the $T_{V_{1}, V_{2} ; W}$ and $T_{V_{1}, V_{2} ; W \otimes U}$ downward arrows in the above diagram by composites involving the invertible $q$ maps from Lemma 4.1 gives the following diagram.


The middle block is commutative by Lemma 1.40. To check the top square, for $h \otimes u \in \operatorname{Hom}\left(V_{1}, \operatorname{Hom}\left(V_{2}, W\right)\right) \otimes U, v \otimes x \in V_{1} \otimes V_{2}$,

$$
\begin{aligned}
\left(q_{3} \circ \operatorname{Hom}\left(I d_{V_{1}}, n_{1}\right) \circ n_{2}\right)(h \otimes u): v \otimes x & \mapsto\left(q_{3}\left(n_{1} \circ\left(n_{2}(h \otimes u)\right)\right)\right)(v \otimes x) \\
& =\left(\left(n_{1} \circ\left(n_{2}(h \otimes u)\right)\right)(v)\right)(x) \\
& =\left(n_{1}(u \otimes(h(v)))\right)(x) \\
& =((h(v))(x)) \otimes u, \\
\left(n_{5} \circ\left[q_{1} \otimes I d_{U}\right]\right)(h \otimes u): v \otimes x & \mapsto\left(n_{5}\left(\left(q_{1}(h)\right) \otimes u\right)\right)(v \otimes x) \\
& =\left(\left(q_{1}(h)\right)(v \otimes x)\right) \otimes u \\
& =((h(v))(x)) \otimes u .
\end{aligned}
$$

The lowest square is analogous, with some re-ordering.

The composite $\operatorname{Hom}\left(I d_{V_{1}}, n_{1}\right) \circ n_{2}$ appearing in the upper left corner of the diagram from Lemma 4.7 is equal to a composite of the following form, using different versions of the $n$ maps, as in Notation 1.39:


The spaces can be re-ordered in various ways to state results analogous to Lemma 4.7, with other versions of the $n$ maps but essentially the same Proof. The following Lemma 4.8 is an analogue of Lemma 4.7 but with a longer composite of $n$ maps.

Lemma 4.8. For any $U_{1}, U_{2}, V_{1}, V_{2}, W$, the following diagram is commutative.


Proof. As remarked after the Proof of Lemma 4.7, the vertical composites of $n$ maps could be re-arranged into composites of different $n$ maps with the spaces in different order as in (4.4). This could be used to prove this Lemma as stated or to state analogous results.

The following Proof is more direct, and analogous to that of Lemma 4.7, replacing the $T$ maps with composites involving the $q$ maps from Lemma 4.1. In the statement of the Lemma and the following diagram, the maps labeled $n_{1}, \ldots, n_{4}, q_{1}, q_{2}$
are the same that appear in Lemma 4.7.


The $q$ and $s$ maps are invertible, and the commutativity around the outside of the diagram can be checked directly, using the formula for $q^{-1}$ from Lemma 1.44. Starting in the upper left corner with $U_{1} \otimes \operatorname{Hom}\left(V_{1} \otimes V_{2}, W\right) \otimes U_{2}$, for $A \in \operatorname{Hom}\left(V_{1} \otimes\right.$ $\left.V_{2}, W\right), u \in U_{1}, v \in U_{2}, y \in V_{1}, z \in V_{2}$,

$$
\begin{aligned}
u \otimes A \otimes v & \mapsto q_{6}\left(n_{10} \circ\left[I d_{U_{1}} \otimes n_{4}\right] \circ\left(n_{8}\left(\left[I d_{U_{1}} \otimes n_{3}\right]\left(u \otimes\left(q_{2}^{-1}(A \circ s)\right) \otimes v\right)\right)\right)\right): \\
z \otimes y & \mapsto\left(\left(n_{10} \circ\left[I d_{U_{1}} \otimes n_{4}\right] \circ\left(n_{8}\left(\left[I d_{U_{1}} \otimes n_{3}\right]\left(u \otimes\left(q_{2}^{-1}(A \circ s)\right) \otimes v\right)\right)\right)\right)(z)\right)(y) \\
& =\left(n_{10}\left(\left[I d_{U_{1}} \otimes n_{4}\right]\left(u \otimes\left(\left(q_{2}^{-1}(A \circ s)\right)(z)\right) \otimes v\right)\right)\right)(y) \\
& =u \otimes\left(\left(\left(q_{2}^{-1}(A \circ s)\right)(z)\right)(y)\right) \otimes v \\
& =u \otimes((A \circ s)(z \otimes y)) \otimes v=u \otimes(A(y \otimes z)) \otimes v, \\
u \otimes A \otimes v & \mapsto\left(q_{5}\left(n_{9} \circ\left[I d_{U_{1}} \otimes n_{1}\right] \circ\left(n_{7}\left(\left[I d_{U_{1}} \otimes n_{2}\right]\left(u \otimes\left(q_{1}^{-1}(A)\right) \otimes v\right)\right)\right)\right)\right) \circ s: \\
z \otimes y & \mapsto\left(\left(n_{9} \circ\left[I d_{U_{1}} \otimes n_{1}\right] \circ\left(n_{7}\left(\left[I d_{U_{1}} \otimes n_{2}\right]\left(u \otimes\left(q_{1}^{-1}(A)\right) \otimes v\right)\right)\right)\right)(y)\right)(z) \\
& =\left(n_{9}\left(\left[I d_{U_{1}} \otimes n_{1}\right]\left(u \otimes v \otimes\left(\left(q_{1}^{-1}(A)\right)(y)\right)\right)\right)\right)(z) \\
& =u \otimes\left(\left(\left(q_{1}^{-1}(A)\right)(y)\right)(z)\right) \otimes v=u \otimes(A(y \otimes z)) \otimes v .
\end{aligned}
$$

The following Lemma 4.9 shows how $T_{V_{1}, V_{2} ; W}$ is related to some switching maps, which are involutions in the case $V_{1}=V_{2}$; an analogue for the scalar case $T_{V}$ is Theorem 3.114.

Lemma 4.9. For any $V_{1}, V_{2}, W$, the following diagram is commutative. If $V_{1}$ and $V_{2}$ are both finite-dimensional, then all the arrows are invertible.


Proof. The block with the $q$ maps is exactly Lemma 4.1, and the next lower block is commutative by Lemma 1.57. The lowest block is easy to check, where the abbreviation $\tilde{\jmath}_{1}=\operatorname{Hom}\left(I d_{V_{1} \otimes V_{2}}, l\right) \circ j_{1}$ as in Notation 2.43 could be used, so that the vertical composite is $\left[\tilde{\jmath}_{1} \otimes I d_{W}\right]$. Inside the top rectangle, the blocks on the left and right are commutative by Lemma 1.57 again. Its top block is commutative: for $\phi \otimes \psi \otimes w \in V_{1}^{*} \otimes V_{2}^{*} \otimes W, v \in V_{1}$,

$$
\begin{array}{rl} 
& n \circ\left[I d_{V_{2}^{*}} \otimes k_{V_{1}, W}\right] \circ\left[s_{2} \otimes I d_{W}\right]: \\
\phi \otimes \psi \otimes w & \mapsto \\
v & n\left(\psi \otimes\left(k_{V_{1}, W}(\phi \otimes w)\right)\right): \\
& \left.\mapsto \otimes(\phi(v) \cdot w)=\left(k_{V_{1}, V_{2}^{*} \otimes W}(\phi \otimes \psi \otimes w)\right)(v)\right) .
\end{array}
$$

The lower block in the top rectangle is commutative: using Definition 4.2 and $\phi \otimes A \in V_{2}^{*} \otimes \operatorname{Hom}\left(V_{1}, W\right), u \in V_{1}, v \in V_{2}$,

$$
\begin{aligned}
& T_{V_{1}, V_{2} ; W} \circ \operatorname{Hom}\left(I d_{V_{1}}, k_{V_{2}, W}\right) \circ n: \\
\phi \otimes A & \mapsto\left(t_{V_{1}, \operatorname{Hom}\left(V_{2}, W\right)}\left(k_{V_{2}, W} \circ(n(\phi \otimes A))\right)\right) \circ d_{V_{2}, W}: \\
v & \mapsto\left(d_{V_{2}, W}(v)\right) \circ k_{V_{2}, W} \circ(n(\phi \otimes A)): \\
u \mapsto & \mapsto\left(k_{V_{2}, W}(\phi \otimes(A(u)))\right)(v) \\
= & \phi(v) \cdot(A(u))=\left(\left(k_{V_{2}, \operatorname{Hom}\left(V_{1}, W\right)}(\phi \otimes A)\right)(v)\right)(u)
\end{aligned}
$$

So the top rectangle is commutative.

Lemma 4.10. For any $V_{1}, V_{2}, V_{3}, W$, if $V_{1}$ and $V_{2}$ are finite-dimensional, then all the arrows in the following diagram are invertible and the diagram is commutative.


Proof. The following diagram is commutative, where the column on the left matches the left column in the above diagram, and the column on the right uses two maps from the diagram in Lemma 4.9.


The upper square is commutative by Lemma 1.40. For the lower square, with $\phi \in V_{1}^{*}, \psi \in V_{2}^{*}, w \in W, v \in V_{3}, u \in V_{1}$,

$$
\begin{align*}
& n_{3} \circ\left[k_{V_{1}, V_{2}^{*} \otimes W} \otimes I d_{V_{3}}\right]: \\
\phi \otimes \psi \otimes w \otimes v & \mapsto
\end{aligned} n_{3}\left(\left(k_{V_{1}, V_{2}^{*} \otimes W}(\phi \otimes \psi \otimes w)\right) \otimes v\right): \begin{aligned}
& u \mapsto \\
& v \otimes(\phi(u) \cdot \psi \otimes w), \\
& k_{V_{1}, V_{3} \otimes V_{2}^{*} \otimes W} \circ\left[I d_{V_{1}^{*}} \otimes s\right]:  \tag{4.5}\\
& \phi \otimes \psi \otimes w \otimes v \mapsto \\
& u \quad k_{V_{1}, V_{3} \otimes V_{2}^{*} \otimes W}(\phi \otimes v \otimes \psi \otimes w): \\
& u \mapsto(u) \cdot v \otimes \psi \otimes w .
\end{align*}
$$

The above diagram is abbreviated to appear in the left block of the following diagram, by labeling its four corners $\left(M_{11}, M_{12}, M_{21}, M_{22}\right)$, and its upward vertical
composites as the vertical arrows $a_{1},\left[a_{2} \otimes I d_{V_{3}}\right]$.


The other two spaces are similarly related to the right column in the top square from Lemma 4.9:

$$
\begin{aligned}
M_{13} & =\operatorname{Hom}\left(V_{2}, \operatorname{Hom}\left(V_{1}, W\right)\right) \otimes V_{3} \\
M_{23} & =V_{2}^{*} \otimes V_{1}^{*} \otimes W \otimes V_{3} \\
a_{3} & =\operatorname{Hom}\left(I d_{V_{2}}, k_{V_{1} W}\right) \circ k_{V_{2}, V_{1}^{*} \otimes W},
\end{aligned}
$$

so that the commutativity of the middle block follows from the commutativity of the top block from Lemma 4.9, together with Lemma 1.35. The right block is a mirror image analogue of the left block, but without the switching map, so the verification that it is commutative again uses Lemma 1.40 and the subsequent steps, but omitting the $s$ in (4.5). Letting $s_{1}=\left[\left[s_{2} \otimes I d_{W}\right] \otimes I d_{V_{3}}\right] \circ\left[I d_{V_{1}} \otimes s^{-1}\right]$, the commutativity around the outside of the diagram gives the claim of the Lemma.

Exercise 4.11. If $V_{1}, V_{2}, W$ have metrics $g_{1}, g_{2}, h$, then

$$
T_{V_{1}, V_{2} ; W}: \operatorname{Hom}\left(V_{1}, \operatorname{Hom}\left(V_{2}, W\right)\right) \rightarrow \operatorname{Hom}\left(V_{2}, \operatorname{Hom}\left(V_{1}, W\right)\right)
$$

is an isometry with respect to the induced metrics.

Hint. From Lemma 4.1, $T_{V_{1}, V_{2} ; W}=q_{2}^{-1} \circ \operatorname{Hom}\left(s, I d_{W}\right) \circ q_{1}$ is a composite of isometries, using Theorem 3.45, Exercise 3.66, and Exercise 3.77. In the special case $V_{1}=V_{2}, g_{1}=g_{2}$, Exercise 3.121 applies to the involution $T_{V_{1} ; W}$. A further special case is $W=\mathbb{K}$, so Corollary 3.48 on the involution $T_{V}$ follows from this claim and Exercise 3.74.

The transpose for bilinear forms can be applied to vector valued trilinear forms: elements of $\operatorname{Hom}(X, \operatorname{Hom}(Y, \operatorname{Hom}(Z, U)))$, to switch the first and second, or second and third, inputs in expressions such as $((h(x))(y))(z) \in U$. An operator switching the first and third inputs can be expressed in terms of $T$ maps, or in terms of $q$ and $s$ maps in analogy with Lemma 4.1, but in more than one way, as shown by the following Lemma 4.12 and Equation (4.6).

Lemma 4.12. For any vector spaces $X, Y, Z, U$, the following diagram is commutative.


Proof. The claim follows from finding a map

$$
a_{1}: \operatorname{Hom}(X, \operatorname{Hom}(Y, \operatorname{Hom}(Z, U))) \rightarrow \operatorname{Hom}(Z, \operatorname{Hom}(Y, \operatorname{Hom}(X, U))),
$$

equal to both downward composites on the left and right sides of the above diagram. This first diagram corresponds to the right side.


All the arrows are invertible - the $q$ maps convert the transpose maps to switching maps. The right blocks are commutative by Lemma 4.1 and Definition 4.2, with the right center block also using Lemma 1.6. The three left blocks are commutative by Lemma 1.46 and the two center blocks by Lemma 1.47.

This second diagram, corresponding to the left side of the claim, is not exactly a mirror image of the first but is commutative in the same way, using Lemma 4.1,

Lemma 1.6, Lemma 1.46, and Lemma 1.47.


The composites of permutations in the diagrams are equal to the same switching map $s_{4}$ :

$$
\begin{aligned}
{\left[s_{3} \otimes I d_{X}\right] \circ\left[I d_{Y} \otimes s_{2}\right] \circ\left[s_{1} \otimes I d_{Z}\right] } & =\left[I d_{Z} \otimes s_{1}\right] \circ\left[s_{2} \otimes I d_{Y}\right] \circ\left[I d_{X} \otimes s_{3}\right] \\
& =s_{4}: X \otimes Y \otimes Z \rightarrow Z \otimes Y \otimes X
\end{aligned}
$$

By Lemma 1.47, $q_{3} \circ q_{1}=q_{9} \circ \operatorname{Hom}\left(I d_{X}, q_{7}\right)$ and $q_{3}^{\prime \prime \prime} \circ q_{1}^{\prime}=q_{9}^{\prime \prime \prime} \circ \operatorname{Hom}\left(I d_{Z} \circ q_{7}^{\prime}\right)$. So, the two diagrams fit together as claimed, with the downward composite in the left column of the first diagram being equal to the composite in the right column
of the second, giving the required map

$$
\begin{align*}
a_{1} & =\left(q_{3}^{\prime \prime \prime} \circ q_{1}^{\prime}\right)^{-1} \circ \operatorname{Hom}\left(\left[s_{3} \otimes I d_{X}\right] \circ\left[I d_{Y} \otimes s_{2}\right] \circ\left[s_{1} \otimes I d_{Z}\right], I d_{U}\right) \circ q_{3} \circ q_{1}  \tag{4.6}\\
& =\operatorname{Hom}\left(I d_{Z},\left(q_{7}^{\prime}\right)^{-1}\right) \circ\left(q_{9}^{\prime \prime \prime}\right)^{-1} \circ \operatorname{Hom}\left(s_{4}, I d_{U}\right) \circ q_{9} \circ \operatorname{Hom}\left(I d_{X}, q_{7}\right)
\end{align*}
$$

### 4.2. Symmetric bilinear forms

Definition 4.13. A $W$-valued form $h \in \operatorname{Hom}(V, \operatorname{Hom}(V, W))$ is symmetric means: $h=T_{V ; W}(h) . h$ is antisymmetric means: $h=-T_{V ; W}(h)$. Let $\overline{\operatorname{Sym}(V ; W)}$ denote the subspace of symmetric forms, and $\operatorname{Alt}(V ; W)$ the subspace of antisymmetric forms.

It follows from Lemma 1.112 and Lemma 4.4 that if $\frac{1}{2} \in \mathbb{K}$, then $T_{V ; W}$ produces a direct sum

$$
\begin{equation*}
\operatorname{Hom}(V, \operatorname{Hom}(V, W))=\operatorname{Sym}(V ; W) \oplus \operatorname{Alt}(V ; W) \tag{4.7}
\end{equation*}
$$

REmARK 4.14. The direct sum (4.7) is canonical, and so is the decomposition of any form $h$ into its symmetric and antisymmetric parts

$$
\begin{equation*}
\frac{1}{2}\left(h+T_{V ; W}(h)\right)+\frac{1}{2}\left(h-T_{V ; W}(h)\right) . \tag{4.8}
\end{equation*}
$$

However, there are several other involutions appearing in the $V=V_{1}=V_{2}$ case of Lemma 4.9, and some of the other spaces admit distinct but equivalent direct sums as in Example 1.136. Recalling the direct sum $V \otimes V=S^{2} V \oplus \Lambda^{2} V$ produced by the involution $s$ as in Example 1.116, Example 1.137 applies to the involutions $T_{V ; W}$ and $\operatorname{Hom}\left(s, I d_{W}\right)$ from Lemma 4.1 and Lemma 4.9, so the map

$$
q: \operatorname{Hom}(V, \operatorname{Hom}(V, W)) \rightarrow \operatorname{Hom}(V \otimes V, W)
$$

respects both of the direct sums on the target:

$$
\begin{aligned}
& \operatorname{Hom}(V \otimes V, W)=\{A: A \circ s=A\} \oplus\{A: A \circ s=-A\} \\
& \operatorname{Hom}(V \otimes V, W)=\operatorname{Hom}\left(S^{2} V, W\right) \oplus \operatorname{Hom}\left(\Lambda^{2} V, W\right)
\end{aligned}
$$

Example 4.15. It follows from Lemma 4.5 that for a map of the form

$$
h=\left(\operatorname{Hom}\left(I d_{V}, k_{V W}\right) \circ n_{1}\right)(g \otimes w),
$$

with $g: V \rightarrow V^{*}, w \in W$, if $g$ is symmetric, or antisymmetric, then so is $h$.
DEfinition 4.16. For any $U, V, W$, the pullback of a $W$-valued form $h: V \rightarrow$ $\operatorname{Hom}(V, W)$ by a map $H: U \rightarrow V$ is another $\overline{W \text {-valued }}$ form $\operatorname{Hom}\left(H, I d_{W}\right) \circ h \circ H$ : $U \rightarrow \operatorname{Hom}(U, W)$.

In the case $W=\mathbb{K}$, this coincides with the previously defined pullback (Definition 3.7).

Lemma 4.17. For maps $H: U \rightarrow V, G: W_{1} \rightarrow W_{2}$, and a form $h: V \rightarrow$ $\operatorname{Hom}(V, W)$,

$$
T_{U ; W}(\operatorname{Hom}(H, G) \circ h \circ H)=\operatorname{Hom}(H, G) \circ\left(T_{V ; W}(h)\right) \circ H
$$

The map
$\operatorname{Hom}(H, \operatorname{Hom}(H, G)): \operatorname{Hom}\left(V, \operatorname{Hom}\left(V, W_{1}\right)\right) \rightarrow \operatorname{Hom}\left(U, \operatorname{Hom}\left(U, W_{2}\right)\right)$
respects the direct sums $\operatorname{Sym}\left(V ; W_{1}\right) \oplus \operatorname{Alt}\left(V ; W_{1}\right) \rightarrow \operatorname{Sym}\left(U ; W_{2}\right) \oplus \operatorname{Alt}\left(U ; W_{2}\right)$.

Proof. The first claim is a special case of Lemma 4.6. The claim about the direct sums follows from Lemma 1.118 and Lemma 4.4.

The $G=I d_{W}$ case of Lemma 4.17 shows that the pullback by $H: U \rightarrow V$ of a symmetric form $h: V \rightarrow \operatorname{Hom}(V, W)$ is a symmetric form $U \rightarrow \operatorname{Hom}(U, W)$, and similarly, the pullback of an antisymmetric form is antisymmetric.

Notation 4.18. For $h_{1}: V_{1} \rightarrow \operatorname{Hom}\left(V_{1}, W\right)$, and $h_{2}: V_{2} \rightarrow \operatorname{Hom}\left(V_{2}, W\right)$, and a direct sum $V=V_{1} \oplus V_{2}$, let $h_{1} \oplus h_{2}: V \rightarrow \operatorname{Hom}(V, W)$ denote the form

$$
\operatorname{Hom}\left(P_{1}, I d_{W}\right) \circ h_{1} \circ P_{1}+\operatorname{Hom}\left(P_{2}, I d_{W}\right) \circ h_{2} \circ P_{2}
$$

In the $W=\mathbb{K}$ case, this is exactly the construction of Notation 3.9.
Lemma 4.19. $T_{V ; W}\left(h_{1} \oplus h_{2}\right)=\left(T_{V_{1} ; W}\left(h_{1}\right)\right) \oplus\left(T_{V_{2} ; W}\left(h_{2}\right)\right)$.
Proof. The proof proceeds exactly as in Theorem 3.10, using Lemma 1.13 and Lemma 1.6.

It follows that the direct sum of symmetric $W$-valued forms is symmetric, and similarly, the direct sum of antisymmetric forms is antisymmetric.

Working with the tensor product of vector valued forms is simpler than the scalar case (Notation 3.13), since the scalar multiplication is omitted. If $h_{1}: V_{1} \rightarrow$ $\operatorname{Hom}\left(V_{1}, W_{1}\right)$ and $h_{2}: V_{2} \rightarrow \operatorname{Hom}\left(V_{2}, W_{2}\right)$ are two vector valued forms, then the map

$$
j \circ\left[h_{1} \otimes h_{2}\right]: V_{1} \otimes V_{2} \rightarrow \operatorname{Hom}\left(V_{1} \otimes V_{2}, W_{1} \otimes W_{2}\right)
$$

has output

$$
\left(\left(j \circ\left[h_{1} \otimes h_{2}\right]\right)\left(u_{1} \otimes u_{2}\right)\right)\left(v_{1} \otimes v_{2}\right)=\left(\left(h_{1}\left(u_{1}\right)\right)\left(v_{1}\right)\right) \otimes\left(\left(h_{2}\left(u_{2}\right)\right)\left(v_{2}\right)\right) \in W_{1} \otimes W_{2}
$$ so it is a $W_{1} \otimes W_{2}$-valued form.

Theorem 4.20.

$$
T_{V_{1} \otimes V_{2} ; W_{1} \otimes W_{2}}\left(j \circ\left[h_{1} \otimes h_{2}\right]\right)=j \circ\left[\left(T_{V_{1} ; W_{1}}\left(h_{1}\right)\right) \otimes\left(T_{V_{2} ; W_{2}}\left(h_{2}\right)\right)\right] .
$$

Proof. In analogy with the proof of Theorem 3.12, the following diagram is commutative:

where

$$
\begin{aligned}
M_{1}= & \operatorname{Hom}\left(\operatorname{Hom}\left(V_{1}, W_{1}\right), W_{1}\right) \otimes \operatorname{Hom}\left(\operatorname{Hom}\left(V_{2}, W_{2}\right), W_{2}\right) \\
M_{2}= & \operatorname{Hom}\left(\operatorname{Hom}\left(V_{1}, W_{1}\right) \otimes \operatorname{Hom}\left(V_{2}, W_{2}\right), W_{1} \otimes W_{2}\right) \\
v_{1} \otimes v_{2} & \mapsto\left(\operatorname{Hom}\left(j, I d_{W_{1}} \otimes W_{2}\right) \circ d_{V_{1} \otimes V_{2}, W_{1} \otimes W_{2}}\right)\left(v_{1} \otimes v_{2}\right) \\
& =\left(d_{V_{1} \otimes V_{2}, W_{1} \otimes W_{2}}\left(v_{1} \otimes v_{2}\right)\right) \circ j: \\
A \otimes B & \mapsto[A \otimes B]\left(v_{1} \otimes v_{2}\right)=\left(A\left(v_{1}\right)\right) \otimes\left(B\left(v_{2}\right)\right), \\
v_{1} \otimes v_{2} & \mapsto\left(j^{\prime} \circ\left[d_{V_{1} W_{1}} \otimes d_{V_{2} W_{2}}\right]\right)\left(v_{1} \otimes v_{2}\right) \\
& =j^{\prime}\left(\left(d_{V_{1} W_{1}}\left(v_{1}\right)\right) \otimes\left(d_{V_{2} W_{2}}\left(v_{2}\right)\right)\right): \\
A \otimes B & \mapsto\left(A\left(v_{1}\right)\right) \otimes\left(B\left(v_{2}\right)\right)
\end{aligned}
$$

The statement of the Theorem follows from Lemma 1.6, the above diagram, Lemma 1.36, and Lemma 1.35:

$$
\begin{aligned}
L H S & =\left(t_{V_{1} \otimes V_{2}, \operatorname{Hom}\left(V_{1} \otimes V_{2}, W_{1} \otimes W_{2}\right)}^{W_{1}}\left(j \circ\left[h_{1} \otimes h_{2}\right]\right)\right) \circ d_{V_{1} \otimes V_{2}, W_{1} \otimes W_{2}} \\
& =\operatorname{Hom}\left(\left[h_{1} \otimes h_{2}\right], I d_{W_{1}} \otimes W_{2}\right) \circ \operatorname{Hom}\left(j, I d_{W_{1}} \otimes W_{2}\right) \circ d_{V_{1} \otimes V_{2}, W_{1} \otimes W_{2}} \\
& =\operatorname{Hom}\left(\left[h_{1} \otimes h_{2}\right], I d_{W_{1}} \otimes W_{2}\right) \circ j^{\prime} \circ\left[d_{V_{1} W_{1}} \otimes d_{V_{2} W_{2}}\right] \\
& =j \circ\left[\operatorname{Hom}\left(h_{1}, I d_{W_{1}}\right) \otimes \operatorname{Hom}\left(h_{2}, I d_{W_{2}}\right)\right] \circ\left[d_{V_{1} W_{1}} \otimes d_{V_{2} W_{2}}\right] \\
& =j \circ\left[\left(T_{V_{1} ; W_{1}}\left(h_{1}\right)\right) \otimes\left(T_{V_{2} ; W_{2}}\left(h_{2}\right)\right)\right] .
\end{aligned}
$$

It follows that the tensor product of symmetric forms is symmetric, as is the tensor product of antisymmetric forms.

In the $W_{1}=\mathbb{K}$ case, the tensor product of a scalar valued form $h_{1}: V_{1} \rightarrow V_{1}^{*}$ and a vector valued form $h_{2}: V_{2} \rightarrow \operatorname{Hom}\left(V_{2}, W\right)$ is a form $j \circ\left[h_{1} \otimes h_{2}\right]$ with values in $\mathbb{K} \otimes W$. The map $\operatorname{Hom}\left(I d_{V_{1} \otimes V_{2}}, l_{W}\right) \circ j \circ\left[h_{1} \otimes h_{2}\right]$ is a $W$-valued form.

Corollary 4.21. For $h_{1}: V_{1} \rightarrow V_{1}^{*}$ and $h_{2}: V_{2} \rightarrow \operatorname{Hom}\left(V_{2}, W\right)$, the following $W$-valued forms are equal.

$$
\begin{aligned}
& T_{V_{1} \otimes V_{2} ; W}\left(\operatorname{Hom}\left(I d_{V_{1} \otimes V_{2}}, l_{W}\right) \circ j \circ\left[h_{1} \otimes h_{2}\right]\right) \\
= & \operatorname{Hom}\left(I d_{V_{1} \otimes V_{2}}, l_{W}\right) \circ j \circ\left[\left(T_{V_{1}}\left(h_{1}\right)\right) \otimes\left(T_{V_{2} ; W}\left(h_{2}\right)\right)\right] .
\end{aligned}
$$

Proof. The equality follows immediately from Lemma 4.6, the previous Theorem, and the equality $T_{V ; \mathbb{K}}=T_{V}$.

Exercise 4.22. Let $V=U \oplus \operatorname{Hom}(U, L)$ be a direct sum with operators $P_{i}$, $Q_{i}$. Then,

$$
\begin{equation*}
\operatorname{Hom}\left(P_{1}, I d_{L}\right) \circ P_{2}+\operatorname{Hom}\left(P_{2}, I d_{L}\right) \circ d_{U L} \circ P_{1} \tag{4.9}
\end{equation*}
$$

is a symmetric $L$-valued form on $V$. If $d_{U L}$ is invertible, then this form is also invertible.

Hint. The proof that the form (4.9) is symmetric is the same as the calculation from Lemma 3.101, but using Lemma 1.13 and Lemma 1.16 in their full generality. If $d_{U L}$ is invertible (for example, as in Proposition 3.78), then the inverse of the form is

$$
Q_{1} \circ d_{U L}^{-1} \circ \operatorname{Hom}\left(Q_{2}, I d_{L}\right)+Q_{2} \circ \operatorname{Hom}\left(Q_{1}, I d_{L}\right)
$$

Exercise 4.23. Let $V=U \oplus \operatorname{Hom}(U, L)$ as in Exercise 4.22. Given maps $E: W \rightarrow U$ and $h: U \rightarrow \operatorname{Hom}(W, L)$, the following are equivalent.
(1) The $L$-valued form $h \circ E: W \rightarrow \operatorname{Hom}(W, L)$ is antisymmetric.
(2) The pullback of the symmetric $L$-valued form (4.9) by the map

$$
Q_{1} \circ E+Q_{2} \circ \operatorname{Hom}\left(h, I d_{L}\right) \circ d_{W L}: W \rightarrow V
$$

is $0_{\operatorname{Hom}(W, \operatorname{Hom}(W, L))}$.
Hint. The statement is analogous to Exercise 3.108, but uses the generalized notion of pullback from Definition 4.16.

Exercise 4.24. Suppose $V=V_{1} \oplus V_{2}$, and there is an invertible map $g: V \rightarrow$ $\operatorname{Hom}(V, L)$ so that these pullbacks are zero:

$$
\begin{aligned}
& \operatorname{Hom}\left(Q_{1}, I d_{L}\right) \circ g \circ Q_{1}=0_{\operatorname{Hom}\left(V_{1}, \operatorname{Hom}\left(V_{1}, L\right)\right)}, \\
& \operatorname{Hom}\left(Q_{2}, I d_{L}\right) \circ g \circ Q_{2}=0_{\operatorname{Hom}\left(V_{2}, \operatorname{Hom}\left(V_{2}, L\right)\right)}
\end{aligned}
$$

Then these maps are invertible:

$$
\begin{aligned}
& \operatorname{Hom}\left(Q_{1}, I d_{L}\right) \circ g \circ Q_{2}: V_{2} \rightarrow \operatorname{Hom}\left(V_{1}, L\right), \\
& \operatorname{Hom}\left(Q_{2}, I d_{L}\right) \circ g \circ Q_{1}: V_{1} \rightarrow \operatorname{Hom}\left(V_{2}, L\right) .
\end{aligned}
$$

Hint. The inverses are $P_{2} \circ g^{-1} \circ \operatorname{Hom}\left(P_{1}, I d_{L}\right), P_{1} \circ g^{-1} \circ \operatorname{Hom}\left(P_{2}, I d_{L}\right)$.
Exercise 4.25. ([EPW]) Let $V=V_{1} \oplus V_{2}$ and $g: V \rightarrow \operatorname{Hom}(V, L)$ be as in the previous Exercise. Then there is another direct sum $V=V_{1} \oplus \operatorname{Hom}\left(V_{1}, L\right)$, defined by operators $P_{1}, Q_{1}$, and

$$
\begin{aligned}
P_{2}^{\prime} & =\operatorname{Hom}\left(Q_{1}, I d_{L}\right) \circ g: V \rightarrow \operatorname{Hom}\left(V_{1}, L\right) \\
Q_{2}^{\prime} & =g^{-1} \circ \operatorname{Hom}\left(P_{1}, I d_{L}\right): \operatorname{Hom}\left(V_{1}, L\right) \rightarrow V
\end{aligned}
$$

If, also, $g$ is symmetric, then $g$ is equal to the $L$-valued form induced by this direct sum, as in Exercise 4.22:

$$
g=\operatorname{Hom}\left(P_{1}, I d_{L}\right) \circ P_{2}^{\prime}+\operatorname{Hom}\left(P_{2}^{\prime}, I d_{L}\right) \circ d_{V_{1}, L} \circ P_{1} .
$$

Hint. It is easy to check that $P_{2}^{\prime} \circ Q_{1}$ is zero, and $P_{2}^{\prime} \circ Q_{2}^{\prime}$ is the identity.

$$
\begin{aligned}
& \operatorname{Hom}\left(Q_{2}, I d_{L}\right) \circ g \circ Q_{1} \circ P_{1} \circ Q_{2}^{\prime} \\
= & \operatorname{Hom}\left(Q_{2}, I d_{L}\right) \circ g \circ Q_{1} \circ P_{1} \circ g^{-1} \circ \operatorname{Hom}\left(P_{1} \circ I d_{L}\right) \\
= & \operatorname{Hom}\left(Q_{2}, I d_{L}\right) \circ g \circ\left(I d_{V}-Q_{2} \circ P_{2}\right) \circ g^{-1} \circ \operatorname{Hom}\left(P_{1}, I d_{L}\right) \\
= & 0_{\operatorname{Hom}\left(\operatorname{Hom}\left(V_{1}, L\right), \operatorname{Hom}\left(V_{2}, L\right)\right)} .
\end{aligned}
$$

By the previous Exercise, $\operatorname{Hom}\left(Q_{2}, I d_{L}\right) \circ g \circ Q_{1}$ is invertible, so

$$
P_{1} \circ Q_{2}^{\prime}=0_{\operatorname{Hom}\left(\operatorname{Hom}\left(V_{1}, L\right), V_{1}\right)}
$$

$$
\begin{aligned}
& Q_{1} \circ P_{1}+Q_{2}^{\prime} \circ P_{2}^{\prime} \\
= & Q_{1} \circ P_{1}+\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right) \circ Q_{2}^{\prime} \circ P_{2}^{\prime} \circ\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right) \\
= & Q_{1} \circ P_{1}+Q_{2} \circ P_{2} \circ g^{-1} \circ \operatorname{Hom}\left(P_{1}, I d_{L}\right) \circ \operatorname{Hom}\left(Q_{1}, I d_{L}\right) \circ g \circ Q_{2} \circ P_{2} \\
= & Q_{1} \circ P_{1}+Q_{2} \circ P_{2}=I d_{V},
\end{aligned}
$$

using the inverse formula from the previous Exercise. As for the claimed equality,

$$
\begin{aligned}
R H S= & \operatorname{Hom}\left(P_{1}, I d_{L}\right) \circ \operatorname{Hom}\left(Q_{1}, I d_{L}\right) \circ g \\
& +\operatorname{Hom}\left(\operatorname{Hom}\left(Q_{1}, I d_{L}\right) \circ g, I d_{L}\right) \circ d_{V_{1}, L} \circ P_{1} \\
= & \operatorname{Hom}\left(P_{1}, I d_{L}\right) \circ \operatorname{Hom}\left(Q_{1}, I d_{L}\right) \circ g \circ\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right)+ \\
& \operatorname{Hom}\left(g, I d_{L}\right) \circ \operatorname{Hom}\left(\operatorname{Hom}\left(Q_{1}, I d_{L}\right), I d_{L}\right) \circ d_{V_{1}, L} \circ P_{1} \\
= & \operatorname{Hom}\left(P_{1}, I d_{L}\right) \circ \operatorname{Hom}\left(Q_{1}, I d_{L}\right) \circ g \circ Q_{2} \circ P_{2} \\
& +\operatorname{Hom}\left(P_{2}, I d_{L}\right) \circ \operatorname{Hom}\left(Q_{2}, I d_{L}\right) \circ g \circ Q_{2} \circ P_{2} \\
& +\operatorname{Hom}\left(g, I d_{L}\right) \circ d_{V L} \circ Q_{1} \circ P_{1} \\
= & \operatorname{Hom}\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}, I d_{L}\right) \circ g \circ Q_{2} \circ P_{2}+\left(T_{V L}(g)\right) \circ Q_{1} \circ P_{1} \\
= & g \circ\left(Q_{2} \circ P_{2}+Q_{1} \circ P_{1}\right)=g .
\end{aligned}
$$

### 4.3. Vector valued trace with respect to a metric

A metric $g$ on $V$ suggests that the scalar trace $\operatorname{Tr}_{g}$ (Definition 3.32) can be generalized to a vector valued trace operator on $W$-valued forms, but at first there would appear to be two constructions of a map $T r_{g ; W}: \operatorname{Hom}(V, \operatorname{Hom}(V, W)) \rightarrow$ $W$. One way would be to combine the previously constructed vector valued trace $\operatorname{Tr}_{V^{*} ; W}$ (Definition 2.50) and composition with $g^{-1}$, and another would be to start with the scalar trace $T r_{g}$, and tensor with $I d_{W}$. Of course, the two approaches have the same result.

Lemma 4.26. Given a metric $g$ on $V$, the following diagram is commutative.


Proof. The upper left triangle is commutative by Lemma 1.6, and the upper right block is commutative by Lemma 1.40, with invertible $n$ maps by the finitedimensionality of $V$. The lower square is the definition of $\operatorname{Tr}_{V^{*} ; W}$, and the right triangle uses the definition of $T r_{g}$.

Definition 4.27. Given a metric $g$ on $V$, an arbitrary vector space $W$, and a $W$-valued form $h: V \rightarrow \operatorname{Hom}(V, W)$, the $W$-valued trace with respect to $g$ is the following element of $W$ :

$$
\operatorname{Tr}_{g ; W}(h)=\operatorname{Tr}_{V^{*} ; W}\left(k_{V W}^{-1} \circ h \circ g^{-1}\right) .
$$

Corollary 2.57 also gives the equality

$$
\operatorname{Tr}_{V^{*} ; W}\left(k_{V W}^{-1} \circ h \circ g^{-1}\right)=\operatorname{Tr}_{V ; W}\left(\left[g^{-1} \otimes I d_{W}\right] \circ k_{V W}^{-1} \circ h\right)
$$

By the previous Lemma,

$$
T r_{g ; W}=\operatorname{Tr}_{V^{*} ; W} \circ \operatorname{Hom}\left(g^{-1}, k_{V W}^{-1}\right)=l_{W} \circ\left[\operatorname{Tr}_{g} \otimes I d_{W}\right] \circ n_{1}^{-1} \circ \operatorname{Hom}\left(I d_{V}, k_{V W}^{-1}\right)
$$

Example 4.28. Given a metric $g$ on $V$, if $h$ is of the form $h=\left(\operatorname{Hom}\left(I d_{V}, k_{V W}\right) \circ\right.$ $\left.n_{1}\right)(E \otimes w)$, for $E: V \rightarrow V^{*}$ and $w \in W$, then $\operatorname{Tr}_{g ; W}(h)=\operatorname{Tr}_{g}(E) \cdot w$, and if $\operatorname{Tr}_{g}(E)=0$, then $\operatorname{Tr}_{g ; W}(h)=0_{W}$.

The previously defined scalar valued trace with respect to $g$ (Definition 3.32) is exactly the $W=\mathbb{K}$ case of the vector valued case:

Theorem 4.29. Given a metric $g$ on $V$, for $h: V \rightarrow V^{*}, T r_{g ; \mathbb{K}}(h)=T r_{g}(h)$.
Proof. By Lemma $1.58, k_{V \mathbb{K}}: V^{*} \otimes \mathbb{K} \rightarrow V^{*}$ is exactly the scalar multiplication appearing in Theorem 2.53, so that

$$
\operatorname{Tr}_{g ; \mathbb{K}}(h)=\operatorname{Tr}_{V^{*} ; \mathbb{K}}\left(k_{V \mathbb{K}}^{-1} \circ h \circ g^{-1}\right)=\operatorname{Tr}_{V^{*}}\left(h \circ g^{-1}\right)=\operatorname{Tr}_{g}(h)
$$

Theorem 4.30. For any metric $h^{\nu}$ on $\mathbb{K}$, as in Lemma 3.67, and a form $h: \mathbb{K} \rightarrow \operatorname{Hom}(\mathbb{K}, W)$,

$$
T r_{h^{\nu} ; W}(h)=\frac{1}{\nu} \cdot(h(1))(1)
$$

Proof.

$$
\begin{aligned}
\operatorname{Tr}_{h^{\nu} ; W}(h) & =\operatorname{Tr}_{\mathbb{K} ; W}\left(\left[\left(h^{\nu}\right)^{-1} \otimes I d_{W}\right] \circ k_{\mathbb{K} W}^{-1} \circ h\right) \\
& =\left(l_{W} \circ\left[\left(h^{\nu}\right)^{-1} \otimes I d_{W}\right] \circ k_{\mathbb{K} W}^{-1} \circ h\right)(1) \\
& =\left(\frac{1}{\nu} \cdot m^{-1}\right)(h(1)) \\
& =\frac{1}{\nu}(h(1))(1),
\end{aligned}
$$

where the first step uses Corollary 2.56, and the last step uses the formula $m^{-1}=$ $d_{\mathbb{K} W}(1)$, from Definition 1.19. The intermediate step uses the commutativity of the diagram


$$
\begin{aligned}
\lambda \otimes w & \mapsto\left(m^{-1} \circ k_{\mathbb{K} W} \circ\left[h^{\nu} \otimes I d_{W}\right]\right)(\lambda \otimes w) \\
& =\left(k_{\mathbb{K} W}\left(\left(h^{\nu}(\lambda)\right) \otimes w\right)\right)(1) \\
& =\nu \cdot \lambda \cdot 1 \cdot w \\
& =\left(\nu \cdot l_{W}\right)(\lambda \otimes w)
\end{aligned}
$$

Theorem 4.31. Given a metric $g$ on $V, \operatorname{Tr}_{g ; W}\left(T_{V ; W}(h)\right)=\operatorname{Tr}_{g ; W}(h)$.
Proof. Since $V$ must be finite-dimensional, Lemma 4.5 and Lemma 4.26 apply.

$$
\begin{aligned}
T r_{g ; W} \circ T_{V ; W}= & l_{W} \circ\left[T r_{g} \otimes I d_{W}\right] \circ n_{1}^{-1} \circ \operatorname{Hom}\left(I d_{V}, k_{V W}^{-1}\right) \\
& \circ \operatorname{Hom}\left(I d_{V}, k_{V W}\right) \circ n_{1} \circ\left[T_{V} \otimes I d_{W}\right] \circ n_{1}^{-1} \circ \operatorname{Hom}\left(I d_{V}, k_{V W}^{-1}\right) \\
= & l_{W} \circ\left[T r_{g} \otimes I d_{W}\right] \circ\left[T_{V} \otimes I d_{W}\right] \circ n_{1}^{-1} \circ \operatorname{Hom}\left(I d_{V}, k_{V W}^{-1}\right) \\
= & l_{W} \circ\left[T r_{g} \otimes I d_{W}\right] \circ n_{1}^{-1} \circ \operatorname{Hom}\left(I d_{V}, k_{V W}^{-1}\right) \\
= & T r_{g ; W},
\end{aligned}
$$

by Lemma 1.35 and Theorem 3.33, which stated that $T r_{g} \circ T_{V}=T r_{g}$.
Corollary 4.32. Given a metric $g$ on $V$, if $h: V \rightarrow \operatorname{Hom}(V, W)$ is antisymmetric and $\frac{1}{2} \in \mathbb{K}$, then $\operatorname{Tr}_{g ; W}(h)=0_{W}$.

Proposition 4.33. Given a metric $g$ on $V$, the $W$-valued trace is invariant under pullback, that is, if $H: U \rightarrow V$ is invertible, then

$$
\operatorname{Tr}_{H^{*} \circ g \circ H ; W}\left(\operatorname{Hom}\left(H, I d_{W}\right) \circ h \circ H\right)=\operatorname{Tr}_{g ; W}(h) .
$$

Proof. Using Corollary 2.57 and Lemma 1.57,

$$
\begin{aligned}
L H S & =\operatorname{Tr}_{U^{*} ; W}\left(k_{U W}^{-1} \circ \operatorname{Hom}\left(H, I d_{W}\right) \circ h \circ H \circ H^{-1} \circ g^{-1} \circ\left(H^{*}\right)^{-1}\right) \\
& =\operatorname{Tr}_{V^{*} ; W}\left(\left[\left(H^{*}\right)^{-1} \otimes I d_{W}\right] \circ k_{U W}^{-1} \circ \operatorname{Hom}\left(H, I d_{W}\right) \circ h \circ g^{-1}\right) \\
& =\operatorname{Tr}_{V^{*} ; W}\left(k_{V W}^{-1} \circ h \circ g^{-1}\right)=R H S .
\end{aligned}
$$

This statement and proof are analogous to Proposition 3.37.
Theorem 4.34. Given a metric $g$ on $V$, for any map $B: W \rightarrow W^{\prime}$,

$$
\operatorname{Tr}_{g ; W^{\prime}}\left(\operatorname{Hom}\left(I d_{V}, B\right) \circ h\right)=B\left(\operatorname{Tr}_{g ; W}(h)\right)
$$

Proof. Using Corollary 2.58 and Lemma 1.57,

$$
\begin{aligned}
L H S & =\operatorname{Tr}_{V^{*} ; W^{\prime}}\left(k_{V W^{\prime}}^{-1} \circ \operatorname{Hom}\left(I d_{V}, B\right) \circ h \circ g^{-1}\right) \\
& =\operatorname{Tr}_{V^{*}, W^{\prime}}\left(\left[I d_{V^{*}} \otimes B\right] \circ k_{V W}^{-1} \circ h \circ g^{-1}\right) \\
& =B\left(\operatorname{Tr}_{V^{*} ; W}\left(k_{V W}^{-1} \circ h \circ g^{-1}\right)\right)=R H S .
\end{aligned}
$$

Corollary 4.35. Given a metric $g$ on $V$, and maps $H: U \rightarrow V, B: W \rightarrow W^{\prime}$, if $H$ is invertible then the following diagram is commutative.


Proof. This follows from Proposition 4.33 and Theorem 4.34.
Proposition 4.36. Given metrics $g_{1}, g_{2}$ on $V_{1}, V_{2}$, and a direct sum $V=$ $V_{1} \oplus V_{2}$, for $W$-valued forms $h_{1}: V_{1} \rightarrow \operatorname{Hom}\left(V_{1}, W\right), h_{2}: V_{2} \rightarrow \operatorname{Hom}\left(V_{2}, W\right)$,

$$
T r_{g_{1} \oplus g_{2} ; W}\left(h_{1} \oplus h_{2}\right)=T r_{g_{1} ; W}\left(h_{1}\right)+T r_{g_{2} ; W}\left(h_{2}\right) \in W
$$

Proof. First, Lemma 1.6 and Lemma 1.57 apply to simplify the following map from $\operatorname{Hom}\left(V_{I}, W\right)$ to $V_{i}^{*} \otimes W$ :

$$
\begin{aligned}
& {\left[Q_{i}^{*} \otimes I d_{W}\right] \circ k_{V W}^{-1} \circ \operatorname{Hom}\left(P_{I}, I d_{W}\right) } \\
= & k_{V_{i} W}^{-1} \circ \operatorname{Hom}\left(Q_{i}, I d_{W}\right) \circ \operatorname{Hom}\left(P_{I}, I d_{W}\right)=k_{V_{i} W}^{-1} \circ \operatorname{Hom}\left(P_{I} \circ Q_{i}, I d_{W}\right) \\
= & k_{V_{i} W}^{-1}, \text { if } i=I, \text { or } 0_{\operatorname{Hom}\left(\operatorname{Hom}\left(V_{I}, W\right), V_{i}^{*} \otimes W\right)} \text { if } i \neq I
\end{aligned}
$$

Then the formula (3.4) for $\left(g_{1} \oplus g_{2}\right)^{-1}$ from Corollary 3.18 applies:

$$
\begin{aligned}
L H S= & \operatorname{Tr}_{V ; W}\left(\left[\left(g_{1} \oplus g_{2}\right)^{-1} \otimes I d_{W}\right] \circ k_{V W}^{-1} \circ\left(h_{1} \oplus h_{2}\right)\right) \\
= & \operatorname{Tr}_{V ; W}\left(\left[\left(Q_{1} \circ g_{1}^{-1} \circ Q_{1}^{*}\right) \otimes I d_{W}\right] \circ k_{V W}^{-1} \circ \operatorname{Hom}\left(P_{1}, I d_{W}\right) \circ h_{1} \circ P_{1}\right. \\
& +\left[\left(Q_{1} \circ g_{1}^{-1} \circ Q_{1}^{*}\right) \otimes I d_{W}\right] \circ k_{V W}^{-1} \circ \operatorname{Hom}\left(P_{2}, I d_{W}\right) \circ h_{2} \circ P_{2} \\
& +\left[\left(Q_{2} \circ g_{2}^{-1} \circ Q_{2}^{*}\right) \otimes I d_{W}\right] \circ k_{V W}^{-1} \circ \operatorname{Hom}\left(P_{1}, I d_{W}\right) \circ h_{1} \circ P_{1} \\
& \left.+\left[\left(Q_{2} \circ g_{2}^{-1} \circ Q_{2}^{*}\right) \otimes I d_{W}\right] \circ k_{V W}^{-1} \circ \operatorname{Hom}\left(P_{2}, I d_{W}\right) \circ h_{2} \circ P_{2}\right) \\
= & T r_{V ; W}\left(\left[\left(Q_{1} \circ g_{1}^{-1}\right) \otimes I d_{W}\right] \circ k_{V_{1} W}^{-1} \circ h_{1} \circ P_{1}\right) \\
& +\operatorname{Tr}_{V ; W}\left(\left[\left(Q_{2} \circ g_{2}^{-1}\right) \otimes I d_{W}\right] \circ k_{V_{2} W}^{-1} \circ h_{2} \circ P_{2}\right) \\
= & \operatorname{Tr}_{V_{1} ; W}\left(\left[\left(P_{1} \circ Q_{1} \circ g_{1}^{-1}\right) \otimes I d_{W}\right] \circ k_{V_{1} W}^{-1} \circ h_{1}\right) \\
& +\operatorname{Tr}_{V_{2} ; W}\left(\left[\left(P_{2} \circ Q_{2} \circ g_{2}^{-1}\right) \otimes I d_{W}\right] \circ k_{V_{2} W}^{-1} \circ h_{2}\right)=R H S .
\end{aligned}
$$

The last steps used Corollary 2.57 and Lemma 1.35.

THEOREM 4.37. For metrics $g_{1}, g_{2}$ on $V_{1}, V_{2}$, and vector valued forms $h_{1}$ : $V_{1} \rightarrow \operatorname{Hom}\left(V_{1}, W_{1}\right), h_{2}: V_{2} \rightarrow \operatorname{Hom}\left(V_{2}, W_{2}\right)$,

$$
\operatorname{Tr}_{\left\{g_{1} \otimes g_{2}\right\} ; W_{1} \otimes W_{2}}\left(j \circ\left[h_{1} \otimes h_{2}\right]\right)=\left(\operatorname{Tr}_{g_{1} ; W_{1}}\left(h_{1}\right)\right) \otimes\left(\operatorname{Tr}_{g_{2} ; W_{2}}\left(h_{2}\right)\right) \in W_{1} \otimes W_{2}
$$

Proof. The following diagram is commutative.

$\operatorname{Hom}\left(V_{2} \otimes V_{2}, \mathbb{K} \otimes \mathbb{K}\right) \otimes W_{1} \otimes W_{2}$
$\operatorname{Hom}\left(V_{1}, W_{1}\right) \otimes \operatorname{Hom}\left(V_{2}, W_{2}\right)$

The commutativity of the lower part is exactly Lemma 2.32. The top square is easy to check, where the $s_{1}$ map is as in Theorem 2.40. The statement of the Theorem follows from Corollary 2.63, using Lemma 1.35 and the formula for $\left\{g_{1} \otimes g_{2}\right\}^{-1}$
from Corollary 3.19:

$$
\begin{aligned}
L H S= & \operatorname{Tr}_{V_{1} \otimes V_{2} ; W_{1} \otimes W_{2}}\left(\left[\left(\left[g_{1}^{-1} \otimes g_{2}^{-1}\right] \circ j^{-1} \circ \operatorname{Hom}\left(I d_{V_{1} \otimes V_{2}}, l^{-1}\right)\right) \otimes I d_{W_{1} \otimes W_{2}}\right]\right. \\
& \left.\circ k_{V_{1} \otimes V_{2}, W_{1} \otimes W_{2}}^{-1} \circ j \circ\left[h_{1} \otimes h_{2}\right]\right) \\
= & \operatorname{Tr}_{V_{1} \otimes V_{2} ; W_{1} \otimes W_{2}}\left(s_{1} \circ\left[\left[g_{1}^{-1} \otimes I d_{W_{1}}\right] \otimes\left[g_{2}^{-1} \otimes I d_{W_{2}}\right]\right]\right. \\
& \left.\circ\left[k_{V_{1} W_{1}}^{-1} \otimes k_{V_{2} W_{2}}^{-1}\right] \circ\left[h_{1} \otimes h_{2}\right]\right) \\
= & \operatorname{Tr}_{V_{1} \otimes V_{2} ; W_{1} \otimes W_{2}}\left(s _ { 1 } \circ \left(j _ { 3 } ^ { \prime } \left(\left(\left[g_{1}^{-1} \otimes I d_{W_{1}}\right] \circ k_{V_{1} W_{1}}^{-1} \circ h_{1}\right)\right.\right.\right. \\
& \left.\left.\left.\otimes\left(\left[g_{2}^{-1} \otimes I d_{W_{2}}\right] \circ k_{V_{2} W_{2}}^{-1} \circ h_{2}\right)\right)\right)\right) \\
= & \left(\operatorname{Tr}_{V_{1} ; W_{1}}\left(\left[g_{1}^{-1} \otimes I d_{W_{1}}\right] \circ k_{V_{1} W_{1}}^{-1} \circ h_{1}\right)\right) \\
& \otimes\left(\operatorname{Tr}_{V_{2} ; W_{2}}\left(\left[g_{2}^{-1} \otimes I d_{W_{2}}\right] \circ k_{V_{2} W_{2}}^{-1} \circ h_{2}\right)\right)=\text { RHS. }
\end{aligned}
$$

Corollary 4.38. For metrics $g_{1}, g_{2}$ on $V_{1}, V_{2}$, a scalar valued form $h_{1}: V_{1} \rightarrow$ $V_{1}^{*}$, and $a W$-valued form $h_{2}: V_{2} \rightarrow \operatorname{Hom}\left(V_{2}, W\right)$,

$$
T r_{\left\{g_{1} \otimes g_{2}\right\} ; W}\left(\operatorname{Hom}\left(I d_{V_{1} \otimes V_{2}}, l_{W}\right) \circ j \circ\left[h_{1} \otimes h_{2}\right]\right)=T r_{g_{1}}\left(h_{1}\right) \cdot T r_{g_{2} ; W}\left(h_{2}\right) .
$$

Proof. Using Theorem 4.34, the previous Theorem, and Theorem 4.29,

$$
\begin{aligned}
L H S & =l_{W}\left(\operatorname{Tr}_{\left\{g_{1} \otimes g_{2}\right\} ; \mathbb{K} \otimes W}\left(j \circ\left[h_{1} \otimes h_{2}\right]\right)\right) \\
& =l_{W}\left(\left(\operatorname{Tr}_{g_{1} ; \mathbb{K}}\left(h_{1}\right)\right) \otimes\left(\operatorname{Tr}_{g_{2} ; W}\left(h_{2}\right)\right)\right)=R H S .
\end{aligned}
$$

Theorem 4.39. If $\frac{1}{2} \in \mathbb{K}$, and $g$ and $y$ are metrics on $V$ and $W$, then the direct $\operatorname{sum} \operatorname{Sym}(V ; W) \oplus \operatorname{Alt}(V ; W)$ is orthogonal with respect to the induced metric.

Proof. Since $V$ is finite-dimensional, all the arrows in the diagram for Lemma 4.5 are invertible. Let $H=\operatorname{Hom}\left(I d_{V}, k_{V W}\right) \circ n_{1}$, so $H$ and $H^{-1}$ are isometries by Theorem 3.41, Theorem 3.45, and Lemma 3.73. Also, $\left[T_{V} \otimes I d_{W}\right]$ is an isometry by Corollary 3.48 and Theorem 3.28, so by Lemma 4.5 and Definition 4.2, $T_{V ; W}$ is an isometry, and an involution by Lemma 4.4. Then Lemma 3.55 applies to the direct sum produced by $T_{V ; W}$.

By Theorem 3.56 and Theorem 3.60, $\operatorname{Hom}\left(V, V^{*}\right) \otimes W=(\operatorname{Sym}(V) \otimes W) \oplus$ $(\operatorname{Alt}(V) \otimes W)$ is an orthogonal direct sum. Since $H$ respects the direct sums, by Lemma 4.5 and Lemma 1.118, it follows from Theorem 3.61 that the maps between $\operatorname{Sym}(V) \otimes W$ and $\operatorname{Sym}(V ; W)$, and between $\operatorname{Alt}(V) \otimes W$ and $\operatorname{Alt}(V ; W)$, are isometries.

Theorem 4.40. If $\operatorname{Tr}_{V}\left(I d_{V}\right) \neq 0$, and $g$ is a metric on $V$, then there is a direct sum $\operatorname{Hom}(V, \operatorname{Hom}(V, W))=W \oplus \operatorname{ker}\left(\operatorname{Tr}_{g ; W}\right)$. If $y$ is a metric on $W$, then the direct sum is orthogonal with respect to the induced metric.

Proof. By Theorem 3.53, $\operatorname{Hom}\left(V, V^{*}\right)=\mathbb{K} \oplus \operatorname{ker}\left(T r_{g}\right)$ is an orthogonal direct sum, with operators $P_{1}^{\prime \prime}=\alpha \cdot \operatorname{Tr}_{g}, Q_{1}^{\prime \prime}: \lambda \mapsto \lambda \cdot \beta \cdot g$, with $\alpha \cdot \beta \cdot \operatorname{Tr}_{V}\left(I d_{V}\right)=1$ as in Example 2.9. Also, $P_{2}^{\prime \prime}=I d_{\operatorname{Hom}\left(V, V^{*}\right)}-Q_{1}^{\prime \prime} \circ P_{1}^{\prime \prime}$, and $Q_{2}^{\prime \prime}$ is just the inclusion of the subspace $\operatorname{ker}\left(T r_{g}\right)$ in $\operatorname{Hom}\left(V, V^{*}\right)$. By Example 1.75 , $\operatorname{Hom}\left(V, V^{*}\right) \otimes W$ is a direct sum of $\mathbb{K} \otimes W$ and $\left(\operatorname{ker}\left(T r_{g}\right)\right) \otimes W$, with operators $P_{i}=\left[P_{i}^{\prime \prime} \otimes I d_{W}\right]$,
$Q_{i}=\left[Q_{i}^{\prime \prime} \otimes I d_{W}\right]$. Let $H=\operatorname{Hom}\left(I d_{V}, k_{V W}\right) \circ n_{1}$, and let $P_{1}^{\prime}=\alpha \cdot T r_{g ; W}$, so that the following diagram is commutative by Lemma 4.26.


Let $Q_{2}^{\prime}$ be the inclusion of $\operatorname{ker}\left(T r_{g ; W}\right)$ in $\operatorname{Hom}(V, \operatorname{Hom}(V, W))$, which is a linear monomorphism so that $P_{1}^{\prime} \circ Q_{2}^{\prime}=0_{\operatorname{Hom}\left(\operatorname{ker}\left(T r_{g ; W}\right), W\right)}$. Define $H_{2}:\left(\operatorname{ker}\left(\operatorname{Tr}_{g}\right)\right) \otimes W \rightarrow$ $\operatorname{ker}\left(T r_{g ; W}\right)$ by $H_{2}=H \circ Q_{2}$; the image of $H_{2}$ is contained in $\operatorname{ker}\left(T r_{g ; W}\right)$ by Lemma 4.26, so $Q_{2}^{\prime} \circ H_{2}=H \circ Q_{2}$. Theorem 1.96 applies, so that $\operatorname{Hom}(V, \operatorname{Hom}(V, W))$ has a direct sum structure $W \oplus \operatorname{ker}\left(T r_{g ; W}\right)$, and $H$ respects the direct sums. By Theorem 3.60, if $W$ has a metric $y$, then the direct $\operatorname{sum} \operatorname{Hom}\left(V, V^{*}\right) \otimes W=(\mathbb{K} \otimes$ $W) \oplus\left(\left(\operatorname{ker}\left(\operatorname{Tr}_{g}\right)\right) \otimes W\right)$ is orthogonal with respect to the induced metric. Since $H$ is an isometry (as mentioned in the proof of the previous Theorem), it follows from Theorem 3.61 that $W \oplus \operatorname{ker}\left(T r_{g ; W}\right)$ is orthogonal with respect to the induced metric.

Corollary 4.41. The metric induced on $W$ by the direct sum from the previous Theorem is $\beta^{2} \cdot \operatorname{Tr}_{V}\left(I d_{V}\right) \cdot y$.

Proof. The induced metric on $\mathbb{K} \otimes W$ is $\left\{h^{\nu} \otimes y\right\}$, for $\nu=\beta^{2} \cdot \operatorname{Tr}_{V}\left(I d_{V}\right)$ by Theorem 3.60 and Lemma 3.71. By Theorem 3.61, $P_{1}^{\prime} \circ H \circ Q_{1}=l_{W} \circ P_{1} \circ Q_{1}=$ $l_{W}: \mathbb{K} \otimes W \rightarrow W$ is an isometry, so by Lemma 3.69 , the metric in the target must be $\nu \cdot y$.

Corollary 4.42. Given a metric $g$ on $V$, if both $\frac{1}{2} \in \mathbb{K}$ and $\operatorname{Tr}_{V}\left(I d_{V}\right) \neq 0$, then there is a direct sum $\operatorname{Hom}(V, \operatorname{Hom}(V, W))=W \oplus \operatorname{Sym}_{0}(g ; W) \oplus \operatorname{Alt}(V ; W)$, where $\operatorname{Sym}_{0}(g ; W)$ is the kernel of the restriction of $\operatorname{Tr}_{g ; W}$ to $\operatorname{Sym}(V ; W)$. If $W$ has a metric $y$, then there is an orthogonal direct sum.

ExErcise 4.43. For $K: V \rightarrow \operatorname{Hom}(V, W)$, an orthogonal direct $\operatorname{sum} V=$ $V_{1} \oplus V_{2}$ with respect to a metric $g$ on $V$, and the induced metrics $g_{1}, g_{2}$, on $V_{1}, V_{2}$, $T r_{g ; W}(K)=\operatorname{Tr}_{g_{1} ; W}\left(\operatorname{Hom}\left(Q_{1}, I d_{W}\right) \circ K \circ Q_{1}\right)+T r_{g_{2} ; W}\left(\operatorname{Hom}\left(Q_{2}, I d_{W}\right) \circ K \circ Q_{2}\right)$.

Hint. In analogy with Exercise 3.100, Lemma 1.57 and Corollary 2.57 apply:

$$
\begin{aligned}
L H S= & \operatorname{Tr}_{V^{*} ; W}\left(k_{V W}^{-1} \circ K \circ g^{-1}\right) \\
= & \operatorname{Tr}_{V^{*} ; W}\left(k_{V W}^{-1} \circ K \circ\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right) \circ g^{-1} \circ\left(Q_{1} \circ P_{1}+Q_{2} \circ P_{2}\right)^{*}\right) \\
= & \operatorname{Tr}_{V^{*} ; W}\left(k_{V W}^{-1} \circ K \circ Q_{1} \circ P_{1} \circ g^{-1} \circ P_{1}^{*} \circ Q_{1}^{*}\right) \\
& +\operatorname{Tr}_{V^{*} ; W}\left(k_{V W}^{-1} \circ K \circ Q_{2} \circ P_{2} \circ g^{-1} \circ P_{2}^{*} \circ Q_{2}^{*}\right) \\
= & \operatorname{Tr}_{V_{1} ; W}\left(\left[Q_{1}^{*} \otimes I d_{W}\right] \circ k_{V W}^{-1} \circ K \circ Q_{1} \circ g_{1}^{-1}\right) \\
& +\operatorname{Tr}_{V_{2} ; W}\left(\left[Q_{2}^{*} \otimes I d_{W}\right] \circ k_{V W}^{-1} \circ K \circ Q_{2} \circ g_{2}^{-1}\right) \\
= & \operatorname{Tr}_{V_{1} ; W}\left(k_{V_{1} W}^{-1} \circ \operatorname{Hom}\left(Q_{1}, I d_{W}\right) \circ K \circ Q_{1} \circ g_{1}^{-1}\right) \\
& +\operatorname{Tr}_{V_{2} ; W}\left(k_{V_{2} W}^{-1} \circ \operatorname{Hom}\left(Q_{2}, I d_{W}\right) \circ K \circ Q_{2} \circ g_{2}^{-1}\right)=R H S .
\end{aligned}
$$

### 4.4. Revisiting the generalized trace

We return to some notions introduced in Section 2.4. Recall, from Notation 2.66 , the map $\eta_{V}=s \circ k^{-1} \circ Q_{1}^{1}: \mathbb{K} \rightarrow V \otimes V^{*}$.

Notation 4.44. For finite-dimensional $V$, consider the following diagram.


The top block is from (2.9), and the commutativity of the back triangle and right block are easily checked. So, a map $\eta_{V U}: U \rightarrow V \otimes \operatorname{Hom}(V, U)$ can be defined by the following equal formulas:

$$
\begin{aligned}
\eta_{V U} & =\left[I d_{V} \otimes k_{V U}\right] \circ\left[\eta_{V} \otimes I d_{U}\right] \circ l_{U}^{-1} \\
& =n_{2}^{-1} \circ n_{1} \circ\left[Q_{1}^{1} \otimes I d_{U}\right] \circ l_{U}^{-1}: \\
u: & \mapsto n_{2}^{-1}\left(n_{1}\left(I d_{V} \otimes u\right)\right)
\end{aligned}
$$

With the above notation, Theorem 2.74 can be re-stated in terms of $\eta_{V U}$.
Corollary 4.45. For finite-dimensional $V, n_{2}$ as in the above diagram, any $F: V \otimes U \rightarrow V \otimes W$, and $u \in U$,

$$
\left(\operatorname{Tr}_{V ; U, W}(F)\right)(u)=\operatorname{Tr}_{V ; W}\left(F \circ\left(n_{2}\left(\eta_{V U}(u)\right)\right)\right)
$$

Proof. The following diagram is a modification of the diagram from the Proof of Theorem 2.74.


The diagram is commutative; the left blocks and lower middle triangle by the construction of $\eta_{V}$ and $\eta_{V U}$ in Notation 4.44, the upper middle triangle by Lemma 1.57, and the right block copied from the Proof of Theorem 2.74. The path from $U$ to $W$ along the top row is $\operatorname{Tr}_{V ; U, W}(F)$ by Theorem 2.67 , and equals the same composite map from $U$ to $W$ along the lower row, so

$$
\begin{align*}
\operatorname{Tr}_{V ; U, W}(F): u & \mapsto E v_{V W}\left(\left(n^{\prime}\right)^{-1}\left(F \circ\left(n_{2}\left(\eta_{V U}(u)\right)\right)\right)\right)  \tag{4.10}\\
& =\operatorname{Tr}_{V ; W}\left(F \circ\left(n_{2}\left(\eta_{V U}(u)\right)\right)\right) \\
& =\operatorname{Tr}_{V ; W}\left(F \circ\left(n_{1}\left(I d_{V} \otimes u\right)\right)\right)
\end{align*}
$$

The composition in (4.10) from the lower path in the diagram, or equivalently

$$
\begin{equation*}
\operatorname{Tr}_{V ; U, W}(F)=E v_{V W} \circ\left(n^{\prime}\right)^{-1} \circ \operatorname{Hom}\left(I d_{V}, F\right) \circ n_{2} \circ \eta_{V U}: U \rightarrow W \tag{4.11}
\end{equation*}
$$

has two interesting properties: it does not involve scalar multiplication or duals (except in the construction of $\eta_{V U}$ ), and the maps $\eta_{V U}$ and $E v_{V W}$ appear in symmetric roles.

EXERCISE 4.46. In the case $U=\mathbb{K}$, these maps are equal: $\eta_{V U}=\eta_{V \mathbb{K}}=\eta_{V}$.

The following pair of Theorems are analogues of Theorem 2.94; the idea is that $\eta_{V U}$ and $E v_{V W}$ satisfy identities analogous to the abstractly defined evaluation and coevaluation maps as in Definition 2.95. Theorem 4.48 uses the transpose for vector valued forms from Definition 4.2.

ThEOREM 4.47. For any $U$ and $V$, if $V$ is finite-dimensional, and $\eta_{V U}: U \rightarrow$ $V \otimes \operatorname{Hom}(V, U)$ is defined as in Notation 4.44, then the following composite is equal to a switching map:

$$
\left[I d_{V} \otimes E v_{V U}\right] \circ\left[\eta_{V U} \otimes I d_{V}\right]=s_{0}: U \otimes V \rightarrow V \otimes U
$$

Proof. The claim is analogous to the first identity from Theorem 2.94, and the proof is also analogous. The labeling $V=V_{1}=V_{2}=V_{3}$ is introduced to track the action of the switching $s$ maps. The upper and middle left squares are from the diagram from Notation 4.44. The claim is that the lower left triangle in the following diagram is commutative.


The commutativity of the right block is easy to check, where the switching map $s_{4}$ is as in Theorem 2.85 and Corollary 2.86. The composition starting at $U \otimes V$ in the lower left and going all the way around the diagram clockwise to $V \otimes U$ is the trace, as in Theorem 2.67, of $s_{4}^{-1}$, and the computation of Example 2.90 applies.

$$
\begin{aligned}
& {\left[I d_{V} \otimes E v_{V U}\right] \circ\left[\eta_{V U} \otimes I d_{V}\right] } \\
= & l_{V \otimes U} \circ\left[E v_{V} \otimes I d_{V \otimes U}\right] \circ\left[I d_{V *} \otimes s_{4}^{-1}\right] \circ\left[\left(k^{-1} \circ Q_{1}^{1}\right) \otimes I d_{U \otimes V}\right] \circ\left[l_{U}^{-1} \otimes I d_{V}\right] \\
= & \operatorname{Tr}_{V ; U \otimes V, V \otimes U}\left(s_{4}^{-1}\right)=s_{3}^{-1}=s_{0} .
\end{aligned}
$$

Theorem 4.48. For any $U$ and $V$, if $V$ is finite-dimensional, then the $n$ maps indicated in the following diagram are invertible,

and the diagram is commutative in the sense that this composite map is equal to the identity map:

$$
\operatorname{Hom}\left(I d_{V}, E v_{V U}\right) \circ n_{2} \circ\left[T_{V ; U} \otimes I d_{V}\right] \circ n_{1}^{-1} \circ \operatorname{Hom}\left(I d_{V}, \eta_{V U}\right)=I d_{\operatorname{Hom}(V, U)}
$$

Proof. The claim is analogous to the second identity from Theorem 2.94, and the overall proof is also analogous. As in the Proof of Theorem 4.47, the labeling $V=V_{1}=V_{2}=V_{3}$ is introduced to track the action of the $n, p$, and $s$ maps in this "main diagram."


The abbreviations $t_{V V}=t, k_{V V}=k, k_{V^{*} V^{*}}=k^{\prime}$, and the map $p$ are as in the notation from Lemma 2.5. The switching involution $s^{\prime \prime}$ appeared in Lemma 2.81. The composite $t \circ Q_{1}^{1}: \mathbb{K} \rightarrow \operatorname{End}\left(V^{*}\right)$ is equal to another inclusion, temporarily denoted $\tilde{Q}_{1}^{1}$, that maps 1 to $I d_{V^{*}}=I d_{V}^{*}=t\left(I d_{V}\right)$ as in Equation (2.4). So, the composition in the right column is the trace, as in Theorem 2.67, of $s_{4}$, and the
computation of Example 2.89 applies:

$$
\begin{aligned}
& l_{U \otimes V^{*}} \circ\left[E v_{V^{*}} \otimes I d_{U \otimes V^{*}}\right] \circ\left[I d_{V^{* *}} \otimes s_{4}\right] \circ\left[\left(\left(k^{\prime}\right)^{-1} \circ \tilde{Q}_{1}^{1}\right) \otimes I d_{V^{*} \otimes U}\right] \circ l_{V^{*} \otimes U}^{-1} \\
= & \operatorname{Tr}_{V ; V^{*} \otimes U, U \otimes V^{*}}\left(s_{4}\right)=s_{3}
\end{aligned}
$$

The $p, k$, and $n$ maps are invertible by the finite-dimensionality of $V$; in the right center block, the triangle with $k, t$, and $p$ is commutative by Lemma 1.69, and it is easy to check that the other triangle with $p^{\prime}$ is also commutative. The claim of the Theorem is that the composition in the left column gives the identity map; this will follow if we can find $a_{1}$ and $a_{2}$ as indicated that make the main diagram commutative.

The following maps, and $s_{1}$ in the above diagram, are from Lemma 4.10, in the case $V=V_{1}=V_{2}=V_{3}, U=W$ :

$$
\begin{aligned}
& a_{1}=\operatorname{Hom}\left(I d_{V},\left[I d_{V} \otimes k_{V U}\right]\right) \circ k_{V, V \otimes V^{*} \otimes U} \\
& a_{2}=\operatorname{Hom}\left(I d_{V},\left[k_{V U} \otimes I d_{V}\right]\right) \circ k_{V, V^{*} \otimes U \otimes V}
\end{aligned}
$$

The commutativity of the left center block then follows from Lemma 4.10, so to prove the Theorem it only remains to show that these maps $a_{1}, a_{2}$ make the upper and lower blocks of the main diagram commutative.

To check the lower block, start with $\psi \otimes \phi \otimes u \otimes v \in V^{*} \otimes V^{*} \otimes U \otimes V$ at its top, and $w \in V$.

$$
\begin{aligned}
& \operatorname{Hom}\left(I d_{V}, E v_{V U}\right) \circ \operatorname{Hom}\left(I d_{V},\left[k_{V U} \otimes I d_{V}\right]\right) \circ k_{V, V^{*} \otimes U \otimes V}: \\
\psi \otimes \phi \otimes u \otimes v & \mapsto E v_{V U} \circ\left[k_{V U} \otimes I d_{V}\right] \circ\left(k_{V, V^{*} \otimes U \otimes V}(\psi \otimes \phi \otimes u \otimes v)\right): \\
w \mapsto & \mapsto v_{V U}\left(\left[k_{V U} \otimes I d_{V}\right](\psi(w) \cdot \phi \otimes u \otimes v)\right) \\
= & E v_{V U}\left(\psi(w) \cdot\left(k_{V U}(\phi \otimes u)\right) \otimes v\right)=\psi(w) \cdot \phi(v) \cdot u, \\
& k_{V U} \circ s_{3}^{-1} \circ l_{U \otimes V^{*}} \circ\left[E v_{V^{*}} \otimes I d_{U \otimes V^{*}}\right] \circ\left[I d_{V^{* *}} \otimes s_{4}\right] \circ p^{\prime}: \\
\psi \otimes \phi \otimes u \otimes v \mapsto & \mapsto\left(k_{V U} \circ s_{3}^{-1} \circ l_{U \otimes V^{*}} \circ\left[E v_{V^{*}} \otimes I d_{U \otimes V^{*}}\right]\right)\left(\left(d_{V}(v)\right) \otimes \phi \otimes u \otimes \psi\right) \\
= & \left(k_{V U} \circ s_{3}^{-1}\right)(\phi(v) \cdot u \otimes \psi)=\phi(v) \cdot k_{V U}(\psi \otimes u): \\
w & \mapsto \phi(v) \cdot \psi(w) \cdot u .
\end{aligned}
$$

In the following diagram, the two lower right commutative squares are from the definition of $\eta_{V U}$.


To check the commutativity of the upper right block, start with $\phi \otimes v \otimes \psi \otimes u \in$ $V_{1}^{*} \otimes V_{3} \otimes V_{2}^{*} \otimes U$ and $w \in V:$

$$
\begin{aligned}
& \operatorname{Hom}\left(I d_{V},\left[k \otimes I d_{U}\right]\right) \circ \operatorname{Hom}\left(I d_{V},\left[s^{-1} \otimes I d_{U}\right]\right) \circ k_{V, V \otimes V^{*} \otimes U}: \\
\phi \otimes v \otimes \psi \otimes u \mapsto & {\left[\left(k \circ s^{-1}\right) \otimes I d_{U}\right] \circ\left(k_{V, V \otimes V^{*} \otimes U}(\phi \otimes v \otimes \psi \otimes u)\right): } \\
w \mapsto & {\left[\left(k \circ s^{-1}\right) \otimes I d_{U}\right](\phi(w) \cdot v \otimes \psi \otimes u)=\phi(w) \cdot(k(\psi \otimes v)) \otimes u } \\
& k_{V, \operatorname{End}(V) \otimes U} \circ\left[s_{5} \otimes I d_{U}\right] \circ\left[k \otimes I d_{V^{*} \otimes U}\right] \circ\left[s^{\prime \prime} \otimes I d_{U}\right]: \\
\phi \otimes v \otimes \psi \otimes u \mapsto & k_{V, \operatorname{End}(V) \otimes U}(\phi \otimes(k(\psi \otimes v)) \otimes u): \\
w \mapsto & \mapsto(w) \cdot(k(\psi \otimes v)) \otimes u .
\end{aligned}
$$

To check the commutativity of the left block, start with $\alpha \otimes \phi \otimes u \in \mathbb{K} \otimes V^{*} \otimes U$ :

$$
\begin{aligned}
& k_{V, \operatorname{End}(V) \otimes U} \circ\left[s_{5} \otimes I d_{U}\right] \circ\left[Q_{1}^{1} \otimes I d_{V^{*} \otimes U}\right]: \\
\alpha \otimes \phi \otimes u \mapsto & k_{V, \operatorname{End}(V) \otimes U}\left(\phi \otimes\left(\alpha \cdot I d_{V}\right) \otimes u\right): \\
v \mapsto & \mapsto(v)) \cdot\left(\alpha \cdot I d_{V}\right) \otimes u \\
& \operatorname{Hom}\left(I d_{V},\left[Q_{1}^{1} \otimes I d_{U}\right]\right) \circ \operatorname{Hom}\left(I d_{V}, l_{U}^{-1}\right) \circ k_{V U} \circ l_{V^{*} \otimes U}: \\
\alpha \otimes \phi \otimes u \mapsto & {\left[Q_{1}^{1} \otimes I d_{U}\right] \circ l_{U}^{-1} \circ\left(k_{V U}(\alpha \cdot \phi \otimes u)\right): } \\
v \mapsto & \mapsto \cdot \phi(v)) \cdot I d_{V} \otimes u
\end{aligned}
$$

The downward composite of the four arrows in the right column equals the previously defined $a_{1}$. So, the above calculation is enough to establish the commutativity of the top block in the main diagram:

$$
\operatorname{Hom}\left(I d_{V}, \eta_{V U}\right) \circ k_{V U}=a_{1} \circ\left[\left(s^{\prime \prime}\right)^{-1} \otimes I d_{U}\right] \circ\left[\left(k^{-1} \circ Q_{1}^{1}\right) \otimes I d_{V^{*} \otimes U}\right] \circ l_{V^{*} \otimes U}^{-1}
$$

As mentioned earlier, this proves the claim of the Theorem.

### 4.5. Topics and applications

### 4.5.1. Quadratic forms.

Proposition 4.49. Given vector spaces $V, W$, and a function $\mathfrak{q}: V \rightsquigarrow W$, if $\frac{1}{2} \in \mathbb{K}$ then the following are equivalent.
(1) There exists a symmetric $W$-valued form $h_{1}: V \rightarrow \operatorname{Hom}(V, W)$ such that for all $v \in V$,

$$
\mathfrak{q}(v)=\left(h_{1}(v)\right)(v)
$$

(2) There exists a $W$-valued bilinear form $h_{2}: V \rightarrow \operatorname{Hom}(V, W)$ such that for all $v \in V$,

$$
\mathfrak{q}(v)=\left(h_{2}(v)\right)(v)
$$

(3) There exists a bilinear function $B_{1}: V \times V \rightsquigarrow W$ such that for all $v \in V$,

$$
\mathfrak{q}(v)=B_{1}(v, v)
$$

(4) For any $\alpha \in \mathbb{K}$ and $v \in V, \mathfrak{q}(\alpha \cdot v)=\alpha^{2} \cdot \mathfrak{q}(v)$, and the function $B_{2}$ : $V \times V \rightsquigarrow W$ defined by

$$
B_{2}(u, v)=\mathfrak{q}(u+v)-\mathfrak{q}(u)-\mathfrak{q}(v)
$$

is bilinear.
(5) For any $\alpha \in \mathbb{K}$ and $v \in V, \mathfrak{q}(\alpha \cdot v)=\alpha^{2} \cdot \mathfrak{q}(v)$, and the function $B_{3}$ : $V \times V \rightsquigarrow W$ defined by

$$
B_{3}(u, v)=\mathfrak{q}(u)+\mathfrak{q}(v)-\mathfrak{q}(u-v)
$$

is bilinear.
(6) For any $\alpha \in \mathbb{K}$ and $v \in V, \mathfrak{q}(\alpha \cdot v)=\alpha^{2} \cdot \mathfrak{q}(v)$, and the function $B_{4}$ : $V \times V \rightsquigarrow W$ defined by

$$
B_{4}(u, v)=\mathfrak{q}(u+v)-\mathfrak{q}(u-v)
$$

is bilinear.
(7) For all $u, v \in V, \mathfrak{q}$ satisfies:

$$
\begin{equation*}
\mathfrak{q}(u+v)+\mathfrak{q}(u-v)=2 \cdot \mathfrak{q}(u)+2 \cdot \mathfrak{q}(v) \tag{4.12}
\end{equation*}
$$

and the function $B_{4}: V \times V \rightsquigarrow W$ defined by

$$
B_{4}(u, v)=\mathfrak{q}(u+v)-\mathfrak{q}(u-v)
$$

satsifies, for all $\alpha \in \mathbb{K}, B_{4}(\alpha \cdot u, v)=\alpha \cdot B_{4}(u, v)$.
Proof. As in Notation 0.36, the $\rightsquigarrow$ arrow symbol refers to functions which are not necessarily linear. The functions $B_{1}, \ldots, B_{4}$ are bilinear as in Definition 1.22.

The implication (1) $\Longrightarrow(2)$ is trivial. For (2) $\Longrightarrow$ (3), define $B_{1}$ by $B_{1}(u, v)=\left(h_{2}(u)\right)(v)$, and similarly for $(3) \Longrightarrow(2)$, define $h_{2}$ by the formula $h_{2}(u): v \mapsto B_{1}(u, v)$. The correspondence between $h_{2}$ and $B_{1}$ is a $W$-valued version of the construction from Example 1.50.

Now, assuming (3), so that $B_{1}$ is bilinear and $\mathfrak{q}(v)=B_{1}(v, v)$, the first property from (4), (5) and (6) is immediate:

$$
\mathfrak{q}(\alpha \cdot v)=B_{1}(\alpha \cdot v, \alpha \cdot v)=\alpha^{2} \cdot B_{1}(v, v)=\alpha^{2} \cdot \mathfrak{q}(v) .
$$

Expanding $B_{2}, B_{3}, B_{4}$ in terms of $B_{1}$ :

$$
\begin{aligned}
B_{2}(u, v) & =\mathfrak{q}(u+v)-\mathfrak{q}(u)-\mathfrak{q}(v) \\
& =B_{1}(u+v, u+v)-B_{1}(u, u)-B_{1}(v, v) \\
& =B_{1}(u, v)+B_{1}(v, u) \\
B_{3}(u, v) & =\mathfrak{q}(u)+\mathfrak{q}(v)-\mathfrak{q}(u-v) \\
& =B_{1}(u, u)+B_{1}(v, v)-B_{1}(u-v, u-v) \\
& =B_{1}(u, v)+B_{1}(v, u) \\
B_{4}(u, v) & =\mathfrak{q}(u+v)-\mathfrak{q}(u-v) \\
& =B_{1}(u+v, u+v)-B_{1}(u-v, u-v) \\
& =B_{1}(u, v)+B_{1}(v, u)+B_{1}(u, v)+B_{1}(v, u)
\end{aligned}
$$

The bilinearity of $B_{1}$ implies the bilinearity of $B_{1}(u, v)+B_{1}(v, u)$, so (3) implies (4), (5), and (6). The relation $B_{4}=B_{2}+B_{3}$ also shows that any two of (4), (5), and (6) together imply the third.

For $(3) \Longrightarrow(7)$, expanding (4.12) in terms of $B_{1}$ shows $L H S=R H S$ (a related quantity already appeared in Proposition 3.124), and $B_{4}$ is bilinear as in (4.13).

So far, the implications have not yet used $\frac{1}{2} \in \mathbb{K}$. To show $(6) \Longrightarrow(3)$, given the bilinear form $B_{4}$, define $B_{1}(u, v)=\left(\frac{1}{2}\right)^{2} \cdot B_{4}(u, v)$, so that $B_{1}$ is bilinear, and for any $v \in V$,

$$
\begin{align*}
B_{1}(v, v) & =\left(\frac{1}{2}\right)^{2} \cdot(\mathfrak{q}(v+v)-\mathfrak{q}(v-v)) \\
& =\left(\frac{1}{2}\right)^{2} \cdot(\mathfrak{q}((1+1) \cdot v)-\mathfrak{q}(0 \cdot v)) \\
& =\left(\frac{1}{2}\right)^{2} \cdot\left((1+1)^{2} \cdot \mathfrak{q}(v)-0^{2} \cdot \mathfrak{q}(v)\right)=\mathfrak{q}(v) \tag{4.14}
\end{align*}
$$

Similar calculations using $\frac{1}{2} \in \mathbb{K}$ would directly show $(4) \Longrightarrow(3)$ and $(5) \Longrightarrow$ (3).
For $(7) \Longrightarrow(3)$, Equation (4.12) with $u=v=0_{V}$ gives $\mathfrak{q}\left(0_{V}\right)=0_{W}$, and with $u=0_{V}$ gives $\mathfrak{q}(-v)=\mathfrak{q}(v)$. Then

$$
B_{4}(v, u)=\mathfrak{q}(v+u)-\mathfrak{q}(v-u)=\mathfrak{q}(v+u)-\mathfrak{q}(u-v)=B_{4}(u, v)
$$

It follows that $B_{4}(u, \alpha \cdot v)=B_{4}(\alpha \cdot v, u)=\alpha \cdot B_{4}(v, u)=\alpha \cdot B_{4}(u, v)$. The following calculation shows that $2 \cdot B_{4}$ is additive in the first entry, using (4.12) in steps (4.16)
and (4.18) and some add-and-subtract steps in (4.15) and (4.17).

$$
\begin{aligned}
& 2 \cdot B_{4}\left(u_{1}+u_{2}, v\right) \\
= & 2 \cdot \mathfrak{q}\left(u_{1}+u_{2}+v\right)-2 \cdot \mathfrak{q}\left(u_{1}+u_{2}-v\right) \\
= & 2 \cdot \mathfrak{q}\left(u_{1}+u_{2}+v\right)+2 \cdot \mathfrak{q}\left(u_{1}-v\right)-2 \cdot \mathfrak{q}\left(u_{1}+u_{2}-v\right)-2 \cdot \mathfrak{q}\left(u_{1}+v\right) \\
& +2 \cdot \mathfrak{q}\left(u_{1}+v\right)-2 \cdot \mathfrak{q}\left(u_{1}-v\right) \\
= & \mathfrak{q}\left(2 \cdot u_{1}+u_{2}\right)+\mathfrak{q}\left(u_{2}+2 \cdot v\right)-\mathfrak{q}\left(2 \cdot u_{1}+u_{2}\right)-\mathfrak{q}\left(u_{2}-2 \cdot v\right) \\
& +2 \cdot \mathfrak{q}\left(u_{1}+v\right)-2 \cdot \mathfrak{q}\left(u_{1}-v\right) \\
= & \mathfrak{q}\left(u_{2}+2 \cdot v\right)+\mathfrak{q}\left(u_{2}\right)-\mathfrak{q}\left(u_{2}-2 \cdot v\right)-\mathfrak{q}\left(u_{2}\right) \\
& +2 \cdot \mathfrak{q}\left(u_{1}+v\right)-2 \cdot \mathfrak{q}\left(u_{1}-v\right) \\
= & 2 \cdot \mathfrak{q}\left(u_{2}+v\right)+2 \cdot \mathfrak{q}(v)-2 \cdot \mathfrak{q}\left(u_{2}-v\right)-2 \cdot \mathfrak{q}(-v) \\
& +2 \cdot \mathfrak{q}\left(u_{1}+v\right)-2 \cdot \mathfrak{q}\left(u_{1}-v\right) \\
= & 2 \cdot B_{4}\left(u_{1}, v\right)+2 \cdot B_{4}\left(u_{2}, v\right) .
\end{aligned}
$$

By symmetry again, $2 \cdot B_{4}$ is bilinear, and so is $B_{1}=\left(\frac{1}{2}\right)^{2} \cdot B_{4}$. The following calculation establishing (3) using (4.12) is different from (4.14):

$$
\begin{aligned}
B_{1}(v, v) & =\left(\frac{1}{2}\right)^{2} \cdot(\mathfrak{q}(v+v)-\mathfrak{q}(v-v)) \\
& =\left(\frac{1}{2}\right)^{2} \cdot(\mathfrak{q}(v+v)+\mathfrak{q}(v-v)) \\
& =\left(\frac{1}{2}\right)^{2} \cdot(2 \cdot \mathfrak{q}(v)+2 \cdot \mathfrak{q}(v))=\mathfrak{q}(v)
\end{aligned}
$$

Finally, to show $(2) \Longrightarrow$ (1) using $\frac{1}{2} \in \mathbb{K}$, let $h_{1}$ be the symmetric part of $h_{2}$ as in (3.2) and (4.7):

$$
\begin{aligned}
\left(h_{1}(u)\right)(v) & =\frac{1}{2} \cdot\left(\left(h_{2}(u)\right)(v)+\left(h_{2}(v)\right)(u)\right) \\
\Longrightarrow\left(h_{1}(v)\right)(v) & =\frac{1}{2} \cdot(\mathfrak{q}(v)+\mathfrak{q}(v))=\mathfrak{q}(v) .
\end{aligned}
$$

Definition 4.50. Assuming $\frac{1}{2} \in \mathbb{K}$, a function $\mathfrak{q}: V \rightsquigarrow W$ satisfying any of the equivalent properties from Proposition 4.49 is a $W$-valued quadratic form.

Remark 4.51. The equations from (4), (5), and (6) are known as polarization formulas. Equation (4.12) from (7) is the parallelogram law for $\mathfrak{q}$. The case where $\frac{1}{2} \notin \mathbb{K}$ is more complicated and not considered here; the remaining statements here in Section 4.5 . 1 will all assume $\frac{1}{2} \in \mathbb{K}$.

EXERCISE 4.52. Given a quadratic form $\mathfrak{q}$, the symmetric form $h_{1}$ from Proposition 4.49 is unique.

Hint. This is a statement about symmetric forms rather than quadratic forms: the claim is that if $h_{0}$ and $h_{1}$ are both symmetric forms and $\left(h_{0}(v)\right)(v)=\left(h_{1}(v)\right)(v)$ for all $v \in V$, then $h_{0}=h_{1}$. The hint is to expand $\left(h_{0}(u+v)\right)(u+v)$ and use $\frac{1}{2} \in \mathbb{K}$.

Exercise 4.53. The set $\mathfrak{Q}(V ; W)$ of $W$-valued quadratic forms on $V$ is a vector space. The map $\mathfrak{f}_{V W}$ defined by $\mathfrak{f}_{V W}: \mathfrak{Q}(V ; W) \rightarrow \operatorname{Sym}(V ; W): \mathfrak{q} \mapsto h_{1}$ as in Exercise 4.52 is linear and invertible.

Hint. $\mathfrak{Q}(V ; W)$ is a subspace of $\mathcal{F}(V, W)$ as in Example 6.28.
Definition 4.54. For vector spaces $U, V, W$, define a linear map $\mathfrak{t}_{U V}^{W}$ by:

$$
\begin{aligned}
\mathfrak{t}_{U V}^{W}: \operatorname{Hom}(U, V) & \rightarrow \operatorname{Hom}(\mathfrak{Q}(V ; W), \mathfrak{Q}(U ; W)) \\
H & \mapsto(\mathfrak{q} \mapsto \mathfrak{q} \circ H)
\end{aligned}
$$

Exercise 4.55. There are a few things to check in Definition 4.54: first, that for $H: U \rightarrow V$, the composite $\mathfrak{q} \circ H$ is a quadratic form, second, that $\mathfrak{t}_{U V}^{W}(H)$ is linear, and third, that $\mathfrak{t}_{U V}^{W}$ is linear. Further, the following diagram is commutative.


The middle horizontal arrow is the map induced by $\operatorname{Hom}\left(H, \operatorname{Hom}\left(H, I d_{W}\right)\right)$ as in Lemma 4.17.

Hint. The linearity of $\mathfrak{t}_{U V}^{W}(H)$ can be checked directly, but also follows from the commutativity of the upper block in the diagram. It is enough to check the commutativity of the large block from upper left to lower right; temporarily denote the left inclusion $Q_{V}$ and the right inclusion $Q_{U}$. For $\mathfrak{q}$ with $\mathfrak{f}_{V W}(\mathfrak{q})=h_{1}$,

$$
\begin{align*}
& \operatorname{Hom}\left(H, I d_{W}\right) \circ\left(Q_{V}\left(\mathfrak{f}_{V W}(\mathfrak{q})\right)\right) \circ H: v \mapsto \\
& u \mapsto\left(h_{1}(H(v))\right) \circ H:  \tag{4.19}\\
& \mapsto\left(h_{1}(H(v))\right)(H(u)) .
\end{align*}
$$

Then $Q_{U} \circ \mathfrak{f}_{U W} \circ\left(\mathfrak{t}_{U V}^{W}(H)\right): \mathfrak{q} \mapsto Q_{U}\left(\mathfrak{f}_{U W}(\mathfrak{q} \circ H)\right)=h_{0}$ is the unique $W$-valued bilinear form that is symmetric and that has the property $(\mathfrak{q} \circ H)(u)=\left(h_{0}(u)\right)(u)$. However, $\mathfrak{q}(H(u))=\left(h_{1}(H(u))\right)(H(u))$, so $\operatorname{Hom}\left(H, \operatorname{Hom}\left(H, I d_{W}\right)\right)\left(Q_{V}\left(h_{1}\right)\right)$ from (4.19) has both these properties and is equal to $h_{0}$ by uniqueness, proving the commutativity of the diagram.

Exercise 4.56. $\mathfrak{t}_{V V}^{W}\left(I d_{V}\right)=I d_{\mathfrak{Q}}(V ; W)$. For $H: U \rightarrow V$ and $A: V \rightarrow X$,

$$
\mathfrak{t}_{U X}^{W}(A \circ H)=\mathfrak{t}_{U V}^{W}(H) \circ \mathfrak{t}_{V X}^{W}(A)
$$

In particular, if $H$ has a linear left (or right) inverse, then $\mathfrak{t}_{U V}^{W}(H)$ has a linear right (or left) inverse.

Proposition 4.57. ([HK] §10.2) Suppose $U$ is finite-dimensional and $W \neq$ $\left\{0_{W}\right\}$. For $H: U \rightarrow U$, the following are equivalent.
(1) $\mathfrak{t}_{U U}^{W}(H): \mathfrak{Q}(U ; W) \rightarrow \mathfrak{Q}(U ; W)$ is one-to-one.
(2) $H$ is invertible.

Proof. The $(2) \Longrightarrow$ (1) direction follows from Exercise 4.56 .
For the other direction, suppose, contrapositively, that $H$ is not invertible; then by Lemma 1.18 (which uses the finite-dimensional property of $U$ ), $H^{*}: U^{*} \rightarrow U^{*}$ is not invertible. By Claim 0.50 (using the finite-dimensional property of $U^{*}$ ), $H^{*}$ is not one-to-one and there exists $\phi \in U^{*}$ so that $\phi \neq 0_{U^{*}}$ and $H^{*}(\phi)=\phi \circ H=0_{U^{*}}$. Pick any $w \in W$ with $w \neq 0_{W}$, and define a bilinear form

$$
g=k_{U, \operatorname{Hom}(U, W)}\left(\phi \otimes\left(k_{U W}(\phi \otimes w)\right)\right) \in \operatorname{Hom}(U, \operatorname{Hom}(U, W)) .
$$

$g \neq 0_{\operatorname{Hom}(U, \operatorname{Hom}(U, W))}$ because there is some $x \in U$ with $\phi(x) \neq 0$, and

$$
(g(x))(x)=\left(\phi(x) \cdot k_{U W}(\phi \otimes w)\right)(x)=\phi(x) \cdot \phi(x) \cdot w \neq 0_{W}
$$

Also, $g$ is symmetric:

$$
\begin{aligned}
& \left(g\left(v_{1}\right)\right)\left(v_{2}\right)=\left(\phi\left(v_{1}\right) \cdot k_{U W}(\phi \otimes w)\right)\left(v_{2}\right)=\phi\left(v_{1}\right) \cdot \phi\left(v_{2}\right) \cdot w \\
& \left(g\left(v_{2}\right)\right)\left(v_{1}\right)=\left(\phi\left(v_{2}\right) \cdot k_{U W}(\phi \otimes w)\right)\left(v_{1}\right)=\phi\left(v_{2}\right) \cdot \phi\left(v_{1}\right) \cdot w
\end{aligned}
$$

$\mathfrak{q}=\mathfrak{f}_{U W}^{-1}(g)$ is the quadratic form $\mathfrak{q}(v)=\phi(v) \cdot \phi(v) \cdot w$, and again using $v=x$, $\mathfrak{q} \neq 0_{\mathfrak{Q}}(U ; W)$.

However, $\mathfrak{t}_{U U}^{W}(H): \mathfrak{q} \mapsto \mathfrak{q} \circ H$, and for any $u \in U$,

$$
(\mathfrak{q} \circ H)(u)=\mathfrak{q}(H(u))=\phi(H(u)) \cdot \phi(H(u)) \cdot w=0 \cdot 0 \cdot w=0_{W} .
$$

So $\mathfrak{q} \circ H=0_{\mathfrak{Q}}(U ; W)$, and $\mathfrak{t}_{U U}^{W}(H)$ is not one-to-one.

### 4.5.2. Algebras.

Definition 4.58. A vector space $V$ together with a $V$-valued bilinear form $h: V \rightarrow \operatorname{End}(V)$ is an algebra $(V, h)$.

Definition 4.59. For any algebra $(V, h)$ with $V$ finite-dimensional, the canonical metric $\left(k^{*}\right)^{-1} \circ e$ on $\operatorname{End}(V)$ from Example 3.142 (and Equation (3.15)) pulls back by $h$ to give a scalar bilinear form on $V$, the Cartan-Killing form

$$
\kappa=h^{*} \circ\left(k^{*}\right)^{-1} \circ e \circ h: v \mapsto \kappa(v): u \mapsto \operatorname{Tr}_{V}((h(v)) \circ(h(u))) .
$$

The CK form $\kappa$ is symmetric by Lemma 4.17 (or Lemma 3.8 or Lemma 2.6), but is not necessarily a metric on $V$.

Theorem 4.60. Given an algebra $(V, h)$, suppose $Q: U \rightarrow V$ satisfies, for any $u \in U, v \in V$,

$$
\begin{equation*}
(h(Q(u)))(v) \in Q(U) \tag{4.20}
\end{equation*}
$$

If $Q$ is one-to-one, then for any left inverse of $Q, P: V \rightsquigarrow U$,

$$
\begin{equation*}
h_{1}: U \rightarrow \operatorname{End}(U): u \mapsto P \circ(h(Q(u))) \circ Q \tag{4.21}
\end{equation*}
$$

defines an algebra $\left(U, h_{1}\right)$, and $h_{1}$ does not depend on the choice of $P$. If, further, $V$ is finite-dimensional, with $C K$ form $\kappa$, then the $C K$ form $\kappa_{1}$ of $\left(U, h_{1}\right)$ is the pullback of $\kappa$ by $Q$.

Proof. Using $P \circ Q=I d_{U}$ and the property (4.20), for any $u \in U$ and $v \in V$,

$$
\begin{align*}
(h(Q(u)))(v) & \in Q(U) \\
\Longrightarrow Q(P((h(Q(u)))(v))) & =(h(Q(u)))(v), \\
\Longrightarrow Q \circ P \circ(h(Q(u))) & =h(Q(u)) . \tag{4.22}
\end{align*}
$$

Note that if $P^{\prime}: V \rightsquigarrow U$ is any other (not necessarily linear) left inverse of $Q$, then composing $P^{\prime}$ with both sides of (4.22) gives, for all $u \in U$ :

$$
P \circ(h(Q(u)))=P^{\prime} \circ(h(Q(u))),
$$

so the expression (4.21) does not depend on the choice of $P$ and defines $h_{1}$ uniquely. Further, because $h(Q(u)) \in \operatorname{End}(V)$ has image contained in $Q(U)$ by (4.20), the composite $P \circ(h(Q(u))): V \rightarrow U$ is linear by Exercise 0.45 , which justifies the use of $\operatorname{End}(U)$ as the target space in (4.21). It remains to check that $h_{1}$ is linear; for $u_{1}, u_{2}, u_{3} \in U$,

$$
\begin{align*}
h_{1}\left(u_{1}+u_{2}\right) & =P \circ\left(h\left(Q\left(u_{1}+u_{2}\right)\right)\right) \circ Q \\
& =P \circ\left(h\left(Q\left(u_{1}\right)\right)+h\left(Q\left(u_{2}\right)\right)\right) \circ Q: \\
u_{3} & \mapsto P\left(\left(h\left(Q\left(u_{1}\right)\right)\right)\left(Q\left(u_{3}\right)\right)+\left(h\left(Q\left(u_{2}\right)\right)\right)\left(Q\left(u_{3}\right)\right)\right) \\
& =P\left(\left(h\left(Q\left(u_{1}\right)\right)\right)\left(Q\left(u_{3}\right)\right)\right)+P\left(\left(h\left(Q\left(u_{2}\right)\right)\right)\left(Q\left(u_{3}\right)\right)\right),  \tag{4.23}\\
& =\left(h_{1}\left(u_{1}\right)+h_{1}\left(u_{2}\right)\right)\left(u_{3}\right) .
\end{align*}
$$

where step (4.23) is from Equation (0.1) in Exercise 0.45. The scaling property for $h_{1}$ similarly follows from Exercise 0.45 . The conclusion is that if $Q: U \rightarrow V$ is one-to-one, then some left inverse exists (as in Exercise 0.43 ) and ( $U, h_{1}$ ) is an algebra as claimed. If $P$ is a linear left inverse, then the expression (4.21) can be denoted $h_{1}=\operatorname{Hom}(Q, P) \circ h \circ Q$.

For finite-dimensional $V, U$ is also finite-dimensional (Exercise 0.44). The CK form on $U$ can be computed for $u_{1}, u_{2} \in U$, using the linearity of the composites $P \circ\left(h\left(Q\left(u_{1}\right)\right)\right)$ and $P \circ\left(h\left(Q\left(u_{2}\right)\right)\right)$ so that Lemma 2.6 applies in step (4.24), and using Equation (4.22) in step (4.25):

$$
\begin{align*}
\left(\kappa_{1}\left(u_{1}\right)\right)\left(u_{2}\right) & =\operatorname{Tr}_{U}\left(\left(P \circ\left(h\left(Q\left(u_{1}\right)\right)\right) \circ Q\right) \circ\left(P \circ\left(h\left(Q\left(u_{2}\right)\right)\right) \circ Q\right)\right) \\
& =\operatorname{Tr}_{V}\left(\left(Q \circ P \circ\left(h\left(Q\left(u_{1}\right)\right)\right)\right) \circ\left(Q \circ P \circ\left(h\left(Q\left(u_{2}\right)\right)\right)\right)\right)  \tag{4.24}\\
& =\operatorname{Tr}_{V}\left(\left(h\left(Q\left(u_{1}\right)\right)\right) \circ\left(h\left(Q\left(u_{2}\right)\right)\right)\right)  \tag{4.25}\\
& =\left(\left(Q^{*} \circ \kappa \circ Q\right)\left(u_{1}\right)\right)\left(u_{2}\right) .
\end{align*}
$$

In particular, $\kappa_{1}=Q^{*} \circ \kappa \circ Q$ also does not depend on $P$.
Remark 4.61. The above property (4.20) represents the notion of an ideal of the algebra $(V, h)$. The next Theorem describes an algebra which is a direct sum of ideals.

THEOREM 4.62. Given an algebra $(V, h)$, suppose there is a direct sum $V=U_{1} \oplus$ $U_{2}$, with projections $\left(P_{1}, P_{2}\right)$ and inclusions $\left(Q_{1}, Q_{2}\right)$. The following are equivalent.
(1) $h$ respects the direct sums

$$
U_{1} \oplus U_{2} \rightarrow \operatorname{Hom}\left(V, U_{1}\right) \oplus \operatorname{Hom}\left(V, U_{2}\right)
$$

(2) For both $i=1,2$, and all $u \in U_{i}, v \in V$,

$$
\left(h\left(Q_{i}(u)\right)\right)(v) \in Q_{i}\left(U_{i}\right)
$$

Proof. In (1), the direct sum is as in Example 1.76, so the assumption is

$$
h \circ Q_{i} \circ P_{i}=\operatorname{Hom}\left(I d_{V}, Q_{i}\right) \circ \operatorname{Hom}\left(I d_{V}, P_{i}\right) \circ h
$$

For any $u \in U_{i}, v \in V$,

$$
\begin{aligned}
h\left(Q_{i}(u)\right) & =h\left(Q_{i}\left(P_{i}\left(Q_{i}(u)\right)\right)\right) \\
& =Q_{i} \circ P_{i} \circ\left(h\left(Q_{i}(u)\right)\right): \\
v & \mapsto Q_{i}\left(P_{i}\left(\left(h\left(Q_{i}(u)\right)\right)(v)\right)\right) \in Q_{i}\left(U_{i}\right),
\end{aligned}
$$

so $(1) \Longrightarrow(2)$. Conversely, assuming (2), for $u \in U_{i}, v \in V$, and different indices $i \neq I$,

$$
\begin{aligned}
\left(h\left(Q_{i}(u)\right)\right)(v) & \in Q_{i}\left(U_{i}\right) \\
\Longrightarrow\left(h\left(Q_{i}(u)\right)\right)(v) & =Q_{i}\left(P_{i}\left(\left(h\left(Q_{i}(u)\right)\right)(v)\right)\right) \\
\Longrightarrow h\left(Q_{i}(u)\right) & =Q_{i} \circ P_{i} \circ\left(h\left(Q_{i}(u)\right)\right) \\
\Longrightarrow h \circ Q_{i} & =\operatorname{Hom}\left(I d_{V}, Q_{i} \circ P_{i}\right) \circ h \circ Q_{i} \\
\Longrightarrow \operatorname{Hom}\left(I d_{V}, P_{I}\right) \circ h \circ Q_{i} & =\operatorname{Hom}\left(I d_{V}, P_{I}\right) \circ \operatorname{Hom}\left(I d_{V}, Q_{i} \circ P_{i}\right) \circ h \circ Q_{i} \\
& =0_{\operatorname{Hom}\left(U_{i}, \operatorname{Hom}\left(V, U_{I}\right)\right)},
\end{aligned}
$$

so by Lemma $1.81, h$ respects the direct sums as in (1).
For a direct sum as in Theorem 4.62, Theorem 4.60 applies, so that each $U_{i}$ has an algebra structure $\left(U_{i}, h_{i}\right)$, and if $V$ is finite-dimensional, then each ( $U_{i}, h_{i}$ ) has CK form $\kappa_{i}=Q_{i}^{*} \circ \kappa \circ Q_{i}$.

Theorem 4.63. For an algebra $(V, h)$, the following are equivalent.
(1) For all $u, v, w \in V$,

$$
(h(u))((h(v))(w))=(h((h(u))(v)))(w)
$$

(2) For any $u \in V$, this diagram is commutative.


Proof. (1) is equivalent to: for all $u, v$,

$$
(h(u)) \circ(h(v))=h((h(u))(v)),
$$

which is equivalent to $\operatorname{Hom}\left(I d_{V}, h(u)\right) \circ h=h \circ(h(u))$ for all $u$, which is (2).
Definition 4.64. An algebra $(V, h)$ satisfying either equivalent property from Theorem 4.63 is an associative algebra.

Example 4.65. The generalized transpose from Definition 1.7 and Example 1.48,

$$
t_{V V}^{V}: \operatorname{End}(V) \rightarrow \operatorname{End}(\operatorname{End}(V)): A \mapsto \operatorname{Hom}\left(A, I d_{V}\right): B \mapsto B \circ A
$$

defines an associative algebra $\left(\operatorname{End}(V), t_{V V}^{V}\right)$. Using Corollary 2.37,

$$
\begin{aligned}
(\kappa(A))(B) & =\operatorname{Tr}_{\operatorname{End}(V)}\left(\left(t_{V V}^{V}(A)\right) \circ\left(t_{V V}^{V}(B)\right)\right) \\
& =\operatorname{Tr}_{\operatorname{End}(V)}\left(\operatorname{Hom}\left(A, I d_{V}\right) \circ \operatorname{Hom}\left(B, I d_{V}\right)\right) \\
& =\operatorname{Tr}_{\operatorname{End}(V)}\left(\operatorname{Hom}\left(B \circ A, I d_{V}\right)\right) \\
& =\operatorname{Tr}_{V}(B \circ A) \cdot \operatorname{Tr}_{V}\left(I d_{V}\right)
\end{aligned}
$$

so the form $\kappa$ for the algebra $\left(\operatorname{End}(V), t_{V V}^{V}\right)$ is a scalar multiple of the canonical metric from Example 3.142.

Definition 4.66. For any vector space $V$, define the linear map $a d$,

$$
\begin{aligned}
a d: \operatorname{End}(V) & \rightarrow \operatorname{End}(\operatorname{End}(V)): \\
A & \mapsto \operatorname{Hom}\left(I d_{V}, A\right)-\operatorname{Hom}\left(A, I d_{V}\right): \\
B & \mapsto A \circ B-B \circ A .
\end{aligned}
$$

Theorem 4.67. For an algebra $(V, h)$, if $h$ is antisymmetric then the following are equivalent.
(1) For all $u, v, w \in V$,

$$
(h((h(v))(w)))(u)+(h((h(w))(u)))(v)+(h((h(u))(v)))(w)=0_{V}
$$

(2) For any $v \in V$, this diagram is commutative.


Proof. The first property is the Jacobi identity for $h$. In (2), the map ad : $\operatorname{End}(V) \rightarrow \operatorname{End}(\operatorname{End}(V))$ is as in Definition 4.66. Using the antisymmetric property, (1) is equivalent to

$$
(h((h(v))(w)))(u)=(h(v))((h(w))(u))-(h(w))((h(v))(u))
$$

for all $u, v, w$, which is equivalent to, for all $v, w$,

$$
\begin{aligned}
h((h(v))(w)) & =(h(v)) \circ(h(w))-(h(w)) \circ(h(v)) \\
& =(\operatorname{ad}(h(v)))(h(w)) .
\end{aligned}
$$

This is equivalent to $h \circ(h(v))=(a d(h(v))) \circ h$ for all $v$, which is (2).
Definition 4.68. An algebra ( $V, h$ ) with $h$ antisymmetric and satisfying either equivalent property from Theorem 4.67 is a Lie algebra.

Exercise 4.69. If $\frac{1}{2} \in \mathbb{K}$ and $h: V \rightarrow \operatorname{End}(V)$ satisfies (1) from Theorem 4.63, then its antisymmetric part $\frac{1}{2}\left(h-T_{V ; V}(h)\right)$ from (4.8) satisfies (1) from Theorem 4.67. Similarly, $h-T_{V ; V}(h)$ satisfies the Jacobi identity even without assuming $\frac{1}{2} \in \mathbb{K}$. So for any associative algebra $(V, h)$, there is a Lie algebra $\left(V, h-T_{V ; V}(h)\right)$.

Example 4.70. $(\operatorname{End}(V), a d)$ is a Lie algebra. This uses the construction of Exercise 4.69 applied to $\left(\operatorname{End}(V), t_{V V}^{V}\right)$ from Example 4.65, although with the opposite sign, so that $a d=T_{V ; V}\left(t_{V V}^{V}\right)-t_{V V}^{V}$. For finite-dimensional $V$, the form $\kappa$ is the pullback of the canonical metric on $\operatorname{End}(\operatorname{End}(V))$ (from Equation (3.16)) by $a d$ (or by its opposite, $-a d$ ),

$$
\kappa=( \pm a d)^{*} \circ\left(k_{\operatorname{End}(V), \operatorname{End}(V)}^{*}\right)^{-1} \circ e_{\operatorname{End}(V), \operatorname{End}(V)} \circ( \pm a d)
$$

Using Equation (3.15), Lemma 2.6, and Corollary 2.37,

$$
\begin{aligned}
(4.26) & (\kappa(A))(B)=\operatorname{Tr}_{\operatorname{End}(V)}((\operatorname{ad}(A)) \circ(\operatorname{ad}(B))) \\
= & \operatorname{Tr}_{\operatorname{End}(V)}\left(\left(\operatorname{Hom}\left(I d_{V}, A\right)-\operatorname{Hom}\left(A, I d_{V}\right)\right) \circ\left(\operatorname{Hom}\left(I d_{V}, B\right)-\operatorname{Hom}\left(B, I d_{V}\right)\right)\right) \\
= & \operatorname{Tr}_{\operatorname{End}(V)}\left(\operatorname{Hom}\left(I d_{V}, A \circ B\right)-\operatorname{Hom}(A, B)-\operatorname{Hom}(B, A)+\operatorname{Hom}\left(B \circ A, I d_{V}\right)\right) \\
= & 2 \cdot \operatorname{Tr}_{V}\left(I d_{V}\right) \cdot \operatorname{Tr}_{V}(A \circ B)-2 \cdot \operatorname{Tr}_{V}(A) \cdot \operatorname{Tr}_{V}(B) .
\end{aligned}
$$

Example 4.71. Direct sums of ideals as in Theorem 4.62 are considered in the Lie algebra case by [Humphreys] §II.5. If $V$ is finite-dimensional and $\operatorname{Tr}_{V}\left(I d_{V}\right) \neq$ 0 , then Theorem 4.60 applies to the Lie algebra $(\operatorname{End}(V), a d)$ and the direct sum $\operatorname{End}(V)=\mathbb{K} \oplus \operatorname{End}_{0}(V)$ from Example 2.9. The corresponding CK forms are $\kappa_{1}=$ $0_{\operatorname{Hom}\left(\mathbb{K}, \mathbb{K}^{*}\right)}$ and $\kappa_{2}=Q_{2}^{*} \circ \kappa \circ Q_{2}$, so that for trace 0 elements $A, B \in \operatorname{End}_{0}(V)$, the pullback of $(4.26)$ by the inclusion $Q_{2}$ gives $\left(\kappa_{2}(A)\right)(B)=2 \cdot \operatorname{Tr}_{V}\left(\operatorname{Id}_{V}\right) \cdot \operatorname{Tr}_{V}(A \circ B)$.

Definition 4.72. An algebra $(V, h)$ is a one-sided division algebra means that for every $v \neq 0_{V}, h(v)$ is invertible. $(V, h)$ is a two-sided division algebra means that for every $v \neq 0_{V}$, both $h(v)$ and $\left(T_{V ; V}(h)\right)(v)$ are invertible.

### 4.5.3. Curvature tensors.

Example 4.73. Consider $V$ with a metric $g$, and an $\operatorname{End}(V)$-valued bilinear form $R \in \operatorname{Hom}(V, \operatorname{Hom}(V, \operatorname{End}(V)))$.

If $\frac{1}{2} \in \mathbb{K}$ and $R$ satisfies

$$
\begin{equation*}
T_{V ; \operatorname{End}(V)}(R)=-R \tag{4.27}
\end{equation*}
$$

so that $R \in \operatorname{Alt}(V ; \operatorname{End}(V))$, then by Corollary 4.32,

$$
T r_{g ; \operatorname{End}(V)}(R)=0_{\operatorname{End}(V)}
$$

If $\frac{1}{2} \in \mathbb{K}$ and $R$ satisfies

$$
\begin{equation*}
\operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(g, g^{-1}\right) \circ t\right)\right)(R)=-R \tag{4.28}
\end{equation*}
$$

so that for any $u, v \in V$,

$$
(R(u))(v)=-g^{-1} \circ((R(u))(v))^{*} \circ g \in \operatorname{End}(V)
$$

then $(R(u))(v)$ is skew-adjoint with respect to $g$ and, as in Exercise 3.118,

$$
\begin{align*}
\operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, T r_{V}\right)\right)(R): u & \mapsto \\
\left(\left(\operatorname{Hom}\left(I d_{V}, T r_{V}\right)\right) \circ R\right)(u): v & \mapsto\left(\operatorname{Tr}_{V} \circ(R(u))\right)(v) \\
& =\operatorname{Tr}_{V}((R(u))(v))=0 \\
\Longrightarrow \operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, T r_{V}\right)\right)(R) & =0_{\operatorname{Hom}\left(V, V^{*}\right)} . \tag{4.29}
\end{align*}
$$

There is another trace that is not necessarily zero even under both of the above conditions. Define:

$$
\operatorname{Ric}=\left(\operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, \operatorname{Tr}_{V}\right)\right) \circ \operatorname{Hom}\left(I d_{V}, T_{V ; V}\right)\right)(R) \in \operatorname{Hom}\left(V, V^{*}\right)
$$

If $\operatorname{Tr}_{V}\left(I d_{V}\right) \neq 0$, then Theorem 3.35 and Theorem 3.53 apply - there is a canonical, orthogonal decomposition:

$$
\begin{equation*}
R i c=\frac{\operatorname{Tr}_{g}(R i c)}{\operatorname{Tr}_{V}\left(I d_{V}\right)} \cdot g+\left(R i c-\frac{\operatorname{Tr}_{g}(R i c)}{\operatorname{Tr}_{V}\left(I d_{V}\right)} \cdot g\right) \tag{4.30}
\end{equation*}
$$

REmARK 4.74. For a smooth manifold where $V$ is a tangent vector space over $\mathbb{K}=\mathbb{R}$ and $g$ is a pseudo-Riemannian metric, the linear algebra properties of the Riemann curvature tensor $R_{q k l}^{i}$ at a point are modeled by a form $R$ as in Example 4.73, with the symmetries (4.27), (4.28), and (4.31). Its trace Ric is the Ricci curvature tensor, and $\operatorname{Tr}_{g}($ Ric $)$ from (4.30) is the scalar curvature. See [DFN] §30.

Remark 4.75. The second term from (4.30) is the trace-free Ricci tensor. There are other interesting linear combinations of Ric and $g$, including the tracereversed Ricci tensor,

$$
R i c-2 \cdot \frac{\operatorname{Tr}_{g}(R i c)}{\operatorname{Tr}_{V}\left(I d_{V}\right)} \cdot g
$$

and the Einstein tensor,

$$
R i c-\frac{1}{2} \cdot \operatorname{Tr}_{g}(R i c) \cdot g
$$

Proposition 4.76. If $\frac{1}{2} \in \mathbb{K}$ and $R \in \operatorname{Hom}(V, \operatorname{Hom}(V, \operatorname{End}(V)))$ satisfies (4.27) and (4.29), and additionally has the property

$$
\begin{equation*}
\left(T_{V ; \operatorname{End}(V)} \circ \operatorname{Hom}\left(I d_{V}, T_{V ; V}\right)+\operatorname{Hom}\left(I d_{V}, T_{V ; V}\right) \circ T_{V ; \operatorname{End}(V)}\right)(R)=-R \tag{4.31}
\end{equation*}
$$

then Ric is symmetric.
Proof. Using Lemma 4.6, (4.31), (4.29), and (4.27),

$$
\begin{aligned}
T_{V}(\text { Ric })= & \left(T_{V ; \mathbb{K}} \circ \operatorname{Hom}\left(\operatorname{Id} d_{V}, \operatorname{Hom}\left(I d_{V}, T r_{V}\right)\right) \circ \operatorname{Hom}\left(I d_{V}, T_{V ; V}\right)\right)(R) \\
= & \left(\operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, \operatorname{Tr}_{V}\right)\right) \circ T_{V ; \operatorname{End}(V)} \circ \operatorname{Hom}\left(I d_{V}, T_{V ; V}\right)\right)(R) \\
= & -\operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, T r_{V}\right)\right)(R) \\
& -\left(\operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, \operatorname{Tr}_{V}\right)\right) \circ \operatorname{Hom}\left(I d_{V}, T_{V ; V}\right) \circ T_{V ; \operatorname{End}(V)}\right)(R) \\
= & -0_{\operatorname{Hom}\left(V, V^{*}\right)} \\
& -\left(\operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, T r_{V}\right)\right) \circ \operatorname{Hom}\left(I d_{V}, T_{V ; V}\right)\right)(-R)=\text { Ric. }
\end{aligned}
$$

If, further, $\operatorname{Tr}_{V}\left(I d_{V}\right) \neq 0$, then it follows that the second, trace-free term in (4.30) is also symmetric.

Remark 4.77. The lowered-index curvature tensor $R_{i q k l}$ is modeled by the multilinear form $R^{\prime}$ in the following Example 4.78. Then Proposition 4.79 demonstrates the symmetry property $R_{i q k l}=R_{k l i q}$.

Example 4.78. For $V, g$, and $R \in \operatorname{Hom}(V, \operatorname{Hom}(V, \operatorname{End}(V)))$ as in Example 4.73, define
$R^{\prime}=\operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, g\right)\right)\right)(R) \in \operatorname{Hom}\left(V, \operatorname{Hom}\left(V, \operatorname{Hom}\left(V, V^{*}\right)\right)\right)$,
so that for $u, v \in V,\left(R^{\prime}(u)\right)(v)=g \circ((R(u))(v)): V \rightarrow V^{*}$. As in Theorem 3.114 and Example 3.116, if $\frac{1}{2} \in \mathbb{K}$ and $(R(u))(v)$ is skew-adjoint then $\left(R^{\prime}(u)\right)(v)$ is an antisymmetric form, so if $R$ has property (4.28) then $R^{\prime}$ satisfies

$$
\begin{equation*}
\operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, T_{V}\right)\right)\left(R^{\prime}\right)=-R^{\prime} \tag{4.32}
\end{equation*}
$$

By Lemma 4.6,

$$
\begin{aligned}
& \operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, g\right)\right)\right) \circ T_{V ; \operatorname{End}(V)} \\
= & T_{V ; \operatorname{Hom}\left(V, V^{*}\right)} \circ \operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, g\right)\right)\right),
\end{aligned}
$$

so if $R$ has property (4.27), then $R^{\prime}$ satisfies

$$
\begin{equation*}
T_{V ; \operatorname{Hom}\left(V, V^{*}\right)}\left(R^{\prime}\right)=-R^{\prime} \tag{4.33}
\end{equation*}
$$

Similarly by Lemma 4.6,

$$
\begin{aligned}
& \operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, g\right)\right)\right) \circ \operatorname{Hom}\left(I d_{V}, T_{V ; V}\right) \\
= & \operatorname{Hom}\left(I d_{V}, T_{V ; V^{*}}\right) \circ \operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, g\right)\right)\right),
\end{aligned}
$$

so if $R$ has property (4.31), then $R^{\prime}$ satisfies
$\left(T_{V ; \operatorname{Hom}\left(V, V^{*}\right)} \circ \operatorname{Hom}\left(I d_{V}, T_{V ; V^{*}}\right)+\operatorname{Hom}\left(I d_{V}, T_{V ; V^{*}}\right) \circ T_{V ; \operatorname{Hom}\left(V, V^{*}\right)}\right)\left(R^{\prime}\right)=-R^{\prime}$.
Proposition 4.79. If $\frac{1}{2} \in \mathbb{K}$ and $R^{\prime} \in \operatorname{Hom}\left(V, \operatorname{Hom}\left(V, \operatorname{Hom}\left(V, V^{*}\right)\right)\right)$ satisfies (4.32), (4.33), and (4.34), then $R^{\prime}$ is a fixed point of the involution (4.35)
$\operatorname{Hom}\left(I d_{V}, T_{V ; V^{*}}\right) \circ T_{V ; \operatorname{Hom}\left(V, V^{*}\right)} \circ \operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, T_{V}\right)\right) \circ \operatorname{Hom}\left(I d_{V}, T_{V ; V^{*}}\right)$.
Proof. Temporarily denote the involutions:

$$
\begin{aligned}
a_{1} & =T_{V ; \operatorname{Hom}\left(V, V^{*}\right)} \\
a_{2} & =\operatorname{Hom}\left(I d_{V}, T_{V ; V^{*}}\right) \\
a_{3} & =\operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(I d_{V}, T_{V}\right)\right)
\end{aligned}
$$

Properties (4.32) and (4.33) then can be stated:

$$
\begin{equation*}
a_{1}\left(R^{\prime}\right)=a_{3}\left(R^{\prime}\right)=-R^{\prime} \tag{4.36}
\end{equation*}
$$

By Lemma 4.6, $a_{1} \circ a_{3}=a_{3} \circ a_{1}$, and this is enough to show that the composite $a_{2} \circ a_{1} \circ a_{3} \circ a_{2}$ from (4.35) is an involution. Lemma 4.12 gives the relations:

$$
\begin{aligned}
a_{2} \circ a_{1} \circ a_{2} & =a_{1} \circ a_{2} \circ a_{1} \\
a_{3} \circ a_{2} \circ a_{3} & =a_{2} \circ a_{3} \circ a_{2} .
\end{aligned}
$$

Starting with property (4.34), applying $a_{3}$ to both sides, and then using (4.36) gives:

$$
\begin{align*}
\left(a_{1} \circ a_{2}+a_{2} \circ a_{1}\right)\left(R^{\prime}\right) & =-R^{\prime}  \tag{4.37}\\
\Longrightarrow\left(a_{3} \circ a_{1} \circ a_{2}+a_{3} \circ a_{2} \circ a_{1}\right)\left(R^{\prime}\right) & =a_{3}\left(-R^{\prime}\right) \\
\left(a_{1} \circ a_{2} \circ a_{3} \circ a_{2} \circ a_{3}+a_{2} \circ a_{3} \circ a_{2} \circ a_{3} \circ a_{1}\right)\left(R^{\prime}\right) & =R^{\prime} \\
\Longrightarrow\left(a_{1} \circ a_{2} \circ a_{3} \circ a_{2}+a_{2} \circ a_{3} \circ a_{2} \circ a_{3}\right)\left(R^{\prime}\right) & =-R^{\prime} . \tag{4.38}
\end{align*}
$$

Applying $a_{2} \circ a_{1} \circ a_{3} \circ a_{2}$ to both sides of (4.37) gives:

$$
\begin{align*}
&\left(a_{2} \circ a_{1} \circ a_{3} \circ a_{2} \circ a_{1} \circ a_{2}\right)\left(R^{\prime}\right) \\
&+\left(a_{2} \circ a_{1} \circ a_{3} \circ a_{2} \circ a_{2} \circ a_{1}\right)\left(R^{\prime}\right)=\left(a_{2} \circ a_{1} \circ a_{3} \circ a_{2}\right)\left(-R^{\prime}\right) \\
&\left(a_{2} \circ a_{3} \circ a_{2} \circ a_{1}+a_{2} \circ a_{1}\right)\left(R^{\prime}\right)=-\left(a_{2} \circ a_{1} \circ a_{3} \circ a_{2}\right)\left(R^{\prime}\right) . \tag{4.39}
\end{align*}
$$

Applying $a_{1}$ to both sides of (4.39) gives:

$$
\begin{align*}
\left(a_{1} \circ a_{2} \circ a_{3} \circ a_{2} \circ a_{1}+a_{1} \circ a_{2} \circ a_{1}\right)\left(R^{\prime}\right) & =-\left(a_{1} \circ a_{2} \circ a_{1} \circ a_{3} \circ a_{2}\right)\left(R^{\prime}\right) \\
\left(a_{1} \circ a_{2} \circ a_{3} \circ a_{2}+a_{1} \circ a_{2}\right)\left(-R^{\prime}\right) & =-\left(a_{2} \circ a_{1} \circ a_{2} \circ a_{3} \circ a_{2}\right)\left(R^{\prime}\right) \\
0) \Longrightarrow\left(a_{1} \circ a_{2} \circ a_{3} \circ a_{2}+a_{1} \circ a_{2}\right)\left(R^{\prime}\right) & =-\left(a_{2} \circ a_{1} \circ a_{3} \circ a_{2}\right)\left(R^{\prime}\right) . \tag{4.40}
\end{align*}
$$

Adding (4.37) and (4.38) and subtracting (4.39) and (4.40), there are cancellations using (4.36) again, to get:

$$
0_{\operatorname{Hom}\left(V, \operatorname{Hom}\left(V, \operatorname{Hom}\left(V, V^{*}\right)\right)\right)}=-2 \cdot R^{\prime}+2 \cdot\left(a_{2} \circ a_{1} \circ a_{3} \circ a_{2}\right)\left(R^{\prime}\right),
$$

which proves the claim.
4.5.4. Partially symmetric forms. A map $A \otimes V \otimes V \rightarrow F$ is called a "trilinear $F$-form" in $[\mathbf{E H M}]$, and it is "partially symmetric" means that it is invariant under switching of the $V$ factors. Such forms, of course, lie in the scope of these notes, and it will also be convenient to consider maps of the form

$$
V \otimes U \rightarrow \operatorname{Hom}(V, W)
$$

as in the vector valued forms of Sections 4.2 and 4.3 , but with the domain twisted by $U$. The two notions are related by a canonical map, as already seen in the Proof of Lemma 4.12.

Notation 4.80. For arbitrary $V, U, W, X$, define

$$
\begin{equation*}
q: \operatorname{Hom}(X \otimes U, \operatorname{Hom}(V, W)) \rightarrow \operatorname{Hom}(V \otimes X \otimes U, W) \tag{4.41}
\end{equation*}
$$

so that for $G: X \otimes U \rightarrow \operatorname{Hom}(V, W), v \in V, x \in X$, and $u \in U$,

$$
q(G): v \otimes x \otimes u \mapsto(G(x \otimes u))(v)
$$

The order of the factors is different from that in Definition 1.43 , but such maps will still have " $q$ " labels (in analogy with the variations on $n$ from Notation 1.39).

In the following Lemma, $T_{V}$ is the transpose map from Definition 3.2, and $q_{1}$ is the $q$ map from (4.41) in the case $X=V$.

Lemma 4.81. The following diagram is commutative.


Proof. Without stating all the details, the upper part of the diagram is analogous to the diagram from Lemma 4.5, and the lower part is analogous to the diagram from Lemma 4.1.

Definition 4.82. Define $T_{V ; U, W} \in \operatorname{End}(\operatorname{Hom}(V \otimes U, \operatorname{Hom}(V, W)))$ by

$$
T_{V ; U, W}=q_{1}^{-1} \circ \operatorname{Hom}\left(\left[s \otimes I d_{U}\right], I d_{W}\right) \circ q_{1}
$$

With this construction, the $T_{V ; U, W}$ maps are analogous to, but not a special case of, the maps $T_{V_{1}, V_{2} ; W}$ from Lemma 4.1 and Definition 4.2. If $V$ is finitedimensional, then $j$ and $k$ in the above diagram are invertible, and by the Lemma,

$$
T_{V ; U, W}=\operatorname{Hom}\left(I d_{V \otimes U}, k_{V W}\right) \circ j \circ\left[T_{V} \otimes I d_{\operatorname{Hom}(U, W)}\right] \circ j^{-1} \circ \operatorname{Hom}\left(I d_{V \otimes U}, k_{V W}^{-1}\right)
$$

As in Section 4.2, $T_{V ; U, W}$ is an involution, and if $\frac{1}{2} \in \mathbb{K}$, then it produces a direct sum structure on $\operatorname{Hom}(V \otimes U, \operatorname{Hom}(V, W))$, by Lemma 1.112. The other two involutions in the above diagram also produce direct sums, and by Lemma 1.118, the maps $q_{1}$ and $\operatorname{Hom}\left(I d_{V \otimes U}, k_{V W}\right) \circ j$ respect these direct sums, although the comments about Example 1.137 in Remark 4.14 apply here also.

Exercise 4.83. With respect to induced metrics, $T_{V ; U, W}$ is an isometry, and if $\frac{1}{2} \in \mathbb{K}$, then it produces an orthogonal direct sum.

Hint. Use Definition 4.82 to show $T_{V ; U, W}$ is a composition of isometries. Then Lemma 3.55 applies, as in Theorem 4.39.

Definition 4.84. A map $G: V \otimes U \rightarrow \operatorname{Hom}(V, W)$ is partially symmetric means: $T_{V ; U, W}(G)=G$. More generally, a $\operatorname{map} G: X \otimes \bar{U} \operatorname{Hom}(V, W)$ is partially symmetric with respect to a map $H: V \rightarrow X$ means that $G \circ\left[H \otimes I d_{U}\right]$ : $V \otimes U \rightarrow \operatorname{Hom}(V, W)$ is partially symmetric.

Lemma 4.85. ([EHM]) For any $V, U, W, X$, and $G: X \otimes U \rightarrow \operatorname{Hom}(V, W)$, the following diagram is commutative.


Proof. The lower square uses Lemma 1.57. In the upper square, the maps are $n$ as in Definition 1.38, and an inclusion $Q_{1}^{1}: \lambda \rightarrow \lambda \cdot I d_{V}$ as in Example 2.9 and Equation (2.4).

$$
\begin{aligned}
\lambda \otimes x \otimes u & \mapsto\left(\operatorname{Hom}\left(I d_{V}, q(G)\right) \circ n \circ\left[Q_{1}^{1} \otimes I d_{X \otimes U}\right]\right)(\lambda \otimes x \otimes u) \\
& =(q(G)) \circ\left(n\left(\lambda \cdot I d_{V} \otimes x \otimes u\right)\right): \\
v & \mapsto(q(G))(\lambda \cdot v \otimes x \otimes u) \\
& =\lambda \cdot(G(x \otimes u))(v)=((G \circ l)(\lambda \otimes x \otimes u))(v) .
\end{aligned}
$$

Theorem 4.86. For any spaces $U, V, W, X, Y$, and any maps $G: X \otimes U \rightarrow$ $\operatorname{Hom}(V, W), M: Y \rightarrow X \otimes U$, the following are equivalent.

$$
\begin{aligned}
(q(G)) \circ\left[I d_{V} \otimes M\right] & =0_{\operatorname{Hom}(V \otimes Y, W)} \\
\Longleftrightarrow G \circ M & =0_{\operatorname{Hom}(Y, \operatorname{Hom}(V, W))}
\end{aligned}
$$

Proof. Let $q$ be the map from Notation 4.80, and let $q_{2}$ be another such map in the following diagram.


The diagram is commutative by Lemma 1.46. So, $q_{2}(G \circ M)=(q(G)) \circ\left[I d_{V} \otimes M\right]$. Since $q_{2}$ is invertible (Lemma 1.44), $G \circ M$ is zero if and only if its output under $q_{2}$ is also zero.

Example 4.87. Suppose there is some direct sum $V \otimes X \otimes U=W_{1} \oplus W_{2}$, with projections $P_{i}: V \otimes X \otimes U \rightarrow W_{i}$. Then, for $q_{i}: \operatorname{Hom}\left(X \otimes U, \operatorname{Hom}\left(V, W_{i}\right)\right) \rightarrow$ $\operatorname{Hom}\left(V \otimes X \otimes U, W_{i}\right)$ and $M: Y \rightarrow X \otimes U$,

$$
P_{i} \circ\left[I d_{V} \otimes M\right]=0_{\operatorname{Hom}\left(V \otimes Y, W_{i}\right)} \Longleftrightarrow\left(q_{i}^{-1}\left(P_{i}\right)\right) \circ M=0_{\operatorname{Hom}\left(Y, \operatorname{Hom}\left(V, W_{i}\right)\right)}
$$

The following Theorem uses the the switching involution $s$ as in Lemma 4.81, and the direct sum $V \otimes V=S^{2} V \oplus \Lambda^{2} V$ produced by $s$ as in Example 1.116, with projections $\left(P_{1}, P_{2}\right)$ and inclusions $\left(Q_{1}, Q_{2}\right)$.

ThEOREM 4.88. Let $H: V \rightarrow X$, and suppose there is some direct sum

$$
V \otimes X=Z_{1} \oplus Z_{2}
$$

with operators $P_{i}^{\prime}, Q_{i}^{\prime}$, such that $\left[I d_{V} \otimes H\right]: V \otimes V \rightarrow V \otimes X$ respects the direct sums and $P_{2}^{\prime} \circ\left[I d_{V} \otimes H\right] \circ Q_{2}: \Lambda^{2} V \rightarrow Z_{2}$ is invertible. If $G: X \otimes U \rightarrow \operatorname{Hom}(V, W)$ is partially symmetric with respect to $H$, then

$$
q(G)=(q(G)) \circ\left[\left(Q_{1}^{\prime} \circ P_{1}^{\prime}\right) \otimes I d_{U}\right]
$$

Proof. The following diagram is commutative by Lemma 1.46, where $q_{1}$ is as in Lemma 4.81.


By the assumption about respecting the direct sum, $P_{I}^{\prime} \circ\left[I d_{V} \otimes H\right] \circ Q_{i}$ is zero for $i \neq I$. Let $P_{2}^{\prime \prime}$ denote the projection $\frac{1}{2} \cdot\left(I_{\operatorname{Hom}(V \otimes U, \operatorname{Hom}(V, W))}-T_{V ; U, W}\right)$, so that if $G$ is partially symmetric with respect to $H$, then

$$
\begin{aligned}
0_{\mathrm{Hom}\left(\Lambda^{2} V \otimes U, W\right)}= & \left(q_{1}\left(P_{2}^{\prime \prime}\left(G \circ\left[H \otimes I d_{U}\right]\right)\right)\right) \circ\left[Q_{2} \otimes I d_{U}\right] \\
= & \left(\frac{1}{2} \cdot q_{1}\left(G \circ\left[H \otimes I d_{U}\right]\right)\right) \circ\left[Q_{2} \otimes I d_{U}\right] \\
& -\left(\frac{1}{2} \cdot q_{1}\left(G \circ\left[H \otimes I d_{U}\right]\right)\right) \circ\left[s \otimes I d_{U}\right] \circ\left[Q_{2} \otimes I d_{U}\right] \\
= & \left(q_{1}\left(G \circ\left[H \otimes I d_{U}\right]\right)\right) \circ\left[Q_{2} \otimes I d_{U}\right] \circ\left[P_{2} \otimes I d_{U}\right] \circ\left[Q_{2} \otimes I d_{U}\right] \\
= & (q(G)) \circ\left[I d_{V} \otimes\left[H \otimes I d_{U}\right]\right] \circ\left[Q_{2} \otimes I d_{U}\right] \\
= & (q(G)) \circ\left(\left[Q_{1}^{\prime} \otimes I d_{U}\right] \circ\left[P_{1}^{\prime} \otimes I d_{U}\right]+\left[Q_{2}^{\prime} \otimes I d_{U}\right] \circ\left[P_{2}^{\prime} \otimes I d_{U}\right]\right) \\
& \circ\left[\left[I d_{V} \otimes H\right] \otimes I d_{U}\right] \circ\left[Q_{2} \otimes I d_{U}\right] \\
= & (q(G)) \circ\left[Q_{2}^{\prime} \otimes I d_{U}\right] \circ\left[P_{2}^{\prime} \otimes I d_{U}\right] \circ\left[\left[I d_{V} \otimes H\right] \otimes I d_{U}\right] \circ\left[Q_{2} \otimes I d_{U}\right]
\end{aligned}
$$

Then, since $\left[P_{2}^{\prime} \otimes I d_{U}\right] \circ\left[\left[I d_{V} \otimes H\right] \otimes I d_{U}\right] \circ\left[Q_{2} \otimes I d_{U}\right]$ is invertible,

$$
0_{\operatorname{Hom}\left(Z_{2} \otimes U, W\right)}=(q(G)) \circ\left[Q_{2}^{\prime} \otimes I d_{U}\right],
$$

and it follows that

$$
q(G)=(q(G)) \circ\left[\left(Q_{1}^{\prime} \circ P_{1}^{\prime}+Q_{2}^{\prime} \circ P_{2}^{\prime}\right) \otimes I d_{U}\right]=(q(G)) \circ\left[\left(Q_{1}^{\prime} \circ P_{1}^{\prime}\right) \otimes I d_{U}\right]
$$

It follows from the previous two Theorems that if $M: Y \rightarrow X \otimes U$ and $G$ is partially symmetric with respect to $H$, then

$$
q_{2}(G \circ M)=(q(G)) \circ\left[\left(Q_{1}^{\prime} \circ P_{1}^{\prime}\right) \otimes I d_{U}\right] \circ\left[I d_{V} \otimes M\right]
$$

Remark 4.89. The map $H: V \rightarrow X$ could be an inclusion of a vector subspace, in which case the above $Z_{1}$ corresponds to the space denoted by $H . V$ in $[\mathbf{E H M}]$.

Big Exercise 4.90. Given a metric $g$ on $V$, there exists a trace operator

$$
T r_{g ; U, W}: \operatorname{Hom}(V \otimes U, \operatorname{Hom}(V, W)) \rightarrow \operatorname{Hom}(U, W)
$$

having nice properties which follow as corollaries of the results in Section 2.2.

## CHAPTER 5

## Complex Structures

At this point we abandon the general field $\mathbb{K}$ and work exclusively with real number scalars and vector spaces over the field $\mathbb{R}$. Some of the objects could be considered vector spaces over the field of complex numbers, but in this Chapter, complex numbers will not be used as scalars or for any other purpose. The objects will instead be real vector spaces paired with some additional structure, and the maps are all $\mathbb{R}$-linear, although some of the $\mathbb{R}$-linear maps will respect the additional structure.

### 5.1. Complex Structure Operators

Definition 5.1. Given a real vector space $V$, an endomorphism $J \in \operatorname{End}(V)$ is a complex structure operator means: $J \circ J=-I d_{V}$.

Notation 5.2. A complex structure operator is more briefly called a CSO. Sometimes a pair $(V, J)$ will be denoted by a matching boldface letter, V. Expressions such as $v \in \mathbf{V}, A: \mathbf{U} \rightarrow \mathbf{V}$, etc., refer to the underlying real space $v \in V$, $A: U \rightarrow V$, etc.

Example 5.3. Given $\mathbf{V}=\left(V, J_{V}\right)$ and another vector space $U,\left[I d_{U} \otimes J_{V}\right] \in$ $\operatorname{End}(U \otimes V)$ is a canonical CSO on $U \otimes V$, so we may denote $U \otimes \mathbf{V}=\left(U \otimes V,\left[I d_{U} \otimes\right.\right.$ $\left.\left.J_{V}\right]\right)$. Similarly, denote $\mathbf{V} \otimes U=\left(V \otimes U,\left[J_{V} \otimes I d_{U}\right]\right)$.

Example 5.4. Given a vector space $V$ with CSO $J_{V}$ and another vector space $U, \operatorname{Hom}\left(I d_{U}, J_{V}\right): A \mapsto J_{V} \circ A$ is a canonical CSO on $\operatorname{Hom}(U, V)$, so we may denote $\operatorname{Hom}(U, \mathbf{V})=\left(\operatorname{Hom}(U, V), \operatorname{Hom}\left(I d_{U}, J_{V}\right)\right)$. Similarly, denote $\operatorname{Hom}(\mathbf{V}, U)=$ $\left(\operatorname{Hom}(V, U), \operatorname{Hom}\left(J_{V}, I d_{U}\right)\right)$.

Example 5.5. Given $V$, a CSO $J$ induces a $\operatorname{CSO} J^{*}=\operatorname{Hom}\left(J, I d_{\mathbb{R}}\right)$ on $V^{*}=$ $\operatorname{Hom}(V, \mathbb{R})$.

Example 5.6. Given $V$, a $\operatorname{CSO} J \in \operatorname{End}(V)$, and any involution $N$ that commutes with $J$ (i.e., $N \in \operatorname{End}(V)$ such that $N \circ N=I d_{V}$ and $N \circ J=J \circ N$ ), $N \circ J$ is a CSO.

Example 5.7. Given $V \neq\left\{0_{V}\right\}$, any CSO $J \in \operatorname{End}(V)$ is not unique, since $-J$ is a different CSO. This is the $N=-I d_{V}$ case from Example 5.6.

Example 5.8. Given $V=V_{1} \oplus V_{2}$, suppose there is an invertible map $A: V_{2} \rightarrow$ $V_{1}$, as in (3) from Theorem 1.128. Then, $V$ also admits a CSO,

$$
\begin{equation*}
J=Q_{2} \circ A^{-1} \circ P_{1}-Q_{1} \circ A \circ P_{2} \tag{5.1}
\end{equation*}
$$

and its opposite, $-J$. In the special case (1) where $V=U \oplus U, A=I d_{V}$, the above CSO is $J=Q_{2} \circ P_{1}-Q_{1} \circ P_{2}$. In the equivalent situation, (8) from Theorem 1.128, where there exist anticommuting involutions $K_{1}$ and $K_{2}$ on $V$, the composite
$K_{1} \circ K_{2}$ and its opposite are CSOs on $V$. Using $K_{1}$ and $K_{2}$ to define a direct sum and a map $A$ as in (1.18), the above construction (5.1) gives the same pair of CSOs: $\left\{ \pm K_{1} \circ K_{2}\right\}=\{ \pm J\}$.

Lemma 5.9. Given $V$ with $C S O J$ and $v \in V$, if $v \neq 0_{V}$, then the ordered list $(v, J(v))$ is linearly independent.

Proof. Linear independence as in Definition 0.27 refers to the scalar field $\mathbb{R}$ in this Chapter. If $J(v)=\alpha \cdot v$ for some $\alpha \in \mathbb{R}$, then $J(J(v))=(-1) \cdot v=\alpha^{2} \cdot v$; there are no solutions for $v \neq 0_{V}$ and $\alpha \in \mathbb{R}$.

ExERCISE 5.10. Not every real vector space admits a CSO.
Lemma 5.11. Given $V$ with $C S O ~ J$ and $v_{1}, \ldots, v_{\ell} \in V$, if the ordered list

$$
\left(v_{1}, \ldots, v_{\ell-1}, v_{\ell}, J\left(v_{1}\right), \ldots, J\left(v_{\ell-1}\right)\right)
$$

is linearly independent, then so is the ordered list

$$
\left(v_{1}, \ldots, v_{\ell-1}, v_{\ell}, J\left(v_{1}\right), \ldots, J\left(v_{\ell-1}\right), J\left(v_{\ell}\right)\right)
$$

Proof. The $\ell=1$ case is Lemma 5.9. For $\ell \geq 2$, suppose there are real scalars $\alpha_{1}, \ldots, \alpha_{\ell}, \beta_{1}, \ldots, \beta_{\ell}$ such that

$$
\begin{equation*}
\alpha_{1} \cdot v_{1}+\ldots+\alpha_{\ell} \cdot v_{\ell}+\beta_{1} \cdot J\left(v_{1}\right)+\ldots+\beta_{\ell} \cdot J\left(v_{\ell}\right)=0_{V} \tag{5.2}
\end{equation*}
$$

Then,

$$
\begin{equation*}
\alpha_{1} \cdot J\left(v_{1}\right)+\ldots+\alpha_{\ell} \cdot J\left(v_{\ell}\right)-\beta_{1} \cdot v_{1}-\ldots-\beta_{\ell} \cdot v_{\ell}=0_{V} \tag{5.3}
\end{equation*}
$$

Subtracting $\alpha_{\ell}$ times (5.2) minus $\beta_{\ell}$ times (5.3), the $J\left(v_{\ell}\right)$ terms cancel, and

$$
\begin{aligned}
& \left(\alpha_{1} \alpha_{\ell}+\beta_{1} \beta_{\ell}\right) \cdot v_{1}+\ldots+\left(\alpha_{\ell-1} \alpha_{\ell}+\beta_{\ell-1} \beta_{\ell}\right) \cdot v_{\ell-1}+\left(\alpha_{\ell}^{2}+\beta_{\ell}^{2}\right) \cdot v_{\ell} \\
& +\left(\alpha_{\ell} \beta_{1}-\alpha_{1} \beta_{\ell}\right) \cdot J\left(v_{1}\right)+\ldots+\left(\alpha_{\ell} \beta_{\ell-1}-\alpha_{\ell-1} \beta_{\ell}\right) \cdot J\left(v_{\ell-1}\right)=0_{V}
\end{aligned}
$$

By the linear independence of the ordered list with $2 \ell-1$ elements, $\alpha_{\ell}^{2}+\beta_{\ell}^{2}=$ $0 \Longrightarrow \alpha_{\ell}=\beta_{\ell}=0$. Then (5.2) and the independence hypothesis again (or Lemma 5.9 if $\ell=2$ ) imply $\alpha_{1}=\ldots=\alpha_{\ell-1}=\beta_{1}=\ldots=\beta_{\ell-1}=0$.

Definition 5.12. Given $V$ with CSO $J$, a subspace $H$ is $J$-invariant means: $J(H) \subseteq H$. Equivalently, because $J$ is invertible, $J(H)=H$.

Lemma 5.13. Given $V$ with $C S O ~ J$, and a $J$-invariant subspace $H$ of $V$, if $H \neq\left\{0_{V}\right\}$ and $H$ is finite-dimensional, then $H$ admits an ordered basis of the form

$$
\left(v_{1}, \ldots, v_{\ell-1}, v_{\ell}, J\left(v_{1}\right), \ldots, J\left(v_{\ell-1}\right), J\left(v_{\ell}\right)\right)
$$

Proof. By hypothesis, there is some $v_{1} \in H$ with $v_{1} \neq 0_{V}$, and by $J_{-}$ invariance, $J(v) \in H$, so by Lemma $5.9,\left(v_{1}, J\left(v_{1}\right)\right)$ is a linearly independent ordered list of vectors in $H$. Suppose inductively that

$$
\left(v_{1}, \ldots, v_{\ell-1}, v_{\ell}, J\left(v_{1}\right), \ldots, J\left(v_{\ell-1}\right), J\left(v_{\ell}\right)\right)
$$

is a linearly independent ordered list of vectors in $H$. If the ordered list spans $H$, it is an ordered basis; otherwise, there is some $v_{\ell+1} \in H$ not in its span, so

$$
\left(v_{1}, \ldots, v_{\ell-1}, v_{\ell}, v_{\ell+1}, J\left(v_{1}\right), \ldots, J\left(v_{\ell-1}\right), J\left(v_{\ell}\right)\right)
$$

is a linearly independent ordered list. $J\left(v_{\ell+1}\right) \in H$ and Lemma 5.11 applies, so

$$
\left(v_{1}, \ldots, v_{\ell-1}, v_{\ell}, v_{\ell+1}, J\left(v_{1}\right), \ldots, J\left(v_{\ell-1}\right), J\left(v_{\ell}\right), J\left(v_{\ell+1}\right)\right)
$$

is a linearly independent ordered list of elements in $H$. The construction eventually terminates by Claim 0.28.

Definition 5.14. Given $V$ with CSO $J$, a subspace $H$ of $V$ which is equal to a span of a two-element set and is also $J$-invariant, $H=J(H) \subseteq V$, will be called a $J$-complex line in $V$.

By Lemma 5.13, a $J$-complex line $H$ must be of the form $\operatorname{span}\{v, J(v)\}$ for some non-zero $v \in H$.

Lemma 5.15. Given $V$ with CSO J, a J-complex line L, and a J-invariant subspace $H \subseteq V$, if there is a non-zero element $v \in L \cap H$, then $L \subseteq H$. In particular, if $H$ is a $J$-complex line, then $L=H$.

Proof. By $J$-invariance, $\{v, J(v)\} \subseteq L \cap H$. By Lemma 5.9, $(v, J(v))$ is a linearly independent ordered list, so it is an ordered basis of $L$ and its span is contained in $H$. Comment: the contrapositive can be stated: Given $V$ with CSO $J$, $v \in V$, and a $J$-invariant subspace $H$, if $v \notin H$, then $H \cap \operatorname{span}\{v, J(v)\}=\left\{0_{V}\right\}$.

Lemma 5.16. Given $V$ with $C S O ~ J$, if $L^{1}, L^{2}$ are distinct $J$-complex lines in $V$, then $\operatorname{span}\left(L^{1} \cup L^{2}\right)$ has an ordered basis with 4 elements. In particular, a subspace $H \subseteq V$ that does not have 4 elements forming a linearly independent list can contain at most one J-complex line.

Proof. Suppose $L_{1}$ is a $J$-complex line in $V$, with $L_{1}=\operatorname{span}\{v, J(v)\}$. If $L_{2}$ is a $J$-complex line with $L_{2} \neq L_{1}$, then $L_{2} \nsubseteq L_{1}$, so there is some $u \in L_{2} \backslash L_{1}$, and $(v, J(v), u)$ is a linearly independent list. Because $L_{2}$ is $J$-invariant, $J(u) \in L_{2}$, so by Lemma 5.11, $(v, J(v), u, J(u))$ is a linearly independent ordered list of elements of $L^{1} \cup L^{2}$, and an ordered basis of $\operatorname{span}\left(L^{1} \cup L^{2}\right)$.

Lemma 5.17. Given $V$ with $C S O J$, and a subspace $H$ of $V$, if $H=\left\{0_{V}\right\}$ or $H$ has an ordered basis of the form $\left(u_{1}, J\left(u_{1}\right), \ldots, u_{\nu}, J\left(u_{\nu}\right)\right)$, then either $H=V$ or there exists a subspace $U$ of $V$ such that $U$ is $J$-invariant, $H \subseteq U$, and $U$ admits an ordered basis with $2(\nu+1)$ elements.

Proof. This is trivial for $H=\left\{0_{V}\right\}$ or $H=V$; otherwise, the ordered basis for $H$ can be extended by two more elements to an ordered basis of a $J$-invariant subspace as in the Proof of Lemma 5.13. Note that this Lemma then applies to $U$ and can be repeated to get another subspace containing $U$.

Lemma 5.18. Given a vector space $V_{1}$ with $C S O J_{1}$ and an element $v \in V_{1}$, another vector space $V_{2}$ with $C S O J_{2}$, and a real linear map $A: V_{1} \rightarrow V_{2}$, the following are equivalent.
(1) $A\left(J_{1}(v)\right) \in \operatorname{span}\left\{A(v), J_{2}(A(v))\right\}$.
(2) A maps the subspace $\operatorname{span}\left\{v, J_{1}(v)\right\} \subseteq V_{1}$ to the subspace

$$
\operatorname{span}\left\{A(v), J_{2}(A(v))\right\} \subseteq V_{2}
$$

Further, if $A$ and $v$ satisfy (1) and $A\left(J_{1}(v)\right) \neq 0_{V_{2}}$, then $A$ and $J_{1}(v)$ satisfy (1):

$$
A\left(J_{1}\left(J_{1}(v)\right)\right) \in \operatorname{span}\left\{A\left(J_{1}(v)\right), J_{2}\left(A\left(J_{1}(v)\right)\right)\right\}
$$

Proof. $(2) \Longleftrightarrow(1)$ is straightforward. If $A\left(J_{1}(v)\right)=\alpha_{1} \cdot A(v)+\alpha_{2} \cdot J_{2}(A(v))$ for some $\left(\alpha_{1}, \alpha_{2}\right) \neq(0,0)$, then there is this linear combination.

$$
\begin{aligned}
& \frac{-\alpha_{1}}{\alpha_{1}^{2}+\alpha_{2}^{2}} \cdot A\left(J_{1}(v)\right)+\frac{\alpha_{2}}{\alpha_{1}^{2}+\alpha_{2}^{2}} \cdot J_{2}\left(A\left(J_{1}(v)\right)\right) \\
= & \frac{-\alpha_{1}}{\alpha_{1}^{2}+\alpha_{2}^{2}} \cdot\left(\alpha_{1} \cdot A(v)+\alpha_{2} \cdot J_{2}(A(v))\right) \\
& +\frac{\alpha_{2}}{\alpha_{1}^{2}+\alpha_{2}^{2}} \cdot J_{2}\left(\alpha_{1} \cdot A(v)+\alpha_{2} \cdot J_{2}(A(v))\right) \\
= & -A(v)=A\left(J_{1}\left(J_{1}(v)\right)\right) .
\end{aligned}
$$

The above notion for a real linear map $A$ is slightly stronger than the statement that $A$ maps the $J_{1}$-complex line $\operatorname{span}\left\{v, J_{1}(v)\right\}$ into some $J_{2}$-complex line; if $A(v)=0_{V_{2}}$, condition (2) implies $A$ maps $\operatorname{span}\left\{v, J_{1}(v)\right\}$ to the zero subspace.

Exercise 5.19. Given $V$ with CSO $J$, if $V \neq\left\{0_{V}\right\}$, then the ordered list $\left(I d_{V}, J\right)$ is linearly independent in $\operatorname{End}(V)$.

Exercise 5.20. Given $V$ with two CSOs $J_{1}$ and $J_{2}$, if $J_{2} \neq \pm J_{1}$, then the ordered list $\left(I d_{V}, J_{1}, J_{2}, J_{1} \circ J_{2}\right)$ is linearly independent in $\operatorname{End}(V)$.

Hint. The hypothesis implies $V \neq\left\{0_{V}\right\}$, so Exercise 5.19 applies and $\left(I d_{V}, J_{1}\right)$ is a linearly independent list. The next step is to show that $\left(I d_{V}, J_{1}, J_{2}\right)$ is a linearly independent list. If there are real scalars such that $\alpha_{1} \cdot I d_{V}+\alpha_{2} \cdot J_{1}+\alpha_{3} \cdot J_{2}=0_{\operatorname{End}(V)}$, then:

$$
\begin{aligned}
\left(\alpha_{1} \cdot I d_{V}+\alpha_{2} \cdot J_{1}\right) \circ\left(\alpha_{1} \cdot I d_{V}+\alpha_{2} \cdot J_{1}\right) & =\left(-\alpha_{3} \cdot J_{2}\right) \circ\left(-\alpha_{3} \cdot J_{2}\right) \\
\left(\alpha_{1}^{2}-\alpha_{2}^{2}\right) \cdot I d_{V}+2 \alpha_{1} \alpha_{2} \cdot J_{1} & =-\alpha_{3}^{2} \cdot I d_{V} \\
\Longrightarrow \alpha_{1} \alpha_{2} & =0 .
\end{aligned}
$$

If $\alpha_{2}=0$ then by the linear independence of $\left(I d_{V}, J_{2}\right)$ from Exercise 5.19, $\alpha_{1}=$ $\alpha_{2}=\alpha_{3}=0$. If $\alpha_{1}=0$ then $\left(\alpha_{2} \cdot J_{1}\right) \circ\left(\alpha_{2} \cdot J_{1}\right)=\left(-\alpha_{3} \cdot J_{2}\right) \circ\left(-\alpha_{3} \cdot J_{2}\right) \Longrightarrow$ $-\alpha_{2}^{2}=-\alpha_{3}^{2} \Longrightarrow \alpha_{2} \cdot\left(J_{1} \pm J_{2}\right)=0_{\operatorname{End}(V)}$, and the hypothesis $J_{2} \neq \pm J_{1}$ implies $\alpha_{1}=\alpha_{2}=\alpha_{3}=0$.

The claimed independence of the list $\left(I d_{V}, J_{1}, J_{2}, J_{1} \circ J_{2}\right)$ then follows from applying Lemma 5.11 to the list $\left(I d_{V}, J_{1}, J_{2}\right)$ and the $\mathrm{CSO} \operatorname{Hom}\left(J_{2}, I d_{V}\right)$ on $\operatorname{End}(V)$ from Example 5.4.

Remark 5.21. The results in this Section give some details omitted from $\left[\mathbf{C}_{1}\right]$ §2.

### 5.2. Complex linear and antilinear maps

Definition 5.22. For $\mathbf{U}=\left(U, J_{U}\right), \mathbf{V}=\left(V, J_{V}\right)$, a (real linear) map $A \in$ $\operatorname{Hom}(U, V)$ is c-linear, means: $A \circ J_{U}=J_{V} \circ A$. A map $A \in \operatorname{Hom}(U, V)$ is a-linear means: $A \circ J_{U}=-J_{V} \circ A$.

Because some vector spaces can admit several complex structures, it will sometimes be more clear to specifically refer to $A: U \rightarrow V$ as c-linear (or a-linear) with respect to the pair $\left(J_{U}, J_{V}\right)$.

Lemma 5.23. If $A: \mathbf{U} \rightarrow \mathbf{V}$ is c-linear (or a-linear) and invertible, then $A^{-1}$ is also c-linear (or a-linear). The composite of two c-linear maps (or two a-linear maps) is c-linear.

Lemma 5.24. Given $\mathbf{V}=\left(V, J_{V}\right)$ and $\mathbf{V}^{\prime}=\left(V^{\prime}, J_{V}^{\prime}\right)$, any map $A: U \rightarrow U^{\prime}$, and a c-linear map $B: \mathbf{V} \rightarrow \mathbf{V}^{\prime}$, the maps $[A \otimes B]: U \otimes \mathbf{V} \rightarrow U^{\prime} \otimes \mathbf{V}^{\prime}$ and $[B \otimes A]: \mathbf{V} \otimes U \rightarrow \mathbf{V}^{\prime} \otimes U^{\prime}$ are c-linear with respect to the induced CSOs from Example 5.3.

Lemma 5.25. Given $\mathbf{V}=\left(V, J_{V}\right)$ and $\mathbf{V}^{\prime}=\left(V^{\prime}, J_{V}^{\prime}\right)$, any map $A: U^{\prime} \rightarrow U$, and a c-linear map $B: \mathbf{V} \rightarrow \mathbf{V}^{\prime}$, the maps $\operatorname{Hom}(A, B): \operatorname{Hom}(U, \mathbf{V}) \rightarrow \operatorname{Hom}\left(U^{\prime}, \mathbf{V}^{\prime}\right)$ and $\operatorname{Hom}(B, A): \operatorname{Hom}\left(\mathbf{V}^{\prime}, U^{\prime}\right) \rightarrow \operatorname{Hom}(\mathbf{V}, U)$ are c-linear with respect to the induced CSOs from Example 5.4.

Lemma 5.26. Given $V$ and a $C S O J \in \operatorname{End}(V)$, for any invertible $A: U \rightarrow V$, the composite $A^{-1} \circ J \circ A \in \operatorname{End}(U)$ is a $C S O$. A is c-linear with respect to $A^{-1} \circ J \circ A$ and $J$. If $B: U \rightarrow V$ is another invertible map and $A^{-1} \circ J \circ A=B^{-1} \circ J \circ B$, then $A \circ B^{-1}$ is a c-linear endomorphism of $(V, J)$.

The CSO $A^{-1} \circ J \circ A$ is the pullback of $J$.
Given a direct sum $V=\overline{V_{1} \oplus V_{2}}$, recall from Definition 1.82 that a CSO $J \in \operatorname{End}(V)$ respects the direct sum if $P_{I} \circ J \circ Q_{i}=0_{\operatorname{Hom}\left(V_{i}, V_{I}\right)}$ for $i \neq I$, or equivalently, $Q_{i} \circ P_{i} \circ J=J \circ Q_{i} \circ P_{i}$ for $i=1$ or 2 , so the map $Q_{i} \circ P_{i}$ is c-linear.

Lemma 5.27. Given $V=V_{1} \oplus V_{2}$ and CSOs $J_{V_{i}} \in \operatorname{End}\left(V_{i}\right)$ for $i=1,2$, then $Q_{1} \circ J_{V_{1}} \circ P_{1}+Q_{2} \circ J_{V_{2}} \circ P_{2} \in \operatorname{End}(V)$ is a CSO, and it respects the direct sum.

Lemma 5.28. Given $V=V_{1} \oplus V_{2}$ and a CSO $J \in \operatorname{End}(V)$ that respects the direct sum, each induced map $P_{i} \circ J \circ Q_{i}$ on $V_{i}$ is a $C S O$.

Proof. The claim is easily checked. This Lemma is compatible with the previous one: given $J$, it is recovered by re-combining the induced maps as in Lemma 5.27:

$$
Q_{1} \circ\left(P_{1} \circ J \circ Q_{1}\right) \circ P_{1}+Q_{2} \circ\left(P_{2} \circ J \circ Q_{2}\right) \circ P_{2}=J
$$

Conversely, given $J_{V_{1}}, J_{V_{2}}$ as in Lemma 5.27 , they agree with CSOs induced by $Q_{1} \circ J_{V_{1}} \circ P_{1}+Q_{2} \circ J_{V_{2}} \circ P_{2}:$

$$
P_{i} \circ\left(Q_{1} \circ J_{V_{1}} \circ P_{1}+Q_{2} \circ J_{V_{2}} \circ P_{2}\right) \circ Q_{i}=J_{V_{i}}
$$

Lemma 5.29. For $V=V_{1} \oplus V_{2}$ and $V^{\prime}=V_{1}^{\prime} \oplus V_{2}^{\prime}$ and invertible maps $A: V_{2} \rightarrow$ $V_{1}, A^{\prime}: V_{2}^{\prime} \rightarrow V_{1}^{\prime}$, let $J, J^{\prime}$ be CSOs on $V$ and $V^{\prime}$ constructed as in Example 5.8. Then, for $H: V \rightarrow V^{\prime}$, the following are equivalent.
(1) $H$ is c-linear with respect to $J$ and $J^{\prime}$.
(2) $A^{\prime} \circ P_{2}^{\prime} \circ H \circ Q_{2}=P_{1}^{\prime} \circ H \circ Q_{1} \circ A$ and $P_{1}^{\prime} \circ H \circ Q_{2}=-A^{\prime} \circ P_{2}^{\prime} \circ H \circ Q_{1} \circ A$.

Hint. To show $(2) \Longrightarrow(1)$, expand

$$
H \circ J=\left(Q_{1}^{\prime} \circ P_{1}^{\prime}+Q_{2}^{\prime} \circ P_{2}^{\prime}\right) \circ H \circ\left(Q_{2} \circ A^{-1} \circ P_{1}-Q_{1} \circ A \circ P_{2}\right)
$$

and similarly $J^{\prime} \circ H$.
For $(1) \Longrightarrow(2)$, apply $\operatorname{Hom}\left(Q_{1}, P_{2}^{\prime}\right)$ to both sides of $H \circ J=J^{\prime} \circ H$ to get one of the equations, and apply $\operatorname{Hom}\left(Q_{2}, P_{2}^{\prime}\right)$ to get the other.

REmark 5.30. The preceding Lemma displays an algebraic pattern analogous to the Cauchy-Riemann equations.

Exercise 5.31. Given $\left(V_{1}, J_{1}\right)$ and $\left(V_{2}, J_{2}\right)$ and $V=V_{1} \oplus V_{2}$, a map $A: V_{1} \rightarrow V_{2}$ is a-linear if and only if

$$
Q_{1} \circ J_{1} \circ P_{1}+Q_{2} \circ A \circ P_{1}+Q_{2} \circ J_{2} \circ P_{2}
$$

is a CSO on $V$. This CSO respects the direct sum if and only if $A=0_{\operatorname{Hom}\left(V_{1}, V_{2}\right)}$, in which case it is the CSO constructed in Lemma 5.27.

Exercise 5.32. For $V, \mathbf{V}_{\mathbf{1}}, \mathbf{V}_{\mathbf{2}}, A$ as in the previous Exercise, the CSO $J_{A}=$ $Q_{1} \circ J_{1} \circ P_{1}+Q_{2} \circ A \circ P_{1}+Q_{2} \circ J_{2} \circ P_{2}$ is similar to the direct sum CSO $J_{0}=$ $Q_{1} \circ J_{1} \circ P_{1}+Q_{2} \circ J_{2} \circ P_{2}$, in the sense that $J_{A}=G^{-1} \circ J_{0} \circ G$ for some invertible $G \in \operatorname{End}(V)$, and $G$ can be chosen so that $P_{2} \circ G \circ Q_{2}=I d_{V_{2}}$.

Hint. Let $G=I d_{V}+\frac{1}{2} \cdot Q_{2} \circ A \circ J_{1} \circ P_{1}$, then check $G \circ J_{A}=J_{0} \circ G$, or use $G^{-1}=I d_{V}-\frac{1}{2} \cdot Q_{2} \circ A \circ J_{1} \circ P_{1}$.

Exercise 5.33. Given $V$ and $A \in \operatorname{End}(V)$, if $V$ is finite-dimensional and there is some CSO $J$ on $V$ such that $A$ is a-linear with respect to $J$, then $\operatorname{Tr}_{V}(A)=0$.

Exercise 5.34. Given $\mathbf{V}=\left(V, J_{V}\right)$, the canonical maps $l_{1}: \mathbb{R} \otimes \mathbf{V} \rightarrow \mathbf{V}$ and $l_{2}: \mathbf{V} \otimes \mathbb{R} \rightarrow \mathbf{V}$ from Example 1.27 are c-linear.

Hint. The CSO on $\mathbb{R} \otimes V$ is as in Example 5.3, and the claim for $l_{1}$ follows from Lemma 1.37. The claim for $l_{2}: V \otimes \mathbb{R} \rightarrow V$ is analogous.

Exercise 5.35. Given $\mathbf{W}=(W, J)$, the map $m: \mathbf{W} \rightarrow \operatorname{Hom}(\mathbb{K}, \mathbf{W})$ from Definition 1.19 is c-linear.

Hint. The CSO on $\operatorname{Hom}(\mathbb{K}, W)$ is as in Example 5.4, and the claim follows from Lemma 1.20.

Exercise 5.36. Given $U, V, W$, with $\mathbf{U}=(U, J)$, the canonical map (Definition 1.7) $t_{U V}^{W}: \operatorname{Hom}(\mathbf{U}, V) \rightarrow \operatorname{Hom}(\operatorname{Hom}(V, W), \operatorname{Hom}(\mathbf{U}, W))$ is c-linear with respect to the induced CSOs as in Example 5.4.

Exercise 5.37. Given $U, V, W$, with $\mathbf{V}=(V, J), t_{U V}^{W}: \operatorname{Hom}(U, \mathbf{V}) \rightarrow$ $\operatorname{Hom}(\operatorname{Hom}(\mathbf{V}, W), \operatorname{Hom}(U, W))$ is c-linear with respect to the induced CSOs.

Exercise 5.38. Given $U, V, W$, with $\mathbf{W}=(W, J)$, and any $A \in \operatorname{Hom}(U, V)$, the map

$$
t_{U V}^{W}(A) \in \operatorname{Hom}(\operatorname{Hom}(V, W), \operatorname{Hom}(U, W))
$$

is c-linear $\operatorname{Hom}(V, \mathbf{W}) \rightarrow \operatorname{Hom}(U, \mathbf{W})$.
Hint. This claim, Exercise 5.36, and Exercise 5.37 all follow from Lemma 1.8.

Exercise 5.39. Given $V$ and $W$, with $\mathbf{V}=\left(V, J_{V}\right)$, the canonical map (Definition 1.12) $d_{V W}: \mathbf{V} \rightarrow \operatorname{Hom}(\operatorname{Hom}(\mathbf{V}, W), W)$ is c-linear with respect to the induced CSO as in Example 5.4.

Exercise 5.40. Given $V$ and $W$, with $\mathbf{W}=\left(W, J_{W}\right)$, and any $v \in V$, the map $d_{V W}(v) \in \operatorname{Hom}(\operatorname{Hom}(V, W), W)$ is c-linear $\operatorname{Hom}(V, \mathbf{W}) \rightarrow \mathbf{W}$.

Hint. This claim and Exercise 5.39 both follow from Lemma 1.13.

Exercise 5.41. Given $U, V, W$, with $\mathbf{U}=(U, J)$, the canonical map (Definition 1.51) $e_{U V}^{W}: \operatorname{Hom}(\mathbf{U}, V) \rightarrow \operatorname{Hom}(\operatorname{Hom}(V, W) \otimes \mathbf{U}, W)$ is c-linear with respect to the induced CSOs.

Exercise 5.42. Given $U, V, W$, with $\mathbf{V}=(V, J), e_{U V}^{W}: \operatorname{Hom}(U, \mathbf{V}) \rightarrow$ $\operatorname{Hom}(\operatorname{Hom}(\mathbf{V}, W) \otimes U, W)$ is c-linear with respect to the induced CSOs.

Exercise 5.43. Given $U, V, W$, with $\mathbf{W}=(W, J)$, and any $A \in \operatorname{Hom}(U, V)$, the map $e_{U V}^{W}(A) \in \operatorname{Hom}(\operatorname{Hom}(V, W) \otimes U, W)$ is c-linear $\operatorname{Hom}(V, \mathbf{W}) \otimes U \rightarrow \mathbf{W}$.

Hint. This claim, Exercise 5.41, and Exercise 5.42 all follow from Lemma 1.52.

Recall from Definition 2.69 that $\operatorname{Hom}(\operatorname{Hom}(V, W) \otimes V, W)$ contains a distinguished element $E v_{V W}: A \otimes v \mapsto A(v)$.

ExERCISE 5.44. Given $V$ and $W$, with $\mathbf{W}=\left(W, J_{W}\right)$, the canonical evaluation $E v_{V W}: \operatorname{Hom}(V, \mathbf{W}) \otimes V \rightarrow \mathbf{W}$ is c-linear.

Hint. This claim can be checked directly; it also follows from Lemma 2.71, or the formula $E v_{V W}=e_{V V}^{W}\left(I d_{V}\right)$ from Equation (2.11) and Exercise 5.43.

Exercise 5.45. Given $U, V, W$, with $\mathbf{W}=\left(W, J_{W}\right)$, the map

$$
T_{U, V ; W}: \operatorname{Hom}(U, \operatorname{Hom}(V, \mathbf{W})) \rightarrow \operatorname{Hom}(V, \operatorname{Hom}(U, \mathbf{W}))
$$

from Definition 4.2 is c-linear.
Hint. The claim follows from Lemma 4.6.
Exercise 5.46. Given $U, V, W$, with $\mathbf{U}=\left(U, J_{U}\right)$, the map

$$
T_{U, V ; W}: \operatorname{Hom}(\mathbf{U}, \operatorname{Hom}(V, W)) \rightarrow \operatorname{Hom}(V, \operatorname{Hom}(\mathbf{U}, W))
$$

and its inverse from Equation (4.2) in Lemma 4.4,

$$
T_{V, U ; W}: \operatorname{Hom}(V, \operatorname{Hom}(\mathbf{U}, W)) \rightarrow \operatorname{Hom}(\mathbf{U}, \operatorname{Hom}(V, W)),
$$

are c-linear.
Hint. Both claims follow from Lemma 4.6. Alternatively, the c-linearity of the composite formula from Definition 4.2,

$$
T_{U, V ; W}=\operatorname{Hom}\left(d_{V W}, I d_{\operatorname{Hom}(U, W)}\right) \circ t_{U, \operatorname{Hom}(V, W)}^{W},
$$

and its inverse could be shown to follow from the c-linearity of the $t$ and $d$ maps, as in Exercise 5.36, Exercise 5.37, and Exercise 5.39.

Proposition 5.47. Given $V$, consider three elements $A, J_{1}, J_{2} \in \operatorname{End}(V)$. The following two statements are equivalent.
(1) $\left(J_{1}+J_{2}\right) \circ A=J_{1}-J_{2}$.
(2) $J_{2} \circ\left(I d_{V}+A\right)=J_{1} \circ\left(I d_{V}-A\right)$.

The following two statements are also equivalent to each other.
$\left(1^{\prime}\right) A \circ\left(J_{1}+J_{2}\right)=J_{1}-J_{2}$.
$\left(2^{\prime}\right)\left(I d_{V}+A\right) \circ J_{2}=\left(I d_{V}-A\right) \circ J_{1}$.
If $A, J_{1}, J_{2}$ satisfy either condition (1) or (1'), then any two of the following imply the remaining third.
(3) $J_{1}$ is invertible.
(4) $J_{1}+J_{2}$ is invertible.
(5) $I d_{V}+A$ is invertible.

If $A, J_{1}, J_{2}$ satisfy (1) or (1'), and also (5), then any two of the following imply the remaining third.
(6) $A \circ J_{1}=-J_{1} \circ A$.
(7) $J_{1}$ is a CSO.
(8) $J_{2}$ is a CSO.

Proof. (1) $\Longleftrightarrow(2)$ by an elementary algebraic manipulation. The $\left(1^{\prime}\right) \Longleftrightarrow$ $\left(2^{\prime}\right)$ and subsequent implications are analogous and left as an exercise. For (3), (4), (5), use (1) or (2) to establish

$$
\left(J_{1}+J_{2}\right) \circ\left(I d_{V}+A\right)=2 \cdot J_{1}
$$

and the claim follows.
For (6), (7), (8), use (2) to establish

$$
\begin{align*}
& \left(J_{1}+J_{2}\right) \circ\left(A \circ J_{1}+J_{1} \circ A\right)  \tag{5.4}\\
= & J_{1} \circ A \circ J_{1}+J_{2} \circ A \circ J_{1}+J_{1} \circ J_{1} \circ A+J_{2} \circ J_{1} \circ A \\
= & J_{1} \circ A \circ J_{1}+J_{2} \circ\left(I d_{V}+A\right) \circ J_{1}+J_{1} \circ J_{1} \circ A-J_{2} \circ J_{1} \circ\left(I d_{V}-A\right) \\
= & J_{1} \circ A \circ J_{1}+J_{1} \circ\left(I d_{V}-A\right) \circ J_{1}+J_{1} \circ J_{1} \circ A-J_{2} \circ J_{2} \circ\left(I d_{V}+A\right) \\
= & \left(J_{1} \circ J_{1}-J_{2} \circ J_{2}\right) \circ\left(I d_{V}+A\right) .
\end{align*}
$$

Given (6), (8), the equation (5.4) becomes $0_{\operatorname{End}(V)}=\left(J_{1} \circ J_{1}+I d_{V}\right) \circ\left(I d_{V}+A\right)$, and (7) follows from (5). Similarly, given (6), (7), (5.4) becomes $0_{\operatorname{End}(V)}=-\left(I d_{V}+\right.$ $\left.J_{2} \circ J_{2}\right) \circ\left(I d_{V}+A\right)$, and (8) follows from (5). For (7), (8), note that (7) implies (3) and then (5) implies (4), so by (7) and (8), (5.4) becomes LHS $=0_{\operatorname{End}(V)}$, and (6) follows from (4).

Given $V$ with a CSO $J_{1}$, Proposition 5.47 establishes a bijective correspondence between the set of CSOs $J_{2}$ on $V$ with $J_{1}+J_{2}$ invertible and the set of $A \in \operatorname{End}(V)$ with $A$ a-linear (with respect to $J_{1}$ ) and $I d_{V}+A$ invertible, as follows. Since $J_{1}$ is a $\mathrm{CSO},(3)$ and $(7)$ hold. For any a-linear $A \in \operatorname{End}(V)$ with $I d_{V}+A$ invertible, (5) and (6) hold. If we define $J_{2}$ by the similarity relation $J_{2}=\left(I d_{V}+A\right) \circ J_{1} \circ\left(I d_{V}+A\right)^{-1}$, then $J_{2}=J_{1} \circ\left(I d_{V}-A\right) \circ\left(I d_{V}+A\right)^{-1}$, so (2) holds, (1), (4), and (8) follow as consequences, and $A$ satisfies $A=\left(J_{1}+J_{2}\right)^{-1} \circ\left(J_{1}-J_{2}\right)$. Conversely, for any CSO $J_{2}$ with $J_{1}+J_{2}$ invertible, (4) and (8) hold. If we define

$$
\begin{equation*}
A=\left(J_{1}+J_{2}\right)^{-1} \circ\left(J_{1}-J_{2}\right), \tag{5.5}
\end{equation*}
$$

then (1) holds, (2), (5), and (6) follow as consequences, and $J_{2}$ satisfies $J_{2}=$ $J_{1} \circ\left(I d_{V}-A\right) \circ\left(I d_{V}+A\right)^{-1}=\left(I d_{V}+A\right) \circ J_{1} \circ\left(I d_{V}+A\right)^{-1}$.

Exercise 5.48. Given $V$ and any two CSOs $J_{1}, J_{2}$, the map $J_{1}+J_{2}$ is c-linear with respect to $J_{1}$ and $J_{2}$, and the maps $\pm\left(J_{1}-J_{2}\right)$ are a-linear with respect to $J_{1}$ and $J_{2}$.

Big Exercise 5.49. Given $V_{1}, V_{2}$ with CSOs $J_{1}, J_{2}$, and a real linear map $A: V_{1} \rightarrow V_{2}$, if the image subspace $A\left(V_{1}\right)$ admits a linearly independent list of 3 or more elements of $V_{2}$, then the following are equivalent.
(1) For each $v \in V_{1}, A\left(J_{1}(v)\right) \in \operatorname{span}\left\{A(v), J_{2}(A(v))\right\}$.
(2) For each $v \in V_{1}, A$ maps the subspace $\operatorname{span}\left\{v, J_{1}(v)\right\} \subseteq V_{1}$ to the subspace $\operatorname{span}\left\{A(v), J_{2}(A(v))\right\} \subseteq V_{2}$.
(3) For each $v \in V_{1}$, either $A\left(J_{1}(v)\right)=J_{2}(A(v))$ or $A\left(J_{1}(v)\right)=-J_{2}(A(v))$.
(4) $A \circ J_{1}=J_{2} \circ A$ or $A \circ J_{1}=-J_{2} \circ A$.

Hint. The idea is that $A$ takes $J_{1}$-complex lines to $J_{2}$-complex lines, and that this is equivalent to $A$ being c-linear or a-linear. See also $\left[\mathbf{C}_{1}\right]$ for other properties of $A$ equivalent to (4).

### 5.3. Commuting Complex Structure Operators

### 5.3.1. Two Commuting Complex Structure Operators.

Lemma 5.50. Given $V$ and two $C S O s J_{1}, J_{2}$, the following are equivalent.
(1) $J_{1}$ and $J_{2}$ commute (i.e., $J_{1} \circ J_{2}=J_{2} \circ J_{1}$ ).
(2) The composite $J_{1} \circ J_{2}$ is an involution.
(3) The composite $-J_{1} \circ J_{2}$ is an involution.

Example 5.51. Given $V$ with commuting $\operatorname{CSOs} J_{1}, J_{2}$, Lemma 1.112 applies to the involution $-J_{1} \circ J_{2}$ as in Lemma 5.50: there is a direct sum $V=V_{c} \oplus V_{a}$ produced by $-J_{1} \circ J_{2}$, where

$$
\begin{aligned}
V_{c} & =\left\{v \in V:\left(-J_{1} \circ J_{2}\right)(v)=v\right\}=\left\{v \in V: J_{2}(v)=J_{1}(v)\right\} \\
V_{a} & =\left\{v \in V:\left(-J_{1} \circ J_{2}\right)(v)=-v\right\}=\left\{v \in V: J_{2}(v)=-J_{1}(v)\right\}
\end{aligned}
$$

with projection operators

$$
P_{c}=\frac{1}{2} \cdot\left(I d_{V}-J_{1} \circ J_{2}\right): V \rightarrow V_{c}, P_{a}=\frac{1}{2} \cdot\left(I d_{V}+J_{1} \circ J_{2}\right): V \rightarrow V_{a}
$$

As remarked in the Proof of Lemma 1.112, the same formulas are also used for $Q_{c} \circ P_{c}, Q_{a} \circ P_{a} \in \operatorname{End}(V)$, where $Q_{c}$ and $Q_{a}$ are the corresponding subspace inclusions.

Note that applying Lemma 1.112 to the involution $J_{1} \circ J_{2}$ would give the direct sum in the other order, $V=V_{a} \oplus V_{c}$.

Lemma 5.52. For $V, J_{1}, J_{2}$ as in Lemma 5.50, and another space $V^{\prime}$ with commuting CSOs $J_{1}^{\prime}$, $J_{2}^{\prime}$, a map $H: V \rightarrow V^{\prime}$ respects the direct sums $V_{c} \oplus V_{a}$ and $V_{c}^{\prime} \oplus V_{a}^{\prime}$ if and only if $H \circ J_{1} \circ J_{2}=J_{1}^{\prime} \circ J_{2}^{\prime} \circ H$.

Proof. This is an example of Lemma 1.118.
Example 5.53. Lemma 5.52 applies to $V^{\prime}=V, J_{1}^{\prime}=J_{1}, J_{2}^{\prime}=J_{2}$, and either $H=J_{1}$ or $H=J_{2}$, each of which induces a CSO on $V_{c}$ and on $V_{a}$ by Lemma 5.28. The subspace $V_{c}$ has a canonical CSO, induced by either $J_{1}$ or $J_{2}$ :

$$
P_{c} \circ J_{1} \circ Q_{c}=P_{c} \circ J_{2} \circ Q_{c} \in \operatorname{End}\left(V_{c}\right)
$$

The maps $P_{c}: V \rightarrow V_{c}$ and $Q_{c}: V_{c} \hookrightarrow V$ are c-linear with respect to either CSO on $V$. The induced CSOs on the subspace $V_{a}$ are opposite, and generally distinct:

$$
P_{a} \circ J_{1} \circ Q_{a}=-P_{a} \circ J_{2} \circ Q_{a} \in \operatorname{End}\left(V_{a}\right) .
$$

Lemma 5.54. For $V, J_{1}, J_{2}$ as in Lemma 5.50, $\mathbf{U}=\left(U, J_{U}\right)$, and a map $H: U \rightarrow V$, if $H$ is c-linear with respect to both $\left(J_{U}, J_{1}\right)$ and $\left(J_{U}, J_{2}\right)$, then the image of $H$ is contained in $V_{c}$.

Proof. This can be checked by showing $P_{a} \circ H=0_{\operatorname{Hom}\left(U, V_{a}\right)}$.

Lemma 5.55. For $V, J_{1}, J_{2}$ as in Lemma 5.50, $\mathbf{U}=\left(U, J_{U}\right)$, and a map $H: V \rightarrow U$, if $H$ is c-linear with respect to either $\left(J_{1}, J_{U}\right)$ or $\left(J_{2}, J_{U}\right)$, then $H \circ Q_{c}: V_{c} \rightarrow \mathbf{U}$ is c-linear.

Proof. By the construction of the CSO on $V_{c}$ from Example 5.53, the LHS quantities in the following two equations are equal to each other:

$$
\begin{aligned}
& \left(H \circ Q_{c}\right) \circ\left(P_{c} \circ J_{1} \circ Q_{c}\right)=H \circ J_{1} \circ Q_{c}, \\
& \left(H \circ Q_{c}\right) \circ\left(P_{c} \circ J_{2} \circ Q_{c}\right)=H \circ J_{2} \circ Q_{c} .
\end{aligned}
$$

The equalities hold because $J_{1}$ and $J_{2}$ commute with $Q_{c} \circ P_{c}$. On the RHS, either $H \circ J_{1}$ or $H \circ J_{2}$ is equal to $J_{U} \circ H$ by hypothesis, so the claim $\left(H \circ Q_{c}\right) \circ\left(P_{c} \circ J_{1} \circ Q_{c}\right)=$ $J_{U} \circ\left(H \circ Q_{c}\right)$ follows.

Lemma 5.56. For $V$ with commuting $C S O s J_{1}, J_{2}$, and $V^{\prime}$ with commuting CSOs $J_{1}^{\prime}$, $J_{2}^{\prime}$ as in Lemma 5.52, if $H: V \rightarrow V^{\prime}$ is c-linear with respect to any of the pairs $\left(J_{1}, J_{1}^{\prime}\right)$ or $\left(J_{1}, J_{2}^{\prime}\right)$ or $\left(J_{2}, J_{1}^{\prime}\right)$ or $\left(J_{2}, J_{2}^{\prime}\right)$, then $P_{c}^{\prime} \circ H \circ Q_{c}: V_{c} \rightarrow V_{c}^{\prime}$ is c-linear with respect to the canonical CSOs.

Proof. The CSOs on $V_{c}$ and $V_{c}^{\prime}$ are as in Example 5.53.
Lemma 5.57. Given $V$ with commuting $C S O s J_{V}^{1}, J_{V}^{2}$, and $U$ with commuting CSOs $J_{U}^{1}, J_{U}^{2}$, if $H: U \rightarrow V$ satisfies both $H \circ J_{U}^{1}=J_{V}^{1} \circ H$ and $H \circ J_{U}^{2}=$ $J_{V}^{2} \circ H$, then $H: U_{c} \oplus U_{a} \rightarrow V_{c} \oplus V_{a}$ respects the direct sums and the induced map $P_{c}^{V} \circ H \circ Q_{c}^{U}: U_{c} \rightarrow V_{c}$ is c-linear with respect to the induced CSOs. If, also, $H$ is invertible, then for $i=c$, a, the induced map $P_{i}^{V} \circ H \circ Q_{i}^{U}: U_{i} \rightarrow V_{i}$ is invertible.

Proof. This follows from Lemma 5.52, Lemma 5.56, and Lemma 1.83.
We remark that the direct summands in Lemma 5.57 are all subspaces; if $u=Q_{c}^{U}(u) \in U_{c} \subseteq U$, then $H(u)=H\left(Q_{c}^{U}(u)\right) \in V_{c} \subseteq V$, so $H(u)$ is in the fixed point set of the idempotent $P_{c}^{V}: V \rightarrow V$, as follows:

$$
\begin{aligned}
u \in U_{c} \Longrightarrow H(u) & =H\left(Q_{c}^{U}(u)\right)=H\left(Q_{c}^{U}\left(P_{c}^{U}\left(Q_{c}^{U}(u)\right)\right)\right)=Q_{c}^{V}\left(P_{c}^{V}\left(H\left(Q_{c}^{U}(u)\right)\right)\right) \\
& =\left(P_{c}^{V} \circ H \circ Q_{c}^{U}\right)(u)=P_{c}^{V}(H(u)) \in V_{c} \subseteq V
\end{aligned}
$$

The induced map $P_{c}^{V} \circ H \circ Q_{c}^{U}: U_{c} \rightarrow V_{c}$ is just the restriction of $H: U \rightarrow V$ to the subspace $U_{c}$, with image contained in the subspace $V_{c}$ of the target.

Lemma 5.58. Given $V$ with commuting $C S O s J_{V}^{1}, J_{V}^{2}$, and $U$ with commuting CSOs $J_{U}^{1}, J_{U}^{2}$, if $H: U \rightarrow V$ satisfies both $H \circ J_{U}^{1}=-J_{V}^{1} \circ H$ and $H \circ J_{U}^{2}=$ $-J_{V}^{2} \circ H$, then $H: U_{c} \oplus U_{a} \rightarrow V_{c} \oplus V_{a}$ respects the direct sums and the induced map $P_{c}^{V} \circ H \circ Q_{c}^{U}: U_{c} \rightarrow V_{c}$ is a-linear with respect to the induced CSOs.

Proof. This is straightforward to check directly, or follows from Lemma 5.57 with $J_{V}^{1}, J_{V}^{2}$ replaced by the opposite CSOs $-J_{V}^{1},-J_{V}^{2}$.

The following Theorem weakens the hypotheses of Lemma 5.57.
TheOrem 5.59. Given $V$ with commuting $\operatorname{CSOs} J_{V}^{1}, J_{V}^{2}$, and $U$ with commuting CSOs $J_{U}^{1}$, $J_{U}^{2}$, if $H: U \rightarrow V$ is c-linear with respect to $\left(J_{U}^{2}, J_{V}^{2}\right)$, then the kernel of the composite $P_{c}^{V} \circ H \circ Q_{a}^{U}: U_{a} \rightarrow V_{c}$ is equal to the set $\left\{u \in U_{a}\right.$ : $\left.\left(H \circ J_{U}^{1} \circ Q_{a}^{U}\right)(u)=\left(J_{V}^{1} \circ H \circ Q_{a}^{U}\right)(u)\right\}$.

Proof. Composing with $Q_{c}^{V}$ does not change the kernel, so using the equalities $J_{U}^{1} \circ Q_{a}^{U}=-J_{U}^{2} \circ Q_{a}^{U}$ and $J_{V}^{2} \circ H=H \circ J_{U}^{2}$,

$$
\begin{aligned}
& Q_{c}^{V} \circ P_{c}^{V} \circ H \circ Q_{a}^{U}=\frac{1}{2} \cdot\left(I d_{V}-J_{V}^{1} \circ J_{V}^{2}\right) \circ H \circ Q_{a} \\
= & \frac{1}{2} \cdot\left(H-J_{V}^{1} \circ H \circ J_{U}^{2}\right) \circ Q_{a}^{U}=\frac{1}{2} \cdot\left(H+J_{V}^{1} \circ H \circ J_{U}^{1}\right) \circ Q_{a}^{U},
\end{aligned}
$$

and the composite with the invertible map $2 \cdot J_{V}^{1}$ has the same kernel:

$$
2 \cdot J_{V}^{1} \circ Q_{c}^{V} \circ P_{c}^{V} \circ H \circ Q_{a}^{U}=J_{V}^{1} \circ H \circ Q_{a}^{U}-H \circ J_{U}^{1} \circ Q_{a}^{U}
$$

Example 5.60. For a vector space $V$ with a CSO $J$ and involution $N$ that commute as in Example 5.6, the CSO $N \circ J$ commutes with $J$ and $N$. The involution $N$ produces a direct sum $V=V_{1} \oplus V_{2}$ with projections $\left(P_{1}, P_{2}\right)$ and inclusions $\left(Q_{1}, Q_{2}\right)$ as in Lemma 1.112, and Lemma 1.118 and Lemma 5.28 apply to both $J$ and $N \circ J$ : they respect the direct sum $V_{1} \oplus V_{2}$, and the induced maps $P_{1} \circ J \circ Q_{1}$ and $P_{1} \circ N \circ J \circ Q_{1}$ are commuting CSOs on $V_{1}$, and similarly for $V_{2}$. More specifically, the CSOs on $V_{1}$ are equal: $P_{1} \circ J \circ Q_{1}=P_{1} \circ N \circ J \circ Q_{1}$, while the CSOs $P_{2} \circ J \circ Q_{2}$ and $P_{2} \circ N \circ J \circ Q_{2}$ on $V_{2}$ are opposite.

Example 5.61. Given $U$ with commuting $\operatorname{CSOs} J_{1}, J_{2}$, if $H \in \operatorname{End}(U)$ is an involution such that $H \circ J_{1} \circ J_{2}=J_{1} \circ J_{2} \circ H$, then $U$ admits two direct sums: $U=U_{1} \oplus U_{2}$ produced by $H$ as in Lemma 1.112, and $U=U_{c} \oplus U_{a}$ produced by $-J_{1} \circ J_{2}$. The composite $\left(-J_{1} \circ J_{2}\right) \circ H$ is a third involution, which produces a direct sum $U=U_{5} \oplus U_{6}$, as denoted in Theorem 1.122. Both $H$ and $-J_{1} \circ J_{2} \circ H$ respect the direct sum $U_{c} \oplus U_{a}$ as in Lemma 1.120 and Lemma 5.52; they both induce involutions $U_{c} \rightarrow U_{c}$ and $U_{a} \rightarrow U_{a}$, with the involutions being equal on $U_{c}$ as in (1.13), and opposite on $U_{a}$ as in (1.14), producing a direct sum $U_{c}=U_{c}^{\prime} \oplus U_{c}^{\prime \prime}$, and an unordered pair of subspaces of $U_{a}$ :

$$
\begin{align*}
U_{c}^{\prime} & =\left\{u \in U: u=-J_{1}\left(J_{2}(u)\right)=H(u)\right\}  \tag{5.6}\\
U_{c}^{\prime \prime} & =\left\{u \in U: u=-J_{1}\left(J_{2}(u)\right)=-H(u)\right\}, \\
U_{a}^{\prime} & =\left\{u \in U: u=J_{1}\left(J_{2}(u)\right)=H(u)\right\} \\
U_{a}^{\prime \prime} & =\left\{u \in U: u=J_{1}\left(J_{2}(u)\right)=-H(u)\right\} .
\end{align*}
$$

Similarly, both $-J_{1} \circ J_{2}$ and $-J_{1} \circ J_{2} \circ H$ respect the direct sum $U_{1} \oplus U_{2}$, and induce involutions on $U_{1}$ and $U_{2}$ that distinguish the same four subspaces:

$$
\begin{aligned}
U_{1}^{\prime} & =\left\{u \in U: u=H(u)=-J_{1}\left(J_{2}(u)\right)\right\} \\
U_{1}^{\prime \prime} & =\left\{u \in U: u=H(u)=J_{1}\left(J_{2}(u)\right)\right\} \\
U_{2}^{\prime} & =\left\{u \in U: u=-H(u)=-J_{1}\left(J_{2}(u)\right)\right\}, \\
U_{2}^{\prime \prime} & =\left\{u \in U: u=-H(u)=J_{1}\left(J_{2}(u)\right)\right\}
\end{aligned}
$$

This configuration of subspaces gives an example of the results of Theorem 1.122, $U_{1}^{\prime}=U_{c}^{\prime}=U_{1} \cap U_{c}=U_{1} \cap U_{c} \cap U_{5}, U_{c}^{\prime \prime}=U_{2}^{\prime}=U_{2} \cap U_{6}, U_{1}^{\prime \prime}=U_{a}^{\prime}=U_{a} \cap U_{6}$, etc.

Lemma 5.62. Given $U$ with commuting $\operatorname{CSOs} J_{1}$, $J_{2}$, if $H \in \operatorname{End}(U)$ is an involution such that $H \circ J_{1}=J_{1} \circ H$ and $H \circ J_{2}=J_{2} \circ H$, then $H$ respects the direct sum $U_{c} \oplus U_{a} \rightarrow U_{c} \oplus U_{a}$, and induces involutions on $U_{c}$ and $U_{a}$. The induced involution $P_{c} \circ H \circ Q_{c}$ on $U_{c}$ is c-linear, and its fixed point set $U_{c}^{\prime}$ has a canonical CSO.

Proof. It follows from the c-linearity of $H$ that $H \circ J_{1} \circ J_{2}=J_{1} \circ J_{2} \circ H$. So, this is a special case of both Lemma 5.57 and Example 5.61: the induced involution on $U_{c}$ is c-linear with respect to the CSO on $U_{c}$ from Example 5.53, and produces a direct sum $U_{c}=U_{c}^{\prime} \oplus U_{c}^{\prime \prime}$ as in (5.6). The subspace $U_{c}^{\prime}=\left\{u \in U: u=-J_{1}\left(J_{2}(u)\right)=\right.$ $H(u)\}$ has a canonical CSO, from Example 5.60.

Lemma 5.63. Given $U$ with commuting CSOs $J_{1}$, $J_{2}$, if $H \in \operatorname{End}(U)$ is an involution such that $H \circ J_{1}=J_{2} \circ H$, then $H$ respects the direct sum $U_{c} \oplus U_{a} \rightarrow$ $U_{c} \oplus U_{a}$, and induces involutions on $U_{c}$ and $U_{a}$. The induced involution $P_{c} \circ H \circ Q_{c}$ on $U_{c}$ is c-linear, and its fixed point set $U_{c}^{\prime}$ has a canonical CSO.

Proof. It follows from the involution property that $H \circ J_{1}=J_{2} \circ H \Longrightarrow$ $J_{1} \circ H=H \circ J_{2} \Longrightarrow H \circ J_{1} \circ J_{2}=J_{1} \circ J_{2} \circ H$. So, this is similar to Lemma 5.62, and also a special case of both Lemma 5.57 and Example 5.61: the induced involution on $U_{c}$ is c-linear and produces a direct sum $U_{c}=U_{c}^{\prime} \oplus U_{c}^{\prime \prime}$. The subspace $U_{c}^{\prime}=\left\{u \in U: u=-J_{1}\left(J_{2}(u)\right)=H(u)\right\}$ has a canonical CSO, from Example 5.60.

Example 5.64. Given $U$ and $V$, suppose there are commuting CSOs $J_{1}, J_{2}$ on $V$. Then the CSOs $\left[J_{1} \otimes I d_{U}\right]$ and $\left[J_{2} \otimes I d_{U}\right]$ on $V \otimes U$, from Example 5.3, also commute. As in Example 5.51, this gives a direct sum $V \otimes U=(V \otimes U)_{c} \oplus(V \otimes U)_{a}$ with projections

$$
\frac{1}{2} \cdot\left(I d_{V \otimes U} \pm\left[J_{1} \otimes I d_{U}\right] \circ\left[J_{2} \otimes I d_{U}\right]\right)
$$

$V \otimes U$ also admits a direct $\operatorname{sum}\left(V_{c} \otimes U\right) \oplus\left(V_{a} \otimes U\right)$ as in Example 1.75, with projections

$$
\left[\left(\frac{1}{2} \cdot\left(I d_{V} \pm J_{1} \circ J_{2}\right)\right) \otimes I d_{U}\right]=\left[P_{i} \otimes I d_{U}\right]
$$

for $P_{i}: V \rightarrow V_{i}, i=c, a$, as in Example 5.51. This is a special case of Example 1.133; the pairs of projections are identical (using the linearity of $j$ and Lemma 1.35), so the direct sums are the same and we have the equalities of subspaces $(V \otimes U)_{c}=V_{c} \otimes U$ and $(V \otimes U)_{a}=V_{a} \otimes U$, with inclusions $\left[Q_{i} \otimes I d_{U}\right]$. Similarly, $(U \otimes V)_{c}=U \otimes V_{c}$ and $(U \otimes V)_{a}=U \otimes V_{a}$.

Example 5.65. Given $\mathbf{U}=\left(U, J_{U}\right)$ and $\mathbf{V}=\left(V, J_{V}\right)$, the two $\operatorname{CSOs}\left[I d_{U} \otimes J_{V}\right]$, $\left[J_{U} \otimes I d_{V}\right] \in \operatorname{End}(U \otimes V)$ commute, so this is a special case of Example 5.51. The direct sum so produced is denoted

$$
U \otimes V=\left(U \otimes_{c} V\right) \oplus\left(U \otimes_{a} V\right)
$$

As in Example 5.53, the subspace

$$
U \otimes_{c} V=\left\{w \in U \otimes V:\left[I d_{U} \otimes J_{V}\right](w)=\left[J_{U} \otimes I d_{V}\right](w)\right\}
$$

has a canonical CSO, induced by either of the CSOs, so we may denote the space $\mathbf{U} \otimes_{c} \mathbf{V}$. The CSOs on $U \otimes V$ induce opposite CSOs on the subspace

$$
U \otimes_{a} V=\left\{w \in U \otimes V:\left[I d_{U} \otimes J_{V}\right](w)=-\left[J_{U} \otimes I d_{V}\right](w)\right\}
$$

Example 5.66. For c-linear maps $A: \mathbf{U} \rightarrow \mathbf{U}^{\prime}$ and $B: \mathbf{V} \rightarrow \mathbf{V}^{\prime}$, the map

$$
[A \otimes B]: U \otimes V \rightarrow U^{\prime} \otimes V^{\prime}
$$

satisfies the hypotheses of Lemma 5.57, and respects the direct sums from Example 5.65. The induced map

$$
P_{c}^{\prime} \circ[A \otimes B] \circ Q_{c}: \mathbf{U} \otimes_{c} \mathbf{V} \rightarrow \mathbf{U}^{\prime} \otimes_{c} \mathbf{V}^{\prime}
$$

is c-linear.
Notation 5.67. For c-linear maps $A: \mathbf{U} \rightarrow \mathbf{U}^{\prime}$ and $B: \mathbf{V} \rightarrow \mathbf{V}^{\prime}$ as in Example 5.66, the bracket notation from Notation 1.34 is adapted in the following abbreviation:

$$
\left[A \otimes_{c} B\right]=P_{c}^{\prime} \circ[A \otimes B] \circ Q_{c}: \mathbf{U} \otimes_{c} \mathbf{V} \rightarrow \mathbf{U}^{\prime} \otimes_{c} \mathbf{V}^{\prime}
$$

As remarked after Lemma 5.57, this is exactly the restriction of the map $[A \otimes B]$ to the $\mathbf{U} \otimes_{c} \mathbf{V}$ subspace of the domain, with image contained in the $\mathbf{U}^{\prime} \otimes_{c} \mathbf{V}^{\prime}$ subspace of the target. The role of the $j$ map in this construction is considered in more detail by Example 5.118.

Exercise 5.68. For a-linear maps $A: \mathbf{U} \rightarrow \mathbf{U}^{\prime}$ and $B: \mathbf{V} \rightarrow \mathbf{V}^{\prime}$, the map

$$
[A \otimes B]: U \otimes V \rightarrow U^{\prime} \otimes V^{\prime}
$$

respects the direct sums. The induced map

$$
P_{c}^{\prime} \circ[A \otimes B] \circ Q_{c}: \mathbf{U} \otimes_{c} \mathbf{V} \rightarrow \mathbf{U}^{\prime} \otimes_{c} \mathbf{V}^{\prime}
$$

is a-linear.
Example 5.69. Given $\mathbf{U}=\left(U, J_{U}\right)$ and $\mathbf{V}=\left(V, J_{V}\right)$, the CSO $\operatorname{Hom}\left(I d_{U}, J_{V}\right)$ commutes with $\operatorname{Hom}\left(J_{U}, I d_{V}\right) \in \operatorname{End}(\operatorname{Hom}(U, V))$, so this is a special case of Example 5.51. The direct sum so produced is denoted

$$
\begin{equation*}
\operatorname{Hom}(U, V)=\operatorname{Hom}_{c}(U, V) \oplus \operatorname{Hom}_{a}(U, V) \tag{5.7}
\end{equation*}
$$

The projection $P_{c}: \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}_{c}(U, V)$ is defined by
$\frac{1}{2} \cdot\left(I d_{\operatorname{Hom}(U, V)}-\operatorname{Hom}\left(I d_{U}, J_{V}\right) \circ \operatorname{Hom}\left(J_{U}, I d_{V}\right)\right)=\frac{1}{2} \cdot\left(I d_{\operatorname{Hom}(U, V)}-\operatorname{Hom}\left(J_{U}, J_{V}\right)\right)$.
As in Example 5.53, the subspace

$$
\begin{aligned}
\operatorname{Hom}_{c}(U, V) & =\left\{A \in \operatorname{Hom}(U, V): \operatorname{Hom}\left(I d_{U}, J_{V}\right)(A)=\operatorname{Hom}\left(J_{U}, I d_{V}\right)(A)\right\} \\
& =\left\{A \in \operatorname{Hom}(U, V): J_{V} \circ A=A \circ J_{U}\right\}
\end{aligned}
$$

has a canonical CSO, induced by either one of the CSOs, so we may denote the space $\operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V})$. This is exactly the set of c-linear maps $\mathbf{U} \rightarrow \mathbf{V}$ as in Section 5.2. The CSOs on $\operatorname{Hom}(U, V)$ induce opposite CSOs on the subspace of a-linear maps,

$$
\begin{aligned}
\operatorname{Hom}_{a}(U, V) & =\left\{A \in \operatorname{Hom}(U, V): \operatorname{Hom}\left(I d_{U}, J_{V}\right)(A)=-\operatorname{Hom}\left(J_{U}, I d_{V}\right)(A)\right\} \\
& =\left\{A \in \operatorname{Hom}(U, V): J_{V} \circ A=-A \circ J_{U}\right\}
\end{aligned}
$$

Example 5.70. Given $\mathbf{V}=\left(V, J_{V}\right)$, there is a direct sum

$$
\operatorname{End}(V)=\operatorname{End}_{c}(V) \oplus \operatorname{End}_{a}(V)
$$

as in Example 5.69, where $\operatorname{End}_{c}(\mathbf{V})$ admits a canonical CSO. The identity element $I d_{V} \in \operatorname{End}_{c}(\mathbf{V}) \subseteq \operatorname{End}(V)$ is c-linear, and so is $J_{V}$.

Lemma 5.71. For c-linear maps $A: \mathbf{U}^{\prime} \rightarrow \mathbf{U}$ and $B: \mathbf{V} \rightarrow \mathbf{V}^{\prime}$, the map

$$
\operatorname{Hom}(A, B): \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}\left(U^{\prime}, V^{\prime}\right)
$$

respects the direct sums from Example 5.69. The induced map

$$
P_{c}^{\prime} \circ \operatorname{Hom}(A, B) \circ Q_{c}: \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V}) \rightarrow \operatorname{Hom}_{c}\left(\mathbf{U}^{\prime}, \mathbf{V}^{\prime}\right): F \mapsto B \circ F \circ A
$$

is c-linear.

Proof. $P_{c}^{\prime}$ is the projection $\operatorname{Hom}\left(U^{\prime}, V^{\prime}\right) \rightarrow \operatorname{Hom}_{c}\left(\mathbf{U}^{\prime}, \mathbf{V}^{\prime}\right)$. Lemma 5.57 applies.

Notation 5.72. The induced map from Lemma 5.71 is denoted

$$
\operatorname{Hom}_{c}(A, B)=P_{c}^{\prime} \circ \operatorname{Hom}(A, B) \circ Q_{c}: \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V}) \rightarrow \operatorname{Hom}_{c}\left(\mathbf{U}^{\prime}, \mathbf{V}^{\prime}\right)
$$

As in Notation 5.67, this is a restriction of the map $\operatorname{Hom}(A, B)$ to subspaces of its domain and target.

Exercise 5.73. For a-linear maps $A: \mathbf{U}^{\prime} \rightarrow \mathbf{U}$ and $B: \mathbf{V} \rightarrow \mathbf{V}^{\prime}$, the map

$$
\operatorname{Hom}(A, B): \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}\left(U^{\prime}, V^{\prime}\right)
$$

respects the direct sums. The induced map

$$
P_{c}^{\prime} \circ \operatorname{Hom}(A, B) \circ Q_{c}: \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V}) \rightarrow \operatorname{Hom}_{c}\left(\mathbf{U}^{\prime}, \mathbf{V}^{\prime}\right): F \mapsto B \circ F \circ A
$$

is a-linear.
Example 5.74. Given $U$ and $V$, suppose there are commuting CSOs $J_{1}, J_{2}$ on $V$. Then the CSOs $\operatorname{Hom}\left(I d_{U}, J_{1}\right)$ and $\operatorname{Hom}\left(I d_{U}, J_{2}\right)$ on $\operatorname{Hom}(U, V)$ also commute. As in Example 5.51, this gives a direct sum temporarily denoted

$$
\begin{equation*}
\operatorname{Hom}(U, V)=(\operatorname{Hom}(U, V))_{c} \oplus(\operatorname{Hom}(U, V))_{a} \tag{5.8}
\end{equation*}
$$

with projections

$$
\frac{1}{2} \cdot\left(I d_{\operatorname{Hom}(U, V)} \pm \operatorname{Hom}\left(I d_{U}, J_{1}\right) \circ \operatorname{Hom}\left(I d_{U}, J_{2}\right)\right)
$$

$\operatorname{Hom}(U, V)$ also admits a direct sum $\operatorname{Hom}\left(U, V_{c}\right) \oplus \operatorname{Hom}\left(U, V_{a}\right)$ as in Example 1.76, with projections

$$
\begin{equation*}
\operatorname{Hom}\left(I d_{U}, \frac{1}{2} \cdot\left(I d_{V} \pm J_{1} \circ J_{2}\right)\right) \tag{5.9}
\end{equation*}
$$

The pairs of projections are identical: this is a special case of Example 1.135. We can identify $\operatorname{Hom}\left(U, V_{c}\right)=(\operatorname{Hom}(U, V))_{c}$, and also identify $\operatorname{Hom}\left(I d_{U}, Q_{c}\right)$ with the inclusion of the subspace $(\operatorname{Hom}(U, V))_{c}$ in $\operatorname{Hom}(U, V)$; similarly, $(\operatorname{Hom}(U, V))_{a}=$ $\operatorname{Hom}\left(U, V_{a}\right)$. More specifically, the set $(\operatorname{Hom}(U, V))_{c}$ is defined as $\{A \in \operatorname{Hom}(U, V)$ : $\left.J_{1} \circ A=J_{2} \circ A\right\}$, while elements of $\operatorname{Hom}\left(U, V_{c}\right)$ are maps $A$ such that for any $u \in U$, $A(u) \in V_{c} \subseteq V$, meaning $J_{1}(A(u))=J_{2}(A(u))$.

Example 5.75. Given $U$ and $V$, suppose there are commuting CSOs $J_{1}, J_{2}$ on $V$. Then the CSOs $\operatorname{Hom}\left(J_{1}, I d_{U}\right)$ and $\operatorname{Hom}\left(J_{2}, I d_{U}\right)$ on $\operatorname{Hom}(V, U)$ also commute. As in Example 5.51, this gives a direct sum $\operatorname{Hom}(V, U)=(\operatorname{Hom}(V, U))_{c} \oplus$ $(\operatorname{Hom}(V, U))_{a}$ (the same notation as (5.8) but not the same subspaces) with projections

$$
\frac{1}{2} \cdot\left(I d_{\operatorname{Hom}(V, U)} \pm \operatorname{Hom}\left(J_{1}, I d_{U}\right) \circ \operatorname{Hom}\left(J_{2}, I d_{U}\right)\right)
$$

$\operatorname{Hom}(V, U)$ also admits a direct sum $\operatorname{Hom}\left(V_{c}, U\right) \oplus \operatorname{Hom}\left(V_{a}, U\right)$ as in Example 1.77, with projections $\operatorname{Hom}\left(Q_{c}, I d_{U}\right), \operatorname{Hom}\left(Q_{a}, I d_{U}\right)$. Unlike Examples 5.64 and 5.74, these pairs of projections are not obviously identical, and in fact this is a special case of Example 1.136. The set $(\operatorname{Hom}(V, U))_{c}$ is defined as $\left\{A \in \operatorname{Hom}(V, U): A \circ J_{1}=\right.$ $\left.A \circ J_{2}\right\}$, while elements of $\operatorname{Hom}\left(V_{c}, U\right)$ are maps $A$ defined only on the subspace of $v \in V$ such that $J_{1}(v)=J_{2}(v)$. The two direct sums are different but equivalent, as
discussed in Example 1.136. Specifically, if, for $i=c, a, P_{i}^{\prime \prime}, Q_{i}^{\prime \prime}$ denote the projections and inclusions for the direct sum $\operatorname{Hom}(V, U)=(\operatorname{Hom}(V, U))_{c} \oplus(\operatorname{Hom}(V, U))_{a}$, then

$$
Q_{i}^{\prime \prime} \circ P_{i}^{\prime \prime}=\operatorname{Hom}\left(P_{i}, I d_{U}\right) \circ \operatorname{Hom}\left(Q_{i}, I d_{U}\right): \operatorname{Hom}(V, U) \rightarrow \operatorname{Hom}(V, U),
$$

and as in Lemma 1.93,

$$
P_{i}^{\prime \prime} \circ \operatorname{Hom}\left(P_{i}, I d_{U}\right): \operatorname{Hom}\left(V_{i}, U\right) \rightarrow(\operatorname{Hom}(V, U))_{i}
$$

is invertible with inverse $\operatorname{Hom}\left(Q_{i}, I d_{U}\right) \circ Q_{i}^{\prime \prime}$, and for $i=c$, c-linear.
Lemma 5.76. Given $U$ and $V$, with commuting CSOs $J_{1}, J_{2} \in \operatorname{End}(V)$, let $W$ be a space admitting a direct sum $W_{1} \oplus W_{2}$. If $H: W \rightarrow \operatorname{Hom}(V, U)$ respects one of the two direct sums from Example 5.75, then $H$ also respects the other direct sum. If, further, $H$ is invertible, then both induced maps $W_{1} \rightarrow(\operatorname{Hom}(V, U))_{c}$ and $W_{1} \rightarrow \operatorname{Hom}\left(V_{c}, U\right)$ are also invertible. If the direct sum on $W$ is given by commuting CSOs $J_{W}, J_{W}^{\prime}$, and $H$ satisfies both $\operatorname{Hom}\left(J_{1}, I d_{U}\right) \circ H=H \circ J_{W}$ and $\operatorname{Hom}\left(J_{2}, I d_{U}\right) \circ H=H \circ J_{W}^{\prime}$, then $H$ respects the direct sums and the induced maps are c-linear.

Proof. The claims follow from Lemmas 1.83, 1.92, and 5.57. If the projection and inclusion operators induced on $W=W_{c} \oplus W_{a}$ by $J_{W}, J_{W}^{\prime}$ are $P_{i}^{\prime}, Q_{i}^{\prime}$, then the induced maps $\operatorname{Hom}\left(Q_{c}, I d_{U}\right) \circ H \circ Q_{c}^{\prime}: W_{c} \rightarrow \operatorname{Hom}\left(V_{c}, U\right)$ and $P_{c}^{\prime \prime} \circ H \circ Q_{c}^{\prime}: W_{c} \rightarrow$ $(\operatorname{Hom}(V, U))_{c}$ are related by composition with the c-linear invertible map from the above Example:

$$
\operatorname{Hom}\left(Q_{c}, I d_{U}\right) \circ H \circ Q_{c}^{\prime}=\left(\operatorname{Hom}\left(Q_{c}, I d_{U}\right) \circ Q_{c}^{\prime \prime}\right) \circ\left(P_{c}^{\prime \prime} \circ H \circ Q_{c}^{\prime}\right)
$$

EXERCISE 5.77. The results of the previous Lemma have analogues for a map $\operatorname{Hom}(V, U) \rightarrow W$.

Example 5.78. For $U$ and commuting $\mathrm{CSOs} J_{1}, J_{2}$ on $V$ as in Example 5.74, suppose there are also commuting CSOs $J_{1}^{\prime}$, $J_{2}^{\prime}$ on $V^{\prime}$. If $B: V \rightarrow V^{\prime}$ respects the direct sums $V_{c} \oplus V_{a} \rightarrow V_{c}^{\prime} \oplus V_{a}^{\prime}$ (equivalently, $B \circ J_{1} \circ J_{2}=J_{1}^{\prime} \circ J_{2}^{\prime} \circ B$ by Lemmas 1.118 and 5.52), then for $i=c, a$, there are induced maps $P_{i}^{\prime} \circ B \circ Q_{i}: V_{i} \rightarrow V_{i}^{\prime}$. By Lemma 1.86, for any map $A: W \rightarrow U$, the map $\operatorname{Hom}(A, B): \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}\left(W, V^{\prime}\right)$ respects the direct sums

$$
\operatorname{Hom}\left(U, V_{c}\right) \oplus \operatorname{Hom}\left(U, V_{a}\right) \rightarrow \operatorname{Hom}\left(W, V_{c}^{\prime}\right) \oplus \operatorname{Hom}\left(W, V_{a}^{\prime}\right)
$$

from Example 5.74, and for $i=c, a$, the induced map

$$
\operatorname{Hom}\left(I d_{W}, P_{i}^{\prime}\right) \circ \operatorname{Hom}(A, B) \circ \operatorname{Hom}\left(I d_{U}, Q_{i}\right)
$$

is equal to $\operatorname{Hom}\left(A, P_{i}^{\prime} \circ B \circ Q_{i}\right)$.
Example 5.79. For $U, V, V^{\prime}, A$ as in Example 5.78, if $B: V \rightarrow V^{\prime}$ is clinear with respect to both pairs $J_{1}, J_{1}^{\prime}$ and $J_{2}, J_{2}^{\prime}$, then $B$ satisfies the hypothesis from Example 5.78, and by Lemma $5.25, \operatorname{Hom}(A, B)$ is also c-linear with respect to the pairs $\operatorname{Hom}\left(I d_{U}, J_{1}\right), \operatorname{Hom}\left(I d_{W}, J_{1}^{\prime}\right)$ and $\operatorname{Hom}\left(I d_{U}, J_{2}\right)$, $\operatorname{Hom}\left(I d_{W}, J_{2}^{\prime}\right)$. Lemma 5.57 applies, so the induced maps from Example $5.78, P_{c}^{\prime} \circ B \circ Q_{c}: V_{c} \rightarrow V_{c}^{\prime}$, and also $\operatorname{Hom}\left(A, P_{c}^{\prime} \circ B \circ Q_{c}\right)$, are both c-linear.

Exercise 5.80. Given $U, V, W$, with $\mathbf{U}=\left(U, J_{U}\right)$ and $\mathbf{V}=\left(V, J_{V}\right)$, the map $t_{U V}^{W}: \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}(\operatorname{Hom}(V, W), \operatorname{Hom}(U, W))$ respects the direct sums and the induced map

$$
\operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V}) \rightarrow \operatorname{Hom}_{c}(\operatorname{Hom}(\mathbf{V}, W), \operatorname{Hom}(\mathbf{U}, W))
$$

is c-linear.
Hint. Exercise 5.36, Exercise 5.37, and then Lemma 5.57 apply.
Example 5.81. For $W=\mathbb{R}$ in the previous Exercise, $t_{U V}^{\mathbb{R}}=t_{U V}: \operatorname{Hom}(U, V) \rightarrow$ $\operatorname{Hom}\left(V^{*}, U^{*}\right) . V^{*}$ has a CSO $J_{V}^{*}$ as in Example 5.5, and similarly $J_{U}^{*}$ is a CSO for $U^{*} . t_{U V}$ respects the direct sums

$$
\operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V}) \oplus \operatorname{Hom}_{a}(U, V) \rightarrow \operatorname{Hom}_{c}\left(V^{*}, U^{*}\right) \oplus \operatorname{Hom}_{a}\left(V^{*}, U^{*}\right)
$$

and the induced map $\operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V}) \rightarrow \operatorname{Hom}_{c}\left(V^{*}, U^{*}\right), A \mapsto t_{U V}(A)=\operatorname{Hom}\left(A, I d_{\mathbb{R}}\right)=$ $A^{*}$, is c-linear.

Exercise 5.82. Given $U, V, W$, with $\mathbf{U}=\left(U, J_{U}\right)$ and $\mathbf{V}=\left(V, J_{V}\right)$, the map $e_{U V}^{W}: \operatorname{Hom}(\mathbf{U}, \mathbf{V}) \rightarrow \operatorname{Hom}(\operatorname{Hom}(\mathbf{V}, W) \otimes \mathbf{U}, W)$ respects the direct sums and the induced map

$$
\operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V}) \rightarrow \operatorname{Hom}\left(\operatorname{Hom}(\mathbf{V}, W) \otimes_{c} \mathbf{U}, W\right)
$$

is c-linear.
Hint. Exercise 5.41, Exercise 5.42, and then Lemma 5.76, apply.
Exercise 5.83. Given $U, V, W$, with $\mathbf{U}=\left(U, J_{U}\right)$ and $\mathbf{W}=\left(W, J_{W}\right)$, the $\operatorname{map} T_{U, V ; W}: \operatorname{Hom}(\mathbf{U}, \operatorname{Hom}(V, \mathbf{W})) \rightarrow \operatorname{Hom}(V, \operatorname{Hom}(\mathbf{U}, \mathbf{W}))$ respects the direct sums and the induced map

$$
\operatorname{Hom}_{c}(\mathbf{U}, \operatorname{Hom}(V, \mathbf{W})) \rightarrow \operatorname{Hom}\left(V, \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W})\right)
$$

is c-linear and invertible, where the inverse is induced by $T_{V, U ; W}$.
Hint. The direct sum for the domain is as in Example 5.69, and for the target is as in Example 5.74. Exercise 5.45, Exercise 5.46, and then Lemma 5.57 apply.

Exercise 5.84. Given $U, V, W$, with $\mathbf{U}=\left(U, J_{U}\right)$ and $\mathbf{V}=\left(V, J_{V}\right)$, the map $T_{U, V ; W}: \operatorname{Hom}(\mathbf{U}, \operatorname{Hom}(\mathbf{V}, W)) \rightarrow \operatorname{Hom}(\mathbf{V}, \operatorname{Hom}(\mathbf{U}, W))$ respects the direct sums and the induced map

$$
\operatorname{Hom}_{c}(\mathbf{U}, \operatorname{Hom}(\mathbf{V}, W)) \rightarrow \operatorname{Hom}_{c}(\mathbf{V}, \operatorname{Hom}(\mathbf{U}, W))
$$

is c-linear and invertible, where the inverse is induced by $T_{V, U ; W}$.
Hint. The direct sums are as in Example 5.69. Exercise 5.46 and Lemma 5.57 apply.

Exercise 5.85. Given $W$ and $\mathbf{V}=\left(V, J_{V}\right)$, the involution $T_{V ; W}$ from Notation 4.3 is c-linear with respect to both induced CSOs as follows:

$$
\begin{aligned}
& \operatorname{Hom}(\mathbf{V}, \operatorname{Hom}(V, W)) \\
& \operatorname{Hom}(V, \operatorname{Hom}(\mathbf{V}, W)) \\
& \operatorname{Hom}(V, \operatorname{Hom}(\mathbf{V}, W)) \\
& (\mathbf{V}, \operatorname{Hom}(V, W))
\end{aligned}
$$

The induced map

$$
\operatorname{Hom}_{c}(\mathbf{V}, \operatorname{Hom}(\mathbf{V}, W)) \rightarrow \operatorname{Hom}_{c}(\mathbf{V}, \operatorname{Hom}(\mathbf{V}, W))
$$

is a c-linear involution, and its fixed point subspace has a canonical CSO.

Hint. The c-linearity claims are the $U=V$ special case of Exercise 5.46, and the induced map is the special case from Exercise 5.84. Lemma 5.63 applies to the involution $T_{V ; W}$ and the commuting CSOs on $\operatorname{Hom}(V, \operatorname{Hom}(V, W))$.

Example 5.86. For $W, \mathbf{V}=\left(V, J_{V}\right)$, and $\operatorname{Hom}(V, \operatorname{Hom}(V, W))$ as in Exercise 5.85, Example 5.61 applies to the commuting involutions $T_{V ; W}$ and

$$
-\operatorname{Hom}\left(J_{V}, I d_{\operatorname{Hom}(V, W)}\right) \circ \operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(J_{V}, I d_{W}\right)\right)=-\operatorname{Hom}\left(J_{V}, \operatorname{Hom}\left(J_{V}, I d_{W}\right)\right)
$$

Recalling the direct sums from (4.7) and (5.7),

$$
\begin{aligned}
& \operatorname{Hom}(V, \operatorname{Hom}(V, W))=\operatorname{Sym}(V ; W) \oplus \operatorname{Alt}(V ; W) \\
& \operatorname{Hom}(V, \operatorname{Hom}(V, W))=\operatorname{Hom}_{c}(\mathbf{V}, \operatorname{Hom}(\mathbf{V}, W)) \oplus \operatorname{Hom}_{a}(\mathbf{V}, \operatorname{Hom}(\mathbf{V}, W)),
\end{aligned}
$$

the four distinguished subspaces from Example 5.61 can be described in terms of properties of their elements, $W$-valued bilinear forms $h$, and are denoted as follows:

$$
\begin{aligned}
\operatorname{Sym}_{c}(\mathbf{V}, W) & =\operatorname{Sym}(V ; W) \cap \operatorname{Hom}_{c}(\mathbf{V}, \operatorname{Hom}(\mathbf{V}, W)) \\
& =\left\{h:\left(h\left(v_{1}\right)\right)\left(v_{2}\right)=\left(h\left(v_{2}\right)\right)\left(v_{1}\right)=-\left(h\left(J_{V}\left(v_{1}\right)\right)\right)\left(J_{V}\left(v_{2}\right)\right)\right\} \\
\operatorname{Sym}_{a}(\mathbf{V}, W) & =\operatorname{Sym}(V ; W) \cap \operatorname{Hom}_{a}(\mathbf{V}, \operatorname{Hom}(\mathbf{V}, W)) \\
& =\left\{h:\left(h\left(v_{1}\right)\right)\left(v_{2}\right)=\left(h\left(v_{2}\right)\right)\left(v_{1}\right)=\left(h\left(J_{V}\left(v_{1}\right)\right)\right)\left(J_{V}\left(v_{2}\right)\right)\right\}, \\
\operatorname{Alt}_{c}(\mathbf{V}, W) & =\operatorname{Alt}(V ; W) \cap \operatorname{Hom}_{c}(\mathbf{V}, \operatorname{Hom}(\mathbf{V}, W)) \\
& =\left\{h:\left(h\left(v_{1}\right)\right)\left(v_{2}\right)=-\left(h\left(v_{2}\right)\right)\left(v_{1}\right)=-\left(h\left(J_{V}\left(v_{1}\right)\right)\right)\left(J_{V}\left(v_{2}\right)\right)\right\}, \\
\operatorname{Alt}_{a}(\mathbf{V}, W) & =\operatorname{Alt}(V ; W) \cap \operatorname{Hom}_{a}(\mathbf{V}, \operatorname{Hom}(\mathbf{V}, W)) \\
& =\left\{h:\left(h\left(v_{1}\right)\right)\left(v_{2}\right)=-\left(h\left(v_{2}\right)\right)\left(v_{1}\right)=\left(h\left(J_{V}\left(v_{1}\right)\right)\right)\left(J_{V}\left(v_{2}\right)\right)\right\} .
\end{aligned}
$$

The c-linear involution on $\operatorname{Hom}_{c}(\mathbf{V}, \operatorname{Hom}(\mathbf{V}, W))$ induced by $T_{V ; W}$ from Exercise 5.85 produces the direct sum

$$
\operatorname{Hom}_{c}(\mathbf{V}, \operatorname{Hom}(\mathbf{V}, W))=\operatorname{Sym}_{c}(\mathbf{V}, W) \oplus \operatorname{Alt}_{c}(\mathbf{V}, W)
$$

and there is a canonical CSO on $\operatorname{Sym}_{c}(\mathbf{V}, W)$.
ExErcise 5.87. Given $V$ with CSOs $J_{1}, J_{2}$, if $J_{1}$ and $J_{2}$ commute and $J_{2} \neq$ $\pm J_{1}$, then the span of $\left\{I d_{V}, J_{1}, J_{2}, J_{1} \circ J_{2}\right\}$ is a 4-dimensional subspace of $\operatorname{End}(V)$. This subspace is closed under composition, so it is a subrng of $\operatorname{End}(V)$.

Hint. The first claim follows from Exercise 5.20. Such a subspace is a commutative ring, and isomorphic to the associative algebra of bicomplex numbers of C. Segre.

### 5.3.2. Three Commuting Complex Structure Operators.

Example 5.88. Given $V$ and three commuting CSOs $J_{1}, J_{2}, J_{3}$, consider an ordered triple $\left(i_{1}, i_{2}, i_{3}\right)$ which is a permutation (no repeats) of the indices 1,2 , 3. For the first two indices, the two CSOs $J_{i_{1}}, J_{i_{2}}$ produce a direct sum $V=$ $V_{c\left(i_{1} i_{2}\right)} \oplus V_{a\left(i_{1} i_{2}\right)}$ with projection $P_{c\left(i_{1} i_{2}\right)}=\frac{1}{2} \cdot\left(I d_{V}-J_{i_{1}} \circ J_{i_{2}}\right)$ as in Example 5.51. The ordering of the pair is irrelevant: $V_{c\left(i_{1} i_{2}\right)}=V_{c\left(i_{2} i_{1}\right)}$. The remaining CSO $J_{i_{3}}$ respects this direct sum by Lemma 5.52 , and by Lemma 5.28 induces a CSO $P_{c\left(i_{1} i_{2}\right)} \circ J_{i_{3}} \circ Q_{c\left(i_{1} i_{2}\right)}$ on $V_{c\left(i_{1} i_{2}\right)}$, which commutes with the CSO induced by $J_{i_{1}}$ and $J_{i_{2}}$. So, again as in Example 5.51, there is a direct sum $V_{c\left(i_{1} i_{2}\right)}=$
$\left(V_{c\left(i_{1} i_{2}\right)}\right)_{c} \oplus\left(V_{c\left(i_{1} i_{2}\right)}\right)_{a}$ with projection $P_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)}: V_{c\left(i_{1} i_{2}\right)} \rightarrow\left(V_{c\left(i_{1} i_{2}\right)}\right)_{c}$. Simplifying the composition of projections gives the formula

$$
P_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)} \circ P_{c\left(i_{1} i_{2}\right)}=\frac{1}{4} \cdot\left(I d_{V}-J_{1} \circ J_{2}-J_{2} \circ J_{3}-J_{1} \circ J_{3}\right) .
$$

Considering $\left(V_{c\left(i_{1} i_{2}\right)}\right)_{c}$ as a subspace of $V$, the above formula shows that neither the composite map nor its image depends on the ordering of the three indices, and so $\left(V_{c\left(i_{1} i_{2}\right)}\right)_{c}$ is equal to the subspace where all three CSOs coincide and it can be denoted $V_{c(123)}$. The composite of inclusions $Q_{c\left(i_{1} i_{2}\right)} \circ Q_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)}$ also does not depend on the ordering. The canonical CSO on $V_{c(123)}$ is:

$$
\begin{equation*}
P_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)} \circ P_{c\left(i_{1} i_{2}\right)} \circ J_{i} \circ Q_{c\left(i_{1} i_{2}\right)} \circ Q_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)}, \tag{5.10}
\end{equation*}
$$

for any $i=1,2$, or 3 .
Example 5.88 is also a special case of both Theorem 1.122 and Example 5.61: given three commuting CSOs, there are commuting involutions on $V$,

$$
\begin{equation*}
K_{1}=-J_{2} \circ J_{3}, \quad K_{2}=-J_{1} \circ J_{3}, \quad K_{1} \circ K_{2}=-J_{1} \circ J_{2} \tag{5.11}
\end{equation*}
$$

The direct sums from Theorem 1.122 produced by these involutions are exactly $V=V_{c\left(i_{1} i_{2}\right)} \oplus V_{a\left(i_{1} i_{2}\right)}$, and each $V_{c\left(i_{1} i_{2}\right)}$ admits a canonically induced involution and direct sum. The conclusions of Theorem 1.122 are $V_{c(12)} \cap V_{c(23)} \cap V_{c(13)}=V_{c(123)}$ and $\left(V_{c\left(i_{1} i_{2}\right)}\right)_{a}=V_{a\left(i_{1} i_{3}\right)} \cap V_{a\left(i_{2} i_{3}\right)}$. From (1.16), each projection $P_{c\left(i_{1} i_{2}\right) i_{3}}$ is equal to a map induced by $P_{c\left(i_{1} i_{3}\right)}$ and also to a map induced by $P_{c\left(i_{2} i_{3}\right)}$.

Lemma 5.89. For $V$ with three commuting $C S O s J_{1}, J_{2}, J_{3}, \mathbf{U}=\left(U, J_{U}\right)$, and a map $H: V \rightarrow U$, if $H$ is c-linear with respect to $\left(J_{1}, J_{U}\right)$, then $H \circ Q_{c(12)}: V_{c(12)} \rightarrow$ $\mathbf{U}$ is c-linear with respect to $\left(P_{c(12)} \circ J_{1} \circ Q_{c(12)}, J_{U}\right)$ and $H \circ Q_{c(13)}: V_{c(13)} \rightarrow \mathbf{U}$ is c-linear with respect to $\left(P_{c(13)} \circ J_{1} \circ Q_{c(13)}, J_{U}\right)$. For any ordering $\left(i_{1}, i_{2}, i_{3}\right)$, $H \circ Q_{c\left(i_{1} i_{2}\right)} \circ Q_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)}: V_{c(123)} \rightarrow \mathbf{U}$ is c-linear.

Proof. The first claim follows from Lemma 5.55, for the induced CSO $P_{c(12)}{ }^{\circ}$ $J_{1} \circ Q_{c(12)}=P_{c(12)} \circ J_{2} \circ Q_{c(12)}$ on $V_{c(12)}$. The second claim similarly follows from Lemma 5.55, and there are analogous claims if $H$ is instead assumed to be c-linear with respect to either $\left(J_{2}, J_{U}\right)$ or $\left(J_{3}, J_{U}\right)$. Lemma 5.55 then applies to $H \circ Q_{c(12)}$, and the two CSOs on $V_{c(12)}$ from Example 5.88, $P_{c(12)} \circ J_{1} \circ Q_{c(12)}$ and $P_{c(12)} \circ J_{3} \circ Q_{c(12)}$, so $\left(H \circ Q_{c(12)}\right) \circ Q_{c((12) 3)}$ is c-linear with respect to $\left(P_{c((12) 3)} \circ\right.$ $\left.\left(P_{c(12)} \circ J_{1} \circ Q_{c(12)}\right) \circ Q_{c((12) 3)}, J_{U}\right)$. The last claim follows from the composites not depending on the ordering.

Lemma 5.90. Given $V$ with commuting $\operatorname{CSOs} J_{V}^{1}, J_{V}^{2}, J_{V}^{3}$, and $U$ with commuting CSOs $J_{U}^{1}, J_{U}^{2}, J_{U}^{3}$, if $H: U \rightarrow V$ satisfies $H \circ J_{U}^{1}=J_{V}^{1} \circ H$ and $H \circ J_{U}^{2}=J_{V}^{2} \circ H$ and $H \circ J_{U}^{3}=J_{V}^{3} \circ H$, then $H$ respects the corresponding direct sums from Example 5.88, and each induced map $P_{c\left(i_{1} i_{2}\right)}^{V} \circ H \circ Q_{c\left(i_{1} i_{2}\right)}^{U}$ is c-linear with respect to the CSOs induced by $J_{U}^{i_{1}}, J_{V}^{i_{1}}$ and also c-linear with respect to the CSOs induced by $J_{U}^{i_{3}}$, $J_{V}^{i_{3}}$. The induced map

$$
P_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)}^{V} \circ P_{c\left(i_{1} i_{2}\right)}^{V} \circ H \circ Q_{c\left(i_{1} i_{2}\right)}^{U} \circ Q_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)}^{U}: U_{c(123)} \rightarrow V_{c(123)}
$$

is c-linear and does not depend on the ordering $\left(i_{1}, i_{2}, i_{3}\right)$. If, also, $H$ is invertible, then the induced maps are invertible.

Proof. Theorem 1.123 applies, with commuting involutions on both $V$ and $U$ as in Example 5.88. In particular, $H$ respects the direct sums

$$
U_{c\left(i_{1} i_{2}\right)} \oplus U_{a\left(i_{1} i_{2}\right)} \rightarrow V_{c\left(i_{1} i_{2}\right)} \oplus V_{a\left(i_{1} i_{2}\right)}
$$

The induced map $P_{c\left(i_{1} i_{2}\right)}^{V} \circ H \circ Q_{c\left(i_{1} i_{2}\right)}^{U}$ respects the direct sum

$$
U_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)} \oplus\left(U_{c\left(i_{1} i_{2}\right)}\right)_{a} \rightarrow V_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)} \oplus\left(V_{c\left(i_{1} i_{2}\right)}\right)_{a},
$$

where $U_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)}=U_{c(123)}$ and $\left(U_{c\left(i_{1} i_{2}\right)}\right)_{a}=U_{a\left(i_{1} i_{3}\right)} \cap U_{a\left(i_{2} i_{3}\right)}$ as in Example 5.88. The first claim of c-linearity follows from Lemma 5.57. The second c-linearity requires checking
$P_{c\left(i_{1} i_{2}\right)}^{V} \circ H \circ Q_{c\left(i_{1} i_{2}\right)}^{U} \circ P_{c\left(i_{1} i_{2}\right)}^{U} \circ J_{U}^{i_{3}} \circ Q_{c\left(i_{1} i_{2}\right)}^{U}=P_{c\left(i_{1} i_{2}\right)}^{V} \circ J_{V}^{i_{3}} \circ Q_{c\left(i_{1} i_{2}\right)}^{V} \circ P_{c\left(i_{1} i_{2}\right)}^{V} \circ H \circ Q_{c\left(i_{1} i_{2}\right)}^{U}$, and then the last claims follow from Lemma 5.57 applied again to the commuting CSOs induced on $U_{c\left(i_{1} i_{2}\right)}, V_{c\left(i_{1} i_{2}\right)}$.

Example 5.91. Given $U$ with commuting CSOs $J_{1}, J_{2}, J_{3}$, suppose $H$ is an involution on $U$ such that $H \circ J_{1}=J_{2} \circ H$ and $H \circ J_{3}=J_{3} \circ H$. By Lemma 5.63, $H$ respects the direct sum $U_{c(12)} \oplus U_{a(12)} \rightarrow U_{c(12)} \oplus U_{a(12)}$, and induces involutions on $U_{c(12)}$ and $U_{a(12)}$. Lemma 5.90 applies to the triple $\left(J_{1}, J_{2}, J_{3}\right)$ on the domain of $H$ and $\left(J_{2}, J_{1}, J_{3}\right)$ on the target. So, $H$ respects the direct sums:

$$
\begin{align*}
& U_{c(13)} \oplus U_{a(13)} \rightarrow  \tag{5.12}\\
& U_{c(23)} \oplus U_{a(23)} \\
& U_{c(23)} \oplus U_{a(23)} \rightarrow
\end{align*} U_{c(13)} \oplus U_{a(13)},
$$

and the induced maps $U_{c(13)} \rightarrow U_{c(23)} \rightarrow U_{c(13)}$ are c-linear and mutually inverses. The induced maps $U_{a(13)} \rightarrow U_{a(23)} \rightarrow U_{a(13)}$ are also mutually inverses. The subspace $U_{c(12)}$ admits commuting CSOs $P_{c(12)} \circ J_{1} \circ Q_{c(12)}=P_{c(12)} \circ J_{2} \circ Q_{c(12)}$ and $P_{c(12)} \circ J_{3} \circ Q_{c(12)}$ as in Example 5.88, producing the direct sum $U_{c(123)} \oplus\left(U_{c(12)}\right)_{a}$. The induced involution $P_{c(12)} \circ H \circ Q_{c(12)}$ on $U_{c(12)}$ commutes with both of these CSOs, respects this direct sum, and induces a c-linear involution on $U_{c(123)}$ by Lemma 5.62. The involutions on $U$ from (5.11) satisfy

$$
\begin{equation*}
\left(-J_{2} \circ J_{3}\right) \circ H=H \circ\left(-J_{1} \circ J_{3}\right), \tag{5.13}
\end{equation*}
$$

so we have a special case of Example 1.124. Adapting the notation from Example 1.124, the involutions $H$ and $H \circ\left(-J_{1} \circ J_{2}\right)$ produce direct sums $U=U_{7} \oplus U_{8}$ and $U_{9} \oplus U_{10}$. The involution $P_{c(12)} \circ H \circ Q_{c(12)}$ on $U_{c(12)}$ commutes with $P_{c(12)} \circ\left(-J_{1} \circ\right.$ $\left.J_{3}\right) \circ Q_{c(12)}=P_{c(12)} \circ\left(-J_{2} \circ J_{3}\right) \circ Q_{c(12)}$, and their product $P_{c(12)} \circ\left(-J_{1} \circ J_{3} \circ H\right) \circ Q_{c(12)}$ is an involution with fixed point subspace $U_{11}$. The following commutative diagram is adapted from Example 1.124.


The subspace $U_{c(123)} \cap U_{7}$ has a canonical CSO.
Exercise 5.92. For $J_{1}, J_{2}, J_{3}$, and $H$ as in Example 5.91, the sixteen operators
$\left\{ \pm I d_{U}, \pm H, \pm J_{1} \circ J_{2}, \pm J_{1} \circ J_{3}, \pm J_{2} \circ J_{3}, \pm H \circ J_{1} \circ J_{2}, \pm H \circ J_{1} \circ J_{3}, \pm H \circ J_{2} \circ J_{3}\right\}$
form a group which is the image of a representation of $D_{4} \times \mathbb{Z}_{2}$. Unlike the group from Exercise 1.131, there is no pair of anticommuting elements.

Example 5.93. For $\mathbf{U}=\left(U, J_{U}\right), \mathbf{V}=\left(V, J_{V}\right)$, and $\mathbf{W}=\left(W, J_{W}\right)$, the space $U \otimes V \otimes W$ admits three commuting CSOs $\left[J_{U} \otimes I d_{V \otimes W}\right], \ldots,\left[I d_{U \otimes V} \otimes J_{W}\right]$. The subspaces $\left(\mathbf{U} \otimes_{c} \mathbf{V}\right) \otimes_{c} \mathbf{W}$ and $\mathbf{U} \otimes_{c}\left(\mathbf{V} \otimes_{c} \mathbf{W}\right)$ are equal, as a special case of Example 5.88.

Example 5.94. For $\mathbf{U}=\left(U, J_{U}\right)$ and commuting CSOs $J_{1}$, $J_{2}$ on $V, U \otimes V$ has three commuting CSOs: $\left[J_{U} \otimes I d_{V}\right],\left[I d_{U} \otimes J_{1}\right],\left[I d_{U} \otimes J_{2}\right]$. This is another special case of Example 5.88. The projection $P_{c(23)}: U \otimes V \rightarrow(U \otimes V)_{c(23)}=U \otimes V_{c}$ is as in Example 5.64, so $P_{c(23)}=\left[I d_{U} \otimes P_{c}\right]$, where $P_{c}: V \rightarrow V_{c}$ is as in Example 5.51. The subspace where all three CSOs agree is $(U \otimes V)_{c(123)}=\mathbf{U} \otimes_{c} V_{c}$.

Example 5.95. Given $U$ and $V$, suppose $\mathbf{V}=\left(V, J_{V}\right)$ and there are commuting CSOs $J_{U}$, $J_{U}^{\prime}$ on $U$. Then $J_{1}=\operatorname{Hom}\left(J_{U}, I d_{V}\right), J_{2}=\operatorname{Hom}\left(J_{U}^{\prime}, I d_{V}\right)$, $J_{3}=\operatorname{Hom}\left(I d_{U}, J_{V}\right)$ are three commuting CSOs on $\operatorname{Hom}(U, V)$, and this is a special case of Example 5.88. There are three direct sums:

$$
\operatorname{Hom}(U, V)=(\operatorname{Hom}(U, V))_{c(13)} \oplus(\operatorname{Hom}(U, V))_{a(13)},
$$

where $(\operatorname{Hom}(U, V))_{c(13)}=\operatorname{Hom}_{c}\left(\left(U, J_{U}\right), \mathbf{V}\right)$ as in Example 5.69,

$$
\operatorname{Hom}(U, V)=(\operatorname{Hom}(U, V))_{c(23)} \oplus(\operatorname{Hom}(U, V))_{a(23)},
$$

where $(\operatorname{Hom}(U, V))_{c(23)}=\operatorname{Hom}_{c}\left(\left(U, J_{U}^{\prime}\right), \mathbf{V}\right)$, and

$$
\operatorname{Hom}(U, V)=(\operatorname{Hom}(U, V))_{c(12)} \oplus(\operatorname{Hom}(U, V))_{a(12)},
$$

as in Example 5.75. Each $(\operatorname{Hom}(U, V))_{c\left(i_{1} i_{2}\right)}$ admits a direct sum with projection onto
$\left((\operatorname{Hom}(U, V))_{c\left(i_{1} i_{2}\right)}\right)_{c}=(\operatorname{Hom}(U, V))_{c(123)}=\left\{A: U \rightarrow V: A \circ J_{U}=A \circ J_{U}^{\prime}=J_{V} \circ A\right\}$.
The invertible map

$$
P_{c}^{\prime \prime} \circ \operatorname{Hom}\left(P_{c}, I d_{U}\right): \operatorname{Hom}\left(U_{c}, V\right) \rightarrow(\operatorname{Hom}(U, V))_{c(12)}
$$

from Example 5.75 (where in this case, $P_{c}^{\prime \prime}=P_{c(12)}$ ) is c-linear with respect to $\operatorname{Hom}\left(I d_{U_{c}}, J_{V}\right)$ and $P_{c(12)} \circ J_{3} \circ Q_{c(12)}$, and is also c-linear with respect to $\operatorname{Hom}\left(P_{c} \circ\right.$ $\left.J_{U} \circ Q_{c}, I d_{V}\right)$ and $P_{c(12)} \circ J_{1} \circ Q_{c(12)}$, so by Lemma 5.57, it respects the direct sums and induces an invertible, c-linear map $\operatorname{Hom}_{c}\left(U_{c}, \mathbf{V}\right) \rightarrow(\operatorname{Hom}(U, V))_{c(123)}$,
as indicated in the following diagram.


Lemma 5.96. Given $\mathbf{V}=\left(V, J_{V}\right)$ and $U$ with commuting CSOs $J_{U}^{1}$, $J_{U}^{2}$, let $W$ be a space with three commuting CSOs $J_{W}^{1}, J_{W}^{2}, J_{W}^{3}$. If $H: W \rightarrow \operatorname{Hom}(U, V)$ satisfies $\operatorname{Hom}\left(J_{U}^{1}, I d_{V}\right) \circ H=H \circ J_{W}^{1}$ and $\operatorname{Hom}\left(J_{U}^{2}, I d_{V}\right) \circ H=H \circ J_{W}^{2}$ and $\operatorname{Hom}\left(I d_{U}, J_{V}\right) \circ H=H \circ J_{W}^{3}$, then $H$ respects the corresponding direct sums from Example 5.95 and the induced maps are c-linear. If also $H$ is invertible, then the induced maps are invertible.

Proof. That $H$ respects the direct sums produced by the three corresponding pairs of CSOs, and that the induced maps

$$
P_{c\left(i_{1} i_{2}\right)} \circ H \circ Q_{c\left(i_{1} i_{2}\right)}^{\prime}: W_{c\left(i_{1} i_{2}\right)} \rightarrow(\operatorname{Hom}(U, V))_{c\left(i_{1} i_{2}\right)}
$$

(for example, the arrow labeled $a_{3}$ in the diagram below) are c-linear, follow from Lemma 5.90, which also showed the induced map $\tilde{a}_{3}: W_{c(123)} \rightarrow(\operatorname{Hom}(U, V))_{c(123)}$ is c-linear, and invertible if $H$ is. In the diagram, $a_{1}$ and $\tilde{a}_{1}$ are the canonical invertible maps which appeared as horizontal arrows in the diagram from Example 5.95; the adjacent projection arrows are also copied from that diagram. Lemma 5.76 showed that $H$ also respects the direct sum $W_{c(12)} \oplus W_{a(12)} \rightarrow \operatorname{Hom}\left(U_{c}, V\right) \oplus$ $\operatorname{Hom}\left(U_{a}, V\right)$ and that the induced map $\operatorname{Hom}\left(Q_{c}, I d_{V}\right) \circ H \circ Q_{c(12)}^{\prime}$, denoted $a_{2}$ in the diagram below, is c-linear with respect to the CSO induced by $J_{W}^{1}$ and the CSO induced by $\operatorname{Hom}\left(J_{U}^{1}, I d_{V}\right)$. In fact, $a_{2}$ is also c-linear with respect to the other pair of CSOs, induced by $J_{W}^{3}$ and $\operatorname{Hom}\left(I d_{U}, J_{V}\right)$. By Lemma 5.57, $a_{2}$ respects the direct sums produced by the commuting CSOs and induces a c-linear map $\tilde{a}_{2}: W_{c(123)} \rightarrow \operatorname{Hom}_{c}\left(U_{c}, \mathbf{V}\right)$; it satisfies the identity $\tilde{a}_{2}=\tilde{a}_{1} \circ \tilde{a}_{3}$.


Example 5.97. Given $U$ and $V$, suppose there are three commuting CSOs $J_{U}$, $J_{U}^{\prime}, J_{U}^{\prime \prime}$ on $U$. Then $J_{1}=\operatorname{Hom}\left(J_{U}, I d_{V}\right), J_{2}=\operatorname{Hom}\left(J_{U}^{\prime}, I d_{V}\right), J_{3}=\operatorname{Hom}\left(J_{U}^{\prime \prime}, I d_{V}\right)$ are three commuting CSOs on $\operatorname{Hom}(U, V)$, and this is a special case of Example 5.88. There are three direct sums: $\operatorname{Hom}(U, V)=(\operatorname{Hom}(U, V))_{c\left(i_{1} i_{2}\right)} \oplus(\operatorname{Hom}(U, V))_{a\left(i_{2} i_{2}\right)}$, each of which is equivalent to a direct sum $\operatorname{Hom}\left(U_{c\left(i_{1} i_{2}\right)}, V\right) \oplus \operatorname{Hom}\left(U_{a\left(i_{1} i_{2}\right)}, V\right)$ as in Example 5.75, with projection $\operatorname{Hom}\left(Q_{c\left(i_{2}, i_{2}\right)}, I d_{V}\right): \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}\left(U_{c\left(i_{1} i_{2}\right)}, V\right)$ and inclusion $\operatorname{Hom}\left(P_{c\left(i_{2}, i_{2}\right)}, I d_{V}\right)$. Each $(\operatorname{Hom}(U, V))_{c\left(i_{1} i_{2}\right)}$ admits a direct sum with projection $P_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)}^{\prime}$ onto
$\left((\operatorname{Hom}(U, V))_{c\left(i_{1} i_{2}\right)}\right)_{c}=(\operatorname{Hom}(U, V))_{c(123)}=\left\{A: U \rightarrow V: A \circ J_{U}=A \circ J_{U}^{\prime}=A \circ J_{U}^{\prime \prime}\right\}$.
Each subspace $\operatorname{Hom}\left(U_{c\left(i_{2} i_{2}\right)}, V\right)$ has two commuting CSOs, and Example 5.75 applies again; there are equivalent direct sums:

$$
\begin{aligned}
& \operatorname{Hom}\left(U_{c\left(i_{1} i_{2}\right)}, V\right)=\left(\operatorname{Hom}\left(U_{c\left(i_{1} i_{2}\right)}, V\right)\right)_{c} \oplus\left(\operatorname{Hom}\left(U_{c\left(i_{1} i_{2}\right)}, V\right)\right)_{a} \\
& \operatorname{Hom}\left(U_{c\left(i_{1} i_{2}\right)}, V\right)=\operatorname{Hom}\left(U_{c(123)}, V\right) \oplus \operatorname{Hom}\left(\left(U_{c\left(i_{1} i_{2}\right)}\right)_{a}, V\right)
\end{aligned}
$$

The following diagram shows the $\left(i_{1} i_{2}\right)=(12)$ case, the other two cases being similar.


The horizontal arrows are

$$
\begin{aligned}
a_{1} & =P_{c(12)}^{\prime} \circ \operatorname{Hom}\left(P_{c(12)}, I d_{V}\right) \\
a_{2} & =P_{c}^{\prime \prime} \circ \operatorname{Hom}\left(P_{c((12) 3)}, I d_{V}\right) \\
a_{3} & =P_{c((12) 3)}^{\prime} \circ a_{1} \circ Q_{c}^{\prime \prime} .
\end{aligned}
$$

Both $a_{1}$ and $a_{2}$ are c-linear and invertible, canonically induced from the equivalent direct sums as in Example 5.75. The $a_{1}$ map is also c-linear with respect to the CSOs induced by $J_{U}^{\prime \prime}$, so the induced map $a_{3}$ is c-linear and invertible by Lemma 5.57. The c-linear invertible composite

$$
a_{3} \circ a_{2}=P_{c((12) 3)}^{\prime} \circ P_{c(12)}^{\prime} \circ \operatorname{Hom}\left(P_{c((12) 3)} \circ P_{c(12)}, I d_{V}\right)
$$

is canonical, not depending on the choice of $\left(i_{1} i_{2}\right)$, as in Example 5.88.
Example 5.98. Given $U$ and $V$, suppose $\mathbf{U}=\left(U, J_{U}\right)$ and there are commuting CSOs $J_{V}, J_{V}^{\prime}$ on $V$. Then $J_{1}=\operatorname{Hom}\left(J_{U}, I d_{V}\right), J_{2}=\operatorname{Hom}\left(I d_{U}, J_{V}\right)$, $J_{3}=\operatorname{Hom}\left(I d_{U}, J_{V}^{\prime}\right)$ are three commuting CSOs on $\operatorname{Hom}(U, V)$, and this is a special case of Example 5.88. There are three direct sums:

$$
\operatorname{Hom}(U, V)=(\operatorname{Hom}(U, V))_{c(12)} \oplus(\operatorname{Hom}(U, V))_{a(12)}
$$

where $(\operatorname{Hom}(U, V))_{c(12)}=\operatorname{Hom}_{c}\left(\mathbf{U},\left(V, J_{V}\right)\right)$ as in Example 5.69,

$$
\operatorname{Hom}(U, V)=(\operatorname{Hom}(U, V))_{c(13)} \oplus(\operatorname{Hom}(U, V))_{a(13)}
$$

where $(\operatorname{Hom}(U, V))_{c(13)}=\operatorname{Hom}_{c}\left(\mathbf{U},\left(V, J_{V}^{\prime}\right)\right)$, and

$$
\operatorname{Hom}(U, V)=(\operatorname{Hom}(U, V))_{c(23)} \oplus(\operatorname{Hom}(U, V))_{a(23)},
$$

where $(\operatorname{Hom}(U, V))_{c(23)}=\operatorname{Hom}\left(U, V_{c}\right)$ as in Example 5.74. Each $(\operatorname{Hom}(U, V))_{c\left(i_{1} i_{2}\right)}$ admits a direct sum with projection onto

$$
\left((\operatorname{Hom}(U, V))_{c\left(i_{1} i_{2}\right)}\right)_{c}=(\operatorname{Hom}(U, V))_{c(123)}=\operatorname{Hom}_{c}\left(\mathbf{U}, V_{c}\right),
$$

as follows:
There are two ways to construct the projection

$$
P^{1}:(\operatorname{Hom}(U, V))_{c(23)}=\operatorname{Hom}\left(U, V_{c}\right) \rightarrow(\operatorname{Hom}(U, V))_{c(123)}=\operatorname{Hom}_{c}\left(\mathbf{U}, V_{c}\right),
$$

which will turn out to give the same map. Denote the projection $P_{c}^{\prime}: V \rightarrow V_{c}$ as in Example 5.51 with corresponding inclusion $Q_{c}^{\prime}$; then $P_{c(23)}=\operatorname{Hom}\left(I d_{U}, P_{c}^{\prime}\right)$ : $\operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}\left(U, V_{c}\right)$ is the projection from (5.9) in Example 5.74, with corresponding inclusion $Q_{c(23)}=\operatorname{Hom}\left(I d_{U}, Q_{c}^{\prime}\right)$.

The first construction of $P^{1}$ is to consider $\operatorname{Hom}\left(U, V_{c}\right)$ as a space with commuting CSOs $\operatorname{Hom}\left(J_{U}, I d_{V_{c}}\right), \operatorname{Hom}\left(I d_{U}, J_{V_{c}}\right)$ and directly apply Example 5.69 to get a projection

$$
\begin{align*}
P^{1} & =\frac{1}{2} \cdot\left(I d_{\operatorname{Hom}\left(U, V_{c}\right)}-\operatorname{Hom}\left(J_{U}, I d_{V_{c}}\right) \circ \operatorname{Hom}\left(I d_{U}, J_{V_{c}}\right)\right) \\
& =\frac{1}{2} \cdot\left(I d_{\operatorname{Hom}\left(U, V_{c}\right)}-\operatorname{Hom}\left(J_{U}, P_{c}^{\prime} \circ J_{V} \circ Q_{c}^{\prime}\right)\right) . \tag{5.14}
\end{align*}
$$

Second, consider the subspace $(\operatorname{Hom}(U, V))_{c(23)}$, with two induced CSOs that commute, as in Example 5.88:

$$
\left(P_{c(23)} \circ \operatorname{Hom}\left(J_{U}, I d_{V}\right) \circ Q_{c(23)}\right), \quad\left(P_{c(23)} \circ \operatorname{Hom}\left(I d_{U}, J_{V}\right) \circ Q_{c(23)}\right) .
$$

Then, using $P_{c(23)}=\operatorname{Hom}\left(I d_{U}, P_{c}^{\prime}\right)$ and $Q_{c(23)}=\operatorname{Hom}\left(I d_{U}, Q_{c}^{\prime}\right)$, the projection $P_{c((23) 1)}$ defined by these two CSOs as in Example 5.88 is the same as (5.14).

The projection $P_{c((12) 3)}:(\operatorname{Hom}(U, V))_{c(12)} \rightarrow(\operatorname{Hom}(U, V))_{c(123)}$ can also be defined by two methods with the same result (and similarly for $\left.P_{c((13) 2)}\right)$. The commuting induced CSOs:

$$
\begin{equation*}
\left(P_{c(12)} \circ \operatorname{Hom}\left(J_{U}, I d_{V}\right) \circ Q_{c(12)}\right), \quad\left(P_{c(12)} \circ \operatorname{Hom}\left(I d_{U}, J_{V}^{\prime}\right) \circ Q_{c(12)}\right) \tag{5.15}
\end{equation*}
$$

define $P_{c((12) 3)}$ as in Example 5.88. The other way to define the projection is to consider the map $\operatorname{Hom}\left(I d_{U}, P_{c}^{\prime}\right): \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}\left(U, V_{c}\right)$, which is c-linear in two different ways: with respect to the pair $\operatorname{Hom}\left(J_{U}, I d_{V}\right), \operatorname{Hom}\left(J_{U}, I d_{V_{c}}\right)$ and also the pair $\operatorname{Hom}\left(I d_{U}, J_{V}\right), \operatorname{Hom}\left(I d_{U}, J_{V_{c}}\right)$, as in Lemma 5.71. The induced map $P^{2}=P^{1} \circ \operatorname{Hom}\left(I d_{U}, P_{c}^{\prime}\right) \circ Q_{c(12)}:(\operatorname{Hom}(U, V))_{c(12)} \rightarrow \operatorname{Hom}_{c}\left(U, V_{c}\right)$ is c-linear; it can be denoted $\operatorname{Hom}_{c}\left(I d_{U}, P_{c}^{\prime}\right)$ as in Notation 5.72. By the equality of the composite projections from Example 5.88,

$$
\begin{align*}
P^{2} & =P^{1} \circ \operatorname{Hom}\left(I d_{U}, P_{c}^{\prime}\right) \circ Q_{c(12)}  \tag{5.16}\\
& =P_{c((23) 1)} \circ P_{c(23)} \circ Q_{c(12)}  \tag{5.17}\\
& =P_{c((12) 3)} \circ P_{c(12)} \circ Q_{c(12)}=P_{c((12) 3)} .
\end{align*}
$$

The expression (5.17) is an example of the construction (1.16) from Theorem 1.122.
Similarly, since the composite inclusions are equal:

$$
\begin{equation*}
Q_{c(12)} \circ Q_{c((12) 3)}=\operatorname{Hom}\left(I d_{U}, Q_{c}^{\prime}\right) \circ Q_{c((23) 1)}, \tag{5.18}
\end{equation*}
$$

the inclusion $Q_{c((12) 3)}$ is equal the induced map:

$$
Q_{c((12) 3)}=P_{c(12)} \circ \operatorname{Hom}\left(I d_{U}, Q_{c}^{\prime}\right) \circ Q_{c((23) 1)}=\operatorname{Hom}_{c}\left(I d_{U}, Q_{c}^{\prime}\right)
$$

Exercise 5.99. Given $\mathbf{V}=\left(V, J_{V}\right)$ and $\mathbf{W}=\left(W, J_{W}\right), \operatorname{Hom}(\operatorname{Hom}(V, W), W)$ admits three commuting CSOs,

$$
\begin{aligned}
J_{1} & =\operatorname{Hom}\left(\operatorname{Hom}\left(J_{V}, I d_{W}\right), I d_{W}\right) \\
J_{2} & =\operatorname{Hom}\left(\operatorname{Hom}\left(I d_{V}, J_{W}\right), I d_{W}\right) \\
J_{3} & =\operatorname{Hom}\left(I d_{\operatorname{Hom}(V, W)}, J_{W}\right)
\end{aligned}
$$

As in Example 5.95, there are three direct sums; $(\operatorname{Hom}(\operatorname{Hom}(V, W), W))_{c(23)}$ was considered in Exercise 5.40. The composite

$$
P_{c((23) 1)} \circ P_{c(23)} \circ d_{V W}: \mathbf{V} \rightarrow(\operatorname{Hom}(\operatorname{Hom}(V, W), W))_{c(123)}
$$

is c-linear with respect to the canonical CSO. Let $Q_{c}: \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \hookrightarrow \operatorname{Hom}(V, W)$ denote the inclusion from Example 5.69. Then the image of

$$
\operatorname{Hom}\left(Q_{c}, I d_{W}\right) \circ d_{V W}: V \rightarrow \operatorname{Hom}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}), W\right)
$$

is contained in $\operatorname{Hom}_{c}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}), \mathbf{W}\right)$, i.e., for any $v \in V$,

$$
d_{V W}(v) \circ Q_{c}: \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \rightarrow \mathbf{W}: H \mapsto\left(Q_{c}(H)\right)(v)=H(v)
$$

is a c-linear map. From the commutativity of the diagram from Example 5.95, considering $\operatorname{Hom}\left(Q_{c}, I d_{W}\right) \circ d_{V W}$ as a map $\mathbf{V} \rightarrow \operatorname{Hom}_{c}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}), \mathbf{W}\right)$, it is identical to the composite of the above map $P_{c((23) 1)} \circ P_{c(23)} \circ d_{V W}$ with the canonical $\operatorname{map}(\operatorname{Hom}(\operatorname{Hom}(V, W), W))_{c(123)} \rightarrow \operatorname{Hom}_{c}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}), \mathbf{W}\right)$, so it is c-linear.

Recall from Definition 1.38 and Notation 1.39 the canonical map

$$
n: V \otimes \operatorname{Hom}(U, W) \rightarrow \operatorname{Hom}(U, V \otimes W):\left(n^{\prime}(v \otimes E)\right): u \mapsto v \otimes(E(u))
$$

Theorem 5.100. If $\mathbf{U}=\left(U, J_{U}\right)$ and $\mathbf{V}=\left(V, J_{V}\right)$ and $\mathbf{W}=\left(W, J_{W}\right)$, then $n: V \otimes \operatorname{Hom}(U, W) \rightarrow \operatorname{Hom}(U, V \otimes W)$ is c-linear with respect to corresponding pairs of the three commuting CSOs induced on each space, so it respects the direct sums and induces c-linear maps

$$
\begin{aligned}
n^{1}: V \otimes \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W}) & \rightarrow \operatorname{Hom}_{c}(\mathbf{U}, V \otimes \mathbf{W}) \\
n^{2}: \mathbf{V} \otimes_{c} \operatorname{Hom}(\mathbf{U}, W) & \rightarrow \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V} \otimes W) \\
n^{3}: \mathbf{V} \otimes_{c} \operatorname{Hom}(U, \mathbf{W}) & \rightarrow \operatorname{Hom}\left(U, \mathbf{V} \otimes_{c} \mathbf{W}\right) \\
\mathbf{n}: \mathbf{V} \otimes_{c} \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W}) & \rightarrow \operatorname{Hom}_{c}\left(\mathbf{U}, \mathbf{V} \otimes_{c} \mathbf{W}\right),
\end{aligned}
$$

which are invertible if $n$ is.
Proof. The c-linearity claims for $n$ follow from Lemma 1.40 (adjusted for variations in ordering; they are also straightforward to check directly), and then Lemma 5.90 applies. The direct sums for the domain $V \otimes \operatorname{Hom}(U, W)$ are as in Example 5.94. The projection onto the subspace $V \otimes \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W})$ is equal to $\left[I d_{V} \otimes P_{H}\right]$ as in Example 5.64, where $P_{H}$ is the projection $\operatorname{Hom}(U, W) \rightarrow$ $\operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W})$. The direct sums for the target space $\operatorname{Hom}(U, V \otimes W)$ are as in Example 5.98. The following diagram shows some of the canonical projections,
including $P^{2}$ as in (5.16).


The invertibility also follows from Lemma 5.90; in particular, if $U$ or $V$ is finitedimensional then these maps are invertible.

Example 5.101. Given $\mathbf{U}=\left(U, J_{U}\right), \mathbf{V}=\left(V, J_{V}\right), \mathbf{W}=\left(W, J_{W}\right)$, the canonical invertible map

$$
q: \operatorname{Hom}(V, \operatorname{Hom}(U, W)) \rightarrow \operatorname{Hom}(V \otimes U, W)
$$

from Definition 1.43 is c-linear with respect to the three corresponding pairs of induced CSOs, by Lemma 1.46. Lemma 5.96 applies, so that the following induced maps are c-linear and invertible:

$$
\begin{aligned}
\operatorname{Hom}_{c}\left(\mathbf{V}, \operatorname{Hom}_{(\mathbf{U}, W))}\right. & \rightarrow \operatorname{Hom}^{\left(\mathbf{V} \otimes_{c} \mathbf{U}, W\right)} \\
\operatorname{Hom}_{\left(V, \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W})\right)} & \rightarrow \operatorname{Hom}_{c}(V \otimes \mathbf{U}, \mathbf{W}) \\
\operatorname{Hom}_{c}\left(\mathbf{V}, \operatorname{Hom}_{c}(U, \mathbf{W})\right) & \rightarrow \operatorname{Hom}_{c}(\mathbf{V} \otimes U, \mathbf{W}) \\
\operatorname{Hom}_{c}\left(\mathbf{V}, \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W})\right) & \rightarrow \operatorname{Hom}_{c}\left(\mathbf{V} \otimes_{c} \mathbf{U}, \mathbf{W}\right) .
\end{aligned}
$$

The direct sums for the domain $\operatorname{Hom}(V, \operatorname{Hom}(U, W))$ are as in Example 5.98. The direct sums for the target space $\operatorname{Hom}(V \otimes U, W)$ are as in Example 5.95.

Example 5.102. Given $\mathbf{V}=\left(V, J_{V}\right)$ and $\mathbf{W}=\left(W, J_{W}\right), \operatorname{Hom}(V, \operatorname{Hom}(V, W))$ admits three commuting CSOs, and the involution $T_{V ; W}$ is c-linear with respect to three corresponding pairs of commuting CSOs as in Exercise 5.45 and Exercise 5.46. $\operatorname{Hom}(V, \operatorname{Hom}(V, W))$ also admits the three involutions from (5.11), and the involution $T_{V ; W}$ satisfies

$$
\left(-\operatorname{Hom}\left(I d_{V}, \operatorname{Hom}\left(J_{V}, J_{W}\right)\right)\right) \circ T_{V ; W}=T_{V ; W} \circ\left(-\operatorname{Hom}\left(J_{V}, \operatorname{Hom}\left(I d_{V}, J_{W}\right)\right)\right)
$$

as in (5.13), so this is a special case of Example 5.91. As in (5.12), $T_{V ; W}$ induces c-linear invertible maps:

$$
\begin{aligned}
& \operatorname{Hom}_{c}(\mathbf{V}, \operatorname{Hom}(V, \mathbf{W})) \\
& \operatorname{Hom}\left(V, \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W})\right) \rightarrow \operatorname{Hom}_{c}\left(V, \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W})\right) \\
& \operatorname{Hom}(V, \mathbf{W})) .
\end{aligned}
$$

The subspace $\operatorname{Hom}_{c}(\mathbf{V}, \operatorname{Hom}(\mathbf{V}, W))$ admits commuting CSOs as in (5.15), and projects onto the subspace $\operatorname{Hom}_{c}\left(\mathbf{V}, \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W})\right)$ as in Example 5.98. The involution on $\operatorname{Hom}_{c}(\mathbf{V}, \operatorname{Hom}(\mathbf{V}, W))$ induced by $T_{V ; W}$ from Exercise 5.85 induces a c-linear involution on $\operatorname{Hom}_{c}\left(\mathbf{V}, \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W})\right)$, producing a direct sum denoted $\operatorname{Sym}_{c}(\mathbf{V} ; \mathbf{W}) \oplus A l t_{c}(\mathbf{V} ; \mathbf{W})$. Combining the notation from Example 1.124, Example 5.86, and Example 5.91, the following commutative diagram shows some of the
projections from Example 5.91.


The projection $P^{2}=P_{c((12) 3)}$ labeled in the diagram, and the vertical arrow $P_{c((13) 2)}$ on the left, are as in (5.16) from Example 5.98. The subspace $U_{11}$ is this fixed point subspace:

$$
\left\{h:\left(h\left(v_{1}\right)\right)\left(v_{2}\right)=-\left(h\left(J_{V}\left(v_{1}\right)\right)\right)\left(J_{V}\left(v_{2}\right)\right)=-J_{W}\left(\left(h\left(J_{V}\left(v_{2}\right)\right)\right)\left(v_{1}\right)\right)\right\}
$$

The conclusions from Example 5.91 are that

$$
\operatorname{Sym}_{c}(\mathbf{V} ; \mathbf{W})=\operatorname{Hom}_{c}\left(\mathbf{V}, \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W})\right) \cap \operatorname{Sym}(V ; W),
$$

and that $\operatorname{Sym}_{c}(\mathbf{V} ; \mathbf{W})$ has a canonical CSO.
Exercise 5.103. Given $\mathbf{U}=\left(U, J_{U}\right)$ and $\mathbf{W}=\left(W, J_{W}\right), \operatorname{Hom}(\operatorname{Hom}(V, W) \otimes$ $U, W)$ admits three commuting CSOs, as in Example 5.95 , so there are three direct sums; $(\operatorname{Hom}(\operatorname{Hom}(V, W) \otimes U, W))_{c(23)}$ was considered in Exercise 5.43. The composite

$$
P_{c((23) 1)} \circ P_{c(23)} \circ e_{U V}^{W}: \operatorname{Hom}(\mathbf{U}, V) \rightarrow(\operatorname{Hom}(\operatorname{Hom}(V, \mathbf{W}) \otimes \mathbf{U}, \mathbf{W}))_{c(123)}
$$

is c-linear with respect to the canonical CSO. Let

$$
Q_{c}: \operatorname{Hom}(V, \mathbf{W}) \otimes_{c} \mathbf{U} \hookrightarrow \operatorname{Hom}(V, W) \otimes U
$$

denote the inclusion from Example 5.65. Then the image of

$$
\operatorname{Hom}\left(Q_{c}, I d_{W}\right) \circ e_{U V}^{W}: \operatorname{Hom}(\mathbf{U}, V) \rightarrow \operatorname{Hom}\left(\operatorname{Hom}(V, \mathbf{W}) \otimes_{c} \mathbf{U}, W\right)
$$

is contained in $\operatorname{Hom}_{c}\left(\operatorname{Hom}(V, \mathbf{W}) \otimes_{c} \mathbf{U}, \mathbf{W}\right)$, i.e., for any $A \in \operatorname{Hom}(U, V)$,
$e_{U V}^{W}(A) \circ Q_{c}: \operatorname{Hom}(V, \mathbf{W}) \otimes_{c} \mathbf{U} \rightarrow \mathbf{W}: B \otimes u \mapsto\left(e_{U V}^{W}(A)\right)\left(Q_{c}(B \otimes u)\right)=B(A(u))$ is a c-linear map. From the commutativity of the diagram from Example 5.95, considering $\operatorname{Hom}\left(Q_{c}, I d_{W}\right) \circ e_{U V}^{W}$ as a map $\operatorname{Hom}(\mathbf{U}, V) \rightarrow \operatorname{Hom}_{c}\left(\operatorname{Hom}(V, \mathbf{W}) \otimes_{c}\right.$ $\mathbf{U}, \mathbf{W})$, it is identical to the composite of the above map $P_{c((23) 1)} \circ P_{c(23)} \circ e_{U V}^{W}$ with the canonical map $(\operatorname{Hom}(\operatorname{Hom}(V, W) \otimes U, W))_{c(123)} \rightarrow \operatorname{Hom}_{c}\left(\operatorname{Hom}(V, \mathbf{W}) \otimes_{c} \mathbf{U}, \mathbf{W}\right)$, so it is c-linear.

Exercise 5.104. Given $\mathbf{V}=\left(V, J_{V}\right)$ and $\mathbf{W}=\left(W, J_{W}\right), \operatorname{Hom}(\operatorname{Hom}(V, W) \otimes$ $U, W)$ admits three commuting CSOs, as in Example 5.95, so there are three direct sums; $(\operatorname{Hom}(\operatorname{Hom}(V, W) \otimes U, W))_{c(23)}$ was considered in Exercises 5.43, 5.103. The composite

$$
P_{c((23) 1)} \circ P_{c(23)} \circ e_{U V}^{W}: \operatorname{Hom}(U, \mathbf{V}) \rightarrow(\operatorname{Hom}(\operatorname{Hom}(\mathbf{V}, \mathbf{W}) \otimes U, \mathbf{W}))_{c(123)}
$$

is c-linear with respect to the canonical CSO. Let $Q_{c}: \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes U \rightarrow$ $\operatorname{Hom}(V, W) \otimes U$ denote the inclusion from Examples 5.64 and 5.69. Then the image of

$$
\operatorname{Hom}\left(Q_{c}, I d_{W}\right) \circ e_{U V}^{W}: \operatorname{Hom}(U, \mathbf{V}) \rightarrow \operatorname{Hom}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes U, W\right)
$$

is contained in $\operatorname{Hom}_{c}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes U, \mathbf{W}\right)$, i.e., for any $A \in \operatorname{Hom}(U, V)$,
$e_{U V}^{W}(A) \circ Q_{c}: \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes U \rightarrow \mathbf{W}: B \otimes u \mapsto\left(e_{U V}^{W}(A)\right)\left(Q_{c}(B \otimes u)\right)=B(A(u))$
is a c-linear map. From the commutativity of the diagram from Example 5.95, considering $\operatorname{Hom}\left(Q_{c}, I d_{W}\right) \circ e_{U V}^{W}$ as a map $\operatorname{Hom}(U, \mathbf{V}) \rightarrow \operatorname{Hom}_{c}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes\right.$ $U, \mathbf{W})$, it is identical to the composite of the above map $P_{c((23) 1)} \circ P_{c(23)} \circ e_{U V}^{W}$ with the canonical map $(\operatorname{Hom}(\operatorname{Hom}(V, W) \otimes U, W))_{c(123)} \rightarrow \operatorname{Hom}_{c}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes U, \mathbf{W}\right)$, so it is c-linear.

Exercise 5.105. Given $U, V, W$, with $\mathbf{U}=\left(U, J_{U}\right), \mathbf{V}=\left(V, J_{V}\right)$, and $\mathbf{W}=\left(W, J_{W}\right)$, we consider the three commuting $\operatorname{CSOs}$ on $\operatorname{Hom}(V, W) \otimes U$, so Example 5.97 applies to $\operatorname{Hom}(\operatorname{Hom}(V, W) \otimes U, W)$. The lower square in the following commutative diagram is a specific case of a square from the diagram in Example 5.97, with the same labeling of arrows, and (12) referring to the CSOs induced by $J_{U}$ and $J_{V}$. The $e_{1}, e_{2}$ arrows are the maps induced by $e_{U V}^{W}$ on the two equivalent direct sums from Exercise 5.82.


The composite $P_{c((12) 3)}^{\prime} \circ e_{2}$ is c-linear, so the composite $\operatorname{Hom}\left(Q_{c((12) 3)}, I d_{W}\right) \circ e_{1}$ is also c-linear. As in Exercises 5.43, 5.103, 5.104, the image of $\operatorname{Hom}\left(Q_{c((12) 3)}, I d_{W}\right) \circ$ $e_{1}$ is contained in $\operatorname{Hom}_{c}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes \mathbf{U}, \mathbf{W}\right)$, i.e., if $Q_{c}^{\prime}$ denotes the inclusion of $\operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V}) \hookrightarrow \operatorname{Hom}(U, V)$ and $Q_{c(12)} \circ Q_{c((12) 3)}$ is the composite inclusion of $\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes_{c} \mathbf{U} \hookrightarrow \operatorname{Hom}(V, W) \otimes U$, then for any $A \in \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V})$, the map

$$
\begin{equation*}
e_{U V}^{W}\left(Q_{c}^{\prime}(A)\right) \circ Q_{c(12)} \circ Q_{c((12) 3)}: \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes_{c} \mathbf{U} \rightarrow \mathbf{W} \tag{5.19}
\end{equation*}
$$

is c-linear.
Example 5.106. For $\mathbf{V}=\left(V, J_{V}\right)$ and $\mathbf{W}=\left(W, J_{W}\right)$, the space $\operatorname{Hom}(V, W) \otimes V$ admits three commuting CSOs as in Example 5.94. The composite of the inclusions, $Q_{c(12)} \circ Q_{c((12) 3)}$,

$$
\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes_{c} \mathbf{V}_{Q_{c((12) 3)}} \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes V{ }_{Q_{c(12)}} \operatorname{Hom}(V, W) \otimes V
$$

does not depend on the ordering of the indices, but in the case of the above diagram, $Q_{c(12)}=\left[Q_{c} \otimes I d_{V}\right]$ for $Q_{c}: \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \hookrightarrow \operatorname{Hom}(V, W)$, as in Example 5.64.

Define a c-linear evaluation map

$$
\begin{equation*}
E v_{\mathbf{V W}}^{c}=E v_{V W} \circ Q_{c(12)} \circ Q_{c((12) 3)}: \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes_{c} \mathbf{V} \rightarrow \mathbf{W} \tag{5.20}
\end{equation*}
$$

This is the restriction of the canonical evaluation from Definition 2.69; it is c-linear by Exercise 5.44 and Lemma 5.89. Considering the formula $E v_{V W}=e_{V V}^{W}\left(I d_{V}\right)$ from Equation (2.11), this construction is also a special case of (5.19) from Exercise 5.105. The domain $\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes_{c} \mathbf{V}$ is spanned by elements of the form $P_{c((12) 3)}(A \otimes v)$ for c-linear maps $A: V \rightarrow W$, on which $E v_{\mathbf{V W}}^{c}$ acts as follows:

$$
\begin{aligned}
& E v_{\mathbf{V W}}^{c}\left(P_{c((12) 3)}(A \otimes v)\right) \\
= & \left(E v_{V W} \circ Q_{c(12)} \circ Q_{c((12) 3)} \circ P_{c((12) 3)}\right)(A \otimes v) \\
= & \left(E v_{V W} \circ\left[Q_{c} \otimes I d_{V}\right] \circ \frac{1}{2}\left(I d_{\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes V}-\left[J_{\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W})} \otimes J_{V}\right]\right)\right)(A \otimes v) \\
= & E v_{V W}\left(\frac{1}{2}\left(\left(Q_{c}(A)\right) \otimes v-\left(Q_{c}\left(A \circ J_{V}\right)\right) \otimes\left(J_{V}(v)\right)\right)\right) \\
= & \frac{1}{2}\left(Q_{c}(A)\right)(v)-\frac{1}{2}\left(Q_{c}\left(A \circ J_{V}\right)\right)\left(J_{V}(v)\right) \\
(5.21)= & A(v)=E v_{V W}(A \otimes v)
\end{aligned}
$$

where in line (5.21), we just forget that $A=Q_{c}(A)$ and $A \circ J_{V}=Q_{c}\left(A \circ J_{V}\right)$ are c-linear.

Lemma 5.107. For any $\mathbf{U}, \mathbf{V}, \mathbf{W}$, and c-linear map $B: \mathbf{U} \rightarrow \mathbf{W}$, the following diagram is commutative.


Proof. This is a c-linear version of Lemma 2.71 (the case $G=I d_{V}$ ), which states the commutativity of the upper block of this diagram (for any $B$, not necessarily c-linear).


The middle block is commutative by definition of $\operatorname{Hom}_{c}\left(I d_{V}, B\right)$ for the c-linear maps $I d_{V}$ and $B$ as in Notation 5.72, together with Lemma 1.35. The lower block is commutative by the construction from Notation 5.67. The upward composites in the left and right columns are $E v_{\mathbf{V U}}^{c}$ and $E v_{\mathbf{V W}}^{c}$ as in Example 5.106.

### 5.3.3. Four Commuting Complex Structure Operators.

Example 5.108. Given $V$ and four commuting CSOs $J_{1}, J_{2}, J_{3}, J_{4}$, the construction of Example 5.88 shows that for any ordered pair $\left(i_{1}, i_{2}\right)$ selected without repeats from the indices $1,2,3,4$, there is a direct sum with projection $P_{c\left(i_{1} i_{2}\right)}: V \rightarrow V_{c\left(i_{1} i_{2}\right)}$, and for a third distinct index, another direct sum with projection $P_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)}: V_{c\left(i_{1} i_{2}\right)} \rightarrow V_{c\left(i_{1} i_{2} i_{3}\right)}$. Repeating the process for the remaining, fourth index, the fourth commuting CSO produces a direct sum $V_{c\left(i_{1} i_{2} i_{3}\right)}=$ $\left(V_{c\left(i_{1} i_{2} i_{3}\right)}\right)_{c} \oplus\left(V_{c\left(i_{1} i_{2} i_{3}\right)}\right)_{a}$, with projection $P_{c\left(\left(i_{1} i_{2} i_{3}\right) i_{4}\right)}: V_{c\left(i_{1} i_{2} i_{3}\right)} \rightarrow\left(V_{c\left(i_{1} i_{2} i_{3}\right)}\right)_{c}$. As in Example 5.88, the composite $P_{c\left(\left(i_{1} i_{2} i_{3}\right) i_{4}\right)} \circ P_{c\left(\left(i_{1} i_{2}\right) i_{3}\right)} \circ P_{c\left(i_{1} i_{2}\right)}$ equals

$$
\frac{1}{8} \cdot\left(I d_{V}-J_{1} \circ J_{2}-J_{2} \circ J_{3}-J_{1} \circ J_{3}-J_{1} \circ J_{4}-J_{2} \circ J_{4}-J_{3} \circ J_{4}+J_{1} \circ J_{2} \circ J_{3} \circ J_{4}\right)
$$

which shows the image of the last projection does not depend on the ordering of the four indices, so the subspace where all four CSOs coincide can be denoted $V_{c(1234)}$.

Example 5.109. Given $V$ and four commuting $\operatorname{CSOs} J_{1}, J_{2}, J_{3}, J_{4}$, the space $V_{c\left(i_{1} i_{2}\right)}$ from Example 5.108 admits three commuting CSOs: $P_{c\left(i_{1} i_{2}\right)} \circ J_{i_{1}} \circ Q_{c\left(i_{1} i_{2}\right)}$, $P_{c\left(i_{1} i_{2}\right)} \circ J_{i_{3}} \circ Q_{c\left(i_{1} i_{2}\right)}, P_{c\left(i_{1} i_{2}\right)} \circ J_{i_{4}} \circ Q_{c\left(i_{1} i_{2}\right)}$. Example 5.108 considered pairing the first one with one of the other two to get two direct sums, but as in Example 5.88, there are three possible direct sums on $V_{c\left(i_{1} i_{2}\right)}$, the third coming from $P_{c\left(i_{1} i_{2}\right)} \circ J_{i_{3}} \circ$ $Q_{c\left(i_{1} i_{2}\right)}, P_{c\left(i_{1} i_{2}\right)} \circ J_{i_{4}} \circ Q_{c\left(i_{1} i_{2}\right)}$ to get a subspace denoted $V_{c\left(i_{1} i_{2}\right)\left(i_{3} i_{4}\right)}$, where $J_{i_{1}}=$ $J_{i_{2}}$ and $J_{i_{3}}=J_{i_{4}}$, equal to the subspace $V_{c\left(i_{3} i_{4}\right)\left(i_{1} i_{2}\right)}$. The composite projection $V \rightarrow V_{c\left(i_{1} i_{2}\right)\left(i_{3} i_{4}\right)}$ is given by the formula

$$
\frac{1}{4} \cdot\left(I d_{V}-J_{1} \circ J_{2}-J_{3} \circ J_{4}+J_{1} \circ J_{2} \circ J_{3} \circ J_{4}\right)
$$

The subspace $V_{c\left(i_{1} i_{2}\right)\left(i_{3} i_{4}\right)}$ admits two commuting CSOs, the one induced by $J_{i_{1}}$ and $J_{i_{2}}$, and the other by $J_{i_{3}}$ and $J_{i_{4}}$, so there is a direct sum, and a projection onto the subspace $V_{c(1234)}$ from Example 5.108.

Theorem 5.110. Given $V$ and four commuting $C S O s J_{1}, J_{2}, J_{3}, J_{4}$, the following diagram is commutative, where the arrows are all the projections from direct sums produced by commuting CSOs described in Examples 5.108 and 5.109.


Proof. Some sub-diagrams were already considered in Examples 5.88, 5.108, 5.109. Some remain to be checked, for example, the equality of the composite projections $V_{c(12)} \rightarrow V_{c(123)} \rightarrow V_{c(1234)}$ and $V_{c(12)} \rightarrow V_{c(12)(34)} \rightarrow V_{c(1234)}$ follows from considering the three CSOs on $V_{c(12)}$ as in Example 5.88. The corresponding composites of inclusions are also equal.

Lemma 5.111. Given $V$ with commuting CSOs $J_{V}^{1}, J_{V}^{2}$, $J_{V}^{3}$, $J_{V}^{4}$, and $U$ with commuting CSOs $J_{U}^{1}, J_{U}^{2}, J_{U}^{3}$, $J_{U}^{4}$, if $H: U \rightarrow V$ satisfies $H \circ J_{U}^{1}=J_{V}^{1} \circ H$ and $H \circ J_{U}^{2}=J_{V}^{2} \circ H$ and $H \circ J_{U}^{3}=J_{V}^{3} \circ H$ and $H \circ J_{U}^{4}=J_{V}^{4} \circ H$, then $H$ respects the corresponding direct sums from Examples 5.108 and 5.109, and induces maps $U_{c\left(i_{1} i_{2}\right)} \rightarrow V_{c\left(i_{1} i_{2}\right)}, U_{c\left(i_{1} i_{2} i_{3}\right)} \rightarrow V_{c\left(i_{1} i_{2} i_{3}\right)}$, and $U_{c\left(i_{1} i_{2}\right)\left(i_{3} i_{4}\right)} \rightarrow V_{c\left(i_{1} i_{2}\right)\left(i_{3} i_{4}\right)}$, which are c-linear with respect to all pairs of CSOs induced by $J_{U}^{i}, J_{V}^{i}$, and invertible if $H$ is. The induced map $U_{c(1234)} \rightarrow V_{c(1234)}$ is c-linear, and invertible if $H$ is.

Proof. All the claims follow from Lemma 5.57 and Lemma 5.90. As in Lemma 5.90 , the map $U_{c(1234)} \rightarrow V_{c(1234)}$ is canonically induced, not depending on the ordering of the indices.

Example 5.112. For $V$ with commuting $\operatorname{CSOs} J_{V}, J_{V}^{\prime}$, and $U$ with commuting CSOs $J_{U}, J_{U}^{\prime}$, the space $U \otimes V$ has four commuting CSOs:

$$
J_{1}=\left[J_{U} \otimes I d_{V}\right], \quad J_{2}=\left[I d_{U} \otimes J_{V}\right], \quad J_{3}=\left[J_{U}^{\prime} \otimes I d_{V}\right], \quad J_{4}=\left[I d_{U} \otimes J_{V}^{\prime}\right]
$$

Theorem 5.110 applies, to give a collection of subspaces of $U \otimes V$. From Example $5.64,(U \otimes V)_{c(13)}=U_{c} \otimes V$ and $(U \otimes V)_{c(24)}=U \otimes V_{c}$. From Example 5.65, $(U \otimes V)_{c(12)}=U \otimes_{c} V$, and we (temporarily) denote a similar construction $(U \otimes$ $V)_{c(34)}=U \otimes^{\prime} V$. The subspaces $(U \otimes V)_{c(14)}$ and $(U \otimes V)_{c(23)}$ did not appear in previous Examples, and are omitted from the following commutative diagram, where the positions of the objects match the corresponding positions in the diagram from Theorem 5.110.


The subspaces $U_{c} \otimes_{c} V, U \otimes_{c} V_{c}, U_{c} \otimes^{\prime} V$, and $U \otimes^{\prime} V_{c}$ are as in Example 5.94. The set $U \otimes_{c}^{\prime} V$ corresponds to $(U \otimes V)_{c(12)(34)}$, where $J_{1}=J_{2}$ and $J_{3}=J_{4}$; this notation
resembles (5.6) from Example 5.61, with the commuting involutions $-J_{1} \circ J_{2}$ and $-J_{3} \circ J_{4}$.

Example 5.113. For $V$ with commuting CSOs $J_{V}, J_{V}^{\prime}$, and $U$ with commuting CSOs $J_{U}, J_{U}^{\prime}$, the space $\operatorname{Hom}(U, V)$ has four commuting CSOs:

$$
\begin{aligned}
& J_{1}=\operatorname{Hom}\left(J_{U}, I d_{V}\right), J_{2}=\operatorname{Hom}\left(J_{U}^{\prime}, I d_{V}\right), \\
& J_{3}=\operatorname{Hom}\left(I d_{U}, J_{V}\right), J_{4}=\operatorname{Hom}\left(I d_{U}, J_{V}^{\prime}\right)
\end{aligned}
$$

Theorem 5.110 applies, to give a collection of subspaces of $\operatorname{Hom}(U, V)$. The subspace $(\operatorname{Hom}(U, V))_{c(12)}$ was considered in Example 5.95. As in Example 5.69, denote $(\operatorname{Hom}(U, V))_{c(13)}=\operatorname{Hom}_{c}(U, V)$, and (temporarily) denote a similar construction $(\operatorname{Hom}(U, V))_{c(24)}=\operatorname{Hom}^{\prime}(U, V)$. From Example 5.74, denote $(\operatorname{Hom}(U, V))_{c(34)}=$ $\operatorname{Hom}\left(U, V_{c}\right)$. The subspaces $(\operatorname{Hom}(U, V))_{c(14)}$ and $(\operatorname{Hom}(U, V))_{c(23)}$ are omitted from the following commutative diagram, but otherwise the positions of the objects match the corresponding positions in the diagram from Theorem 5.110 and Example 5.112.


Adapting the notation from (5.6) in Example 5.61, $\operatorname{Hom}_{c}^{\prime}(U, V)$ denotes the subspace

$$
(\operatorname{Hom}(U, V))_{c(13)(24)}=\left\{A: U \rightarrow V: A \circ J_{U}=J_{V} \circ A \text { and } A \circ J_{U}^{\prime}=J_{V}^{\prime} \circ A\right\} .
$$

If we ignore $J_{U}^{\prime}$, then the two projections onto $\operatorname{Hom}_{c}\left(U, V_{c}\right)$ in the above diagram are as in Example 5.98. Similarly ignoring $J_{U}$, the two projections onto $\operatorname{Hom}^{\prime}\left(U, V_{c}\right)$ are also as in Example 5.98.

Example 5.114. The space $(\operatorname{Hom}(U, V))_{c(12)}$ from Example 5.113 is related to $\operatorname{Hom}\left(U_{c}, V\right)$ as in Example 5.95 , by an invertible map $P_{c(12)} \circ \operatorname{Hom}\left(P_{c}, I d_{V}\right)$. Both $(\operatorname{Hom}(U, V))_{c(12)}$ and $\operatorname{Hom}\left(U_{c}, V\right)$ admit three induced CSOs, and $\operatorname{Hom}\left(U_{c}, V\right)$ admits three direct sums as in Example 5.98. The map $P_{c(12)} \circ \operatorname{Hom}\left(P_{c}, I d_{V}\right)$ is c-linear with respect to the three corresponding pairs of CSOs, so by Lemma 5.90, it respects the direct sums and induces c-linear invertible maps as indicated by the unlabeled horizontal arrows in the following diagram. The left part is copied from the diagram in Example 5.113, and the top triangle and top square appeared already in the diagram for Example 5.95.


The projections $P^{1}, P^{2}$ are labeled to match (5.14), (5.16) from Example 5.98, and the lower right vertical arrow is also from (5.16).

Theorem 5.115. For $V$ with commuting $C S O s J_{V}, J_{V}^{\prime}$, and $U$ with commuting CSOs $J_{U}, J_{U}^{\prime}$, let $W$ be a space with four commuting CSOs $J_{W}^{1}, J_{W}^{2}, J_{W}^{3} J_{W}^{4}$. If $H: W \rightarrow \operatorname{Hom}(U, V)$ satisfies $\operatorname{Hom}\left(J_{U}, I d_{V}\right) \circ H=H \circ J_{W}^{1}$ and $\operatorname{Hom}\left(J_{U}^{\prime}, I d_{V}\right) \circ H=$ $H \circ J_{W}^{2}$ and $\operatorname{Hom}\left(I d_{U}, J_{V}\right) \circ H=H \circ J_{W}^{3}$ and $\operatorname{Hom}\left(I d_{U}, J_{V}^{\prime}\right) \circ H=H \circ J_{W}^{4}$, then $H$ respects the corresponding direct sums from Examples 5.113 and 5.114, and the induced maps are c-linear. If also $H$ is invertible, then the induced maps are invertible.

Proof. The claims for the induced maps

$$
\begin{aligned}
W_{c\left(i_{1} i_{2}\right)} & \rightarrow(\operatorname{Hom}(U, V))_{c\left(i_{1} i_{2}\right)} \\
W_{c\left(i_{1} i_{2} i_{3}\right)} & \rightarrow(\operatorname{Hom}(U, V))_{c\left(i_{1} i_{2} i_{3}\right)} \\
W_{c\left(i_{1} i_{2}\right)\left(i_{3} i_{4}\right)} & \rightarrow(\operatorname{Hom}(U, V))_{c\left(i_{1} i_{2}\right)\left(i_{3} i_{4}\right)} \\
\tilde{a}_{3}: W_{c(1234)} & \rightarrow(\operatorname{Hom}(U, V))_{c(1234)}
\end{aligned}
$$

follow from Lemma 5.111. The target spaces are as in the diagram from Example 5.113 , for example, $H$ induces a map $W_{c(13)(24)} \rightarrow \operatorname{Hom}_{c}^{\prime}(U, V)$, labeled $a_{3}$ in the diagram below, and $a_{3}$ induces $\tilde{a}_{3}$. The claims for the induced maps

$$
a_{2}=\operatorname{Hom}\left(Q_{c}, I d_{V}\right) \circ H \circ Q_{c(12)}^{\prime}: W_{c(12)} \rightarrow \operatorname{Hom}\left(U_{c}, V\right),
$$

and $W_{c(123)} \rightarrow \operatorname{Hom}_{c}\left(U_{c},\left(V, J_{V}\right)\right)\left(=\operatorname{Hom}_{c}\left(U_{c}, V\right)\right.$ in the diagram from Example 5.114), and $W_{c(124)} \rightarrow \operatorname{Hom}_{c}\left(U_{c},\left(V, J_{V}^{\prime}\right)\right)=\operatorname{Hom}^{\prime}\left(U_{c}, V\right)$ follow from Lemma 5.96. The map $a_{2}$ is c-linear with respect to the pair of CSOs induced by $J_{W}^{3}$ and $\operatorname{Hom}\left(I d_{U}, J_{V}\right)$, as mentioned in the Proof of Lemma 5.96, and is also c-linear with respect to the pair of CSOs induced by $J_{W}^{4}$ and $\operatorname{Hom}\left(I d_{U}, J_{V}^{\prime}\right)$, so it satisfies the hypotheses of Lemma 5.90, and respects the corresponding direct sums in the diagram from Example 5.114. The maps induced by $a_{2}$ are c-linear:

$$
\begin{aligned}
& W_{c(12)(34)} \rightarrow \\
& \operatorname{Hom}_{c}\left(U_{c}, V_{c}\right) \\
& \tilde{a}_{2}: W_{c(1234)} \rightarrow \\
& \operatorname{Hom}_{c}\left(U_{c}, V_{c}\right)
\end{aligned}
$$

In the following diagram, the left half is copied from the diagram from Example 5.114, where $a_{1}=\operatorname{Hom}\left(Q_{c}, I d_{V}\right) \circ Q_{c(12)}$ induces $\tilde{a}_{1}$, and they are both c-linear and invertible. The space $\operatorname{Hom}_{c}^{\prime}(U, V)$ and projections $P_{c(13)(24)}, P_{3}$ are copied from Example 5.113, and the right half of the diagram is part of the diagram from

Theorem 5.110.


Finally, we remark that $\tilde{a}_{2}=\tilde{a}_{1} \circ \tilde{a}_{3}$; an analogous property was observed in the Proof of Lemma 5.96. The identity can be checked directly, using the c-linearity of $H$. The map $\tilde{a}_{2}$ acts on $w \in W_{c(1234)}$ as: $\tilde{a}_{2}: w \mapsto P_{c}^{\prime} \circ H(w) \circ Q_{c}$, where $P_{c}^{\prime}$ is the projection $V \rightarrow V_{c}$.

Exercise 5.116. Given $U, V, W$, with $\mathbf{U}=\left(U, J_{U}\right), \mathbf{V}=\left(V, J_{V}\right)$, and $\mathbf{W}=$ $(W, J)$, for any $A \in \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V})$, the map $t_{U V}^{W}(A): \operatorname{Hom}(V, W) \rightarrow \operatorname{Hom}(U, W)$ (or, more precisely, $t_{U V}^{W}\left(Q_{c}^{\prime}(A)\right)$, where $Q_{c}^{\prime}$ is the inclusion of $\operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V})$ in $\operatorname{Hom}(U, V))$ is c-linear with respect to both pairs $\operatorname{Hom}\left(I d_{V}, J_{W}\right), \operatorname{Hom}\left(I d_{U}, J_{W}\right)$ and $\operatorname{Hom}\left(J_{U}, I d_{W}\right), \operatorname{Hom}\left(J_{V}, I d_{W}\right)$, so $t_{U V}^{W}(A)$ respects the direct sums and induces a c-linear map $\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \rightarrow \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W})$. The resulting map, denoted

$$
t_{\mathbf{U V}}^{\mathbf{W}}: \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V}) \rightarrow \operatorname{Hom}_{c}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}), \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W})\right)
$$

is c-linear.
Hint. Lemma 5.57, Exercise 5.80, and Exercise 5.38 apply. The last claim can be checked directly. However, by following the diagrams from Examples 5.113 and 5.114, a little more can be obtained. Let $Q_{i}$ and $P_{i}$ denote the operators for the direct sum $\operatorname{Hom}(V, W)=\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \oplus \operatorname{Hom}_{a}(V, W)$, so that

$$
\begin{aligned}
\operatorname{Hom}\left(Q_{c}, I d_{\operatorname{Hom}(U, W)}\right) & : \\
\operatorname{Hom}(\operatorname{Hom}(V, W), \operatorname{Hom}(U, W)) & \rightarrow \quad \operatorname{Hom}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}), \operatorname{Hom}(U, W)\right)
\end{aligned}
$$

is as in Example 5.114. Then

$$
\operatorname{Hom}\left(Q_{c}, I d_{\operatorname{Hom}(U, W)}\right) \circ t_{U V}^{W}: \operatorname{Hom}(U, V) \rightarrow \operatorname{Hom}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}), \operatorname{Hom}(U, W)\right)
$$

is c-linear with respect to $\operatorname{Hom}\left(J_{U}, I d_{V}\right)$ and the CSO induced by

$$
J^{3}=\operatorname{Hom}\left(I d_{\operatorname{Hom}(V, W)}, \operatorname{Hom}\left(J_{U}, I d_{W}\right)\right),
$$

and is also c-linear with respect to $\operatorname{Hom}\left(I d_{U}, J_{V}\right)$ and the CSO induced by

$$
J^{1}=\operatorname{Hom}\left(\operatorname{Hom}\left(J_{V}, I d_{W}\right), I d_{\operatorname{Hom}(U, W)}\right) .
$$

So by Lemma 5.57, it induces a c-linear map

$$
\operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V}) \rightarrow \operatorname{Hom}_{c}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}), \operatorname{Hom}(\mathbf{U}, W)\right)
$$

As claimed above, the image of this induced map is contained in the subspace $\operatorname{Hom}_{c}\left(\operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}), \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W})\right)$. For $A \in \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{V})$ and $K \in \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W})$,

$$
\left(t_{U V}^{W}\left(Q_{c}^{\prime}(A)\right)\right) \circ Q_{c}: K \mapsto\left(Q_{c}(K)\right) \circ\left(Q_{c}^{\prime}(A)\right)=K \circ A \in \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W})
$$

Example 5.117. Given $U_{1}, U_{2}, V_{1}, V_{2}$, and $\mathbf{U}_{\mathbf{1}}=\left(U_{1}, J_{U_{1}}\right)$, the canonical map (Definition 1.32)

$$
j: \operatorname{Hom}\left(\mathbf{U}_{\mathbf{1}}, V_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, V_{2}\right) \rightarrow \operatorname{Hom}\left(\mathbf{U}_{\mathbf{1}} \otimes U_{2}, V_{1} \otimes V_{2}\right)
$$

is c-linear with respect to the induced CSOs, by Lemma 1.36. A similar statement holds if any one of the four spaces has a CSO.

If every one of the above four spaces has a CSO, $\mathbf{U}_{\mathbf{1}}=\left(U_{1}, J_{U_{1}}\right), \mathbf{U}_{\mathbf{2}}=$ $\left(U_{2}, J_{U_{2}}\right), \mathbf{V}_{\mathbf{1}}=\left(V_{1}, J_{V_{1}}\right), \mathbf{V}_{\mathbf{2}}=\left(V_{2}, J_{V_{2}}\right)$, then $\operatorname{Hom}\left(U_{1}, V_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, V_{2}\right)$ admits four commuting CSOs:

$$
\begin{aligned}
J_{1}^{\prime} & =\left[\operatorname{Hom}\left(J_{U_{1}}, I d_{V_{1}}\right) \otimes I d_{\operatorname{Hom}\left(U_{2}, V_{2}\right)}\right] \\
J_{2}^{\prime} & =\left[I d_{\operatorname{Hom}\left(U_{1}, V_{1}\right)} \otimes \operatorname{Hom}\left(J_{U_{2}}, I d_{V_{2}}\right)\right] \\
J_{3}^{\prime} & =\left[\operatorname{Hom}\left(I d_{U_{1}}, J_{V_{1}}\right) \otimes I d_{\operatorname{Hom}\left(U_{2}, V_{2}\right)}\right] \\
J_{4}^{\prime} & =\left[I d_{\operatorname{Hom}\left(U_{1}, V_{1}\right)} \otimes \operatorname{Hom}\left(I d_{U_{2}}, J_{V_{2}}\right)\right]
\end{aligned}
$$

and $\operatorname{Hom}\left(U_{1} \otimes U_{2}, V_{1} \otimes V_{2}\right)$ also admits four commuting CSOs:

$$
\begin{aligned}
& J_{1}=\operatorname{Hom}\left(\left[J_{U_{1}} \otimes I d_{U_{2}}\right], I d_{V_{1} \otimes V_{2}}\right) \\
& J_{2}=\operatorname{Hom}\left(\left[I d_{U_{1}} \otimes J_{U_{2}}\right], I d_{V_{1} \otimes V_{2}}\right) \\
& J_{3}=\operatorname{Hom}\left(I d_{U_{1} \otimes U_{2}},\left[J_{V_{1}} \otimes I d_{V_{2}}\right]\right) \\
& J_{4}=\operatorname{Hom}\left(I d_{U_{1} \otimes U_{2}},\left[I d_{V_{1}} \otimes J_{V_{2}}\right]\right) .
\end{aligned}
$$

Since $j$ is c-linear with respect to each pair $J_{i}^{\prime}, J_{i}$, Theorem 5.115 applies, with $H=j$ and $W=\operatorname{Hom}\left(U_{1}, V_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, V_{2}\right)$, so $j$ induces maps on corresponding subspaces, which are c-linear with respect to (possibly several pairs of) corresponding CSOs, and which are invertible if $j$ is. From the diagrams in Theorem 5.110 and Examples 5.112, 5.113, some induced maps from Lemma 5.111 are evident:

$$
\begin{align*}
& \operatorname{Hom}\left(\mathbf{U}_{\mathbf{1}}, V_{1}\right) \otimes_{c} \operatorname{Hom}\left(U_{2}, \mathbf{V}_{\mathbf{2}}\right) \rightarrow \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}} \otimes U_{2}, V_{1} \otimes \mathbf{V}_{\mathbf{2}}\right) \\
& \operatorname{Hom}\left(U_{1}, \mathbf{V}_{\mathbf{1}}\right) \otimes_{c} \operatorname{Hom}\left(\mathbf{U}_{\mathbf{2}}, V_{2}\right) \rightarrow \operatorname{Hom}_{c}\left(U_{1} \otimes \mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{1}} \otimes V_{2}\right) \\
& \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}}, \mathbf{V}_{\mathbf{1}}\right) \otimes \operatorname{Hom}\left(U_{2}, V_{2}\right) \rightarrow \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}} \otimes U_{2}, \mathbf{V}_{\mathbf{1}} \otimes V_{2}\right) \\
& \operatorname{Hom}\left(U_{1}, V_{1}\right) \otimes \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{2}}\right) \rightarrow \operatorname{Hom}_{c}\left(U_{1} \otimes \mathbf{U}_{\mathbf{2}}, V_{1} \otimes \mathbf{V}_{\mathbf{2}}\right) \\
& \operatorname{Hom}\left(U_{1}, \mathbf{V}_{\mathbf{1}}\right) \otimes_{c} \operatorname{Hom}\left(U_{2}, \mathbf{V}_{\mathbf{2}}\right) \rightarrow{\operatorname{Hom}\left(U_{1} \otimes U_{2}, \mathbf{V}_{\mathbf{1}} \otimes_{c} \mathbf{V}_{\mathbf{2}}\right)}_{\operatorname{Hom}\left(U_{1}, \mathbf{V}_{\mathbf{1}}\right) \otimes_{c} \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{2}}\right)} \rightarrow \operatorname{Hom}_{c}\left(U_{1} \otimes \mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{1}} \otimes_{c} \mathbf{V}_{\mathbf{2}}\right) \\
&) a_{3}: \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}}, \mathbf{V}_{\mathbf{1}}\right) \otimes \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{2}}\right) \rightarrow \operatorname{Hom}_{c}^{\prime}\left(U_{1} \otimes U_{2}, V_{1} \otimes V_{2}\right) \\
& \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}}, \mathbf{V}_{\mathbf{1}}\right) \otimes_{c}{\operatorname{Hom}\left(U_{2}, \mathbf{V}_{\mathbf{2}}\right)} \rightarrow \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}} \otimes U_{2}, \mathbf{V}_{\mathbf{1}} \otimes_{c} \mathbf{V}_{\mathbf{2}}\right)  \tag{5.22}\\
& \tilde{a}_{3}: \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}}, \mathbf{V}_{\mathbf{1}}\right) \otimes_{c} \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{2}}\right) \rightarrow\left({\left.\operatorname{Hom}\left(U_{1} \otimes U_{2}, V_{1} \otimes V_{2}\right)\right)_{c(1234)} .}^{2} .\right.
\end{align*}
$$

For example, the seventh map, labeled $a_{3}$ as in the diagram from Theorem 5.115, is c-linear with respect to both corresponding pairs of induced CSOs, and for c-linear maps $A$ and $B$, takes $A \otimes B$ to the map $j(A \otimes B): U_{1} \otimes U_{2} \rightarrow V_{1} \otimes V_{2}$, which is c-linear with respect to the pair $\left[J_{U_{1}} \otimes I d_{U_{2}}\right],\left[J_{V_{1}} \otimes I d_{V_{2}}\right]$, and also c-linear with respect to the pair $\left[I d_{U_{1}} \otimes J_{U_{2}}\right],\left[I d_{V_{1}} \otimes J_{V_{2}}\right]$.

Also, if some but not all of the four spaces have CSOs, then there may still be some induced maps, for example, the first one in the above list makes sense if only $U_{1}$ and $V_{2}$ have CSOs.

Let $Q_{c(12)}^{\prime}, P_{c(12)}^{\prime}$, and $Q_{c(12)}, P_{c(12)}$ denote the inclusion and projection operators for the direct sums produced by $J_{1}^{\prime}, J_{2}^{\prime}$, and $J_{1}, J_{2}$, respectively, as appearing in the diagram from the Proof of Theorem 5.115. By Lemma 5.76, the map $j$ also respects the direct sum

$$
\operatorname{Hom}\left(\mathbf{U}_{\mathbf{1}} \otimes_{c} \mathbf{U}_{\mathbf{2}}, V_{1} \otimes V_{2}\right) \oplus \operatorname{Hom}\left(U_{1} \otimes_{a} U_{2}, V_{1} \otimes V_{2}\right)
$$

and induces a c-linear map, labeled

$$
a_{2}=\operatorname{Hom}\left(Q_{c}, I d_{V_{1} \otimes V_{2}}\right) \circ j \circ Q_{c(12)}^{\prime}
$$

as in the following diagram, a copy of two blocks of the diagram from Theorem 5.115 .


The map $a_{2}$ is equal to the composite of the induced map
$P_{c(12)} \circ j \circ Q_{c(12)}^{\prime}: \operatorname{Hom}\left(\mathbf{U}_{\mathbf{1}}, V_{1}\right) \otimes_{c} \operatorname{Hom}\left(\mathbf{U}_{\mathbf{2}}, V_{2}\right) \rightarrow\left(\operatorname{Hom}\left(U_{1} \otimes U_{2}, V_{1} \otimes V_{2}\right)\right)_{c(12)}$ with the invertible c-linear map from Example 5.114, labeled $a_{1}$ in Theorem 5.115, $\operatorname{Hom}\left(Q_{c}, I d_{V_{1} \otimes V_{2}}\right) \circ Q_{c(12)}:\left(\operatorname{Hom}\left(U_{1} \otimes U_{2}, V_{1} \otimes V_{2}\right)\right)_{c(12)} \rightarrow \operatorname{Hom}\left(\mathbf{U}_{\mathbf{1}} \otimes_{c} \mathbf{U}_{\mathbf{2}}, V_{1} \otimes V_{2}\right)$.
Also, $a_{2}$ is c-linear with respect to all three corresponding pairs of induced CSOs, so as in Example 5.113 and Theorem 5.115 , it respects the corresponding direct sums, to induce c-linear maps:

$$
\begin{aligned}
\operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}}, \mathbf{V}_{\mathbf{1}}\right) \otimes_{c} \operatorname{Hom}\left(\mathbf{U}_{\mathbf{2}}, V_{2}\right) & \rightarrow \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}} \otimes_{c} \mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{1}} \otimes V_{2}\right) \\
\operatorname{Hom}\left(U_{1}, V_{1}\right) \otimes_{c}^{\prime} \operatorname{Hom}\left(U_{2}, V_{2}\right) & \rightarrow \operatorname{Hom}\left(\mathbf{U}_{\mathbf{1}} \otimes_{c} \mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{1}} \otimes_{c} \mathbf{V}_{\mathbf{2}}\right) \\
\operatorname{Hom}\left(\mathbf{U}_{\mathbf{1}}, V_{1}\right) \otimes_{c} \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{2}}\right) & \rightarrow \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}} \otimes_{c} \mathbf{U}_{\mathbf{2}}, V_{1} \otimes_{\left.\mathbf{V}_{\mathbf{2}}\right)}\right. \\
\tilde{a}_{2}: \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}}, \mathbf{V}_{\mathbf{1}}\right) \otimes_{c} \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{2}}\right) & \rightarrow \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}} \otimes_{c} \mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{1}} \otimes_{c} \mathbf{V}_{\mathbf{2}}\right) .
\end{aligned}
$$

As remarked in the Proof of Theorem 5.115 , let $\tilde{a}_{1}$ denote the invertible map induced by $a_{1}$,

$$
\left(\operatorname{Hom}\left(U_{1} \otimes U_{2}, V_{1} \otimes V_{2}\right)\right)_{c(1234)} \rightarrow \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}} \otimes_{c} \mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{1}} \otimes_{c} \mathbf{V}_{\mathbf{2}}\right)
$$

so that then $\tilde{a}_{2}=\tilde{a}_{1} \circ \tilde{a}_{3}$. The map $\tilde{a}_{2}$ is invertible if $j$ is; it acts on $w \in$ $\operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}}, \mathbf{V}_{\mathbf{1}}\right) \otimes_{c} \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{2}}\right) \subseteq \operatorname{Hom}\left(U_{1}, V_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, V_{2}\right)$ as: $\tilde{a}_{2}: w \mapsto$ $P_{c}^{\prime} \circ j(w) \circ Q_{c}$, where $P_{c}^{\prime}$ is the projection $V_{1} \otimes V_{2} \rightarrow \mathbf{V}_{\mathbf{1}} \otimes_{c} \mathbf{V}_{\mathbf{2}}$.

Example 5.118. For $\mathbf{U}_{\mathbf{1}}, \mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{1}}, \mathbf{V}_{\mathbf{2}}$ as in Example 5.117 , suppose $A: \mathbf{U}_{\mathbf{1}} \rightarrow$ $\mathbf{V}_{\mathbf{1}}$ and $B: \mathbf{U}_{\mathbf{2}} \rightarrow \mathbf{V}_{\mathbf{2}}$ are c-linear. Then

$$
A \otimes B \in \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}}, \mathbf{V}_{\mathbf{1}}\right) \otimes \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{2}}\right) \subseteq \operatorname{Hom}\left(U_{1}, V_{1}\right) \otimes \operatorname{Hom}\left(U_{2}, V_{2}\right)
$$

so $A \otimes B$ is in the domain of $a_{3}=\left.j\right|_{\operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}}, \mathbf{V}_{\mathbf{1}}\right) \otimes \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{2}}\right)}$ as in (5.22) and the following diagram, a copy of two blocks of the diagram from Theorem 5.115.


Starting with $A \otimes B$, these outputs are equal by the commutativity of the diagram from Theorem 5.115:

$$
\begin{align*}
& \left(\tilde{a}_{2} \circ P_{2}^{\prime}\right)(A \otimes B)=\tilde{a}_{2}\left(\frac{1}{2}\left(A \otimes B-\left(J_{V_{1}} \circ A\right) \otimes\left(B \circ J_{U_{2}}\right)\right)\right) \\
= & P_{c}^{\prime} \circ\left(\frac{1}{2}\left([A \otimes B]-\left[\left(J_{V_{1}} \circ A\right) \otimes\left(B \circ J_{U_{2}}\right)\right]\right)\right) \circ Q_{c},  \tag{5.23}\\
& \left(\tilde{a}_{1} \circ P_{3} \circ a_{3}\right)(A \otimes B)=\tilde{a}_{1}\left(P_{3}([A \otimes B])\right) \\
= & P_{c}^{\prime} \circ\left(\frac{1}{2}\left([A \otimes B]-\left[J_{V_{1}} \otimes I d_{V_{2}}\right] \circ[A \otimes B] \circ\left[I d_{U_{1}} \otimes J_{U_{2}}\right]\right)\right) \circ Q_{c} .
\end{align*}
$$

As in Lemma 5.71, this is the restriction of the map $\frac{1}{2}\left([A \otimes B]-\left[\left(J_{V_{1}} \circ A\right) \otimes\right.\right.$ $\left.\left.\left(B \circ J_{U_{2}}\right)\right]\right) \in \operatorname{Hom}\left(U_{1} \otimes U_{2}, V_{1} \otimes V_{2}\right)$ to the subspace $\mathbf{U}_{1} \otimes_{c} \mathbf{U}_{2}$ in the domain and $\mathbf{V}_{1} \otimes_{c} \mathbf{V}_{2}$ in the target.

For $u_{1} \in U_{1}, u_{2} \in U_{2}$, these elements of $V_{1} \otimes V_{2}$ are equal:

$$
\begin{aligned}
& \left([A \otimes B] \circ Q_{c}\right)\left(P_{c}\left(u_{1} \otimes u_{2}\right)\right) \\
= & {[A \otimes B]\left(\frac{1}{2}\left(u_{1} \otimes u_{2}-\left(J_{U_{1}}\left(u_{1}\right)\right) \otimes\left(J_{U_{2}}\left(u_{2}\right)\right)\right)\right) } \\
= & \frac{1}{2}\left(\left(A\left(u_{1}\right)\right) \otimes\left(B\left(u_{2}\right)\right)-\left(A\left(J_{U_{1}}\left(u_{1}\right)\right)\right) \otimes\left(B\left(J_{U_{2}}\left(u_{2}\right)\right)\right)\right) \\
& \left(-\left[\left(J_{V_{1}} \circ A\right) \otimes\left(B \circ J_{U_{2}}\right)\right] \circ Q_{c}\right)\left(P_{c}\left(u_{1} \otimes u_{2}\right)\right) \\
= & -\left[\left(J_{V_{1}} \circ A\right) \otimes\left(B \circ J_{U_{2}}\right)\right]\left(\frac{1}{2}\left(u_{1} \otimes u_{2}-\left(J_{U_{1}}\left(u_{1}\right)\right) \otimes\left(J_{U_{2}}\left(u_{2}\right)\right)\right)\right) \\
= & \frac{1}{2}\left(-\left(J_{V_{1}}\left(A\left(u_{1}\right)\right)\right) \otimes\left(B\left(J_{U_{2}}\left(u_{2}\right)\right)\right)+\left(J_{V_{1}}\left(A\left(J_{U_{1}}\left(u_{1}\right)\right)\right)\right) \otimes\left(B\left(J_{U_{2}}\left(J_{U_{2}}\left(u_{2}\right)\right)\right)\right)\right) .
\end{aligned}
$$

Because $\mathbf{U}_{\mathbf{1}} \otimes_{c} \mathbf{U}_{\mathbf{2}}$ is spanned by elements of the form $P_{c}\left(u_{1} \otimes u_{2}\right)$, these maps $\mathbf{U}_{\mathbf{1}} \otimes_{c} \mathbf{U}_{\mathbf{2}} \rightarrow \mathbf{V}_{\mathbf{1}} \otimes_{c} \mathbf{V}_{\mathbf{2}}$ are equal:

$$
P_{c}^{\prime} \circ\left(\frac{1}{2}\left([A \otimes B]-\left[\left(J_{V_{1}} \circ A\right) \otimes\left(B \circ J_{U_{2}}\right)\right]\right)\right) \circ Q_{c}=P_{c}^{\prime} \circ[A \otimes B] \circ Q_{c}
$$

The above LHS is as in (5.23), and the RHS is from Notation 5.67, giving the equality:

$$
\left(\tilde{a}_{2} \circ P_{2}^{\prime}\right)(A \otimes B)=\left[A \otimes_{c} B\right]=\left(\left.\operatorname{Hom}\left(Q_{c}, P_{c}^{\prime}\right) \circ j\right|_{\operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{1}}, \mathbf{V}_{\mathbf{1}}\right) \otimes \operatorname{Hom}_{c}\left(\mathbf{U}_{\mathbf{2}}, \mathbf{V}_{\mathbf{2}}\right)}\right)(A \otimes B)
$$

There would be no ambiguity in denoting $\mathbf{j}=\tilde{a}_{2}$.

Lemma 5.119. For any U, V, W, the following diagram is commutative.


Proof. This is a c-linear version of Lemma 2.75, so all these objects are subspaces of spaces from Lemma 2.75; the following argument keeps track of all of the inclusions. The spaces $U \otimes \operatorname{Hom}(V, W) \otimes V$ and $\operatorname{Hom}(V, U \otimes W) \otimes V$ each admit four commuting CSOs, and the map $\left[n \otimes I d_{V}\right]$ is c-linear with respect to four corresponding pairs as in Lemma 5.111, by Lemma 5.24 and Theorem 5.100. Some of the projections and induced maps from Lemma 5.111 are as in the following diagram.


In the upper block, $\left[n^{1} \otimes I d_{V}\right]$ is induced by $\left[n \otimes I d_{V}\right]$ as in Lemma 1.85 and Theorem 5.100, where $n$ induces $n^{1}$. The middle block is similarly related to the lower block from Theorem 5.100. In the lowest block, $\left[\mathbf{n} \otimes_{c} I d_{V}\right]$ is induced as in

Example 5.66, and $\left[\mathbf{n} \otimes_{c} I d_{V}\right]$ also appears in the following diagram.


In the upper block, $Q_{c(23)}$ is the inclusion corresponding to the projection $P_{c(23)}$ from the previous diagram, and as in Example 5.64, $Q_{c(23)}=\left[I d_{U} \otimes\left[Q_{c} \otimes I d_{V}\right]\right]$ for $Q_{c}: \operatorname{Hom}(\mathbf{V}, \mathbf{W}) \hookrightarrow \operatorname{Hom}(V, W)$. The inclusion $Q_{c((23) 4)}$ does not correspond to any projection from the previous diagram, but again as in Example 5.64, it is equal to $\left[I d_{U} \otimes \tilde{Q}\right]$, for the inclusion $\tilde{Q}: \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes_{c} \mathbf{V} \hookrightarrow \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes V$. The upper block is then commutative by Lemma 1.35 and adapting formula (5.20) from Example 5.106, $E v_{\mathbf{V W}}^{c}=E v_{V W} \circ\left[Q_{c} \otimes I d_{V}\right] \circ \tilde{Q}$. The second block is commutative by Notation 5.67 for the induced map $\left[I d_{U} \otimes_{c} E v_{\mathbf{V W}}^{c}\right]$. The commutativity of the center block is the claim of the Lemma. The fourth block is commutative, it is an adaptation of formula (5.20) defining $E v_{\mathbf{V}, \mathbf{U} \otimes_{c} \mathbf{W}}^{c}$. The inclusion $Q_{c((132) 4)}^{\prime}$ is equal to the inclusion with the first three indices re-ordered, $Q_{c((231) 4)}^{\prime}$, corresponding to the projection in the first diagram. In the lowest block, $P_{c(13)}^{\prime}$ does not appear in the first diagram; it is equal to $\left[\operatorname{Hom}\left(I d_{V}, P_{c}^{\prime}\right) \otimes I d_{V}\right]$ as in Example 5.64 and Example 5.74. So, the lowest block is commutative by Lemma 2.71. The claim follows, using Lemma 2.75 and equalities of composite inclusions from Theorem
5.110 .

$$
\begin{aligned}
& E v_{\mathbf{V}, \mathbf{U} \otimes_{c} \mathbf{W}}^{c} \circ\left[\mathbf{n} \otimes_{c} I d_{V}\right] \\
&= E v_{V, \mathbf{U} \otimes_{c} \mathbf{W} \circ Q_{c((13) 2)}^{\prime} \circ Q_{c((132) 4)}^{\prime} \circ\left[\mathbf{n} \otimes_{c} I d_{V}\right]}^{=} \quad E v_{V, \mathbf{U} \otimes_{c} \mathbf{W} \circ P_{c(13)}^{\prime} \circ Q_{c(13)}^{\prime} \circ Q_{c((13) 2)}^{\prime} \circ Q_{c((132) 4)}^{\prime} \circ\left[\mathbf{n} \otimes_{c} I d_{V}\right]}= \\
& P_{c}^{\prime} \circ E v_{V, U \otimes W} \circ{Q_{c(23)}^{\prime} \circ{Q_{c((23) 1)}^{\prime} \circ Q_{c((231) 4)}^{\prime} \circ\left[\mathbf{n} \otimes_{c} I d_{V}\right]}^{\prime}}^{\prime} P_{c}^{\prime} \circ E v_{V, U \otimes W} \circ\left[n \otimes I d_{V}\right] \circ Q_{c(23)} \circ Q_{c((23) 1)} \circ Q_{c((231) 4)} \\
&= P_{c}^{\prime} \circ\left[I d_{U} \otimes E v_{V W}\right] \circ Q_{c(23)} \circ Q_{c((23) 4)} \circ Q_{c((234) 1)} \\
&= {\left[I d_{U} \otimes_{c} E v_{\mathbf{V W}}^{c}\right] . }
\end{aligned}
$$

Theorem 5.120. For any $\mathbf{V}=\left(V, J_{V}\right)$, $\mathbf{U}, \mathbf{W}$, and c-linear $F: \mathbf{V} \otimes_{c} \mathbf{U} \rightarrow$ $\mathbf{V} \otimes_{c} \mathbf{W}$, if $V$ is finite-dimensional then the $\mathbf{n}$ maps in the following diagram are invertible:

and the diagram is commutative, in the sense that

$$
\begin{aligned}
& F \circ\left[I d_{V} \otimes_{c} E v_{\mathbf{V U}}^{c}\right] \circ\left[\mathbf{n}_{2} \otimes_{c} I d_{V}\right]^{-1} \\
= & {\left[I d_{V} \otimes_{c} E v_{\mathbf{V W}}^{c}\right] \circ\left[\mathbf{n}_{2}^{\prime} \otimes_{c} I d_{V}\right]^{-1} \circ\left[\operatorname{Hom}_{c}\left(I d_{V}, F\right) \otimes_{c} I d_{V}\right] . }
\end{aligned}
$$

Proof. This is a c-linear version of Theorem 2.76, and the Proof is analogous. The maps $\mathbf{n}_{2}$ and $\mathbf{n}_{2}^{\prime}$ are special cases of the $\mathbf{n}$ map from Lemma 5.119; they are invertible by Lemma 1.42 and Theorem 5.100 , with $\left[\mathbf{n}_{2} \otimes_{c} I d_{V}\right]^{-1}=\left[\mathbf{n}_{2}^{-1} \otimes_{c} I d_{V}\right]$.

By Lemma 5.119, the upward composite on the left is equal to $E v_{\mathbf{V}, \mathbf{V} \otimes_{c} \mathbf{U}}^{c}$, and similarly the upward composite on the right is equal to $E v_{\mathbf{V}, \mathbf{V} \otimes_{c} \mathbf{W}}^{c}$. The claim then follows from Lemma 5.107.

Remark 5.121. The results in this Section on the c-linear evaluation map from Example 5.106: Lemma 5.107, Lemma 5.119, and Theorem 5.120, give some details omitted from $\left[\mathbf{C}_{2}\right] \S 4$.

### 5.4. Real trace with complex vector values

In this Section we develop the notion of vector valued trace of $\mathbb{R}$-linear maps, where the value spaces have complex structure operators. The approach will be to refer to Chapter 2, while avoiding scalar multiplication.

Theorem 5.100 on the c-linearity of $n$ maps generalizes in a straightforward way to the various orderings of $n$ maps from Notation 1.39, as in the following Corollary. Recall from Theorem 2.72 the special case

$$
n^{\prime}: \operatorname{Hom}(V, W) \otimes V \rightarrow \operatorname{Hom}(V, V \otimes W): A \otimes v \mapsto(u \mapsto v \otimes(A(u))),
$$

which is invertible if $V$ is finite-dimensional.
Corollary 5.122. If $\mathbf{V}=\left(V, J_{V}\right)$ and $\mathbf{W}=\left(W, J_{W}\right)$, then $n^{\prime}: \operatorname{Hom}(V, W) \otimes$ $V \rightarrow \operatorname{Hom}(V, V \otimes W)$ is c-linear with respect to corresponding pairs of the three commuting CSOs induced on each space, so it respects the direct sums and induces maps

$$
\begin{aligned}
n_{1}^{\prime}: \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes V & \rightarrow \operatorname{Hom}_{c}(\mathbf{V}, V \otimes \mathbf{W}) \\
n_{2}^{\prime}: \operatorname{Hom}(\mathbf{V}, W) \otimes_{c} \mathbf{V} & \rightarrow \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{V} \otimes W) \\
n_{3}^{\prime}: \operatorname{Hom}(V, \mathbf{W}) \otimes_{c} \mathbf{V} & \rightarrow \operatorname{Hom}\left(V, \mathbf{V} \otimes_{c} \mathbf{W}\right) \\
\mathbf{n}^{\prime}: \operatorname{Hom}_{c}(\mathbf{V}, \mathbf{W}) \otimes_{c} \mathbf{V} & \rightarrow \operatorname{Hom}_{c}\left(\mathbf{V}, \mathbf{V} \otimes_{c} \mathbf{W}\right),
\end{aligned}
$$

which are invertible if $n^{\prime}$ is.
THEOREM 5.123. If $V$ is finite-dimensional and $\mathbf{W}=\left(W, J_{W}\right)$, then the map

$$
T r_{V ; W}=E v_{V W} \circ\left(n^{\prime}\right)^{-1}: \operatorname{Hom}(V, V \otimes \mathbf{W}) \rightarrow \mathbf{W}
$$

is c-linear.
Proof. The map $n^{\prime}$ is from Corollary 5.122: it is c-linear with respect to $\left[\operatorname{Hom}\left(I d_{V}, J_{W}\right) \otimes I d_{V}\right]$ and $\operatorname{Hom}\left(I d_{V},\left[I d_{V} \otimes J_{W}\right]\right)$ (without assuming any CSO on $V)$. The canonical evaluation $E v_{V W}: A \otimes v \mapsto A(v)$ from Definition 2.69 is c-linear $\operatorname{Hom}(V, \mathbf{W}) \otimes V \rightarrow \mathbf{W}$ as in Exercise 5.44, and the equality $T r_{V ; W} \circ n^{\prime}=E v_{V W}$ is from Theorem 2.72. The result could also be proved by applying Corollary 2.58 (or Corollary 2.73) with $B=J_{W}$.

Theorem 5.124. If $V$ is finite-dimensional and $W$ admits commuting CSOs $J_{1}, J_{2}$, then the map $\operatorname{Tr}_{V ; W}$ respects the direct sums

$$
\operatorname{Hom}\left(V, V \otimes W_{c}\right) \oplus \operatorname{Hom}\left(V, V \otimes W_{a}\right) \rightarrow W_{c} \oplus W_{a}
$$

and the induced c-linear map $\operatorname{Hom}\left(V, V \otimes W_{c}\right) \rightarrow W_{c}$ is equal to $\operatorname{Tr}_{V ; W_{c}}$.
Proof. Lemma 2.60 applies. The direct sums on $V \otimes W$ and $\operatorname{Hom}(V, V \otimes W)$ are as in Example 5.64 and Example 5.74, with canonical projections as indicated in the diagram. $T r_{V ; W}$ is c-linear with respect to both corresponding pairs of CSOs by Theorem 5.123, and the c-linearity of the induced map follows from Lemma 5.57.


Theorem 5.125. For finite-dimensional $V$, and $U$, $W$ with $C S O s ~ J_{U}$, $J_{W}$, the generalized trace

$$
\operatorname{Tr}_{V ; U, W}: \operatorname{Hom}(V \otimes U, V \otimes W) \rightarrow \operatorname{Hom}(U, W)
$$

is c-linear with respect to both pairs of corresponding commuting CSOs, and respects the direct sums, inducing a c-linear map, denoted

$$
\operatorname{Tr}_{V ; \mathbf{U}, \mathbf{w}}: \operatorname{Hom}_{c}(V \otimes \mathbf{U}, V \otimes \mathbf{W}) \rightarrow \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W})
$$

Proof. The c-linearity claims follow from Theorem 2.30, and then Lemma 5.57 applies. That is enough for the Proof, but to see how the generalized trace is related to two different vector valued traces, consider the following diagram,

where

$$
\begin{aligned}
M_{11} & =\operatorname{Hom}(V, \operatorname{Hom}(U, V \otimes W)) \\
M_{12} & =\operatorname{Hom}(V, V \otimes \operatorname{Hom}(U, W)) \\
M_{21} & =\operatorname{Hom}\left(V, \operatorname{Hom}_{c}(\mathbf{U}, V \otimes \mathbf{W})\right) \\
M_{22} & =\operatorname{Hom}\left(V, V \otimes \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W})\right) .
\end{aligned}
$$

All the vertical arrows are the canonical projections of the direct sums produced by the commuting CSOs induced by $J_{U}$ and $J_{W}$. The right square is commutative by Lemma 2.60; this is an example of Theorem 5.124 , where the projection $M_{12} \rightarrow M_{22}$ is equal to $\operatorname{Hom}\left(I d_{V},\left[I d_{V} \otimes P_{H}\right]\right)$. The map $n: V \otimes \operatorname{Hom}(U, W) \rightarrow$ $\operatorname{Hom}(U, V \otimes W)$ from Theorem 5.100 is invertible and c-linear with respect to the commuting corresponding pairs of CSOs induced by $J_{U}$ and $J_{W}$. Example 5.79 applies to $\operatorname{Hom}\left(I d_{V}, n\right)$ and the middle square in the diagram: the induced map (lower middle arrow) is invertible, c-linear, and equal to $\operatorname{Hom}\left(I d_{V}, n^{1}\right)$, where $n^{1}$ is the induced map from Theorem 5.100. The map $q$ is as in Theorem 2.52, which asserts the commutativity of the diagram's top triangle. By Example 5.101, the map $q$ similarly induces an invertible c-linear map, $q_{1}$. We can conclude, for $K: V \rightarrow V \otimes \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W})$,

$$
\operatorname{Tr}_{V ; \operatorname{Hom}_{c}(\mathbf{U}, \mathbf{W})}(K)=\operatorname{Tr}_{V ; \mathbf{U}, \mathbf{W}}\left(q_{1}\left(n^{1} \circ K\right)\right) .
$$

## CHAPTER 6

## Appendices

### 6.1. Appendix: Functions and Binary Operations

Definition 6.1. Given sets $S$ and $T$, the product set $S \times T$ is the set of ordered pairs $\{(\sigma, \tau): \sigma \in S, \tau \in T\}$.

Definition 6.2. Given sets $S$ and $T$, suppose there is a subset $G \subseteq S \times T$ with the following properties.

- If $\left(s_{1}, t_{1}\right) \in G$ and $\left(s_{2}, t_{2}\right) \in G$ and $s_{1}=s_{2}$ then $t_{1}=t_{2}$.
- For each $s \in S$, there is an element $(s, t) \in G$.

Then for each $s \in S$, there is exactly one element $\alpha(s) \in T$ so that $(s, \alpha(s)) \in G$. This defines a function $\alpha$, with domain $S$, target $T$, and graph $G$, which is denoted (as in Notation 0.36) by the arrow notation $\alpha: S \rightsquigarrow T$.

DEfinition 6.3. Given a set $S$, a binary operation on $S$ is any function from $S \times S$ to $S$. The notation $(S, *)$ denotes a set $S$, together with $*$, a binary operation on $S$. For $x, y \in S$, and a binary operation $*$, the element $*((x, y))$ will be abbreviated $x * y$.

DEFINITION 6.4. A binary operation $*$ on $S$ is associative means: for all $x, y, z \in$ $S,(x * y) * z=x *(y * z)$. The binary operation $*$ is commutative means: for all $x, y \in S, x * y=y * x$.

Definition 6.5. Given $(S, *)$, any element $e \in S$ such that $e * x=x * e=x$ for all $x \in S$ is called an identity element.

Exercise 6.6. Given $(S, *)$, suppose there is an identity element $e \in S$. Then, the identity element is unique.

Exercise 6.7. Given $(S, *)$, with an identity element $e$, if for all $x, y, z \in S$, $x *(y * z)=(x * z) * y$, then $*$ is commutative and associative.

ExERCISE 6.8. Give an example of a set and an operation $*$ where $x *(y * z)=$ $(x * z) * y$ holds but $*$ is not associative.

Definition 6.9. Given $(S, *)$, and an identity element $e \in S$, and $x, y \in S$, $\underline{y \text { is a } * \text {-inverse for } x}$ means that $x * y=y * x=e$.

Note that $*$-inverse cannot be defined without an identity element, so in any statement asserting the existence of a $*$-inverse, it is assumed that there exists an identity element for the operation $*$.

Exercise 6.10. Given $(S, *)$, let $e$ be an identity element. Then $e$ has a $*-$ inverse, and this inverse is unique.

Exercise 6.11. Given $(S, *)$, and $x \in S$, if $*$ is associative, and there exist $y \in S, z \in S$ such that $y * x=e$ and $x * z=e$, then $y=z$ and $y$ is a $*$-inverse for $x$. In particular, any $*$-inverse for $x$ is unique.

Notation 6.12. Usually it is more convenient to call a $*$-inverse just an "inverse," and if an element $x$ has a unique inverse, it can be denoted $x^{-1}$. There may be some other abbreviations for certain operations; customarily a + -inverse of $x$ is denoted $-x$.

ExErcise 6.13. Given $(S, *)$, and $x, y \in S$, if $*$ is associative, and $x$ and $y$ both have $*$-inverses, then $x * y$ has a unique $*$-inverse, $y^{-1} * x^{-1}$.

Exercise 6.14. Given $(S, *)$, and $x \in S$, if $*$ is associative, and there exists a $*$-inverse for $x$, and $x * x=x$, then $x=e$.

Example 6.15. Given a set $S$, let $\mathcal{F}$ denote the set of functions $\{\alpha: S \rightsquigarrow S\}$. Composition of functions is an example of a binary operation on $\mathcal{F}$, denoted $\circ$, so that the function $\alpha \circ \beta$ is defined by the formula depending on $x \in S$ :

$$
\begin{equation*}
(\alpha \circ \beta)(x)=\alpha(\beta(x)) \tag{6.1}
\end{equation*}
$$

The operation $\circ$ is associative and has an identity element denoted $I d_{S} \in \mathcal{F}$, which is the function with graph $G=\{(x, x): x \in S\}$, so that $I d_{S}(x)=x$ for all $x \in S$.

Notation 6.16. The same symbol $\circ$ is used for composites of functions between other sets, although this is no longer an example of a binary operation as in Definition 6.3. For any sets $S, T, U$, and any functions $\beta: S \rightsquigarrow T$ and $\alpha: T \rightsquigarrow U$, there is a composite function $\alpha \circ \beta: S \rightsquigarrow U$, defined as in (6.1). An associative property holds: $(\alpha \circ \beta) \circ \gamma=\alpha \circ(\beta \circ \gamma)$.

ExErcise 6.17. Given $S \neq \varnothing$, and a function $\alpha: S \rightsquigarrow T$, the following are equivalent.
(1) For all $s_{1}, s_{2} \in S$, if $s_{1} \neq s_{2}$, then $\alpha\left(s_{1}\right) \neq \alpha\left(s_{2}\right)$ ( $\alpha$ has the one-to-one property).
(2) For any set $C$ and any functions $\gamma: C \rightsquigarrow S, \delta: C \rightsquigarrow S$, if $\alpha \circ \gamma: C \rightsquigarrow T$ and $\alpha \circ \delta: C \rightsquigarrow T$ are the same function, then $\gamma=\delta$ ( $\alpha$ has the left cancellable property).
(3) There is a function $\beta: T \rightsquigarrow S$ so that $\beta \circ \alpha: S \rightsquigarrow S$ is equal to the identity function $I d_{S}: S \rightsquigarrow S$ ( $\alpha$ has a left inverse).

ExERCISE 6.18. Given a function $\alpha: S \rightsquigarrow T$, the following are equivalent.
(1) For all $t \in T$, there is some $s \in S$ so that $\alpha(s)=t$ ( $\alpha$ has the onto property).
(2) For any set $C$ and any functions $\gamma: T \rightsquigarrow C, \delta: T \rightsquigarrow C$, if $\gamma \circ \alpha: S \rightsquigarrow C$ and $\delta \circ \alpha: S \rightsquigarrow C$ are the same function, then $\gamma=\delta$ ( $\alpha$ has the right cancellable property).
(3) There is a function $\beta: T \rightsquigarrow S$ so that $\alpha \circ \beta: T \rightsquigarrow T$ is equal to the identity function $I d_{T}: T \rightsquigarrow T$ ( $\alpha$ has a right inverse).

Hint. The $(1) \Longrightarrow(3)$ step requires the Axiom of Choice.

Exercise 6.19. If $\beta: T \rightsquigarrow S$ is a left inverse of $\alpha$ and $\gamma: T \rightsquigarrow S$ is a right inverse of $\alpha$ then $\beta=\gamma$.

Hint. This is analogous to Exercise 6.11.
Exercise 6.20. Given $S \neq \varnothing$ and a function $\alpha: S \rightsquigarrow T$, the following are equivalent.
(1) $\alpha$ is both one-to-one and onto.
(2) $\alpha$ has a left inverse $\gamma: T \rightsquigarrow S$ and a right inverse $\beta: T \rightsquigarrow S$.
(3) There exists a function $\delta: T \rightsquigarrow S$ so that $\alpha \circ \delta=I d_{T}$ and $\delta \circ \alpha=I d_{S}$.

Hint. The equivalence (1) $\Longleftrightarrow(2)$ uses Exercise 6.17 and Exercise 6.18, although with the one-to-one assumption in (1), the Axiom of Choice is no longer required to construct the right inverse in (2). (3) $\Longrightarrow(2)$ is trivial, and the converse uses Exercise 6.19 to get $\delta=\beta=\gamma$.

Definition 6.21. A function $\alpha: S \rightsquigarrow T$ is invertible means that $\alpha$ satisfies any of the equivalent properties (1), (2), or (3) from Exercise 6.20.

Notation 6.22. A function (such as $\delta=\beta=\gamma$ as in Exercise 6.19), that is both a left inverse and a right inverse of the function $\alpha: S \rightsquigarrow T$ is an inverse of $\alpha$. If an inverse of $\alpha$ exists, then it is unique by Exercise 6.19, it can be denoted $\alpha^{-1}: T \rightsquigarrow U$, and $\alpha^{-1}$ is also invertible, with inverse $\alpha$.

### 6.2. Appendix: Quotient spaces

Definition 6.23. Given any vector space $(V,+v, \cdot v)$ and a subspace $W$, for any element $v \in V$ the following subset of $V$ is called a coset of $W$ :

$$
v+W=\left\{v+{ }_{V} w: w \in W\right\}
$$

Definition 6.24. Given a subspace $W$ of $V$ as in Definition 6.23 , the set of cosets of $W$ is a vector space with the following operations:

$$
\begin{aligned}
\left(v_{1}+W\right)+\left(v_{2}+W\right) & =\left(v_{1}+v v_{2}\right)+W \\
\rho \cdot(v+W) & =(\rho \cdot v v)+W
\end{aligned}
$$

and zero element $0_{V}+W=W$. This vector space is the quotient space, denoted $V / W$.

Exercise 6.25. The function $\pi: V \rightarrow V / W: v \mapsto v+W$ is linear and right cancellable. If $S$ is a subset of $V$ such that $V=\operatorname{span}(S)$, then $V / W=\operatorname{span}(\boldsymbol{\pi}(S))$.

Exercise 6.26. Given a subspace $W$ of $V$ as in Definition 6.23 , and any set $S$, if $B: V \rightsquigarrow S$ is constant on each coset $v+W$ then there exists a unique function $b: V / W \rightsquigarrow S$ such that $b \circ \pi=B$.

Hint. For $v+W \in V / W$, choose any element $x=v+w \in v+W$. Define $b(v+W)=B(x)$; this does not depend on the choice of $x$ by hypothesis, and $v \in v+W$ (because $\left.0_{V} \in W\right)$ so $b(v+W)=B(x)=B(v)$. Then for any $v \in V$, $(b \circ \boldsymbol{\pi})(v)=b(\boldsymbol{\pi}(v))=b(v+W)=B(x)=B(v)$ as claimed. For uniqueness, use the right cancellable property of $\boldsymbol{\pi}$.

Exercise 6.27. Given a subspace $W$ of $V$ as in Definition 6.23 , and another vector space $U$, if $B: V \rightarrow U$ is linear and satisfies $B(w)=0_{U}$ for all $w \in W$, then there exists a unique function $b: V / W \rightarrow U$ such that $b \circ \pi=B$, and $b$ is linear.

Hint. For any $v \in V$, if $x \in v+W$ then $x=v+w$ for some $w \in W$ and $B(x)=B(v+w)=B(v)+B(w)=B(v)+0_{U}=B(v)$. So, $B$ is constant on the coset $v+W$, and the previous Exercise applies to show there is a unique $b$ with $b \circ \boldsymbol{\pi}=B$. The linearity of $b$ easily follows from the linearity of $B$.

### 6.3. Appendix: Construction of the tensor product

As mentioned in Section 1.2, we elaborate on the existence of a tensor product of two vector spaces. The notation and methods in this Appendix are specific to this construction and not widely used in the Chapters. We start with a set of functions $\mathcal{F}(S, W)$ only because it comes with a convenient vector space structure.

Example 6.28 . For any set $S \neq \emptyset$ and any vector space $W$, the set of functions

$$
\mathcal{F}(S, W)=\{f: S \rightsquigarrow W\}
$$

is a vector space, with the usual operations of pointwise addition of functions and scalar multiplication of functions, and zero element given by the constant function $f(x) \equiv 0_{W}$.

Notation 6.29. For a set $S \neq \emptyset$ and any field $\mathbb{K}$, for each $x \in S$ there is an element $\boldsymbol{\delta}(x) \in \mathcal{F}(S, \mathbb{K})$ defined by:

$$
\begin{array}{lll}
\boldsymbol{\delta}(x): y & \mapsto & 1 \text { for } y=x  \tag{6.2}\\
\boldsymbol{\delta}(x): y & \mapsto & 0 \text { for } y \neq x
\end{array}
$$

The span of the set of such functions is denoted

$$
\mathcal{F}_{0}(S, \mathbb{K})=\operatorname{span}(\{\boldsymbol{\delta}(x): x \in S\}),
$$

so $\mathcal{F}_{0}(S, \mathbb{K})$ is a subspace of $\mathcal{F}(S, \mathbb{K})$. The notation (6.2) defines a function

$$
\boldsymbol{\delta}: S \rightsquigarrow \mathcal{F}_{0}(S, \mathbb{K}): x \mapsto \boldsymbol{\delta}(x) .
$$

ExErcise 6.30. For $S$ as above and any function $f: S \rightsquigarrow \mathbb{K}$, the following are equivalent.
(1) $f \in \mathcal{F}_{0}(S, \mathbb{K})$.
(2) The function $f$ is uniquely expressible as a finite sum of functions with coefficients $\alpha_{\nu} \in \mathbb{K}$ and $x_{\nu} \in S: f=\sum_{\nu=1}^{N} \alpha_{\nu} \cdot \boldsymbol{\delta}\left(x_{\nu}\right)$.
(3) $f(x)=0$ for all but finitely many $x \in S$.

Exercise 6.31. Given $S, \mathbb{K}$, and $\boldsymbol{\delta}$ as in Notation 6.29, and any vector space $W$, If $g: S \rightsquigarrow W$ is any function, then there exists a unique linear map $\bar{g}: \mathcal{F}_{0}(S, \mathbb{K}) \rightarrow$ $W$ such that $\bar{g} \circ \boldsymbol{\delta}=g: S \rightsquigarrow W$.

Hint. As in Exercise 6.30, the general element $f$ of $\mathcal{F}_{0}(S, \mathbb{K})$ has a unique expression of the form $f=\sum_{\nu=1}^{N} \alpha_{\nu} \cdot \boldsymbol{\delta}\left(x_{\nu}\right)$; define $\bar{g}$ on such an expression by using the same coefficients $\alpha_{\nu}$ and elements $x_{\nu}$ :

$$
\bar{g}(f)=\sum_{\nu=1}^{N} \alpha_{\nu} \cdot g\left(x_{\nu}\right)
$$

Then for each $x \in S$, the composite function satisfies the claim:

$$
(\bar{g} \circ \boldsymbol{\delta})(x)=\bar{g}(1 \cdot \boldsymbol{\delta}(x))=1 \cdot g(x)=g(x) .
$$

The uniqueness and $\mathbb{K}$-linearity of $\bar{g}$ are easily checked.

Definition 6.32. Given vector spaces $U$ and $V$, define the following subsets of $\mathcal{F}_{0}(U \times V, \mathbb{K})$ :

$$
\begin{aligned}
R_{1} & =\left\{\boldsymbol{\delta}\left(\left(u_{1}+u_{2}, v\right)\right)-\boldsymbol{\delta}\left(\left(u_{1}, v\right)\right)-\boldsymbol{\delta}\left(\left(u_{2}, v\right)\right): u_{1}, u_{2} \in U, v \in V\right\} \\
R_{2} & =\left\{\boldsymbol{\delta}\left(\left(u, v_{1}+v_{2}\right)\right)-\boldsymbol{\delta}\left(\left(u, v_{1}\right)\right)-\boldsymbol{\delta}\left(\left(u, v_{2}\right)\right): u \in U, v_{1}, v_{2} \in V\right\} \\
R_{3} & =\{\boldsymbol{\delta}((\rho \cdot u, v))-\rho \cdot \boldsymbol{\delta}((u, v)): \rho \in \mathbb{K}, u \in U, v \in V\} \\
R_{4} & =\{\boldsymbol{\delta}((u, \rho \cdot v))-\rho \cdot \boldsymbol{\delta}((u, v)): \rho \in \mathbb{K}, u \in U, v \in V\} \\
R & =\operatorname{span}\left(R_{1} \cup R_{2} \cup R_{3} \cup R_{4}\right) .
\end{aligned}
$$

The tensor product space of $U$ and $V$ is defined to be the quotient space:

$$
U \otimes V=\mathcal{F}_{0}(U \times V, \mathbb{K}) / R
$$

Let $\boldsymbol{\pi}: \mathcal{F}_{0}(U \times V, \mathbb{K}) \rightarrow U \otimes V$ denote the quotient map as in Exercise 6.25.
Definition 6.33. Define a function $\boldsymbol{\tau}: U \times V \rightsquigarrow U \otimes V$ by:

$$
\boldsymbol{\tau}=\boldsymbol{\pi} \circ \boldsymbol{\delta}:(u, v) \mapsto \boldsymbol{\pi}(\boldsymbol{\delta}((u, v)))=\boldsymbol{\delta}((u, v))+R
$$

The output $\boldsymbol{\tau}((u, v))$ is abbreviated $u \otimes v \in U \otimes V$.
ExERCISE 6.34. $\tau: U \times V \rightsquigarrow U \otimes V$ is a bilinear function.
Hint. Definition 1.22 is easily checked.
Theorem 6.35. For any bilinear function $A: U \times V \rightsquigarrow W$, there exists a unique linear map $a: U \otimes V \rightarrow W$ such that $A=a \circ \boldsymbol{\tau}$.

Proof. By Exercise 6.31, there exists a unique linear map $\bar{A}: \mathcal{F}_{0}(U \times V, \mathbb{K}) \rightarrow$ $W$ such that $\bar{A} \circ \boldsymbol{\delta}=A$. The linear map $\bar{A}$ has value $0_{W}$ on every element of the subspace $R$; it is enough to check that $\bar{A}(r)=0_{W}$ for $r$ in each of the four subsets $R_{1}, \ldots, R_{4}$ from Definition 6.32 , for example, for $r \in R_{1}$,

$$
\begin{aligned}
\bar{A}(r) & =\bar{A}\left(\boldsymbol{\delta}\left(\left(u_{1}+u_{2}, v\right)\right)-\boldsymbol{\delta}\left(\left(u_{1}, v\right)\right)-\boldsymbol{\delta}\left(\left(u_{2}, v\right)\right)\right) \\
& =A\left(\left(u_{1}+u_{2}, v\right)\right)-A\left(\left(u_{1}, v\right)\right)-A\left(\left(u_{2}, v\right)\right) \\
& =0_{W}
\end{aligned}
$$

The other $\bar{A}(r)$ values follow similarly from the bilinear property of $A$. Exercise 6.27 applies to $\bar{A}$, to give a unique linear map

$$
a: \mathcal{F}_{0}(U \times V, \mathbb{K}) / R \rightarrow W: f+R \mapsto \bar{A}(f)
$$

such that $a \circ \boldsymbol{\pi}=\bar{A}$. The conclusion is that

$$
a \circ \boldsymbol{\tau}=a \circ(\boldsymbol{\pi} \circ \boldsymbol{\delta})=(a \circ \boldsymbol{\pi}) \circ \boldsymbol{\delta}=\bar{A} \circ \boldsymbol{\delta}=A \Longrightarrow a(u \otimes v)=A(u, v)
$$

For the uniqueness, suppose there is some $a^{\prime}$ with $a \circ \boldsymbol{\pi} \circ \boldsymbol{\delta}=A=a^{\prime} \circ \boldsymbol{\pi} \circ \boldsymbol{\delta}$. The set $\{\boldsymbol{\delta}((u, v)): u \in U, v \in V\}$ spans $\mathcal{F}_{0}(U \times V, \mathbb{K})$ as in Notation 6.29 , and the image under $\boldsymbol{\pi}$ of this set, $\{u \otimes v: u \in U, v \in V\}$, spans $U \otimes V=\mathcal{F}_{0}(U \times V, \mathbb{K}) / R$ by Exercise 6.25. So $a$ and $a^{\prime}$ agree on a spanning set of $U \otimes V$ and must be equal.

### 6.4. Appendix: Comments on $\left[\mathrm{C}_{2}\right]$

6.4.1. Errata. The following typo appears in the published paper, $\left[\mathbf{C}_{2}\right]$.

On page 535 , line 3 , the symbol should be $\vec{x}_{q^{\prime}} \mapsto$ instead of $\vec{x}_{q^{\prime}}=$.
6.4.2. Updates. The topic of defining a "trace without duals" (as in $\left[\mathbf{C}_{2}\right] \S 3$ ) is briefly considered by $[\mathbf{S}] \S 1.7$.

Some details omitted from $\left[\mathbf{C}_{2}\right]$ are presented here in Chapter 2 (see Remark 2.109) and Section 5.3 (see Remark 5.121).

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